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A Logical Investigation of Interaction Systems Une investigation logique des systèmes d'interaction

Pierre Hyvernat

Insitut mathématique de Luminy Université Aix-Marseille 2

PhD Defense, December 12th 2005

Supervisors: Thierry Coquand (Chalmers Universitet, Göteborg, Sweden) Thomas Ehrhard (Institut mathématique de Luminy, Marseille, France)

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Part 0: Simple 0000	Part 1: More Precisely (Interaction Systems for Experts) 0000 000 000000	Part ∞ : and then?

Programs and proofs are complex things!



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Programs and proofs are complex things! We want to give a simpler "denotation" and proofs or programs.

(We can thus forget about syntactical details like the choice of programming language...)

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We use a notion of abstract games...

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Programs and proofs are complex things!

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(We can thus forget about syntactical details like the choice of programming language...) We use a notion of abstract games...

Games also give a computational interpretation to "topology"...

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Where are we?

Part 0: Simple Interaction Systems for everyone

Part 1: More Precisely (Interaction Systems for Experts) The category of Interaction Systems Interaction Systems and Topology Interaction and Predicate Transformers, Linear Logic

Part ∞ : and then? Achievements and Future Work

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Interaction Systems for every	one	
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Games "Interaction Systems"

We are interested in games between players with full information. (Like chess or Go and unlike soccer or Poker)

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Interaction Systems for everyone		
Games		

We are interested in games between players with full information. (Like chess or Go and unlike soccer or Poker)

the first player is called the Angel;

"Interaction Systems"

Part 0: Simple ●000	Part 1: More Precisely (Interaction Systems for Experts) 0000 000000	Part ∞ : and then?
Interaction Systems for everyone		
Games		

We are interested in games between players with full information. (Like chess or Go and unlike soccer or Poker)

- the first player is called the Angel;
- the second is called the Demon;

"Interaction Systems"

Part 0: Simple ●000	Part 1: More Precisely (Interaction Systems for Experts) 0000 0000000	Part ∞ : and then?
Interaction Systems for everyone		
Games		

We are interested in games between players with full information. (Like chess or Go and unlike soccer or Poker)

- the first player is called the Angel;
- the second is called the Demon;
- moves alternate: first the Angel, then the Demon etc.

"Interaction Systems"

Part 0: Simple ○●○○	Part 1: More Precisely (Interaction Systems for Experts) 0000 0000 000000	Part ∞ : and then?
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Some games are equivalent:



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Some games are equivalent:

all moves in the first games can be translated into moves in the second game; and vice and versa.

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Interaction Systems for everyon	e	

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More generally, we say that a game G_1 is easier than a game G_2 if:

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Interaction Systems for everyone	2	

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Part 0: Simple o●oo	Part 1: More Precisely (Interaction Systems for Experts) 0000 000 000000	Part ∞ : and then?
Interaction Systems for everyor	e	

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Part 0: Simple ⊙●○○	Part 1: More Precisely (Interaction Systems for Experts) 0000 000 000000	Part ∞ : and then?
Interaction Systems for everyone		

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Thus G_1 is easier for the Angel but more difficult for the Demon.

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Interaction Systems for everyon	2	

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Thus G_1 is easier for the Angel but more difficult for the Demon.

We write $G_1 \leq G_2$ and say " G_2 simulates G_1 ".

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Interaction Systems for everyone		
Examples of ga	ames	

► The game of Chess;



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Interaction Systems for eve	eryone	

Examples of games

- The game of Chess;
- ▶ game of "*Devinettes*":
 - the Angel asks the questions,
 - the Demon answers by YES or NO;

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Interaction Systems for e	veryone	

Examples of games

- The game of Chess;
- ▶ game of "*Devinettes*":
 - the Angel asks the questions,
 - the Demon answers by YES or NO;
- potential executions of a program:
 - the Angel is the user,
 - the Demon is the computer;

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Interaction Systems for ev	reryone	

Examples of games

- The game of Chess;
- ▶ game of "*Devinettes*":
 - the Angel asks the questions,
 - the Demon answers by YES or NO;
- potential executions of a program:
 - the Angel is the user,
 - the Demon is the computer;
- ▶ a specification for a sequential / interactive program.

This was the starting intuition... (cf. Peter Hancock)

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Safety Propert	ies	

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Safety Prop	erties	

... i.e. a set of "winning positions" for the Angel

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Interaction Systems for everyone		
Safety Prop	erties	

... *i.e.* a set of "winning positions" for the Angel:

from each winning position,

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Interaction Systems for everyone		
Safety Prop	erties	

... *i.e.* a set of "winning positions" for the Angel:

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Part 0: Simple 000●	Part 1: More Precisely (Interaction Systems for Experts) 0000 000 000000	Part ∞ : and then?
Interaction Systems for everyone		
Safety Proper	ties	

... *i.e.* a set of "winning positions" for the Angel:

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Interaction Systems for everyone		
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... *i.e.* a set of "winning positions" for the Angel:

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Interaction Systems for everyone		
Safety Properties		

... *i.e.* a set of "winning positions" for the Angel:

from each winning position, the Angel can find a smart move to always remain in a winning position no matter what the Demon plays...

(In particular, the Angel always has a move to play!)

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Part ∞ : and then? Achievements and Future Work

Part 1: More Precisely (Interaction Systems for Experts) •OOO •OOO •OOO Part ∞ : and then? 000

The category of Interaction Systems

Objects: Interaction Systems

Definition An interaction system *w* is given by the following:

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Part 1: More Precisely (Interaction Systems for Experts) •OOO •OOO •OOO Part ∞ : and then? 000

The category of Interaction Systems

Objects: Interaction Systems

Definition

An interaction system *w* is given by the following:

► a set *S* of states;

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Part 1: More Precisely (Interaction Systems for Experts) •OOO •OOO •OOO Part $\infty :$ and then? 000

The category of Interaction Systems

Objects: Interaction Systems

Definition

An interaction system w is given by the following:

- a set S of states;
- for each state $s \in S$, a set A(s) of actions;

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The category of Interaction Systems

Objects: Interaction Systems

Definition

An interaction system w is given by the following:

- a set S of states;
- for each state $s \in S$, a set A(s) of actions;
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The category of Interaction Systems

Objects: Interaction Systems

Definition

An interaction system w is given by the following:

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- for each state $s \in S$, a set A(s) of actions;
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- ▶ for each reaction $d \in D(s, a)$, a new state $n(s, a, d) \in S$.

The category of Interaction Systems

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An interaction system w is given by the following:

- a set S of states;
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- ▶ for each reaction $d \in D(s, a)$, a new state $n(s, a, d) \in S$.

(Equivalently, an interaction system is a coalgebra for the monad \mathcal{F}^2 of "doubly iterated families" over the category **Set**.)

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The category of Interaction Systems

Morphisms: Simulations

Definition

If w_1 and w_2 are interaction systems,

a relation $R \subseteq S_1 \times S_2$ is a simulation from w_1 to w_2 iff

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The category of Interaction Systems

Morphisms: Simulations

Definition

If w_1 and w_2 are interaction systems,

a relation $R \subseteq S_1 \times S_2$ is a simulation from w_1 to w_2 iff

$$(s_1, s_2) \in R \Rightarrow \forall a_1 \in A_1(s_1) \\ \exists a_2 \in A_2(s_2)$$

 $(n_1(s_1, a_1), n_2(s_2, a_2)) \in R$

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The category of Interaction Systems

Morphisms: Simulations

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If w_1 and w_2 are interaction systems,

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$$\begin{array}{ll} (s_1, s_2) \in R \Rightarrow & \forall a_1 \in A_1(s_1) \\ & \exists a_2 \in A_2(s_2) \\ & \forall d_2 \in D_2(s_2, a_2) \\ & \exists d_1 \in D_1(s_1, a_1) \\ & & \left(n_1(s_1, a_1, d_1), n_2(s_2, a_2, d_2) \right) \in R \end{array}$$

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The category of Interaction Systems

Morphisms: Simulations

Definition

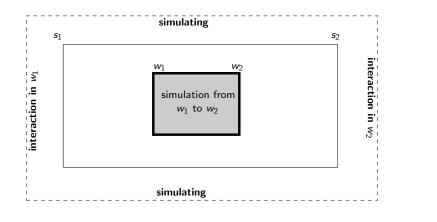
If w_1 and w_2 are interaction systems, a relation $P \subset S_1 \times S_2$ is a simulation from w_1 t

a relation $R \subseteq S_1 \times S_2$ is a simulation from w_1 to w_2 iff

$$\begin{array}{ll} (s_1, s_2) \in R \Rightarrow & \forall a_1 \in A_1(s_1) \\ & \exists a_2 \in A_2(s_2) \\ & \forall d_2 \in D_2(s_2, a_2) \\ & \exists d_1 \in D_1(s_1, a_1) \\ & & \left(n_1(s_1, a_1, d_1), n_2(s_2, a_2, d_2) \right) \in R \end{array}$$

(This is not a morphism of coalgebras...)

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The category of Interact	ion Systems	



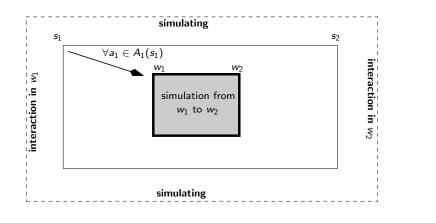
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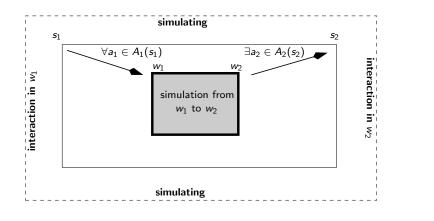
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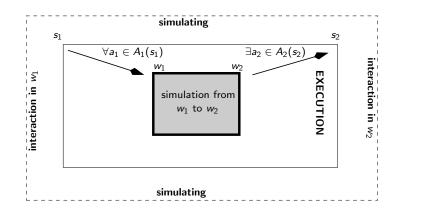
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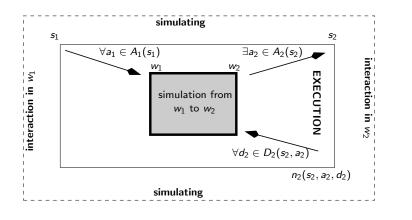
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The category of Interaction Systems

Simulation, Visually



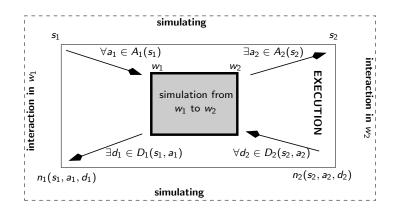
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The category of Interaction Systems

Simulation, Visually



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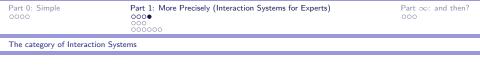
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The category of Interaction S	ystems	
Composition		

To compose two simulations from w_1 to w_2 and from w_2 to w_3 use the relational composition:

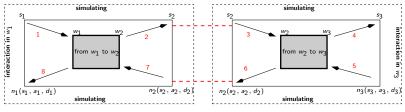
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Composition

To compose two simulations from w_1 to w_2 and from w_2 to w_3use the relational composition:



⁽flow of interaction)

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Part 1: More Precisely (Interaction Systems for Experts) ${}^{\circ\circ\circ\circ}_{\bullet\circ\circ}$

Part $\infty :$ and then? 000

Interaction Systems and Topology

Reflexive and Transitive Closure

Definition There is a functorial operation $w \mapsto w^*$

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Reflexive and Transitive Closure

Definition

There is a functorial operation $w \mapsto w^*$ s.t.

• an Angel action in w^* is a strategy to play several times in w;

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Reflexive and Transitive Closure

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There is a functorial operation $w \mapsto w^*$ s.t.

- > an Angel action in w^* is a strategy to play several times in w;
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Reflexive and Transitive Closure

Definition

There is a functorial operation $w \mapsto w^*$ s.t.

- > an Angel action in w^* is a strategy to play several times in w;
- a Demon reaction is a sequence of responses.

This operation satisfies w^* is "least" s.t. $w^* \simeq \text{skip} \cup w$; w^* ,

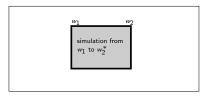
where w_1 ; w_2 is the game

"one move in w_1 and then one move in w_2 ."

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Programming Interpretation

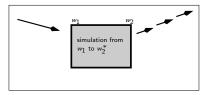
- A simulation from w_1 to w_2^* is a relation R s.t. if $(s_1, s_2) \in R$:
 - for every action from s_1 , there is a "list" of actions from s_2 ;
 - s.t. for any "list" of reactions, there is a reaction;
 - s.t. the simulation can be sustained from the new states.



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Programming Interpretation

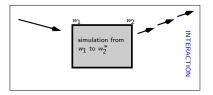
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Programming Interpretation

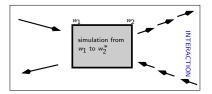
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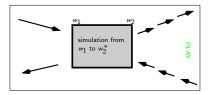
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Programming Interpretation

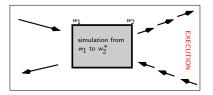
- A simulation from w_1 to w_2^* is a relation R s.t. if $(s_1, s_2) \in R$:
 - for every move from s_1 , there is a strategy from s_2 ;
 - s.t. for any counter-strategy, there is a counter-move;
 - s.t. the simulation can be sustained from the new states.



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Programming Interpretation

- for every command from s_1 , there is a program from s_2 ;
- s.t. for any sequence of responses, there is a response;
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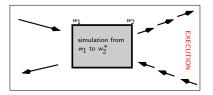


Part 0:	Simple
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Programming Interpretation

A simulation from w_1 to w_2^* is a relation R s.t. if $(s_1, s_2) \in R$:

- for every command from s_1 , there is a program from s_2 ;
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This is just a program implementing w_1 in terms of w_2 !

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Interaction Systems and Top	ology	

► *S* is a basis for a topological space;



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Interaction Systems and Topo	logy	

- ► *S* is a basis for a topological space;
- A(s) corresponds to the atomic covering of the basic open s;

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Interaction Systems and Topolog	5y	

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- n(s, a, d) is the basic open corresponding to index d.

(This bears similarities with Grothendieck topologies.)

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Theorem

There is a full and faithful functor from **Ref**^{op} to **BTop**.

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There is a full and faithful functor from Ref^{op} to BTop.

i.e. a simulation from w_1 to w_2^* ...

... is exactly a continuous function from w_2 to w_1 .

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Advantages of interaction systems:

very concrete (cf. link with programming);

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- adequate to model "predicative" topology.

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Advantages of interaction systems:

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Advantages of interaction systems:

- very concrete (cf. link with programming);
- simple computational content;
- adequate to model "predicative" topology.

Drawbacks of interaction systems:

- very concrete;
- too simple (?!) computational content;
- some simple operations look complicated.

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Predicate Transformers

In a classical setting, we simplify the structure:



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Predicate Transformers

In a classical setting, we simplify the structure: to any interaction system w we associate

$$\begin{array}{rcccc} w^{\circ} & : & \mathcal{P}(S) & \to & \mathcal{P}(S) \\ & & U & \mapsto & \left\{ s \mid (\exists a)(\forall d) \, n(s,a,d) \in U \right\} \end{array}$$

i.e. $s \in w^{\circ}(U)$ iff "the Angel can reach U from s in exactly one interaction".

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In a classical setting, we simplify the structure: to any interaction system w we associate

$$w^{\circ}$$
 : $\mathcal{P}(S) \rightarrow \mathcal{P}(S)$
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Theorem

We have that R is a simulation from w_1 to w_2 iff

$$R \cdot w_1^\circ \subseteq w_2^\circ \cdot R$$

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This defines an equivalence of categories $PT \simeq Sim!$

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For
$$P_1 : \mathcal{P}(S_1) \to \mathcal{P}(S_1)$$
 and $P_2 : \mathcal{P}(S_2) \to \mathcal{P}(S_2)$:

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$$P_1 : \mathcal{P}(S_1) \to \mathcal{P}(S_1)$$
 and $P_2 : \mathcal{P}(S_2) \to \mathcal{P}(S_2)$:
 $P_1^{\perp} : \mathcal{P}(S_1) \to \mathcal{P}(S_1)$

(In particular involutivity of $_^{\perp}$ is trivial.)

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 $x \mapsto \overline{P_1(\overline{x})}$

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$$P_1 : \mathcal{P}(S_1) \to \mathcal{P}(S_1)$$
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 $P_1^{\perp} : \mathcal{P}(S_1) \to \mathcal{P}(S_1)$ $P_1 \otimes P_2 : \mathcal{P}(S_1 \times S_2) \to \mathcal{P}(S_1 \times S_2)$
 $x \mapsto \overline{P_1(\overline{x})}$

(In particular involutivity of $_^{\perp}$ is trivial.)

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 $x \mapsto \overline{P_1(\overline{x})}$ $r \mapsto \bigcup_{x_1 \times x_2 \subseteq r} P_1(x_1) \times P_2(x_2)$

(In particular involutivity of $_^{\perp}$ is trivial.)

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 $x \mapsto \overline{P_1(\overline{x})}$ $r \mapsto \bigcup_{x_1 \times x_2 \subseteq r} P_1(x_1) \times P_2(x_2)$

This gives a self-dual symmetric monoidal category. (In particular involutivity of $_^{\perp}$ is trivial.)

Those correspond to concrete operations on interaction systems...

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Monoidal closure

We can extend this to a self-dual monoidal closed category.



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Monoidal closure

We can extend this to a self-dual monoidal closed category.

The adjoint to \otimes is given by

$$P_1 \multimap P_2 : \mathcal{P}(S_1 \times S_2) \to \mathcal{P}(S_1 \times S_2)$$

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with

$$(s_1, s_2) \in (P_1 \multimap P_2)(r)$$

iff
 $(\forall x_1 \subseteq S_1) s_1 \in P_1(x_1) \Rightarrow s_2 \in P_2(r(x_1))$

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Linear Logic

With an appropriate construction

$$!P: \mathcal{P}(\mathcal{M}_f(S)) \to \mathcal{P}(\mathcal{M}_f(S))$$

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Linear Logic

With an appropriate construction

$$!P: \mathcal{P}(\mathcal{M}_f(S)) \to \mathcal{P}(\mathcal{M}_f(S))$$

we can interpret all of linear logic or typed λ -calculus.

(This corresponds to the construction of the free \otimes -comonoid...)

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A proof/term becomes a safety property,

i.e. a subset $x \subseteq S$ s.t. $x \subseteq P(x)$.

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Differential λ -calculus has an intrinsic notion of

- non-determinism (addition);
- Inear substitution (differentiation).

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Differential λ -calculus has an intrinsic notion of

- non-determinism (addition);
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Traditional models do not model those new features!

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Safety properties are closed under arbitrary union,

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Differential λ -calculus has an intrinsic notion of

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Safety properties are closed under arbitrary union, we can thus interpret non-determinism

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Safety properties are closed under arbitrary union, we can thus interpret non-determinism and even differentiation.

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Differential λ -calculus has an intrinsic notion of

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Safety properties are closed under arbitrary union, we can thus interpret non-determinism and even differentiation.

We get a simple, non-trivial model for the differential λ -calculus!

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Where are we?

Part 0: Simple Interaction Systems for everyone

Part 1: More Precisely (Interaction Systems for Experts) The category of Interaction Systems Interaction Systems and Topology Interaction and Predicate Transformers, Linear Logic

Part ∞ : and then? Achievements and Future Work

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Achievements and Future Work		

Achievements

- a new category of games and simulations;
- ▶ an intuitive/informal model for "real-life" programming;
- giving a computational interpretation of "basic topologies";
- concrete example of interaction system to give a (complete) topological semantics to "linear geometric theories";
- this category is a denotational model for full linear logic;
- and the differential (typed) λ -calculus;
- which can extended to second order.

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Future Work		

link the topology part and the linear logic part;

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Future Work		

- Ink the topology part and the linear logic part;
- \blacktriangleright study the model of differential λ -calculus in more details;

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Future Work		

- Ink the topology part and the linear logic part;
- **>** study the model of differential λ -calculus in more details;
- b do we have denotational completeness?

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Achievements and Future Work		
Future Work		

- Ink the topology part and the linear logic part;
- study the model of differential λ -calculus in more details;
- do we have denotational completeness?
- Study in particular untyped differential λ-calculus;

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Achievements and Future Work		
Future Work		

- link the topology part and the linear logic part;
- study the model of differential λ -calculus in more details;
- do we have denotational completeness?
- Study in particular untyped differential λ -calculus;
- do we get a model of Lionel Vaux's differential $\lambda \mu$ -calculus?

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Future Work		

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- do we have denotational completeness?
- Study in particular untyped differential λ -calculus;
- do we get a model of Lionel Vaux's differential $\lambda \mu$ -calculus?
- generalize in the spirit of "containers";

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Future Work		

- link the topology part and the linear logic part;
- study the model of differential λ -calculus in more details;
- do we have denotational completeness?
- Study in particular untyped differential λ-calculus;
- do we get a model of Lionel Vaux's differential $\lambda \mu$ -calculus?
- generalize in the spirit of "containers";
- study concrete example of interfaces.

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Et voilà !

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