# Solving large linear systems with multiple right-hand sides 

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## Motivations

In electromagnetism design, it is necessary to be able to predict the currents induced by an incident plane wave on a given object.
Using the boundary element method on the Maxwell equation, this amounts to solve the linear system

$$
\mathbb{Z} x=b
$$

where

- $\mathbb{Z}$ represents the impedance of the object ( Ohm )
- brepresents the incident field (Volt )

D represents the current on the object ( Ampere )

## Antenna design



Representation of the electric current due to an antenna on the Citroën C5 car.

## Monostatic radar cross section




Monostatic Radar Cross Section (RCS) for the Airbus 23676.

## Motivation

## This class of problem naturally leads to

$$
\mathbb{Z}\left(x_{1}, x_{2}, \ldots, x_{p}\right)=\left(b_{1}, b_{2}, \ldots, b_{p}\right),
$$

that is to say
solve a linear system with multiple right-hand sides.

## Outline

Study of the Gram-Schmidt algorithm and its variants

- Implementation of iterative methods

The electromagnetism applications

## Study of the Gram-Schmidt algorithm and its variants

## The GMRES method

The GMRES method (Saad \& Schultz '86) gives, at each setp $n$, the approximate solution $x_{n}$ that solves the least-squares problem

$$
\min _{x \in \mathcal{K}_{n}(\mathbb{Z}, b)}\|b-\mathbb{Z} x\|_{2}
$$

where $\mathcal{K}_{n}(\mathbb{Z}, b)$ is the Krylov space

$$
\mathcal{K}_{n}(\mathbb{Z}, b)=\operatorname{Span}\left(b, \mathbb{Z} b, \mathbb{Z}^{2} b, \ldots \mathbb{Z}^{n-1} b\right) .
$$

## Link with QR-factorization

$$
\begin{array}{cccc}
\left(b, \mathbb{Z} V_{n}\right) & = & V_{n+1} & \left(e_{1} \beta, H_{n+1, n}\right) \\
\downarrow & & \downarrow & \downarrow \\
A & = & Q & R
\end{array}
$$

To summarize the GMRES methods needs

- a matrix-vector product operation (and also a preconditioner operation)
- an orthogonalization scheme


## Gram-Schmidt algorithm

Starting from $\mathbf{A}=\left(\mathbf{a}_{1}, \ldots, \mathbf{a}_{n}\right) \in \mathbb{R}^{m \times n}$ with full rank, the Gram-Schmidt algorithm computes Q and R so as

- $\mathbf{A}=\mathbf{Q R}$
- $\mathbf{Q} \in \mathbb{R}^{m \times n}, \mathbf{Q}^{T} \mathbf{Q}=\mathbf{I}_{n}$
- $\mathbf{R} \in \mathbb{R}^{n \times n}, \mathbf{R}$ is upper triangular with positive elements on the diagonal


## Gram-Schmidt algorithm



Jörgen P. Gram Erhard Schmidt
for $j=1, n$ do

$$
\mathbf{w}=\mathbf{a}_{j}
$$

$$
\mathbf{w}=\left(\mathbf{I}-\mathbf{Q}_{j-1} \mathbf{Q}_{j-1}^{T}\right) \mathbf{a}_{j}
$$

$$
\mathbf{q}_{j}=\mathbf{w} /\|\mathbf{w}\|_{2}
$$

end for

## Outline of the first part

- When modified Gram-Schmidt generates a well conditioned set of vectors
- Reorthogonalization issues: twice is enough
- Reorthogonalization issues: about selective reorthogonalization criterion
- Reorthogonalization issues: a-posteriori reorthogonalization algorithm in the modified Gram-Schmidt algorithm


## Classical/Modified

Classical Gram-Schmidt (CGS)
for $j=1, n$ do

$$
\begin{aligned}
& \quad \mathbf{w}=\left(\mathbf{I}-\mathbf{Q}_{j-1} \mathbf{Q}_{j-1}^{T}\right) \mathbf{a}_{j} \\
& \mathbf{q}_{j}=\mathbf{w} /\|\mathbf{w}\|_{2} \\
& \text { end for }
\end{aligned}
$$

Modified Gram-Schmidt (MGS)
for $j=1, n$ do

$$
\begin{aligned}
& \mathbf{w}=\left(\mathbf{I}-\mathbf{q}_{j-1} \mathbf{q}_{j-1}^{T}\right) \ldots\left(\mathbf{I}-\mathbf{q}_{1} \mathbf{q}_{1}^{T}\right) \mathbf{a}_{j} \\
& \mathbf{q}_{j}=\mathbf{w} /\|\mathbf{w}\|_{2}
\end{aligned}
$$

end for

## An experimental fact

Let take $A$ is the $12-$ by- 12 Hilbert matrix with elements $1 /(i+j-1)$

$$
A=\operatorname{hill}(12)=\left(\begin{array}{ccccc}
1 & 1 / 2 & 1 / 3 & \ldots & 1 / 12 \\
& 1 / 3 & 1 / 4 & \ldots & 1 / 13 \\
& & 1 / 5 & \ldots & 1 / 14 \\
& & & \ddots & \vdots \\
& & & & 1 / 23
\end{array}\right) .
$$

It is an example of a ill-conditioned matrix, we have $\kappa(A)=1.68 e+16$.

$$
\left\|I_{n}-Q^{T} Q\right\|_{2}=0.302364
$$

$\Rightarrow Q$ is far from being orthogonal.

## Round-off errors

Computation in floating-point arithmetic implies in general round-off error. Standard exists to control these errors, we work here with the IEEE 754 standard

$$
\mathrm{fl}(x \mathrm{op} y)=(x \text { op } y)(1+\delta) \quad|\delta|<u
$$

## Björck ('67)

$A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular values :
$\sigma_{1} \geq \ldots \geq \sigma_{n}>0, \kappa(A)=\sigma_{1} / \sigma_{n}$,
MGS computes $\bar{Q}$ so as $\left\|I_{n}-Q^{T} Q\right\|_{2}=0 \rightarrow$

$$
\left\|I_{n}-\bar{Q}^{T} \bar{Q}\right\|_{2} \leq \bar{c}_{2} \kappa(A) u
$$

where $\bar{c}_{2}=1.5 n^{\frac{3}{2}}$ and $u$ is the unit round-off. These results hold
under the assumptions :

$$
\bar{c}_{2} u \kappa(\mathbf{A})<1 .
$$

## An experimental fact

Let take $A$ is the $12-$ by-12 Hilbert matrix with elements $1 /(i+j-1)$
It is an example of a ill-conditioned matrix, we have $\kappa(A)=1.68 e+16$.

$$
\begin{gathered}
\left\|I_{n}-Q^{T} Q\right\|_{2}=0.302364 \\
\Rightarrow Q \text { is far from being orthogonal. }
\end{gathered}
$$

However,

$$
\begin{gathered}
\kappa(Q)=1.3 \\
\Rightarrow Q \text { is well conditioned. }
\end{gathered}
$$

## Giraud Langou ('02) - IMAJNA

Let us define $U$ the polar factor of $\bar{Q}\left(U^{T} U=I_{n}\right)$ then Schönemann ('66), Higham ('94) showed

$$
\|\bar{Q}-U\|_{2} \leq\left\|I-\bar{Q}^{T} \bar{Q}\right\|_{2}
$$

Björck ('67) showed that

$$
\left\|I-\bar{Q}^{T} \bar{Q}\right\|_{2} \leq \bar{c}_{2} \kappa(A) u .
$$

This implies that

$$
\kappa(\bar{Q}) \leq \frac{1+\bar{c}_{2} \kappa(A) u}{1-\bar{c}_{2} \kappa(A) u} .
$$

## Giraud Langou ('02) - IMAJNA



## Two MGS loops

$$
\begin{array}{cccc}
A & \text { MGS } & \bar{Q}_{1} & \text { MGS } \\
\bar{c}_{2} u \kappa(A) \leq 0.1 & & \kappa\left(\bar{Q}_{1}\right) \leq 1.3 & \left\|I_{n}-\bar{Q}_{2}^{T} \bar{Q}_{2}\right\|_{2} \leq \bar{c}_{2} \kappa\left(\bar{Q}_{1}\right) u \\
& \\
\operatorname{cu\kappa }(A) \leq 0.1 \longrightarrow\left\|I_{n}-\bar{Q}_{2}^{T} \bar{Q}_{2}\right\|_{2} \leq 40.52 \cdot u \cdot n n^{\frac{3}{2}} .
\end{array}
$$

## TMGS / MGS2

$$
Q^{(0)}=A
$$

for $r=1,2$ do

$$
\text { for } j=1, n \text { do }
$$

$$
w=q_{j}^{(r-1)}
$$

$$
\text { for } i=1, j-1 \text { do }
$$

$$
r_{i j}^{(r)}=q_{i}^{(r) T} w
$$

$$
w=w-q_{i}^{(r)} r_{i j}^{(r)}
$$

end for
$r_{j j}^{(r)}=\|w\|_{2}$
$q_{j}^{(r)}=w / r_{j j}^{(r)}$
end for
end for
$Q=Q^{(2)}$
$R=R^{(2)} R^{(1)}$
for $j=1, n$ do

$$
w=a_{j}
$$

$$
\text { for } r=1,2 \text { do }
$$

$$
\text { for } i=1, j-1 \text { do }
$$

$$
r_{i j}^{(r)}=q_{i}^{T} w
$$

$$
w=w-q_{i} r_{i j}^{(r)}
$$

end for
end for

$$
\begin{aligned}
& r_{j j}^{(2)}=\|w\|_{2} \\
& q_{j}=w / r_{j j}^{(r)}
\end{aligned}
$$

## end for

$R=R^{(2)}+R^{(1)}$

## MGS2(K), $K=1, \infty$

$$
\begin{aligned}
& \text { for } j=1, n \text { do } \\
& \quad \mathbf{w}=\mathbf{a}_{j} \\
& \text { for } r=1,2 \text { do }
\end{aligned}
$$

$$
\text { for } i=1, j-1 \text { do }
$$

$$
r_{i j}^{(r)}=\mathbf{q}_{i}^{T} \mathbf{w}
$$

$$
\mathbf{w}=\mathbf{w}-\mathbf{q}_{i} r_{i j}^{(r)}
$$

end for
if $\frac{\left\|a_{j}\right\|_{2}}{\|w\|_{2}} \leq K$ then reorthogonalize endif end for
$r_{j j}^{(2)}=\|\mathbf{w}\|_{2}$
$\mathbf{q}_{j}=\mathbf{w} / r_{j j}^{(r)}$
end for
$\mathbf{R}=\mathbf{R}^{(2)}+\mathbf{R}^{(1)}$

## Giraud Langou Rozložník ('01)

twice is enough for CGS2 (and MGS2 as well) if $A$ is not too ill conditioned

Sketch of the proof
For all $j$, we have

$$
\frac{\left\|\mathbf{a}_{j}\right\|_{2}}{\|\mathbf{w}\|_{2}} \leq 1.1 \kappa(A) .
$$

and then by induction on $\left\|I-\bar{Q}_{j}^{T} \bar{Q}_{j}\right\|_{2}$.

## Giraud and Langou ('03) - SISC

A rather comonly used criterion (Rutishauser ('67), Gander ('77), Ruhe('83), Hoffmann ('89), Dax ('00))

$$
\frac{\left\|a_{j}\right\|_{2}}{\|w\|_{2}} \leq \sqrt{2} \Leftrightarrow \frac{\sqrt{\sum_{i=1}^{j-1} r_{i j}^{2}}}{r_{j j}} \leq 1 \Rightarrow \text { no proof exists } . .
$$

Giraud-Langou ('03)

$$
\frac{\sum_{i=1}^{j-1}\left|r_{i j}\right|}{r_{j j}} \leq 1
$$

Abdelmaleck ('72) \& Kiełbasiński ('74)

$$
\frac{\sqrt{\sum_{i=1}^{j-1} r_{i j}^{2}}}{\sqrt{j-1-r_{j j}}} \leq 1
$$

Daniel, Gragg, Kaufman and Stewart ('76)

$$
\frac{\left\|a_{j}\right\|_{2}}{\|w\|_{2}}+\omega \frac{\left\|Q_{j-1}^{T} a_{j}\right\|_{2}}{\|w\|_{2}} \leq \sqrt{2} \text { where } \omega \sim\left\|I-Q_{j-1}^{T} Q_{j-1}\right\|_{2}
$$

## Giraud Langou ('03) - SISC

| $(K)$ | $K=1.40$ | $K=1.30$ | $K=1.17$ | $K=1.05$ |
| :---: | :---: | :---: | :---: | :---: |
| matrix $B$ | $B(400,0.97)$ | $B(500,0.82)$ | $B(1000,0.50)$ | $B(2500,0.30)$ |
| $\kappa(B)$ | $3.4 \cdot 10^{15}$ | $8.6 \cdot 10^{14}$ | $1.8 \cdot 10^{13}$ | $5.9 \cdot 10^{12}$ |
| MGS2 $(K)$ | $7.2 \cdot 10^{-1}$ | $1.1 \cdot 10^{0}$ | $1.0 \cdot 10^{-2}$ | $7.6 \cdot 10^{-3}$ |
| MGS2 | $1.5 \cdot 10^{-14}$ | $1.9 \cdot 10^{-14}$ | $3.5 \cdot 10^{-14}$ | $8.0 \cdot 10^{-14}$ |
| CGS2 $(K)$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ |
| CGS2 | $1.2 \cdot 10^{-14}$ | $1.5 \cdot 10^{-14}$ | $2.8 \cdot 10^{-14}$ | $6.0 \cdot 10^{-14}$ |
| $\left\\|I_{n}-Q^{T} Q\right\\|_{2}$ |  |  |  |  |

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| CGS2( $K)$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ |
| CGS2 | $1.2 \cdot 10^{-14}$ | $1.5 \cdot 10^{-14}$ | $2.8 \cdot 10^{-14}$ | $6.0 \cdot 10^{-14}$ |
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| CGS2 $(K)$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ | $1.6 \cdot 10^{0}$ |
| CGS2 | $1.2 \cdot 10^{-14}$ | $1.5 \cdot 10^{-14}$ | $2.8 \cdot 10^{-14}$ | $6.0 \cdot 10^{-14}$ |
| $\left\\|I_{n}-Q^{T} Q\right\\|_{2}$ |  |  |  |  |

## Blindly MGS

$$
A=\left(\begin{array}{llll}
1 & 0 & 1 & 0 \\
0 & 1 & 1 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0
\end{array}\right)
$$

gives

$$
Q=\left(\begin{array}{cccc}
1 & 0 & 1 / 2 & -1 / 2 \\
0 & 1 & 1 / 2 & -1 / 2 \\
0 & 0 & \sqrt{2} / 2 & \sqrt{2} / 2 \\
0 & 0 & 0 & 0
\end{array}\right) \text { and } R=\left(\begin{array}{cccc}
1 & 0 & 1 & 0 \\
0 & 1 & 1 & 0 \\
0 & 0 & 0 & \sqrt{2} / 2 \\
0 & 0 & 0 & \sqrt{2} / 2
\end{array}\right)
$$

## Blindy MGS


$\left(q_{1}, q_{2}, q_{3}, q_{4}\right)$ given by blindy MGS on $A$.

## Giraud Gratton Langou ('03)

Singular values study.

$$
F=\tilde{Q}-\hat{Q}
$$

under the assumption cuк $<1$, for all $i=1, \ldots, n$,

$$
\sigma_{i}(F) \leq 2 c u \frac{\|A\|_{2}}{\sigma_{n-i+1}(A)}
$$

E.g.

$$
\begin{gathered}
\sigma_{1}(F) \leq 2 c u \frac{\|A\|_{2}}{\sigma_{n}(A)} \\
\sigma_{2}(F) \leq 2 c u \frac{\|A\|_{2}}{\sigma_{n-1}(A)}
\end{gathered}
$$

## Proof

Follow Björck and Paige ('92) and instead of doing

$$
\|A B\|_{2} \leq\|A\|_{2}\|B\|_{2}
$$

do

$$
\sigma_{i}(A B) \leq \sigma_{i}(A)\|B\|_{2}, \quad i=1, \ldots, n
$$

## Interpretation in term of rank.



Singular values of $A$


## How to find $F$ ? - the rank-1 case

- Run MGS to have $Q$ and $R$.
- Form $T$ and find its singular value decomposition such that $T=u_{T} \sigma_{T} w_{T}^{T}$.
- Compute $c=\sigma+\sigma^{2}\left(w_{T}^{T} u_{T}\right)$ and $s=\sqrt{1-c^{2}}$.
- Form $F$ :

$$
F=\left(Q\left(w_{T}\left(1-s^{-1}\right)+u_{T}\left(1-s^{-1}-c\right)\right)\right) w_{T}^{T}
$$

This algorithm needs 8 mn flops! For comparison, we recall that a complete reorthogonalization loop costs $2 m n^{2}$ flops.

## Application to iterative methods

|  | $m$ | \# iter | $\kappa$ | $\kappa_{2}$ |
| :---: | :---: | :---: | :---: | :---: |
| Cetaf | 5391 | 31 | $9.7 \cdot 10^{14}$ | 27 |
| Airbus | 23676 | 104 | $3.6 \cdot 10^{14}$ | 14 |
| Sphere | 40368 | 59 | $3.9 \cdot 10^{14}$ | 6.4 |
| Almond | 104973 | 71 | $5.1 \cdot 10^{14}$ | 5.9 |

Characteristics of $A=\left(b, \mathbb{Z} V_{n-1}\right)$


(b) airbus

(c) sphere

(d) almond

## Application to iterative methods

|  | MGS | MGS2 $(\sqrt{2})$ | a-posteriori reorth. |
| :---: | :---: | :---: | :---: |
| Cetaf | $2.8 \cdot 10^{-17}$ | $1.8 \cdot 10^{-16}$ | $2.9 \cdot 10^{-16}$ |
| Airbus | $4.0 \cdot 10^{-17}$ | $2.7 \cdot 10^{-16}$ | $4.4 \cdot 10^{-16}$ |
| Sphere | $5.8 \cdot 10^{-17}$ | $1.6 \cdot 10^{-16}$ | $2.7 \cdot 10^{-16}$ |
| Almond | $3.9 \cdot 10^{-17}$ | $3.9 \cdot 10^{-16}$ | $2.2 \cdot 10^{-16}$ |

Residual errors - \|A - $Q R\left\|_{2} /\right\| A \|_{2}$

## Application to iterative methods

|  | MGS | MGS2 $(\sqrt{2})$ | a-posteriori reorth. |
| :---: | :---: | :---: | :---: |
| Cetaf | $1.6 \cdot 10^{-02}$ | $2.8 \cdot 10^{-16}$ | $2.4 \cdot 10^{-15}$ |
| Airbus | $1.8 \cdot 10^{-02}$ | $3.7 \cdot 10^{-16}$ | $1.6 \cdot 10^{-15}$ |
| Sphere | $3.9 \cdot 10^{-02}$ | $3.0 \cdot 10^{-16}$ | $7.8 \cdot 10^{-16}$ |
| Almond | $4.1 \cdot 10^{-02}$ | $2.8 \cdot 10^{-16}$ | $7.9 \cdot 10^{-16}$ |

Orthogonality - \|I $I_{n}-\bar{Q}^{T} \bar{Q} \|$

## Summary

- MGS generates a well conditioned set of vectors
- twice is enough
- a new selective reorthogonalization criterion has been exhibited
- counter example matrices for the $K$-criterion are given
- a new a-posteriori reorthogonalization schemes is provided


## Future work

the singular case has not been treated (RRQR, SVD,...)

- currently, we are interested in CGS
- as well as the study of Gram-Schmidt algorithm with non Euclidean scalar product


## Implementation of iterative methods

## The electromagnetism applications

## Motivations

- Boundary element method in the Maxwell equations that leads to complex, dense and huge linear systems to solve,
- $\mathbb{Z} J=F(\varphi)$, where $\varphi=0^{\circ}: 1^{\circ}: 180^{\circ}$,
- $\mathbb{Z}$ is accessed via matrix-vector products using the fast multipole method, a Krylov solver is used,
- Previous work:
- Frobenius norm minimizer preconditioner,
- flexible GMRES solver (inner GMRES preconditioner),
- spectral low rank update preconditioner,
$\Rightarrow$ still problematic to have a complete monostatic radar cross section.


## Outline of the third part

I. techniques to improve one right-hand side solvers for multiple right-hand sides problem,
II. seed-GMRES algorithm: two cases, two problems and two remedies,
III. linear dependencies of the right-hand sides in the electromagnetism context.

## Co EOOMEHOTS

This presentation uses results and codes provided by Guillaume Alléon EADS, Guillaume Sylvand (INRIA(Sophia-Antipolis)-CERMICS),
Bruno Carpentieri and Émeric Martin.
lain S. Duff (CERFACS-RAL) and Luc Giraud (CERFACS) supervise the work at CERFACS.
Francis Collino is also working with us.

## The single right-hand side solver

1. increase the amount of work in the preconditioner in order to increase its efficiency. In our case, for example, we can 1.a. increase the density of the Frobenius norm minimizer preconditioner (Bruno)
1.b. add a spectral low rank update that shifts the smallest eigenvalue close to one (Émeric)

## The single right-hand side solver

1. increase the amount of work in the preconditioner in order to increase its efficiency
2. find an initial approximate solution for the current system $\ell$ from the previous systems solved
2.a. An obvious strategy is to take

$$
J^{(0)}\left(\varphi_{\ell}\right)=J\left(\varphi_{\ell-1}\right)
$$

2.b. Another strategy is to solve the least squares problem

$$
\min _{y \in \mathbb{R}^{\ell-1}}\left\|F\left(\varphi_{\ell}\right)-\sum_{j=0}^{\ell-1} F\left(\varphi_{j}\right) y_{j}\right\|_{2}
$$

then take the initial guess $J^{(0)}\left(\varphi_{\ell}\right)=\sum_{j=0}^{\ell-1} J\left(\varphi_{j}\right) y_{j}$

## The single right-hand side solver



## The single right-hand side solver



## The single right-hand side solver

1. increase the amount of work in the preconditioner in order to increase its efficiency
2. find an initial approximate solution for the current system $\ell$ from the previous systems solved
3. gathered multiple GMRES iterations

## The almond case

A first test case: the almond $104793 \theta=0^{\circ}: 0.5^{\circ}: 180^{\circ}$ and CFIE formulation (JINA 2002)


## The almond case

|  | \# iterations | elapse time (s) |
| :---: | :---: | :---: |
| seed-GMRES | 1185 |  |
| GMRES with initial guess strategy 2 | 1791 |  |

\# iterations and elapsed time (s) on 8 processors (Compaq-CERFACS).

## The almond case

|  | \# iterations | elapse time (s) |
| :---: | :---: | :---: |
| seed-GMRES | 1185 | 10460 |
| GMRES with initial guess strategy 2 | 1791 | 6202 |

\# iterations and elapsed time (s) on 8 processors (Compaq-CERFACS).

## The almond case



Elapsed time and number iterations versus the size of the restart $w$ for restart seed-GMRES.

## The almond case

|  | \# iterations | elapse time (s) |
| :---: | :---: | :---: |
| seed-GMRES | 1185 | 10460 |
| GMRES with initial guess strategy 2 | 1791 | 6202 |
| seed-GMRES $(w=33)$ | 1318 | 5300 |

\# iterations and elapsed time (s) on 8 processors (Compaq-CERFACS).

## The cobra case

A second test case: the cobra $60695 \theta=0^{\circ}: 0.5^{\circ}: 180^{\circ}$ and EFIE formulation


## The cobra case



## The cobra case

|  | default guess | strat. 2 |  | seed-GMRES |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $(\theta, \varphi)$ | \# iter | \# iter | $\left\\|r_{0}\right\\|_{2} /\\|F\\|_{2}$ | \# iter | $\left\\|r_{0}\right\\|_{2} /\\|b\\|_{2}$ |
| $(0.0,0.0)$ | 338 | 338 | 1.000 | 338 | 1.000 |
| $(0.5,0.0)$ | 339 | 339 | 1.000 | 190 | 0.230 |
| $(1.0,0.0)$ | 340 | 63 | 0.071 | 210 | 0.074 |
| $(1.5,0.0)$ | 341 | 56 | 0.048 | 130 | 0.024 |
| $(2.0,0.0)$ | 341 | 81 | 0.039 | 197 | 0.007 |
| $(2.5,0.0)$ | 341 | 116 | 0.037 | 215 | 0.004 |
| $(3.0,0.0)$ | 342 | 139 | 0.028 | 237 | 0.004 |
| $(3.5,0.0)$ | 342 | 151 | 0.028 | 226 | 0.004 |
| $(4.0,0.0)$ | 343 | 159 | 0.024 | 254 | 0.004 |
| $(4.5,0.0)$ | 344 | 180 | 0.022 | 258 | 0.004 |
| $(5.0,0.0)$ | 345 | 179 | 0.027 | 265 | 0.004 |
| $(5.5,0.0)$ | 346 | 192 | 0.022 | 299 | 0.004 |

## The cobra case



Comparison between the seed-GMRES method and the GMRES method with initial guess strategy 2.

## The cobra case

## Seed moral in le Cid

Ô rage ! Ô désespoir ! Ô vieillesse ennemie! N'ai-je donc tant tant vécu que pour cette infamie ?
Ô Anger! Ô despair! Ô ennemy of age! Should I have lived so much for such infamy?

Corneile (1682), Le Cid.

## Seed GMRES + Spectral LRU



## Seed GMRES + Spectral LRU



## Seed GMRES + Spectral LRU

in a race starting close from the arrival and running fast ensures to finish first!

## Seed GMRES + Spectral LRU

in a race starting close from the arrival and running fast ensures to finish first!

Luc Giraud ( my thesis advisor).

## Linear dependencies RHS



Singular values distribution of $\left[F\left(0^{\circ}\right), \ldots, F\left(360^{\circ}\right)\right]$.

## $p$, the size in wavelengths

|  | dof | $F$ | $\lambda$ | $p$ |
| :---: | ---: | ---: | ---: | ---: |
| cetaf | 5391 | 3.0 GHz | 10.0 cm | 6 |
| sphere | 40368 | 0.9 GHz | 33.3 cm | 6 |
| sphere | 71148 | 1.2 GHz | 25.0 cm | 8 |
| sphere | 161472 | 1.8 GHz | 16.7 cm | 12 |
| sphere | 288300 | 2.4 GHz | 12.5 cm | 16 |
| Airbus | 23676 | 2.3 GHz | 13.0 cm | 14 |
| Airbus | 94704 | 4.6 GHz | 6.5 cm | 29 |
| Airbus | 213084 | 6.9 GHz | 4.3 cm | 44 |
| cobra | 3823 | 1.0 GHz | 30.0 cm | 2 |
| cobra | 60695 | 10.0 GHz | 3.0 cm | 24 |
| almond | 8112 | 0.7 GHz | 42.8 cm | 6 |
| almond | 104793 | 2.6 GHz | 11.5 cm | 22 |

## Harmonic spheric decomposition

$$
M=2\left(\pi p+C_{\varepsilon} \log (\pi p+\pi)\right)+1
$$

where $C_{\varepsilon}$ is such that the errors done by representing the right-hand sides in the basis of the spherical harmonic is $10^{-C_{s}}$.

This is joint work with Francis Collino.

## Comparison of $M$ and $q$

|  | dof | $F$ | $\lambda$ | $p$ | $M$ | $q$ |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| cetaf | 5391 | 3.0 GHz | 10.0 cm | 6 |  |  |
| sphere | 40368 | 0.9 GHz | 33.3 cm | 6 |  |  |
| sphere | 71148 | 1.2 GHz | 25.0 cm | 8 |  |  |
| sphere | 161472 | 1.8 GHz | 16.7 cm | 12 |  |  |
| sphere | 288300 | 2.4 GHz | 12.5 cm | 16 |  |  |
| Airbus | 23676 | 2.3 GHz | 13.0 cm | 14 |  |  |
| Airbus | 94704 | 4.6 GHz | 6.5 cm | 29 |  |  |
| Airbus | 213084 | 6.9 GHz | 4.3 cm | 44 |  |  |
| cobra | 3823 | 1.0 GHz | 30.0 cm | 2 |  |  |
| cobra | 60695 | 10.0 GHz | 3.0 cm | 24 |  |  |
| almond | 8112 | 0.7 GHz | 42.8 cm | 6 |  |  |
| almond | 104793 | 2.6 GHz | 11.5 cm | 22 |  |  |

We take $C_{\varepsilon}=4$ and compute $M$, we compare with $q$, the number of singular values greater than $10^{-4}$.

## Comparison of $M$ and $q$

|  | dof | $F$ | $\lambda$ | $p$ | $M$ | $q$ |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| cetaf | 5391 | 3.0 GHz | 10.0 cm | 6 |  |  |
| sphere | 40368 | 0.9 GHz | 33.3 cm | 6 | 63 | 60 |
| sphere | 71148 | 1.2 GHz | 25.0 cm | 8 | 78 | 76 |
| sphere | 161472 | 1.8 GHz | 16.7 cm | 12 | 106 | 104 |
| sphere | 288300 | 2.4 GHz | 12.5 cm | 16 | 133 | 130 |
| Airbus | 23676 | 2.3 GHz | 13.0 cm | 14 |  |  |
| Airbus | 94704 | 4.6 GHz | 6.5 cm | 29 |  |  |
| Airbus | 213084 | 6.9 GHz | 4.3 cm | 44 |  |  |
| cobra | 3823 | 1.0 GHz | 30.0 cm | 2 |  |  |
| cobra | 60695 | 10.0 GHz | 3.0 cm | 24 |  |  |
| scriptsize almond | 8112 | 0.7 GHz | 42.8 cm | 6 |  |  |
| almond | 104793 | 2.6 GHz | 11.5 cm | 22 |  |  |

We take $C_{\varepsilon}=4$ and compute $M$, we compare with $q$, the number of singular values greater than $10^{-4}$.

## Comparison of $M$ and $q$

|  | dof | $F$ | $\lambda$ | $p$ | $M$ | $q$ |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| cetaf | 5391 | 3.0 GHz | 10.0 cm | 6 | 63 | 24 |
| sphere | 40368 | 0.9 GHz | 33.3 cm | 6 | 63 | 60 |
| sphere | 71148 | 1.2 GHz | 25.0 cm | 8 | 78 | 76 |
| sphere | 161472 | 1.8 GHz | 16.7 cm | 12 | 106 | 104 |
| sphere | 288300 | 2.4 GHz | 12.5 cm | 16 | 133 | 130 |
| Airbus | 23676 | 2.3 GHz | 13.0 cm | 14 | 120 | 80 |
| Airbus | 94704 | 4.6 GHz | 6.5 cm | 29 | 220 | 139 |
| Airbus | 213084 | 6.9 GHz | 4.3 cm | 44 | 317 | 198 |
| cobra | 3823 | 1.0 GHz | 30.0 cm | 2 | 32 | 17 |
| cobra | 60695 | 10.0 GHz | 3.0 cm | 24 | 186 | 68 |
| almond | 8112 | 0.7 GHz | 42.8 cm | 6 | 63 | 26 |
| almond | 104793 | 2.6 GHz | 11.5 cm | 22 | 133 | 67 |

We take $C_{\varepsilon}=4$ and compute $M$, we compare with $q$, the number of singular values greater than $10^{-4}$.

## Linear dependency of RHS

To solve the $p$ systems

$$
\mathbb{Z} J=F,
$$

since we can write

$$
F=U S+E \quad \text { with } \quad\|E\|_{2}=\sigma_{q+1},
$$

1. we solve the system with the $q$ right-hand sides $U$

$$
\mathbb{Z} X=U
$$

and then update the solutions with $J=X S$.
2. with block-GMRES algorithm, we minimize the right-hand sides $F$ on the block-Krylov space constructed with $U$.

## On the Airbus 23676



For each right-hand sides we plot the number of iterations (matrix-vector product) required to converge. The test example is the Airbus $23676 \theta=0^{\circ}: 1^{\circ}: 180^{\circ}$.

## Results

|  | DOF | \# RHS | \# SVD | \# it | avr. \# it <br> SVD |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| coated cone sphere | 77604 | 181 | 15 | 285 | 1.5 | avr. \# it <br> classic |
| almond | 104793 | 361 | 63 | 532 | 1.4 | 20 |
| cobra LRU(15) | 60695 | 91 | 35 | 1712 | 18.8 | 185 |
| Airbus (5e-2) | 94704 | 181 | 70 | 1430 | 7.9 | 130 |

## Summary

D adapting one right hand-side solver to the multiple right-hand sides case is worthly to be considered

D seed-GMRES algorithm may greatly be improved by restart or spectral low rank update
D linear dependencies of the right-hand sides is systematic in the electromagnetism context

- SVD preprocessing and use with the block-GMRES algorithm is the best method at that moment


## Prospectives (1) - block/seed

- set the vectors in-core to gain in the orthogonalization process
- restart in block-GMRES has the same catastrophic effect (in our case) than restart in GMRES and prevents from convergence on hard cases, block-GMRES with restart and spectral low rank update is therefore tested on big test cases where full block-GMRES is not affordable anymore. Also we are thinking on how implementing block-GMRES-DR algorithm in the code since GMRES-DR works fine.


## Prospectives (2) - relax

Relaxing the accuracy of the matrix-vector product operation during the convergence of GMRES - Bouras, Frayssé and Giraud ('00) strategy


Cetaf 5391

## Jury

Guillaume Alléon Director of project, EADS-CCR<br>Åke Björck<br>Professor, Linköping University<br>lain S. Duff Project leader cerfacs et ral<br>Luc Giraud Senior researcher, cerfacs<br>Gene H. Golub Professor, Stanford University<br>Gérard Meurant Research director, ceA<br>Chris C. Paige Professor, McGill University<br>Yousef Saad Professor, University of Minnesota

## Study of the Gram-Schmidt algorithm and its variants

## Classical/Modified

Classical Gram-Schmidt (CGS)

$$
\begin{aligned}
& \text { for } j=1, n \text { do } \\
& \quad \mathbf{w}=\mathbf{a}_{j} \\
& \text { for } i=1, j-1 \mathbf{d o} \\
& \quad r_{i j}=\mathbf{q}_{i}^{T} \mathbf{a}_{j} \\
& \mathbf{w}=\mathbf{w}-\mathbf{q}_{i} r_{i j} \\
& \text { end for } \\
& r_{j j}=\|\mathbf{w}\|_{2} \\
& \mathbf{q}_{j}=\mathbf{w} / r_{j j} \\
& \text { end for }
\end{aligned}
$$

Modified Gram-Schmidt (MGS)

$$
\begin{aligned}
& \text { for } j=1, n \mathbf{d o} \\
& \quad \mathbf{w}=\mathbf{a}_{j} \\
& \quad \text { for } i=1, j-1 \mathbf{d o} \\
& \quad r_{i j}=\mathbf{q}_{i}^{T} \mathbf{w} \\
& \mathbf{w}=\mathbf{w}-\mathbf{q}_{i} r_{i j} \\
& \text { end for } \\
& r_{j j}=\|\mathbf{w}\|_{2} \\
& \mathbf{q}_{j}=\mathbf{w} / r_{j j} \\
& \text { end for }
\end{aligned}
$$

## The Arnoldi algorithm

The Arnoldi method provides, at each step $n$, an orthonormal basis $V_{n+1}$ for the Krylov space $\mathcal{K}_{n}(\mathbb{Z}, b)$ that verifies

$$
\left(b, \mathbb{Z} V_{n}\right)=V_{n+1}\left(e_{1} \beta, H_{n+1, n}\right) .
$$

## So

find $x_{n} \in \mathcal{K}_{n}(\mathbb{Z}, b)$ that minimizes $\|b-\mathbb{Z} x\|_{2}$
$\Leftrightarrow$ find $y_{n} \in \mathbb{R}^{n}$ that minimizes $\left\|e_{1} \beta-H_{n+1, n} y\right\|_{2}$ and set $x_{n}=V_{n} y_{n}$.

## Björck ('67)

$A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular values :
$\sigma_{1} \geq \ldots \geq \sigma_{n}>0, \kappa(A)=\sigma_{1} / \sigma_{n}$,
MGS computes $\bar{R}$ so as
$A=Q R \rightarrow$

$$
A+\bar{E}=\bar{Q} \bar{R}, \quad\|\bar{E}\|_{2} \leq \bar{c}_{1} u\|A\|_{2}
$$

$\left\|I_{n}-Q^{T} Q\right\|_{2}=0 \rightarrow$

$$
\left\|I_{n}-\bar{Q}^{T} \bar{Q}\right\|_{2} \leq \bar{c}_{2} \kappa(A) u
$$

where $\bar{c}_{i}$ are constants depending on $m, n$ and the details of the arithmetic, and $u$ is the unit round-off.

## Björck ('67)

$$
\bar{c}_{1}=1.5 n^{\frac{3}{2}} \quad \text { and } \quad \bar{c}_{2}=31.6863 n^{\frac{3}{2}} .
$$

These results hold under the assumptions :

$$
2.12 \cdot(m+1) \cdot u<0.01 \quad \text { and } \quad \bar{c}_{2} u \kappa(\mathbf{A})<1 .
$$

## Gram-Schmidt algorithm

for $j=1, n$ do

$$
\mathbf{w}=\mathbf{a}_{j}
$$

$$
\text { for } i=1, j-1 \text { do }
$$

$$
r_{i j}=\mathbf{q}_{i}^{T} \mathbf{a}_{j}
$$

$$
\mathbf{w}=\mathbf{w}-\mathbf{q}_{i} r_{i j}
$$

$$
\text { cost: } 2 m n^{2} \text { flops }
$$

end for

$$
\begin{aligned}
& \quad r_{j j}=\|\mathbf{w}\|_{2} \\
& \mathbf{q}_{j}=\mathbf{w} / r_{j j} \\
& \text { end for }
\end{aligned}
$$

## Unitary transformations



## Householder \& Givens

Idea : find a series of unitary matrix $\left(Q_{i}\right)_{i=1, \ldots, n}$ such that for all $i=1, \ldots, n$, the $i$-th first columns of

$$
Q_{i} \ldots Q_{1} A=A_{i}
$$

are upper triangular.
Choice : typically we use
Givens rotations: $Q_{i}="\left(\begin{array}{cc}\cos & -\sin \\ \sin & \cos \end{array}\right) "$,
Householder reflections: $Q_{i}=I_{m}-2 z_{i} z_{i}^{T}$ where $\left\|z_{i}\right\|_{2}=1$.
Cost : $2 m n^{2}-n^{3} / 3$ for $R, 2 \times\left(2 m n^{2}-n^{3} / 3\right)$ for $R$ and $Q$.

## Advantages \& drawbacks

## Advantages :

- possibility to exploit the structure of $A$ (e.g. $A$ Hessenberg $\longrightarrow$

Givens rotations)

- if only the $R$ factor is needed then the number of flops is less than Gram-Schmidt algorithm
- the $Q$ factor has columns orthornormal up to machine precision (Wilkinson, '63)


## Drawbacks :

- to obtain $Q$ doubles the cost of the method
- the fact that unitary transformations implies a $Q$ factor with orthonormal columns highly depends on the dot product used


## Björck and Paige ('92)

$A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular
values : $\sigma_{1} \geq \ldots \geq \sigma_{n}>0, \kappa(A)=\sigma_{1} / \sigma_{n}$,
MGS computes $\bar{R}$ such that

$$
A+\hat{E}=\hat{Q} \bar{R}, \quad \hat{Q}^{T} \hat{Q}=I_{n} \quad \text { and } \quad\|\hat{E}\|_{2} \leq c u\|A\|_{2},
$$

where $c=18.53 n^{\frac{3}{2}}$ and $u$ is the unit round-off. This results holds under the assumptions
$2.12 \cdot(m+1) \cdot u<0.01$ and $\operatorname{cu\kappa }(\mathbf{A})<1$.

## Daniel and al. ('76)

Let take $Q \in \mathbb{R}^{m \times n}$ such that

$$
\left.\left\|I_{n}-Q^{T} Q\right\|_{2}=10^{-3} \quad \text { (e.g. }\right)
$$

and $w^{(0)} \mathbb{R}^{m}$, we consider the serie of vectors $\left(w^{(i)}\right)$

$$
w^{(i)}=\left(I_{n}-Q Q^{T}\right) w^{(i-1)} .
$$

Then Daniel and al. showed that

$$
\left\|Q^{T} w^{(i)}\right\|_{2} /\left\|w^{(i)}\right\|_{2} \leq \xi_{i},
$$

where $\xi_{i}$ is defined via

$$
\begin{aligned}
& \xi_{0}=\left\|Q^{T} w^{(0)}\right\|_{2} /\left\|w^{(0)}\right\|_{2}=10^{0} \text { (e.g.) } \\
& \xi_{i}=\varphi\left(\xi_{i-1}\right), i=1, \ldots .
\end{aligned}
$$

## Giraud, Langou and Rozložník ('0

$$
\left\|I-Q^{T} Q\right\|_{2}=10^{-3}, \xi_{0}=\left\|Q^{T} w^{(0)}\right\|_{2} /\left\|w^{(0)}\right\|_{2}=10^{0}
$$

## How to find $F$ ?

$$
\begin{aligned}
F & =Q-\hat{Q}, \\
& =P_{21}(I-T)-\hat{Q}, \\
& =U_{2}(S-I) W^{T}-P_{21} T, \\
& \sim U_{2 k}\left(S_{k}-I\right) W_{k}^{T}-P_{21}\left(U_{T k} \Sigma_{T k} W_{T k}^{T}\right) .
\end{aligned}
$$

We have expressed $F$ as a sum of to low rank matrix of rank $k$. The choice of $k$ is a compromise between accuracy and efficiency.

## 2D case



## 2D case

## We run full GMRES with MGS without preconditionner and a right-hand side corresponding to an incident wave at $0^{\circ}$.

The tolerance is fixed to $10^{-12}$.


## 2D example

From Greenbaum, Rozložník and Strakoš ('97) we know that $\left\|r_{m}\right\|_{2} \sim \sigma_{\text {min }}\left(v_{0}, A V_{m}\right)$

```
-|rm|}\mp@subsup{|}{2}{}/|b\mp@subsup{|}{2}{
- }\mp@subsup{\sigma}{\operatorname{min}}{}(\mp@subsup{v}{0}{},A\mp@subsup{V}{m}{})/\mp@subsup{\sigma}{\operatorname{min}}{}(A
```



## 2D example

so from Björck (1967) we can check that the loss of orthogonality is proportionnal to $1 /\left\|r_{m}\right\|_{2}$.

```
-|rm}\mp@subsup{|}{2}{}/|b\mp@subsup{|}{2}{
- }\mp@subsup{\sigma}{min}{m}(\mp@subsup{v}{0}{},A\mp@subsup{V}{m}{})/\mp@subsup{\sigma}{min}{m}(A
```



## 2D example

As $A V_{m}=V_{m} \bar{H}_{m}, V_{m}$ and $A$ are well-conditionned, we deduced that the second smallest singular value of $\left(v_{0}, A V_{m}\right)$ is reasonnably big.

```
-|rm|}|2/|b\mp@subsup{|}{2}{
- }\mp@subsup{\sigma}{m+1}{}(\mp@subsup{v}{0}{},A\mp@subsup{V}{m}{})/\mp@subsup{\sigma}{min}{}(A
```



## LLS problems with multiple RHS

with MGS

$$
\left(\begin{array}{r}
v_{1}^{T} b^{(i)} \\
v_{2}^{T}\left(I_{m}-v_{1} v_{1}^{T}\right) b^{(i)} \\
\vdots \\
v_{n}^{T}\left(I_{m}-v_{n-1} v_{n-1}^{T}\right) \ldots\left(I_{m}-v_{1} v_{1}^{T}\right) b^{(i)}
\end{array}\right)
$$

when using an orthonormal basis $Q$

$$
\left(\begin{array}{c}
q_{1}^{T} b^{(i)} \\
q_{2}^{T} b^{(i)} \\
\vdots \\
q_{n}^{T} b^{(i)}
\end{array}\right)
$$

## Application to iterative methods

|  | MGS2 $(\sqrt{2})$ | $\operatorname{MGS2}(2)$ | $\operatorname{MGS2}(\sqrt{5})$ |
| :---: | :---: | :---: | :---: |
| Cetaf | $2.8 \cdot 10^{-16}(\nu=2.00)$ | $6.3 \cdot 10^{-16}(\nu=1.90)$ | $1.2 \cdot 10^{-15}(\nu=1.87)$ |
| Airbus | $3.7 \cdot 10^{-16}(\nu=2.00)$ | $3.9 \cdot 10^{-03}(\nu=1.02)$ | $8.8 \cdot 10^{-03}(\nu=1.01)$ |
| Sphere | $3.0 \cdot 10^{-16}(\nu=2.00)$ | $7.5 \cdot 10^{-15}(\nu=1.52)$ | $4.9 \cdot 10^{-04}(\nu=1.07)$ |
| Almond | $2.8 \cdot 10^{-16}(\nu=2.00)$ | $1.7 \cdot 10^{-03}(\nu=1.06)$ | $5.2 \cdot 10^{-03}(\nu=1.03)$ |
| $\left\\|I_{n}-\bar{Q}^{T} \bar{Q}\right\\|$ |  |  |  |

## Implementation of iterative methods

## Outline

## GMRES-DR seed-GMRES block-GMRES

## GMRES-DR

$$
V_{k+1}^{\text {new }} \longleftarrow V_{n+1} P_{k+1},
$$

need $n+k+2$ vectors of size $m$. whereas if we first perform the LU decomposition of $P_{k+1}$ and then do

$$
V_{k+1}^{\text {new }} \longleftarrow\left(V_{n+1} L\right) U
$$

; we only need $n+1$ vectors.

## The electromagnetism applications

## One right-hand side solvers

spectrum


Cetaf preconditioned with "default" Frobenius norm minimizer preconditioner

Cetaf preconditioned with "default" Frobenius norm min-

## One right-hand side solvers

|  | assembly |  |  | application |  |  | \# procs |
| :---: | ---: | ---: | ---: | ---: | :---: | :---: | :---: |
|  | FMM | Frob | SLRU | FMM | Frob | SLRU |  |
| cetaf 5391 | 9.6 | 631.8 | $3.7(20)$ | 0.25 | 0.11 | $0.02(20)$ | 4 |
| Airbus 23676 | 114.8 | 184.8 | $36.7(20)$ | 1.86 | 0.29 | $0.03(20)$ | 4 |
| cobra 60695 | 33.3 | 120.2 | $30.6(15)$ | 1.93 | 0.22 | $0.03(15)$ | 8 |
| almond104793 | 53.1 | 345.8 | $182.8(60)$ | 2.92 | 0.41 | $0.10(60)$ | 8 |
| almond104793 | 53.1 | 345.8 | $59.3(20)$ | 2.92 | 0.41 | $0.05(20)$ | 8 |

Time of assembly and application of the FMM (prec-3), the Frobenius preconditioner and the spectral update (the number of shifted eigenvalues is given in bracket).

## One right-hand side solvers



Airbus 23676

## Gathered multiple GMRES

|  | unitary <br> FMM (s) | unitary <br> Precond (s) | \# FMM <br> \&Precond | total |
| :---: | :---: | :---: | :---: | :---: |
| gathered GMRES (10) | 0.7 | 0.05 | 180 | 205.1 |
| GMRES with zero <br> as initial guess | 1.8 | 0.27 | 177 | 401.4 |

(a) Airbus 23676.

|  | unitary <br> FMM (s) | unitary <br> Precond (s) | \# FMM <br> \&Precond | total |
| :---: | :---: | :---: | :---: | :---: |
| GMRES gathered (19) | 1.6 | 0.13 | 931 | 2340.8 |
| GMRES with strategy 2 <br> for the initial guess | 7.1 | 0.42 | 856 | 7703.2 |

(b) coated cone sphere 77604.

## The seed GMRES algorithm (1)

We first run GMRES to solve the linear system $\mathbb{Z} J\left(\varphi_{0}\right)=F\left(\varphi_{0}\right)$. This amounts to solving the linear least squares problem

$$
\min _{J \in \mathcal{K}_{0}}\left\|F\left(\varphi_{0}\right)-\mathbb{Z} J\right\|_{2},
$$

where $\mathcal{K}_{0}$ is the Krylov space of size $n$ built with an Arnoldi process on $\mathbb{Z}$ using the starting vector $F\left(\varphi_{0}\right)$.
In most applications, the computational burden lies in the matrix-vector products and the scalar products required to solve this linear least squares problem.
In seed-GMRES, the subsequent right-hand sides benefit from this work. An effective initial guess $J^{(0)}\left(\varphi_{\ell}\right)=V_{n}^{(0)} y^{(\ell)}$ for the system $\ell$ is obtained by solving the same linear least squares problem but with another right-hand side, namely

$$
\min _{J \in \mathcal{K}_{0}}\left\|F\left(\varphi_{\ell}\right)-\mathbb{Z} J\right\|_{2} .
$$

The additional cost is $n$ dot products and $2 n$ zaxpy operations per right-hand sides.

## The seed GMRES algorithm (2)



Norm of the residuals after each minimization on the Krylov spaces. The test example is the cobra 60695, $\theta=0^{\circ}: 0.5^{\circ}: 5.5^{\circ}$.

## The almond case

Starting the seed-GMRES method from the right-hand side $F\left(\theta=0^{\circ}\right)$, we obtain the following sequence for the number of iterations for the first 15 right-hand sides:

| $\theta$ | $0^{o}$ | $0.5^{o}$ | $1^{o}$ | $1.5^{o}$ | $2^{o}$ | $2.5^{o}$ | $3^{o}$ | $3.5^{o}$ | $4^{o}$ | $4.5^{o}$ | $5^{o}$ | $5.5^{o}$ | $6^{o}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \# iter | 11 | 7 | 5 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 | 3 | 2 |

## The almond case

Starting the seed-GMRES method from the right-hand side $F\left(\theta=0^{\circ}\right)$, we obtain the following sequence for the number of iterations for the first 15 right-hand sides:

| $\theta$ | $0^{\circ}$ | $0.5^{\circ}$ | $1^{\circ}$ | $1.5^{\circ}$ | $2^{0}$ | $2.5^{\circ}$ | $3^{\circ}$ | $3.5^{\circ}$ | $4^{0}$ | $4.5{ }^{\circ}$ | $5^{\circ}$ | 5. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \# iter | 11 | 7 | 5 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 | 3 |

We define the transient phase by the sequence 11,7 and 5 ; the stationnary phase is the remaining where the number of iterations does not change much. It is well defined by a plateau at a value equal to the average number of iterations for the right-hand sides solved in this stationnary phase. Finally we obtain the following model law:

| $\theta$ | $0^{o}$ | $0.5^{o}$ | $1^{o}$ | $1.5^{o}$ | $2^{o}$ | $2.5^{o}$ | $3^{o}$ | $3.5^{o}$ | $4^{o}$ | $4.5^{o}$ | $5^{o}$ | 5. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \# iter | 11 | 7 | 5 | 2.67 | 2.67 | 2.67 | 2.67 | 2.67 | 2.67 | 2.67 | 2.67 | 2. |

This law describes the number of iterations of the seed-GMRES method on 15 right-hand sides starting from $F\left(\theta=0^{\circ}\right)$. We assume that this behaviour holds for any starting right-hand side $F(\theta)$.

## Kernel operations

|  | zaxpy | zdscal | zcopy | zdot | precond | FMM | \# proc. |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Airbus 23676 | 0.0027 | 0.0026 | 0.0019 | 0.0024 | 0.27 | 1.83 | 4 |
| Airbus 94704 | 0.0066 | 0.0063 | 0.0046 | 0.0051 | 0.80 | 4.61 | 8 |
| Airbus 213084 | 0.0148 | 0.0142 | 0.0105 | 0.0106 | 1.78 | 11.13 | 8 |
| sphere 40368 | 0.0044 | 0.0042 | 0.0030 | 0.0036 | 0.29 | 2.16 | 4 |
| sphere 71148 | 0.0079 | 0.0059 | 0.0079 | 0.0061 | 0.54 | 3.84 | 4 |
| sphere 161472 | 0.0131 | 0.0129 | 0.0093 | 0.0098 | 0.61 | 4.63 | 8 |
| sphere 288300 | 0.0202 | 0.0194 | 0.0143 | 0.0140 | 1.09 | 8.25 | 8 |
| cetaf | 5391 | 0.0010 | 0.0001 | 0.0001 | 0.0013 | 0.13 | 0.25 |
| cobra 60695 | 0.0045 | 0.0003 | 0.0004 | 0.0040 | 0.22 | 1.93 | 8 |
| almond 104793 | 0.0082 | 0.0006 | 0.0007 | 0.0064 | 0.41 | 2.92 | 8 |

Elsapsed time for each basic operation needed by the iterative solvers.

## Kernel operations

|  | 100 <br> zaxpy | 100 <br> zdscal | 100 <br> zcopy | 100 <br> zdot | precond | FMM | \# proc. |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Airbus 23676 | 14.75 | 14.21 | 10.38 | 13.11 | 14.75 | 100 | 4 |
| Airbus 94704 | 14.32 | 13.67 | 9.98 | 11.06 | 17.35 | 100 | 8 |
| Airbus 213084 | 13.30 | 12.76 | 9.43 | 9.52 | 15.99 | 100 | 8 |
| sphere 40368 | 20.37 | 19.44 | 13.89 | 16.67 | 13.42 | 100 | 4 |
| sphere 71148 | 20.57 | 15.36 | 20.57 | 15.89 | 14.06 | 100 | 4 |
| sphere 161472 | 28.29 | 27.86 | 20.09 | 21.17 | 13.17 | 100 | 8 |
| sphere 288300 | 24.48 | 23.52 | 17.33 | 16.97 | 13.21 | 100 | 8 |
| cetaf 5391 | 40.80 | 2.40 | 2.40 | 50.80 | 52.00 | 100 | 4 |
| cobra 60695 | 23.47 | 1.66 | 2.18 | 20.89 | 11.40 | 100 | 8 |
| almond 104793 | 28.05 | 1.89 | 2.47 | 21.99 | 14.04 | 100 | 8 |

Percentage of time required by 100 calls to each basic operations with respect to one call to the FMM

## The cobra case

|  | default guess | strat. 2 |  | seed-GMRES |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $(\theta, \varphi)$ | $\#$ iter | $\#$ iter | $\left\\|r_{0}\right\\|_{2} /\\|F\\|_{2}$ | \# iter | $\left\\|r_{0}\right\\|_{2} /\\|b\\|_{2}$ |
| \# iterations | 4102 |  | 2005 | 2819 |  |
| elapsed time (s) | 15565.6 |  | 6765.6 | 9863.7 |  |

## The cobra case

rien ne sert de courir, il faut partir à point

Jean de la Fontaine.

## Special feature RHS

The $j$-st entry of the right-hand side $F(\varphi)$ corresponding to a plane wave coming from the direction $\varphi$ and wave number $k$ on the object $\Gamma$ is

$$
F_{j}(\varphi)=\int_{\Gamma} e^{i k x \cdot \hat{u}_{r}(\varphi)} \hat{z} \cdot \vec{\Psi}_{j}(x) d s(x)
$$

## Seed-GMRES $\neq$ SVD preprocess.

## Linear dependency of RHS Lö̀stedtit and Nilsson

('02)use initial guess strategy 2.b. :
solve the least squares problem

$$
\min _{y \in \mathbb{R}^{\ell-1}}\left\|F\left(\varphi_{\ell}\right)-\sum_{j=0}^{\ell-1} F\left(\varphi_{j}\right) y_{j}\right\|_{2}
$$

then take the initial guess $J^{(0)}\left(\varphi_{\ell}\right)=\sum_{j=0}^{\ell-1} J\left(\varphi_{j}\right) y_{j}$.

## Seed GMRES

$$
\min _{x \in \mathcal{K}_{1}}\left\|F\left(\varphi_{\ell}\right)-\mathbb{Z} x\right\|_{2}
$$

## Control of the error

| \# SVD | \# it | $\\|E\\|$ | \# verif |
| :---: | :---: | :---: | :---: |
| 15 | - | $2.285445132223185 \mathrm{E}-003$ |  |
| 16 | 299 | $9.430404985428857 \mathrm{E}-004$ | 603 |
| 17 | 303 | $3.785604066482061 \mathrm{E}-004$ | 243 |
| 18 | 316 | $1.416418780336473 \mathrm{E}-004$ | 196 |
| 19 | 322 | $5.349504623890520 \mathrm{E}-005$ | 184 |
| 20 | 334 | $1.892546027913748 \mathrm{E}-005$ | 182 |
| 21 | 341 | $6.750489170848254 \mathrm{E}-006$ | 181 |
| 22 | 350 | $2.264388221336797 \mathrm{E}-006$ | 181 |

## 

| Size of the problem | Elapsed time SVD | Elapsed time GMRES | \# procs |
| :---: | :---: | :---: | :---: |
| 40368 | 1063 | 214 | 4 |
| 71148 | 1903 | 388 | 4 |
| 161472 | 2992 | 550 | 8 |
| 288300 | 4923 | 1649 | 8 |

Elapsed time to compute the SVD for 360 right-hand sides the sphere. For comparison, we give the average elapsed time for the solution of one right-hand side using full GMRES (assembly of the preconditioner phase not included). The backward error is set to $10^{-2}$ for the GMRES solve.

## On the coated-cone-sphere

|  | \# iterations | elapsed time (s) |
| :--- | ---: | ---: |
| GMRES with second strategy initial guess | 3797 | 29726 |
| seed-GMRES | 784 | 10328 |
| seed-GMRES SVD(16) | 632 | 10930 |
| block-GMRES SVD(19) | 329 | 8894 |
| FOUr COmpetitive methods on the coated cone sphere, |  |  |
| $\theta=0^{\circ}: 1^{\circ}: 180^{\circ}$. |  |  |

## Prospectives (3/4)

Toward an adapted stopping criterion


Airbus 23676

coated cone 77604

## Prospectives (4/4)



## GMRES-DR



## GMRES-DR



## GMRES-DR



