Solving large linear systems with multiple right-hand sides

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Motivations

In electromagnetism design, it is necessary to be able to predict the currents induced by an incident plane wave on a given object.

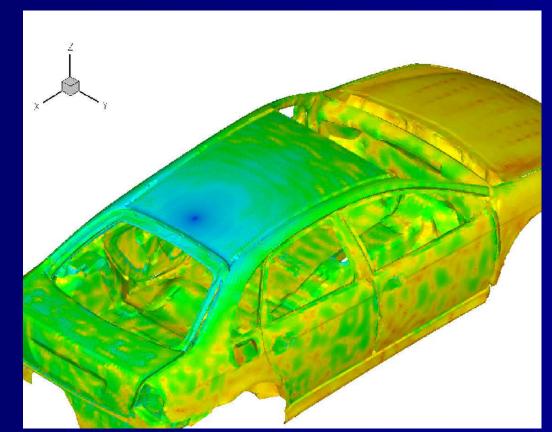
Using the boundary element method on the Maxwell equation, this amounts to solve the linear system

$$\mathbb{Z}x = b$$

where

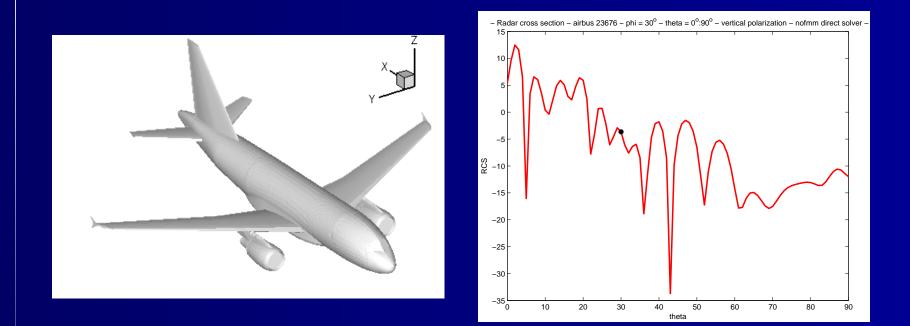
- \mathbb{Z} represents the impedance of the object (Ohm)
- b represents the incident field (Volt)
- x represents the current on the object (Ampere)

Antenna design



Representation of the electric current due to an antenna on the Citroën C5 car.

Monostatic radar cross section



Monostatic Radar Cross Section (RCS) for the Airbus 23676.

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Motivation

This class of problem naturally leads to $\mathbb{Z}(x_1, x_2, \dots, x_p) = (b_1, b_2, \dots, b_p),$ that is to say

solve a linear system with multiple right-hand sides.

Outline

- Study of the Gram–Schmidt algorithm and its variants
- Implementation of iterative methods
- The electromagnetism applications

Study of the Gram–Schmidt algorithm and its variants

The GMRES method

The GMRES method (Saad & Schultz '86) gives, at each setp n, the approximate solution x_n that solves the least–squares problem

 $\min_{x \in \mathcal{K}_n(\mathbb{Z},b)} \|b - \mathbb{Z}x\|_2$

where $\mathcal{K}_n(\mathbb{Z}, b)$ is the Krylov space

 $\mathcal{K}_n(\mathbb{Z},b) = \operatorname{Span}(b,\mathbb{Z}b,\mathbb{Z}^2b,\dots\mathbb{Z}^{n-1}b).$

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Link with QR-factorization

$$(b, \mathbb{Z}V_n) = V_{n+1} \quad (e_1\beta, H_{n+1,n})$$
$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$
$$A = Q \qquad R$$

To summarize the GMRES methods needs

- a matrix-vector product operation (and also a preconditioner operation)
- an orthogonalization scheme

Gram–Schmidt algorithm

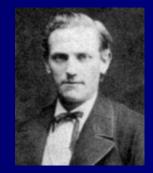
Starting from $\mathbf{A} = (\mathbf{a}_1, \dots, \mathbf{a}_n) \in \mathbb{R}^{m \times n}$ with full rank, the Gram–Schmidt algorithm computes \mathbf{Q} and \mathbf{R} so as

•
$$\mathbf{A} = \mathbf{Q}\mathbf{R}$$

•
$$\mathbf{Q} \in \mathbb{R}^{m \times n}, \ \mathbf{Q}^T \mathbf{Q} = \mathbf{I}_n$$

• $\mathbf{R} \in \mathbb{R}^{n \times n}$, \mathbf{R} is upper triangular with positive elements on the diagonal

Gram–Schmidt algorithm





Jörgen P. Gram Erhard Schmidt for j = 1, n do $\mathbf{w} = \mathbf{a}_j$ $\mathbf{w} = (\mathbf{I} - \mathbf{Q}_{j-1}\mathbf{Q}_{j-1}^T)\mathbf{a}_j$ $\mathbf{q}_j = \mathbf{w}/||\mathbf{w}||_2$ end for

Outline of the first part

- When modified Gram-Schmidt generates a well conditioned set of vectors
- Reorthogonalization issues: twice is enough
- Reorthogonalization issues: about selective reorthogonalization criterion

 Reorthogonalization issues: a-posteriori reorthogonalization algorithm in the modified Gram–Schmidt algorithm

Classical/Modified

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Classical Gram–Schmidt (CGS)
for j = 1, n do
\mathbf{w} = (\mathbf{I} - \mathbf{Q}_{j-1}\mathbf{Q}_{j-1}^T)\mathbf{a}_j
\mathbf{q}_j = \mathbf{w}/||\mathbf{w}||_2
end for
```

Modified Gram–Schmidt (MGS) for j = 1, n do $\mathbf{w} = (\mathbf{I} - \mathbf{q}_{j-1}\mathbf{q}_{j-1}^T) \dots (\mathbf{I} - \mathbf{q}_1\mathbf{q}_1^T)\mathbf{a}_j$ $\mathbf{q}_j = \mathbf{w}/||\mathbf{w}||_2$ end for

An experimental fact

Let take A is the 12–by–12 Hilbert matrix with elements 1/(i+j-1)

$$A = \mathsf{hilb}(12) = \begin{pmatrix} 1 & 1/2 & 1/3 & \dots & 1/12 \\ & 1/3 & 1/4 & \dots & 1/13 \\ & & 1/5 & \dots & 1/14 \\ & & & \ddots & \vdots \\ & & & & & 1/23 \end{pmatrix}$$

It is an example of a ill–conditioned matrix, we have $\kappa(A) = 1.68e + 16$.

 $||I_n - Q^T Q||_2 = 0.302364$

 $\Rightarrow Q$ is far from being orthogonal.

Round–off errors

Computation in floating–point arithmetic implies in general round–off error. Standard exists to control these errors, we work here with the IEEE 754 standard

 $fl(x \text{ op } y) = (x \text{ op } y)(1+\delta) \quad |\delta| < u$

Björck ('67)

 $A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular values : $\sigma_1 \geq \ldots \geq \sigma_n > 0, \ \kappa(A) = \sigma_1 / \sigma_n,$ MGS computes \bar{Q} so as $\|I_n - Q^T Q\|_2 = 0 \rightarrow$

$$\|I_n - \bar{Q}^T \bar{Q}\|_2 \le \bar{c}_2 \kappa(A) u$$

where $\bar{c}_2 = 1.5n^{\frac{3}{2}}$ and u is the unit round–off. These results hold

under the assumptions :

$$\bar{c}_2 u\kappa(\mathbf{A}) < 1.$$

An experimental fact

Let take *A* is the 12–by–12 Hilbert matrix with elements 1/(i + j - 1)It is an example of a ill–conditioned matrix, we have $\kappa(A) = 1.68e + 16$.

> $||I_n - Q^T Q||_2 = 0.302364$ $\Rightarrow Q \text{ is far from being orthogonal.}$

However,

 $\kappa(Q) = 1.3$ $\Rightarrow Q \text{ is well conditioned.}$

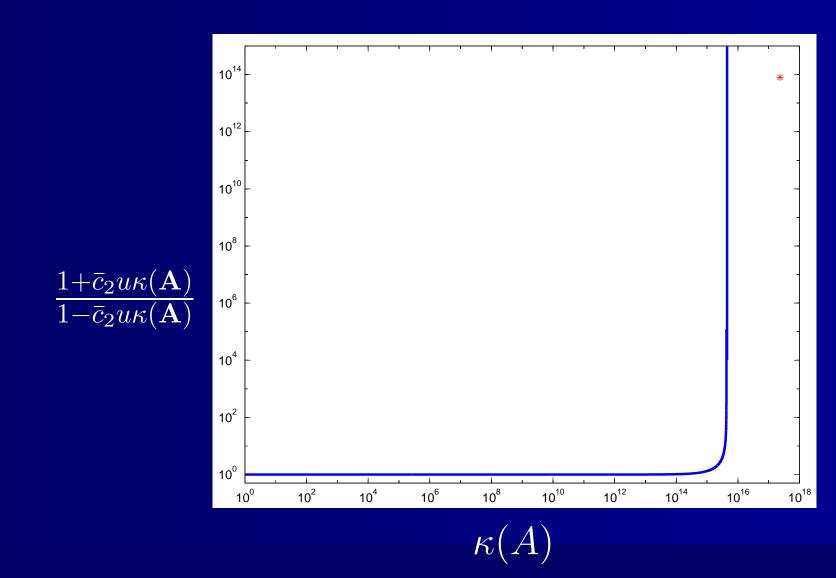
Giraud Langou ('02) – IMAJNA

Let us define U the polar factor of Q ($U^T U = I_n$) then Schönemann ('66), Higham ('94) showed $\|\bar{Q} - U\|_2 \le \|I - \bar{Q}^T \bar{Q}\|_2$. Björck ('67) showed that $\|I - \bar{Q}^T \bar{Q}\|_2 \le \bar{c}_2 \kappa(A) u$.

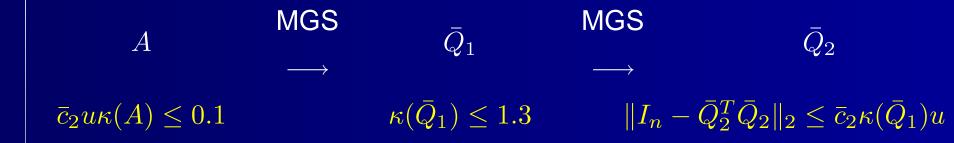
This implies that

$$\kappa(\bar{Q}) \le \frac{1 + \bar{c}_2 \kappa(A) u}{1 - \bar{c}_2 \kappa(A) u}.$$

Giraud Langou ('02) – IMAJNA



Two MGS loops



 $cu\kappa(A) \le 0.1 \longrightarrow ||I_n - \bar{Q}_2^T \bar{Q}_2||_2 \le 40.52 \cdot u \cdot n^{\frac{3}{2}}.$

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TMGS / MGS2

$$\begin{array}{l} Q^{(0)} = A \\ \text{for } r = 1, 2 \text{ do} \\ \text{for } j = 1, n \text{ do} \\ w = q_j^{(r-1)} \\ \text{for } i = 1, j - 1 \text{ do} \\ r_{ij}^{(r)} = q_i^{(r)T} w \\ w = w - q_i^{(r)T} r_{ij}^{(r)} \\ \text{end for} \\ r_{jj}^{(r)} = \|w\|_2 \\ q_j^{(r)} = w/r_{jj}^{(r)} \\ \text{end for} \\ Q = Q^{(2)} \\ R = R^{(2)} R^{(1)} \end{array}$$

for j = 1, n do $w = a_j$ for r = 1, 2 do for i=1, j-1 do $r_{ij}^{(r)} = q_i^T w$ $w = w - q_i r_{ij}^{(r)}$ end for end for $r_{jj}^{(2)} = \|w\|_2$ $q_j = w/r_{ij}^{(r)}$ end for $R = R^{(2)} + R^{(1)}$

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MGS2(*K*), $K = 1, \infty$

for
$$j = 1, n$$
 do
 $\mathbf{w} = \mathbf{a}_j$
for $r = 1, 2$ do
for $i = 1, j - 1$ do
 $r_{ij}^{(r)} = \mathbf{q}_i^T \mathbf{w}$
 $\mathbf{w} = \mathbf{w} - \mathbf{q}_i r_{ij}^{(r)}$
end for
if $\frac{\|\mathbf{a}_j\|_2}{\|\mathbf{w}\|_2} \leq K$ then reorthogonalize endif
end for
 $r_{jj}^{(2)} = \|\mathbf{w}\|_2$
 $\mathbf{q}_j = \mathbf{w}/r_{jj}^{(r)}$
end for
 $\mathbf{R} = \mathbf{R}^{(2)} + \mathbf{R}^{(1)}$

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Giraud Langou Rozložník ('01)

twice is enough for CGS2 (and MGS2 as well) if A is not too ill conditioned

Sketch of the proof For all j, we have

$$\frac{\|\mathbf{a}_j\|_2}{\|\mathbf{w}\|_2} \le 1.1\kappa(A).$$

and then by induction on $||I - \bar{Q}_j^T \bar{Q}_j||_2$.

Giraud and Langou ('03) – SISC

A rather comonly used criterion (Rutishauser ('67), Gander ('77), Ruhe('83), Hoffmann ('89), Dax ('00)) $\frac{\|a_j\|_2}{\|w\|_2} \leq \sqrt{2} \Leftrightarrow \frac{\sqrt{\sum_{i=1}^{j-1} r_{ij}^2}}{r_{jj}} \leq 1 \Rightarrow \text{no proof exists } \dots$ Giraud–Langou ('03) $rac{\sum_{i=1}^{j-1} |r_{ij}|}{r_{ij}} \le 1$ Abdelmaleck ('72) & Kiełbasiński ('74) $\frac{\sqrt{\sum_{i=1}^{j-1} r_{ij}^2}}{\sqrt{j-1} \cdot r_{ij}} \leq 1$ Daniel, Gragg, Kaufman and Stewart ('76) $\frac{\|a_j\|_2}{\|w\|_2} + \omega \frac{\|Q_{j-1}^T a_j\|_2}{\|w\|_2} \le \sqrt{2} \text{ where } \omega \sim \|I - Q_{j-1}^T Q_{j-1}\|_2.$

Giraud Langou ('03) – SISC

(K)	K = 1.40	K = 1.30	K = 1.17	K = 1.05
matrix B	B(400, 0.97)	B(500, 0.82)	B(1000, 0.50)	B(2500,0.30)
$\kappa(B)$	$3.4\cdot10^{15}$	$8.6\cdot10^{14}$	$1.8\cdot 10^{13}$	$5.9\cdot 10^{12}$
MGS2(K)	$7.2 \cdot 10^{-1}$	$1.1 \cdot 10^0$	$1.0 \cdot 10^{-2}$	$7.6 \cdot 10^{-3}$
MGS2	$1.5 \cdot 10^{-14}$	$1.9 \cdot 10^{-14}$	$3.5\cdot10^{-14}$	$8.0\cdot10^{-14}$
CGS2(K)	$1.6\cdot 10^0$	$1.6\cdot 10^0$	$1.6 \cdot 10^0$	$1.6\cdot 10^0$
CGS2	$1.2 \cdot 10^{-14}$	$1.5 \cdot 10^{-14}$	$2.8 \cdot 10^{-14}$	$6.0 \cdot 10^{-14}$
		$ I_n - Q^T Q _2$		

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		$\boxed{\ I_n - Q^T Q\ _2}$		

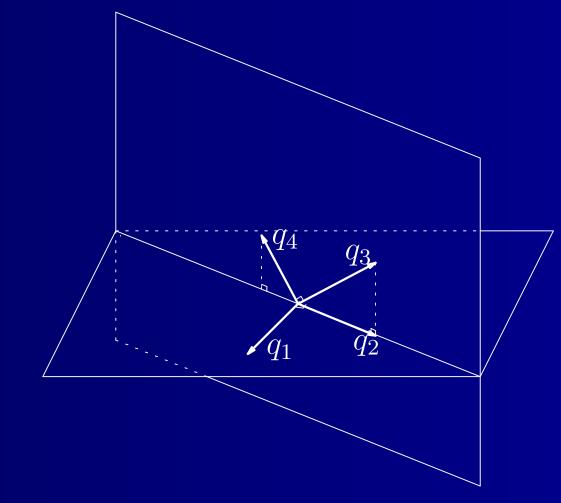
Blindy MGS

$$A = \left(\begin{array}{rrrrr} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right).$$

gives

$$Q = \begin{pmatrix} 1 & 0 & 1/2 & -1/2 \\ 0 & 1 & 1/2 & -1/2 \\ 0 & 0 & \sqrt{2}/2 & \sqrt{2}/2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } R = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & \sqrt{2}/2 \\ 0 & 0 & 0 & \sqrt{2}/2 \\ 0 & 0 & 0 & \sqrt{2}/2 \end{pmatrix}$$

Blindy MGS



 (q_1, q_2, q_3, q_4) given by blindy MGS on A.

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Giraud Gratton Langou ('03)

Singular values study.

 $F = \tilde{Q} - \hat{Q}$

under the assumption $cu\kappa < 1$, for all $i = 1, \ldots, n$,

$$\sigma_i(F) \le 2cu \frac{\|A\|_2}{\sigma_{n-i+1}(A)}.$$

E.g.

$$\sigma_1(F) \le 2cu \frac{\|A\|_2}{\sigma_n(A)}$$
$$\sigma_2(F) \le 2cu \frac{\|A\|_2}{\sigma_{n-1}(A)}$$

Solving large linear systems with multiple right-hand sides - p. 30/12



Follow Björck and Paige ('92) and instead of doing

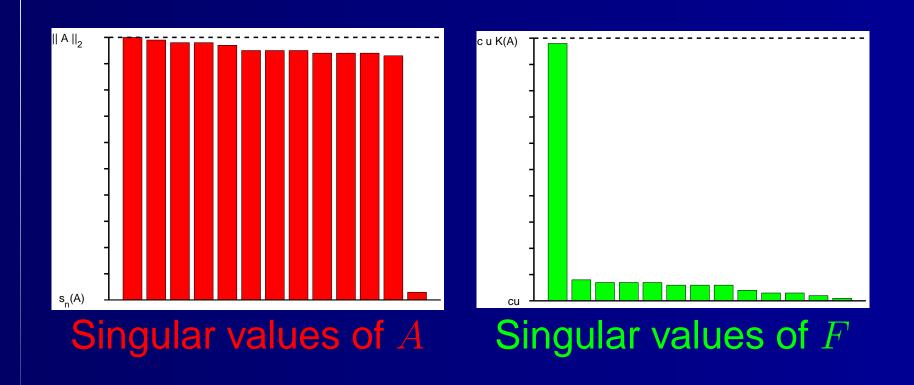
 $||AB||_2 \le ||A||_2 ||B||_2,$

do

 $\sigma_i(AB) \le \sigma_i(A) ||B||_2, \qquad i = 1, \dots, n.$

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Interpretation in term of rank.



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How to find F? - the rank-1 case

- Run MGS to have Q and R.
- Form T and find its singular value decomposition such that $T = u_T \sigma_T w_T^T$.
- Compute $c = \sigma + \sigma^2(w_T^T u_T)$ and $s = \sqrt{1 c^2}$. • Form F :

$$F = \left(\left(Q \left(w_T (1 - s^{-1}) + u_T (1 - s^{-1} - c) \right) \right) w_T^T \right).$$

This algorithm needs 8mn flops! For comparison, we recall that a complete reorthogonalization loop costs $2mn^2$ flops.

Application to iterative methods

		m	# iter	κ	κ_2	
	Cetaf	5391	31	$9.7\cdot10^{14}$	27	
	Airbus	23676	104	$3.6\cdot 10^{14}$	14	
	Sphere	40368	59	$3.9\cdot 10^{14}$	6.4	
	Almond	104973	71	$5.1\cdot10^{14}$	5.9	
Characteristics of $A = (b, \mathbb{Z}V_{n-1})$						
					v.	
(a) cetaf	(b)	(b) airbus		sphere	(d) a	Imon

Application to iterative methods

	MGS	$MGS2(\sqrt{2})$	a-posteriori reorth.
Cetaf	$2.8 \cdot 10^{-17}$	$1.8 \cdot 10^{-16}$	$2.9 \cdot 10^{-16}$
Airbus	$4.0 \cdot 10^{-17}$	$2.7 \cdot 10^{-16}$	$4.4 \cdot 10^{-16}$
Sphere	$5.8 \cdot 10^{-17}$	$1.6 \cdot 10^{-16}$	$2.7 \cdot 10^{-16}$
Almond	$3.9 \cdot 10^{-17}$	$3.9 \cdot 10^{-16}$	$2.2 \cdot 10^{-16}$
Residual errors – $ A - QR _2 / A _2$			

Application to iterative methods

	MGS	$MGS2(\sqrt{2})$	a-posteriori reorth.
Cetaf	$1.6 \cdot 10^{-02}$	$2.8 \cdot 10^{-16}$	$2.4 \cdot 10^{-15}$
Airbus	$1.8 \cdot 10^{-02}$	$3.7 \cdot 10^{-16}$	$1.6 \cdot 10^{-15}$
Sphere	$3.9 \cdot 10^{-02}$	$3.0 \cdot 10^{-16}$	$7.8 \cdot 10^{-16}$
Almond	$4.1 \cdot 10^{-02}$	$2.8 \cdot 10^{-16}$	$7.9 \cdot 10^{-16}$
Orthogonality – $\ I_n - \bar{Q}^T \bar{Q}\ $			

Summary

- MGS generates a well conditioned set of vectors
- twice is enough
- a new selective reorthogonalization criterion has been exhibited
- counter example matrices for the K-criterion are given
- a new a-posteriori reorthogonalization schemes is provided

Future work

- the singular case has not been treated (RRQR, SVD,...)
- currently, we are interested in CGS
- as well as the study of Gram–Schmidt algorithm with non Euclidean scalar product

Implementation of iterative methods

Solving large linear systems with multiple right-hand sides - p. 39/12

The electromagnetism applications

Motivations

- Boundary element method in the Maxwell equations that leads to complex, dense and huge linear systems to solve,
- $\mathbb{Z}J = F(\varphi)$, where $\varphi = 0^o : 1^o : 180^o$,
- Z is accessed via matrix-vector products using the fast multipole method, a Krylov solver is used,
- Previous work:
 - Frobenius norm minimizer preconditioner,
 - flexible GMRES solver (inner GMRES preconditioner),
 - spectral low rank update preconditioner,

 \Rightarrow still problematic to have a *complete* monostatic radar cross section.

Outline of the third part

- I. techniques to improve one right-hand side solvers for multiple right-hand sides problem,
- II. seed–GMRES algorithm: two cases, two problems and two remedies,
- *III*. linear dependencies of the right–hand sides in the electromagnetism context.

Collaborators

This presentation uses results and codes provided by Guillaume Alléon EADS, Guillaume Sylvand (INRIA(Sophia–Antipolis)–CERMICS), Bruno Carpentieri and Émeric Martin. Iain S. Duff (CERFACS–RAL) and Luc Giraud (CERFACS) supervise the work at CERFACS. Francis Collino is also working with us.

 increase the amount of work in the preconditioner in order to increase its efficiency. In our case, for example, we can
 increase the density of the Frobenius norm minimizer preconditioner (Bruno)

1.b. add a spectral low rank update that shifts the smallest eigenvalue close to one (Émeric)

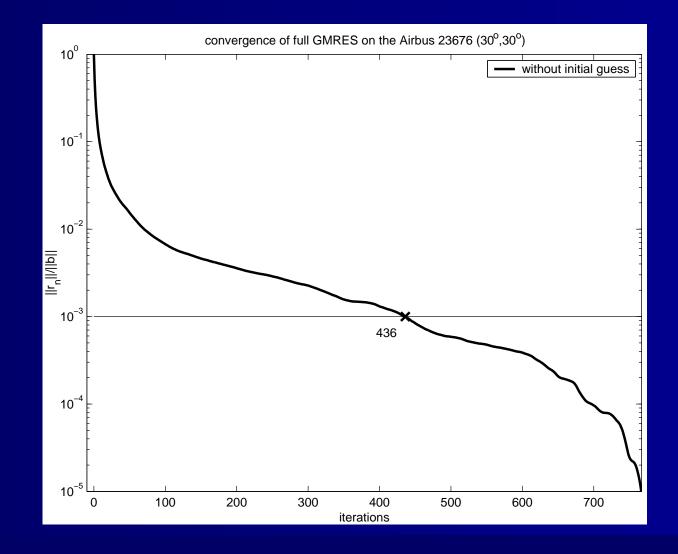
- 1. increase the amount of work in the preconditioner in order to increase its efficiency
- find an initial approximate solution for the current system ℓ from the previous systems solved
 2.a. An obvious strategy is to take

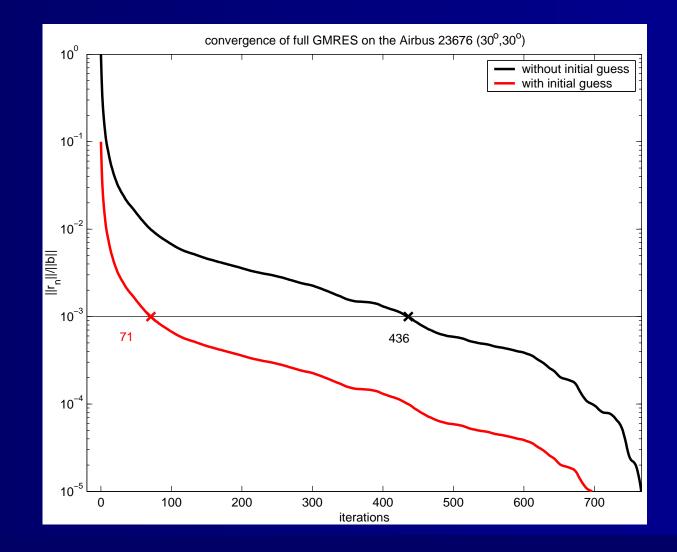
$$J^{(0)}(\varphi_{\ell}) = J(\varphi_{\ell-1})$$

2.b. Another strategy is to solve the least squares problem

$$\min_{y \in \mathbb{R}^{\ell-1}} \|F(\varphi_\ell) - \sum_{j=0}^{\ell-1} F(\varphi_j) y_j\|_2$$

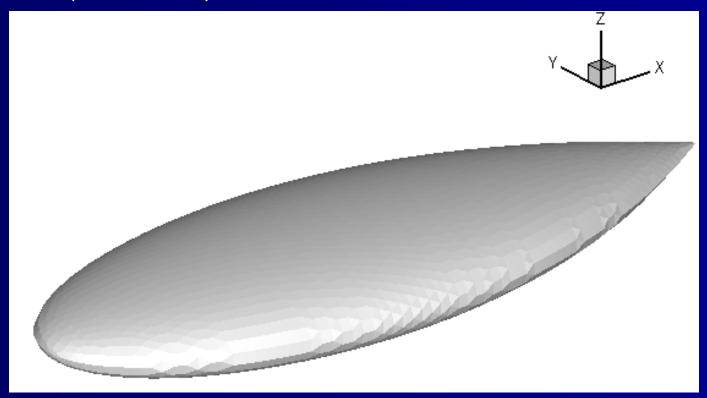
then take the initial guess $J^{(0)}(\varphi_{\ell}) = \sum_{j=0}^{\ell-1} J(\varphi_j) y_j$





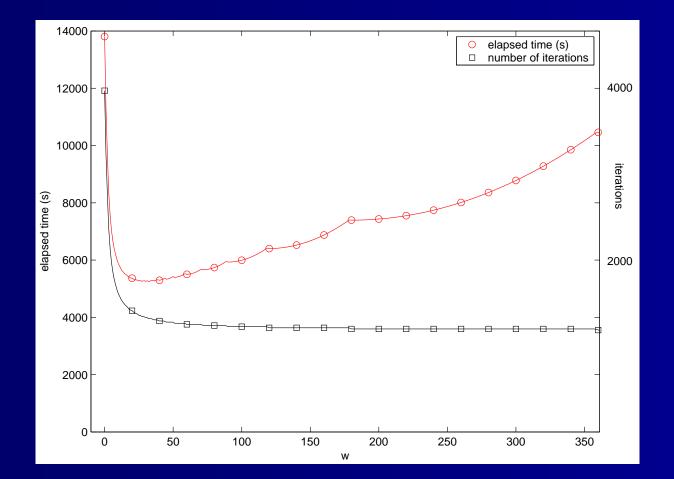
- 1. increase the amount of work in the preconditioner in order to increase its efficiency
- 2. find an initial approximate solution for the current system ℓ from the previous systems solved
- 3. gathered multiple GMRES iterations

A first test case: the almond 104793 $\theta = 0^{\circ} : 0.5^{\circ} : 180^{\circ}$ and CFIE formulation (JINA 2002)



	# iterations	elapse time (s)				
seed–GMRES	1185					
GMRES with initial guess strategy 2	1791					
# iterations and elapsed time (s) on 8 processors						
(Compaq–CERFACS).						

	# iterations	elapse time (s)				
seed–GMRES	1185	10460				
GMRES with initial guess strategy 2	1791	6202				
# iterations and elapsed time (s) on 8 processors						
(Compag-CEREACS).						



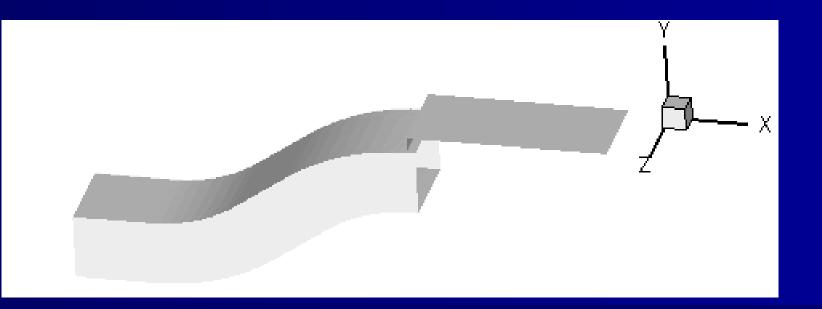
Elapsed time and number iterations versus the size of the restart w for restart seed–GMRES.

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	# iterations	elapse time (s)			
seed–GMRES	1185	10460			
GMRES with initial guess strategy 2	1791	6202			
seed–GMRES ($w = 33$)	5300				
# iterations and elapsed time (s) on 8 processors					

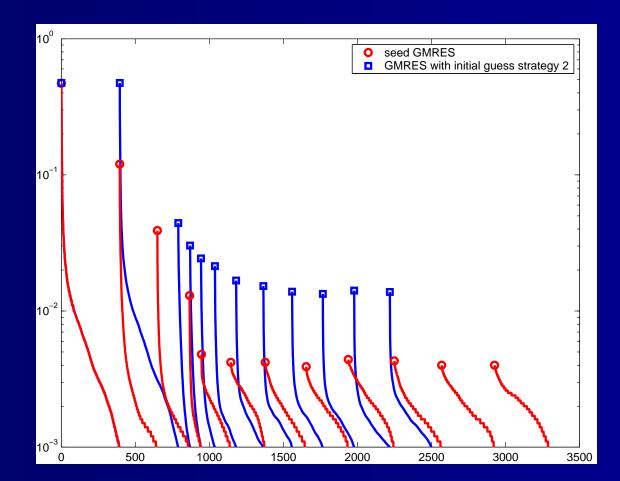
(Compaq-CERFACS).

A second test case: the cobra 60695 $\theta = 0^{\circ} : 0.5^{\circ} : 180^{\circ}$ and EFIE formulation



	default guess		strat. 2	seed	–GMRES
(heta,arphi)	<i>⋕</i> iter	<i>#</i> iter	$ r_0 _2/ F _2$	<i></i> # iter	$ r_0 _2/ b _2$
(0.0,0.0)			1.000		1.000
(0.5,0.0)			1.000		0.230
(1.0,0.0)			0.071		0.074
(1.5,0.0)			0.048		0.024
(2.0,0.0)			0.039		0.007
(2.5,0.0)			0.037		0.004
(3.0,0.0)			0.028		0.004
(3.5,0.0)			0.028		0.004
(4.0,0.0)			0.024		0.004
(4.5,0.0)			0.022		0.004
(5.0,0.0)			0.027		0.004
(5.5,0.0)			0.022		0.004

	default guess	:	strat. 2	seed	J–GMRES
(heta,arphi)	<i>⋕</i> iter	<i></i> # iter	$ r_0 _2/ F _2$	<i>⊭</i> iter	$\ r_0\ _2 / \ b\ _2$
(0.0,0.0)	338	338	1.000	338	1.000
(0.5,0.0)	339	339	1.000	190	0.230
(1.0,0.0)	340	63	0.071	210	0.074
(1.5,0.0)	341	56	0.048	130	0.024
(2.0,0.0)	341	81	0.039	197	0.007
(2.5,0.0)	341	116	0.037	215	0.004
(3.0,0.0)	342	139	0.028	237	0.004
(3.5,0.0)	342	151	0.028	226	0.004
(4.0,0.0)	343	159	0.024	254	0.004
(4.5,0.0)	344	180	0.022	258	0.004
(5.0,0.0)	345	179	0.027	265	0.004
(5.5,0.0)	346	192	0.022	299	0.004



Comparison between the seed–GMRES method and the GMRES method with initial guess strategy 2.

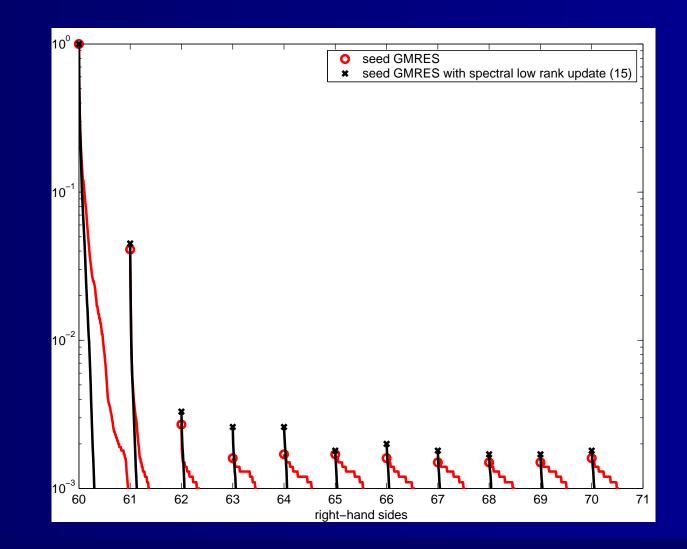
Seed moral in le Cid

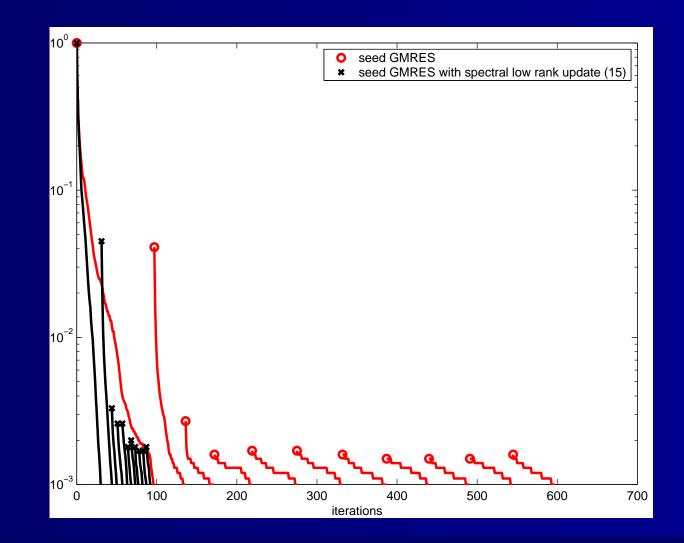
Ô rage ! Ô désespoir ! Ô vieillesse ennemie ! N'ai-je donc tant tant vécu que pour cette infamie ? Ô Anger! Ô despair! Ô ennemy of age! Should I have lived so much for such infamy?



Corneile (1682), Le Cid.

Solving large linear systems with multiple right-hand sides - p. 58/12

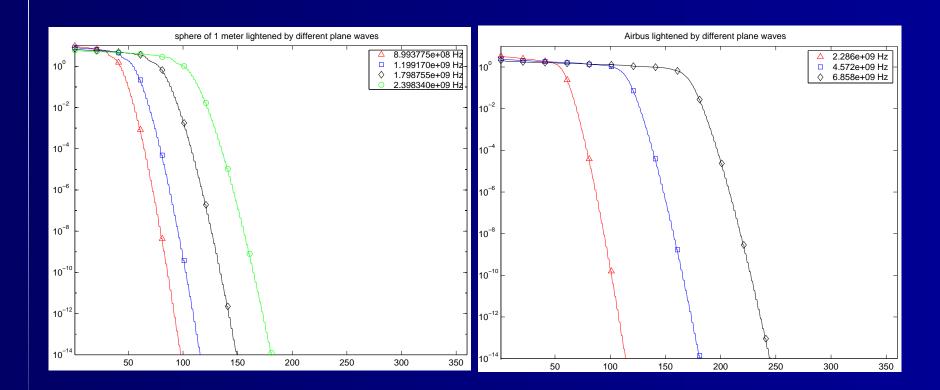




in a race starting close from the arrival and running fast ensures to finish first!

in a race starting close from the arrival and running fast ensures to finish first! Luc Giraud (my thesis advisor).

Linear dependencies RHS



Singular values distribution of $[F(0^{\circ}), \ldots, F(360^{\circ})]$.

Solving large linear systems with multiple right-hand sides - p. 63/12

p, the size in wavelengths

	dof	F	λ	p
cetaf	5391	3.0 GHz	10.0 cm	6
sphere	40368	0.9 GHz	33.3 cm	6
sphere	71148	1.2 GHz	$25.0 \ \mathrm{cm}$	8
sphere	161472	1.8 GHz	16.7~cm	12
sphere	288300	2.4 GHz	$12.5~{ m cm}$	16
Airbus	23676	2.3 GHz	13.0 cm	14
Airbus	94704	4.6 GHz	6.5 cm	29
Airbus	213084	6.9 GHz	$4.3 \ \mathrm{cm}$	44
cobra	3823	1.0 GHz	30.0 cm	2
cobra	60695	10.0 GHz	3.0 cm	24
almond	8112	0.7 GHz	42.8 cm	6
almond	104793	2.6 GHz	$11.5~\mathrm{cm}$	22

Harmonic spheric decomposition

 $M = 2\left(\pi p + C_{\varepsilon} \log(\pi p + \pi)\right) + 1,$

where C_{ε} is such that the errors done by representing the right-hand sides in the basis of the spherical harmonic is $10^{-C_{\varepsilon}}$.

This is joint work with Francis Collino.

Comparison of M and q

	dof	F	λ	p	M	q
cetaf	5391	3.0 GHz	10.0 cm	6		
sphere	40368	0.9 GHz	33.3 cm	6		
sphere	71148	1.2 GHz	$25.0 \ \mathrm{cm}$	8		
sphere	161472	1.8 GHz	$16.7 \ \mathrm{cm}$	12		
sphere	288300	$2.4~\mathrm{GHz}$	$12.5~\mathrm{cm}$	16		
Airbus	23676	2.3 GHz	13.0 cm	14		
Airbus	94704	4.6 GHz	6.5 cm	29		
Airbus	213084	6.9 GHz	$4.3 \ \mathrm{cm}$	44		
cobra	3823	1.0 GHz	30.0 cm	2		
cobra	60695	10.0 GHz	3.0 cm	24		
almond	8112	0.7 GHz	42.8 cm	6		
almond	104793	2.6 GHz	11.5 cm	22		

We take $C_{\varepsilon} = 4$ and compute M, we compare with q, the number of singular values greater than 10^{-4} .

Comparison of M and q

	dof	F	λ	p	M	q
cetaf	5391	3.0 GHz	10.0 cm	6		
sphere	40368	0.9 GHz	33.3 cm	6	63	60
sphere	71148	1.2 GHz	$25.0~{ m cm}$	8	78	76
sphere	161472	1.8 GHz	$16.7~{ m cm}$	12	106	104
sphere	288300	$2.4 \; \mathrm{GHz}$	$12.5~\mathrm{cm}$	16	133	130
Airbus	23676	2.3 GHz	13.0 cm	14		
Airbus	94704	4.6 GHz	$6.5~\mathrm{cm}$	29		
Airbus	213084	6.9 GHz	$4.3 \ \mathrm{cm}$	44		
cobra	3823	1.0 GHz	30.0 cm	2		
cobra	60695	10.0 GHz	3.0 cm	24		
scriptsize almond	8112	0.7 GHz	42.8 cm	6		
almond	104793	2.6 GHz	$11.5~\mathrm{cm}$	22		

We take $C_{\varepsilon} = 4$ and compute M, we compare with q, the number of singular values greater than 10^{-4} .

Comparison of M and q

	dof	F	λ	p	M	q
cetaf	5391	3.0 GHz	10.0 cm	6	63	24
sphere	40368	0.9 GHz	33.3 cm	6	63	60
sphere	71148	1.2 GHz	$25.0\ \mathrm{cm}$	8	78	76
sphere	161472	1.8 GHz	$16.7 \ cm$	12	106	104
sphere	288300	$2.4 \; \mathrm{GHz}$	$12.5~\mathrm{cm}$	16	133	130
Airbus	23676	2.3 GHz	13.0 cm	14	120	80
Airbus	94704	4.6 GHz	$6.5~{ m cm}$	29	220	139
Airbus	213084	6.9 GHz	$4.3~{ m cm}$	44	317	198
cobra	3823	1.0 GHz	30.0 cm	2	32	17
cobra	60695	10.0 GHz	3.0 cm	24	186	68
almond	8112	0.7 GHz	42.8 cm	6	63	26
almond	104793	2.6 GHz	$11.5~\mathrm{cm}$	22	133	67

We take $C_{\varepsilon} = 4$ and compute M, we compare with q, the number of singular values greater than 10^{-4} .

Solving large linear systems with multiple right-hand sides - p. 68/12

Linear dependency of RHS

To solve the p systems

$$\mathbb{Z}J=F,$$

since we can write

$$F = US + E$$
 with $||E||_2 = \sigma_{q+1}$,

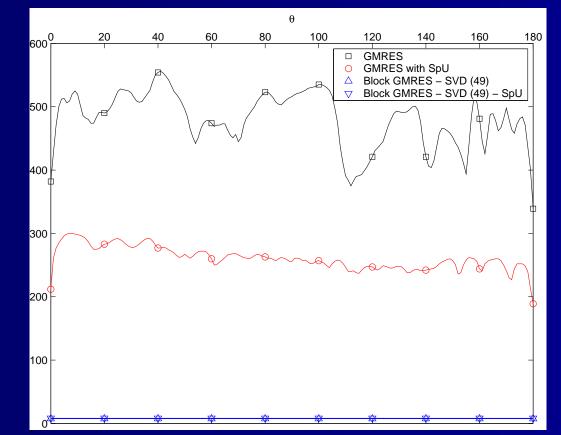
1. we solve the system with the q right-hand sides U

$$\mathbb{Z}X = U$$

and then update the solutions with J = XS.

2. with block–GMRES algorithm, we minimize the right–hand sides F on the block–Krylov space constructed with U.

On the Airbus 23676



For each right-hand sides we plot the number of iterations (matrix-vector product) required to converge. The test example is the Airbus 23676 $\theta = 0^{\circ} : 1^{\circ} : 180^{\circ}$.

Results

	DOF	# RHS	# SVD	# it	avr. # it SVD	avr. # it classic
coated cone sphere	77604	181	15	285	1.5	20
almond	104793	361	63	532	1.4	10
cobra LRU(15)	60695	91	35	1712	18.8	185
Airbus (5e-2)	94704	181	70	1430	7.9	130

Summary

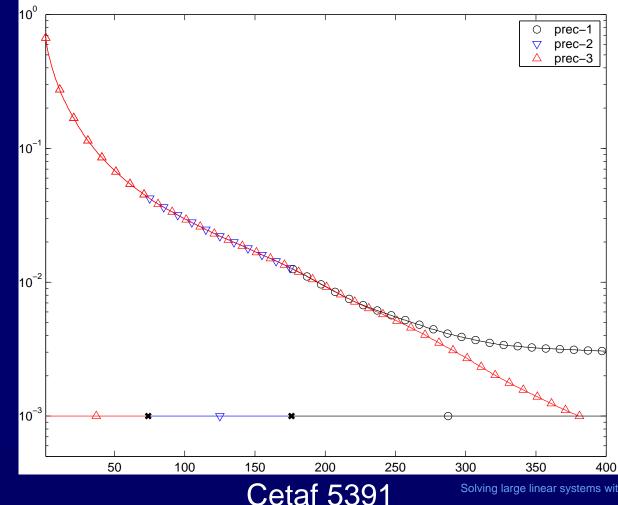
- adapting one right hand—side solver to the multiple right—hand sides case is worthly to be considered
- seed–GMRES algorithm may greatly be improved by restart or spectral low rank update
- linear dependencies of the right-hand sides is systematic in the electromagnetism context
- SVD preprocessing and use with the block–GMRES algorithm is the best method at that moment

Prospectives (1) – block/seed

set the vectors in-core to gain in the orthogonalization process
 restart in block-GMRES has the same catastrophic effect (in our case) than restart in GMRES and prevents from convergence on hard cases, block-GMRES with restart and spectral low rank update is therefore tested on big test cases where full block-GMRES is not affordable anymore. Also we are thinking on how implementing block-GMRES-DR algorithm in the code since GMRES-DR works fine.

Prospectives (2) – relax

Relaxing the accuracy of the matrix–vector product operation during the convergence of GMRES – Bouras, Frayssé and Giraud ('00) strategy



Solving large linear systems with multiple right-hand sides - p. 74/12

Jury

Guillaume Alléon Director of project, EADS-CCR Åke Björck Professor, Linköping University lain S. Duff Project leader CERFACS et RAL Luc Giraud Senior researcher, CERFACS Gene H. Golub Professor, Stanford University Gérard Meurant **Research director**, CEA Chris C. Paige Professor, McGill University Yousef Saad Professor, University of Minnesota

Study of the Gram–Schmidt algorithm and its variants

Classical/Modified

Classical Gram-Schmidt (CGS) for j = 1, n do $\mathbf{w} = \mathbf{a}_j$ for i = 1, j - 1 do $r_{ij} = \mathbf{q}_i^T \mathbf{a}_j$ $\mathbf{w} = \mathbf{w} - \mathbf{q}_i r_{ij}$ end for $r_{jj} = \|\mathbf{w}\|_2$ $\mathbf{q}_j = \mathbf{w}/r_{jj}$ end for Modified Gram-Schmidt (MGS) for j = 1, n do $\mathbf{w} = \mathbf{a}_j$ for i = 1, j - 1 do $r_{ij} = \mathbf{q}_i^T \mathbf{w}$ $\mathbf{w} = \mathbf{w} - \mathbf{q}_i r_{ij}$ end for $r_{jj} = \|\mathbf{w}\|_2$ $\mathbf{q}_j = \mathbf{w}/r_{jj}$ end for

The Arnoldi algorithm

The Arnoldi method provides, at each step n, an orthonormal basis V_{n+1} for the Krylov space $\mathcal{K}_n(\mathbb{Z}, b)$ that verifies

$$(b, \mathbb{Z}V_n) = V_{n+1}(e_1\beta, H_{n+1,n}).$$

So

find $x_n \in \mathcal{K}_n(\mathbb{Z}, b)$ that minimizes $||b - \mathbb{Z}x||_2$ \Leftrightarrow find $y_n \in \mathbb{R}^n$ that minimizes $||e_1\beta - H_{n+1,n}y||_2$ and set $x_n = V_n y_n$.

Björck ('67)

 $A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular values : $\sigma_1 \geq \ldots \geq \sigma_n > 0$, $\kappa(A) = \sigma_1/\sigma_n$, MGS computes \overline{R} so as

 $A = QR \rightarrow$ $A + \bar{E} = \bar{Q}\bar{R}, \quad \|\bar{E}\|_2 \le \bar{c}_1 u \|A\|_2$ $\|I_n - Q^T Q\|_2 = 0 \rightarrow$ $\|I_n - \bar{Q}^T \bar{Q}\|_2 \le \bar{c}_2 \kappa(A) u$

where \bar{c}_i are constants depending on m, n and the details of the arithmetic, and u is the unit round–off.

Björck ('67)

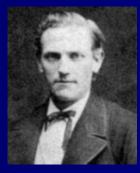
 $\overline{c_1} = 1.5n^{\frac{3}{2}}$ and $\overline{c_2} = 31.6863n^{\frac{3}{2}}$. These results hold under the assumptions : $2.12 \cdot (m+1) \cdot u < 0.01$ and $\overline{c_2}u\kappa(\mathbf{A}) < 1$.

Gram–Schmidt algorithm

for j = 1, n do $\mathbf{w} = \mathbf{a}_i$ for i = 1, j - 1 do $\overline{r}_{ij} = \mathbf{q}_i^T \mathbf{a}_j$ $\mathbf{w} = \mathbf{w} - \mathbf{q}_i r_{ij}$ end for $r_{jj} = \|\mathbf{w}\|_2$ $\mathbf{q}_{j} = \mathbf{w}/r_{jj}$ end for

cost: $2mn^2$ flops

Unitary transformations





Gram

Schmidt VS





GIVENS HOUSEHOLDER

Solving large linear systems with multiple right-hand sides - p. 82/12

Householder & Givens

Idea : find a series of unitary matrix $(Q_i)_{i=1,...,n}$ such that for all i = 1, ..., n, the *i*-th first columns of

 $Q_i \dots Q_1 A = A_i$

are upper triangular. **Choice :** typically we use Givens rotations: $Q_i = "\begin{pmatrix} \cos & -\sin \\ \sin & \cos \end{pmatrix}$ ", Householder reflections: $Q_i = I_m - 2z_i z_i^T$ where $||z_i||_2 = 1$. **Cost :** $2mn^2 - n^3/3$ for R, $2 \times (2mn^2 - n^3/3)$ for R and Q.

Advantages & drawbacks

Advantages :

- possibility to exploit the structure of A (e.g. A Hessenberg \rightarrow Givens rotations)

- if only the R factor is needed then the number of flops is less than Gram–Schmidt algorithm

- the Q factor has columns orthornormal up to machine precision (Wilkinson, '63)

Drawbacks :

- to obtain Q doubles the cost of the method

- the fact that unitary transformations implies a Q factor with orthonormal columns highly depends on the dot product used

Björck and Paige ('92)

 $A \in \mathbb{R}^{m \times n}$ with full rank $n \leq m$, with singular values : $\sigma_1 \geq \ldots \geq \sigma_n > 0$, $\kappa(A) = \sigma_1/\sigma_n$, MGS computes \bar{R} such that

$$A + \hat{E} = \hat{Q}\bar{R}, \quad \hat{Q}^T\hat{Q} = I_n \text{ and } \|\hat{E}\|_2 \le cu\|A\|_2,$$

where $c = 18.53n^{\frac{3}{2}}$ and u is the unit round-off. This results holds under the assumptions $2.12 \cdot (m+1) \cdot u < 0.01$ and $cu\kappa(\mathbf{A}) < 1$.

Daniel and al. ('76)

Let take $Q \in \mathbb{R}^{m \times n}$ such that

$$||I_n - Q^T Q||_2 = 10^{-3}$$
 (e.g.)

and $w^{(0)}\mathbb{R}^m$, we consider the serie of vectors $(w^{(i)})$

$$w^{(i)} = (I_n - QQ^T)w^{(i-1)}.$$

Then Daniel and al. showed that

$$\|Q^T w^{(i)}\|_2 / \|w^{(i)}\|_2 \le \xi_i,$$

where ξ_i is defined via $\xi_0 = \|Q^T w^{(0)}\|_2 / \|w^{(0)}\|_2 = 10^0$ (e.g.) $\xi_i = \varphi(\xi_{i-1}), i = 1, \dots$

Giraud, Langou and Rozložník ('0'

 $||I - Q^T Q||_2 = 10^{-3}, \xi_0 = ||Q^T w^{(0)}||_2 / ||w^{(0)}||_2 = 10^0$ 10⁰ ς, 10⁻² 10⁻⁴ ζ, 10⁻⁶ ζз 10⁻⁸ 10⁻¹⁰ 10⁻¹² 10⁻¹⁴ 10⁻¹⁶ 10⁻¹⁶ 10^{-12} 10⁻¹⁰ 10^{-14} 10⁻⁸ 10^{-6} 10^{-4} 10⁻² 10⁰ • $\|Q^T w^{(i)}\|_2 / \|w^{(i)}\|_2, -y = \varphi(x), -y = x, \bullet \xi_i$

How to find F?

$$F = Q - \hat{Q},$$

= $P_{21}(I - T) - \hat{Q},$
= $U_2(S - I)W^T - P_{21}T,$
~ $U_{2k}(S_k - I)W_k^T - P_{21}(U_{Tk}\Sigma_{Tk}W_{Tk}^T).$

We have expressed F as a sum of to low rank matrix of rank k. The choice of k is a compromise between accuracy and efficiency.

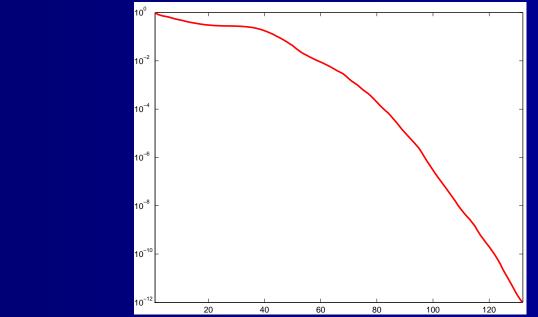




Goldorak (n=715 , $\kappa(A)=546$).



We run full GMRES with MGS without preconditionner and a right-hand side corresponding to an incident wave at 0° . The tolerance is fixed to 10^{-12} .



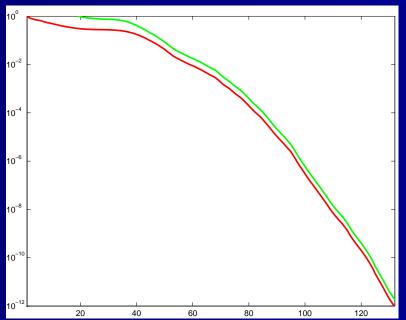
Solving large linear systems with multiple right-hand sides - p. 90/12

2D example

From Greenbaum, Rozložník and Strakoš ('97) we know that $||r_m||_2 \sim \sigma_{min} (v_0, AV_m)$

 $- ||r_m||_2/||b||_2$

 $\overline{\left(-\sigma_{min}\left(v_{0},AV_{m}
ight) }/\sigma_{min}\left(A
ight) }$



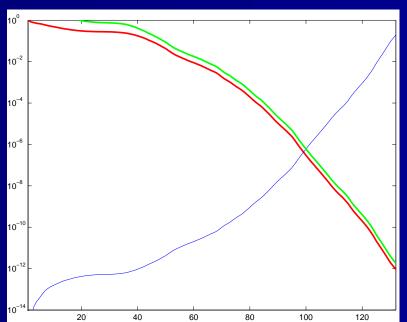
2D example

so from Björck (1967) we can check that the loss of orthogonality is proportionnal to $1/||r_m||_2$.

 $- \|r_m\|_2 / \|b\|_2$

- $\sigma_{min}\left(v_{0},AV_{m}
ight)/\sigma_{min}\left(A
ight)$

 $- \|I - V_m^T V_m\|_2$



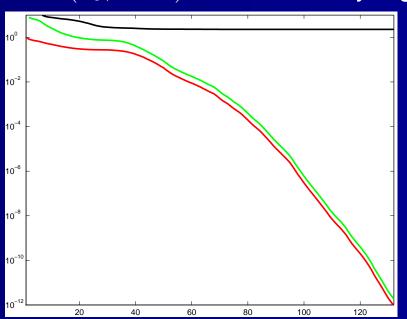
2D example

As $AV_m = V_m \overline{H}_m$, V_m and A are well-conditionned, we deduced that the second smallest singular value of (v_0, AV_m) is reasonnably big.

 $- \|r_m\|_2 / \|b\|_2$

 $-\sigma_{m+1}\left(v_{0},AV_{m}\right)/\sigma_{min}\left(A\right)$

 $-\frac{\sigma_m(v_0,AV_m)}{\sigma_{min}(A)}$



LLS problems with multiple RHS

with MGS

$$\begin{pmatrix} v_1^T b^{(i)} \\ v_2^T (I_m - v_1 v_1^T) b^{(i)} \\ \vdots \\ v_n^T (I_m - v_{n-1} v_{n-1}^T) \dots (I_m - v_1 v_1^T) b^{(i)} \end{pmatrix}$$

when using an orthonormal basis Q

$$\begin{pmatrix}
q_1^T b^{(i)} \\
q_2^T b^{(i)} \\
\vdots \\
q_n^T b^{(i)}
\end{pmatrix}$$

Application to iterative methods

	$MGS2(\sqrt{2})$	MGS2(2)	MGS2($\sqrt{5}$)					
Cetaf	$2.8 \cdot 10^{-16} \ (\nu = 2.00)$	$6.3 \cdot 10^{-16} \ (\nu = 1.90)$	$1.2 \cdot 10^{-15} \ (\nu = 1.87)$					
Airbus	$3.7 \cdot 10^{-16} \ (\nu = 2.00)$	$3.9 \cdot 10^{-03} \ (\nu = 1.02)$	$8.8 \cdot 10^{-03} \ (\nu = 1.01)$					
Sphere	$3.0 \cdot 10^{-16} \ (\nu = 2.00)$	$7.5 \cdot 10^{-15} \ (\nu = 1.52)$	$4.9 \cdot 10^{-04} \ (\nu = 1.07)$					
Almond	$2.8 \cdot 10^{-16} \ (\nu = 2.00)$	$1.7 \cdot 10^{-03} \ (\nu = 1.06)$	$5.2 \cdot 10^{-03} \ (\nu = 1.03)$					
	$\ I_n-ar{Q}^Tar{Q}\ $.							

Implementation of iterative methods

Solving large linear systems with multiple right-hand sides - p. 96/12

Outline

GMRES–DR

- seed–GMRES
- block–GMRES

GMRES-DR

$$V_{k+1}^{\mathsf{new}} \longleftarrow V_{n+1} P_{k+1},$$

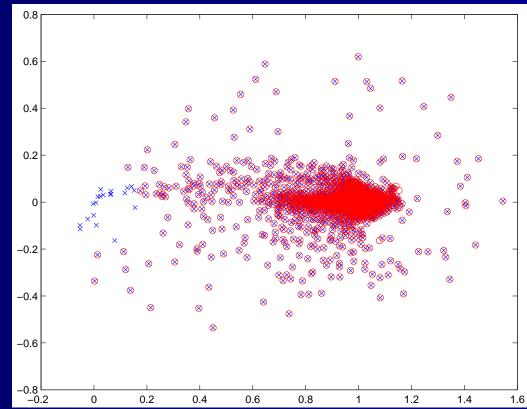
need n + k + 2 vectors of size m. whereas if we first perform the LU decomposition of P_{k+1} and then do

$$V_{k+1}^{\mathsf{new}} \longleftarrow (V_{n+1}L)U$$

; we only need n+1 vectors.

The electromagnetism applications

One right-hand side solvers



spectrum

 \times Cetaf preconditioned with "default" Frobenius norm minimizer preconditioner

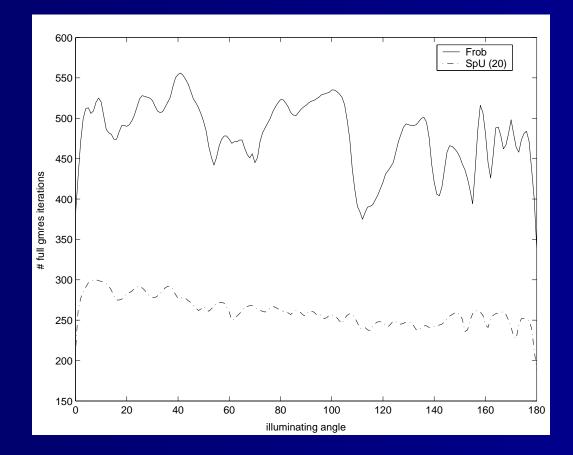
Cetaf preconditioned with "default" Frobenius norm minsolving large linear systems with multiple right-hand sides - p. 10

One right-hand side solvers

		assem	bly		# procs		
	FMM Frob SLRU			FMM	Frob	SLRU	
cetaf 5391	9.6	631.8	3.7 (20)	0.25	0.11	0.02 (20)	4
Airbus 23676	114.8	184.8	36.7 (20)	1.86	0.29	0.03 (20)	4
cobra 60695	33.3	120.2	30.6 (15)	1.93	0.22	0.03 (15)	8
almond104793	53.1	345.8	182.8 (60)	2.92	0.41	0.10 (60)	8
almond104793	53.1	345.8	59.3 (20)	2.92	0.41	0.05 (20)	8

Time of assembly and application of the FMM (prec-3), the Frobenius preconditioner and the spectral update (the number of shifted eigenvalues is given in bracket).

One right-hand side solvers



Airbus 23676

Gathered multiple GMRES

	unitary FMM (s)	unitary Precond (s)	<pre> # FMM &Precond </pre>	total
gathered GMRES (10)	0.7	0.05	180	205.1
GMRES with zero as initial guess	1.8	0.27	177	401.4
	(a) Airbu	c 23676		

(a) Airbus 23676.

	unitary FMM (s)	unitary Precond (s)	# FMM &Precond	total
GMRES gathered (19)	1.6	0.13	931	2340.8
GMRES with strategy 2 for the initial guess	7.1	0.42	856	7703.2

(b) coated cone sphere 77604.

The seed GMRES algorithm (1)

We first run GMRES to solve the linear system $\mathbb{Z}J(\varphi_0) = F(\varphi_0)$. This amounts to solving the linear least squares problem

 $\min_{J\in\mathcal{K}_0}\|F(\varphi_0)-\mathbb{Z}J\|_2,$

where \mathcal{K}_0 is the Krylov space of size *n* built with an Arnoldi process on \mathbb{Z} using the starting vector $F(\varphi_0)$.

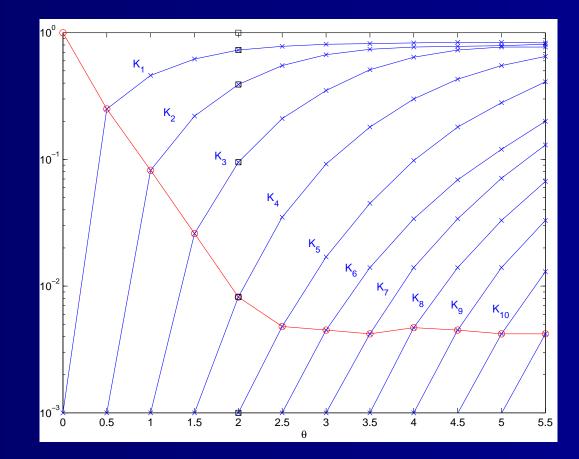
In most applications, the computational burden lies in the matrix–vector products and the scalar products required to solve this linear least squares problem.

In seed–GMRES, the subsequent right–hand sides benefit from this work. An effective initial guess $J^{(0)}(\varphi_{\ell}) = V_n^{(0)} y^{(\ell)}$ for the system ℓ is obtained by solving the same linear least squares problem but with another right–hand side, namely

$$\min_{J\in\mathcal{K}_0}\|F(\varphi_\ell)-\mathbb{Z}J\|_2.$$

The additional cost is n dot products and 2n zaxpy operations per right-hand sides.

The seed GMRES algorithm (2)



Norm of the residuals after each minimization on the Krylov spaces. The test example is the cobra 60695, $\theta = 0^{\circ} : 0.5^{\circ} : 5.5^{\circ}$.

The almond case

Starting the seed–GMRES method from the right–hand side $F(\theta = 0^{\circ})$, we obtain the following sequence for the number of iterations for the first 15 right–hand sides:

θ	0^{o}	0.5^{o}	1^o	1.5^{o}	2^{o}	2.5^{o}	3^o	3.5^{o}	4^{o}	4.5^{o}	5^{o}	5.5^{o}	6^{o}
# iter	11	7	5	3	3	3	3	2	3	3	2	3	2

The almond case

Starting the seed–GMRES method from the right–hand side $F(\theta = 0^{\circ})$, we obtain the following sequence for the number of iterations for the first 15 right-hand sides:

θ	0^{o}	0.5^{o}	1^o	1.5^{o}	2^{o}	2.5^{o}	3^o	3.5^{o}	4^{o}	4.5^{o}	5^{o}	5.5
# iter	11	7	5	3	3	3	3	2	3	3	2	3
We define	e the	transien	t phas	se by the	e seque	nce 11,	7 and 5	; the sta	tionnar	y phase	is the	
remaining	g whe	re the n	umbei	r of itera	ations do	pes not o	change	much. I	t is well	defined	by a	
plateau a	it a va	lue equa	al to th	ne avera	age num	ber of it	erations	s for the	right-h	and side	es	
solved in this stationnary phase. Finally we obtain the following model law:												
solved in		•			Ŭ				Ŭ			
solved in θ		•			Ŭ				Ŭ		5 ⁰	5.:
	this s	tationna	iry pha	ase. Fin	ally we	obtain tl	he follov	ving mo	del law:			5.ŧ 2.(
θ	this s 0 ⁰ 11	tationna 0.5 ⁰ 7	nry pha 1 ⁰ 5	ase. Fin 1.5 ⁰ 2.67	ally we 2 ^o 2.67	obtain tl 2.5 ⁰ 2.67	he follov 3 ⁰ 2.67	ving mo 3.5 ⁰ 2.67	del law: 4 ^o 2.67	4.5 ^o 2.67	5 ⁰	5.8 2.(

starting right–hand side $F(\theta)$.

Kernel operations

	zaxpy	zdscal	zcopy	zdot	precond	FMM	# proc.
Airbus 23676	0.0027	0.0026	0.0019	0.0024	0.27	1.83	4
Airbus 94704	0.0066	0.0063	0.0046	0.0051	0.80	4.61	8
Airbus 213084	0.0148	0.0142	0.0105	0.0106	1.78	11.13	8
sphere 40368	0.0044	0.0042	0.0030	0.0036	0.29	2.16	4
sphere 71148	0.0079	0.0059	0.0079	0.0061	0.54	3.84	4
sphere 161472	0.0131	0.0129	0.0093	0.0098	0.61	4.63	8
sphere 288300	0.0202	0.0194	0.0143	0.0140	1.09	8.25	8
cetaf 5391	0.0010	0.0001	0.0001	0.0013	0.13	0.25	4
cobra 60695	0.0045	0.0003	0.0004	0.0040	0.22	1.93	8
almond 104793	0.0082	0.0006	0.0007	0.0064	0.41	2.92	8

Elsapsed time for each basic operation needed by the iterative solvers.

Kernel operations

	100	100	100	100	precond	FMM	# proc.
	zaxpy	zdscal	zcopy	zdot	precond		
Airbus 23676	14.75	14.21	10.38	13.11	14.75	100	4
Airbus 94704	14.32	13.67	9.98	11.06	17.35	100	8
Airbus 213084	13.30	12.76	9.43	9.52	15.99	100	8
sphere 40368	20.37	19.44	13.89	16.67	13.42	100	4
sphere 71148	20.57	15.36	20.57	15.89	14.06	100	4
sphere 161472	28.29	27.86	20.09	21.17	13.17	100	8
sphere 288300	24.48	23.52	17.33	16.97	13.21	100	8
cetaf 5391	40.80	2.40	2.40	50.80	52.00	100	4
cobra 60695	23.47	1.66	2.18	20.89	11.40	100	8
almond 104793	28.05	1.89	2.47	21.99	14.04	100	8

Percentage of time required by 100 calls to each basic operations with respect to one call to the FMM

The cobra case

	default guess	strat. 2	seed–GMRES	
(heta,arphi)	<i>⋕</i> iter	# iter $ r_0 _2/ F _2$	# iter $\ r_0\ _2/\ b\ _2$	
# iterations	4102	2005	2819	
elapsed time (s)	15565.6	6765.6	9863.7	

The cobra case

rien ne sert de courir, il faut partir à point



Jean de la Fontaine.

Solving large linear systems with multiple right-hand sides - p. 111/12

Special feature RHS

The *j*-st entry of the right-hand side $F(\varphi)$ corresponding to a plane wave coming from the direction φ and wave number k on the object Γ is

$$F_j(\varphi) = \int_{\Gamma} e^{ikx \cdot \hat{u}_r(\varphi)} \hat{z} \cdot \vec{\Psi}_j(x) ds(x)$$

Seed–GMRES \neq SVD preprocess.

Linear dependency of RHS Lötstedt and Nilsson

('02)use initial guess strategy 2.b. : solve the least squares problem

$$\min_{\varphi \in \mathbb{R}^{\ell-1}} \|F(\varphi_\ell) - \sum_{j=0}^{\ell-1} F(\varphi_j) y_j\|_2,$$

then take the initial guess $J^{(0)}(\varphi_{\ell}) = \sum_{j=0}^{\ell-1} J(\varphi_j) y_j$. Seed GMRES

$$\min_{x \in \mathcal{K}_1} \|F(\varphi_\ell) - \mathbb{Z}x\|_2$$

Solving large linear systems with multiple right-hand sides - p. 113/12

Control of the error

# SVD	# it	E	# verif
15		2.285445132223185E-003	
16	299	9.430404985428857E-004	603
17	303	3.785604066482061E-004	243
18	316	1.416418780336473E-004	196
19	322	5.349504623890520E-005	184
20	334	1.892546027913748E-005	182
21	341	6.750489170848254E-006	181
22	350	2.264388221336797E-006	181

Cost of the SVD preprocessing

Size of the problem	Elapsed time SVD	Elapsed time GMRES	# procs
40368	1063	214	4
71148	1903	388	4
161472	2992	550	8
288300	4923	1649	8

Elapsed time to compute the SVD for 360 right-hand sides the sphere. For comparison,

we give the average elapsed time for the solution of one right-hand side using full

GMRES (assembly of the preconditioner phase not included). The backward error is set

to 10^{-2} for the GMRES solve.

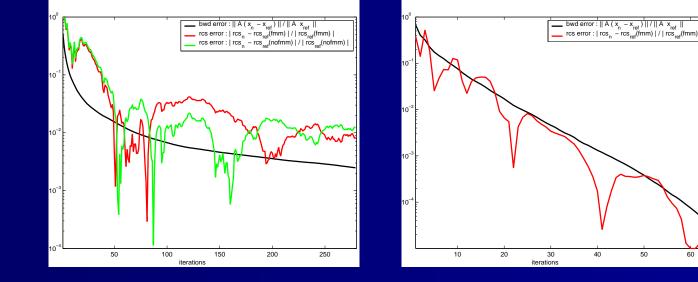
On the coated-cone-sphere

	# iterations	elapsed time (s)	
GMRES with second strategy initial guess	3797	29726	
seed–GMRES	784	10328	
seed–GMRES SVD(16)	632	10930	
block–GMRES SVD(19)	329	8894	
Four compatitive matheda on the costed cope ophere			

Four competitive methods on the coated cone sphere, $\theta = 0^o : 1^o : 180^o$.

Prospectives (3/4)

Toward an adapted stopping criterion



Airbus 23676

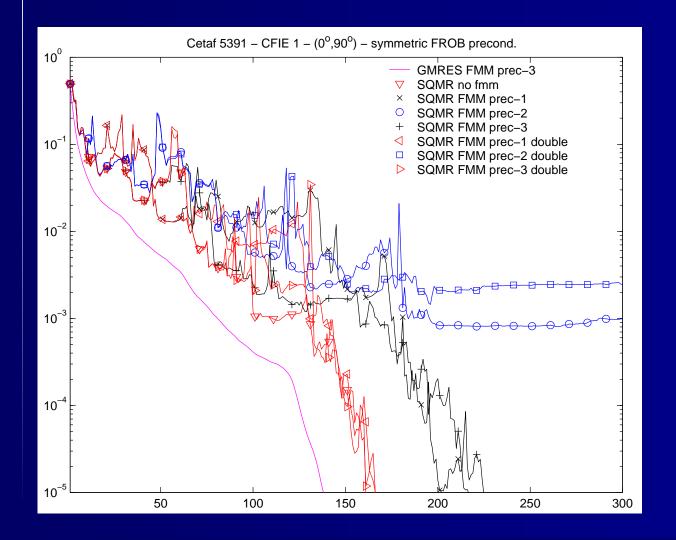
coated cone 77604

40

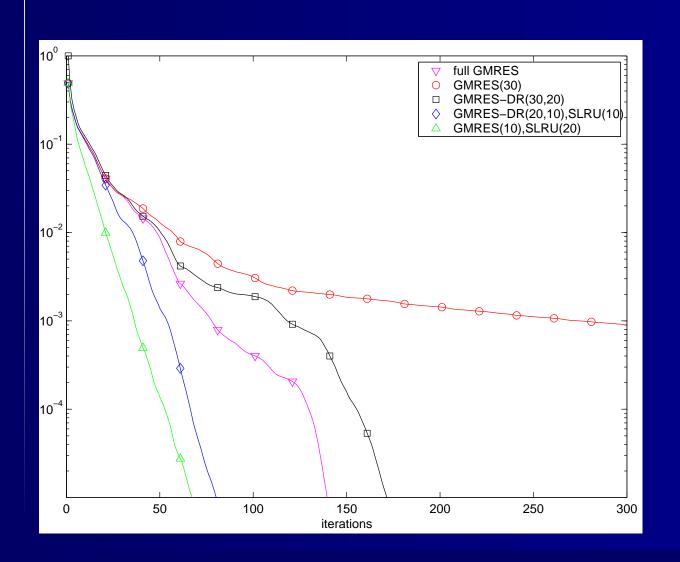
50

60

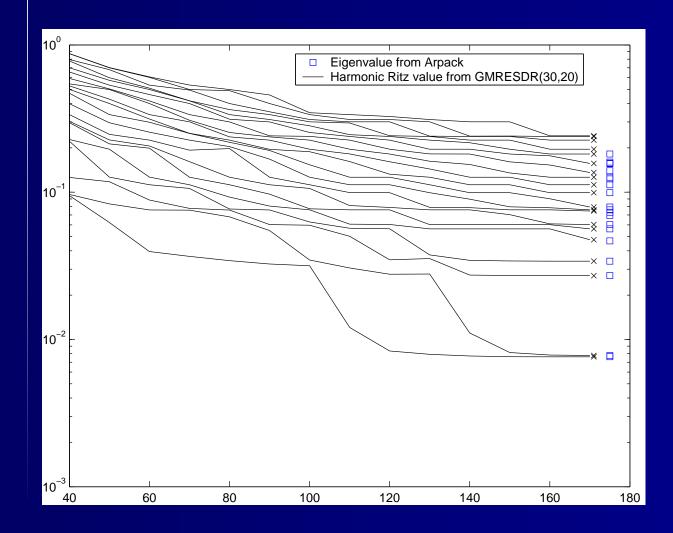
Prospectives (4/4)



GMRES-DR



GMRES-DR



GMRES-DR

