

Modélisation de l'expression génétique bactérienne dans un pi-calcul stochastique à objets concurrents

Céline Kuttler

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Université des Sciences et Technologies de Lille

Thèse de doctorat en informatique préparée au Laboratoire d'informatique fondamentale de Lille

presentée par Céline KUTTLER

Modélisation de l'expression génétique bactérienne dans un pi-calcul stochastique à objets concurrents

Soutenance le 24 janvier 2007 devant le jury composé de:

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Résumé

La biologie systémique cherche à comprendre la dynamique cellulaire qui émerge des interactions des constituantes cellulaires au cours du temps. La modélisation et la simulation sont des méthodes fondamentales de ce domaine.

Nous nous inspirons de la proposition de Regev et Shapiro (2002) consistant à appliquer le pi-calcul stochastique comme langage formel de représentation de connaissances biomoléculaires. Nos études portent sur la modélisation à l'échelle moléculaire de l'expression génétique bactérienne et s'avèrent pertinentes pour des organismes supérieurs. Nos points de départs sont des études de cas concrets de la régulation de la bascule génétique du phage lambda, de la transcription et de la traduction. Ces études révèlent l'utilité de concepts de programmation tels que les objets concurrents et motivent une extension du pi-calcul stochastique avec des motifs de réception. Nous présentons une sémantique pour ce langage qui attribue des chaînes Markoviennes en temps continu aux programmes. Nous validons nos modèles par des simulations stochastiques.

Résumé long

La biologie systémique cherche à comprendre la dynamique cellulaire qui émerge des interactions des constituants cellulaires au cours du temps. La modélisation et la simulation sont des méthodes fondamentales de ce domaine. Idéalement, les modèles informels peuvent être affinés en modèles formels, permettant ainsi leur simulation. Ceci permet de valider la cohérence des connaissances que le modèle intègre, d'obtenir des prédictions, et éventuellement d'approfondir la compréhension du comportement cellulaire.

Dans cette thèse, nous étudions la modélisation et la simulation de l'expression génétique. Nous nous concentrons sur l'étude des bactéries, qui ont été l'objet de recherches approfondies au cours des dernières decénnies en biologie. La modélisation des systèmes d'expression génétique bactérienne s'en trouve d'autant facilitée au niveau de précision nécessaire à la simulation. Quoique plus simples, les phénomènes associés à l'expression génétique bactérienne sont également pertinents pour l'étude d'organismes supérieurs.

Nous nous inspirons de la proposition de Regev et Shapiro (2002) consistant à appliquer le π -calcul stochastique comme langage formel de représentation de connaissances biomoléculaires. Le π -calcul est un langage fondamental pour décrire le comportement dynamique d'acteurs concurrents en interaction. Suivant la métaphore chimique, les acteurs sont des molécules et les interactions des réactions chimiques. Milner, Parrow et Walker (1992) ont conçu les opérateurs du π -calcul afin d'être fortement expressifs, quoique abstraits et minimalistes. La sémantique stochastique du π -calcul par Priami (1995) ajoute une notion de vitesse de réaction, déterminant les distributions des instants de réactions au cours du temps.

Cette thèse a pour amorce des d'études de modélisation de cas concrets. Celles-ci nous mènent à considérer des concepts de programmation tels que les objets concurrents, motivant une extension de notre langage de modélisation : le π -calcul.

Etude de modélisation de la bascule du phage lambda. Nous étudions la régulation transcriptionelle de la bascule du phage lambda (Ptashne, 2004). Depuis des décennies, cet exemple bactérien prototype reste central au déchiffrement des principes de la régulation génétique. La régulation transcriptionelle est un phénomène clé.

Les modèles quantitatifs précédents du contrôle de la transcription de la bascule du phage lambda reposent majoritairement sur l'analyse de Shea et Ackers (1985). Les approches de ce type mènent à des prédictions exactes de l'évolution temporelle à l'échelle de populations bactériennes. Néanmoins, elles laissent de côté les interactions individuelles entre molécules, interac-

tions qui déterminent la dynamique du contrôle de la transcription pour un gène unique. Par conséquent, elles ne peuvent prédire la dynamique de la population moléculaire au sein d'une unique cellule bactérienne.

Les techniques expérimentales pour l'évaluation quantitative de l'expression génétique de cellules individuelles ont considérablement progressé ces dernières années. De nouvelles données expérimentales suggèrent la réflexion par de nouvelles études de modélisation et simulation, et tenant compte des interactions précises entre molécules individuelles, permettant ainsi de prédire leur dynamique. Notre étude de l'initiation de la transcription de la bascule du phage lambda représente un premier modèle de ce type, et permet des simulations correspondantes.

Outre l'identification des acteurs et de leurs interactions précises dans la littérature, l'une des difficultés de ce travail est la quantification stochastique précise de toutes les réactions.

Langage et concepts de modélisation. Nous considérons le contrôle de l'initiation de la transcription de la bascule du phage lambda au niveau moléculaire en tant que contrôle concurrent dans le π -calcul stochastique. Des sémaphores correspondent à des sites opératoires de l'ADN, auxquels précisément une protéine peut être liée, en exclusion mutuelle de l'accès de l'ARN polymérase aux promoteurs chevauchants. Nous montrons comment formuler le renforcement coopératif du taux de réactions chimiques en tant que modulation de taux de fonctions dans le π -calcul.

La transcription et la traduction procèdent itérativement le long des macromolécules linéaires d'ADN et d'ARNm, qui sont considérés commes listes. Il est possible de modéliser les éléments de telles listes comme des objets concurrents, afin que l'héritage entre objets permette de déduire des modèles d'ADN et d'ARNm d'un modèle commun de liste élémentaire.

Néanmoins, le π -calcul stochastique ne facilite guère l'expression de tels objets concurrents. Vasconcelos *et al.* (1993) résolvent ce problème pour le π -calcul asynchrone — qui sous-tend le langage de programmation distribué TyCO— en proposant une extension avec des motifs de réception.

Dans cette thèse, nous présentons une extension du π -calcul stochastique avec des motifs de réception, permettant d'exprimer des objets concurrents et qui s'avère utile en tant que langage de modélisation pour la biologie systémique. En sus d'introduire et motiver l'usage des motifs de réception pour le π -calcul stochastique, une difficulté de ce travail réside dans la définition d'une sémantique stochastique en termes de chaînes Markoviennes en temps continu. L'algorithme de Gillespie (1976) spécifie l'exécution de telles chaînes de Markov, c'est à dire montre comment calculer des traces

de simulation à partir de programmes en π -calcul stochastique. Nous montrons comment encoder les motifs de réception dans le π -calcul considéré sans ces dernières, et prouvons que cette opération préserve la sémantique stochastique.

Simulation stochastique. Nous faisons usage du système BioSpi afin d'implanter et d'exécuter nos modèles dans le π -calcul stochastique sans motifs de réception. Ceci est possible grâce à notre codage. Nous menons des simulations stochastiques exhaustives du système contrôlant la bascule du phage λ , ainsi que de la transcription et traduction bactrérienne. Nos résultats sont en accord quantitatif avec les connaissances expérimentales, ce qui souligne la pertinence de notre approche.

University of Lille 1

Thesis submitted for a doctoral degree in Computer Science

Céline Kuttler

Modeling Bacterial Gene Expression in a Stochastic Pi-Calculus with Concurrent Objects

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Abstract

Systems biology seeks to understand the cellular-level dynamics arising from the interaction of cellular constituents over time. Modeling and simulation are essential techniques of the field. We follow Regev and Shapiro (2002) in using the stochastic pi-calculus as a formal representation language for biomolecular knowledge. We elaborate molecular level modeling studies for bacterial gene expression, which is relevant to higher organisms as well. Our starting point are concrete case studies on regulation at the lambda switch, transcription and translation. These reveal the usefulness of programming concepts such as concurrent objects, and motivate an extension of the stochastic pi-calculus with input patterns. We present a semantics for this language that maps programs to continuous time Markov chains. We validate our models through exhaustive stochastic simulation.

Extended abstract

Systems biology seeks to understand the cellular-level dynamics arising from the interaction of cellular constituents over time. Modeling and simulation are essential techniques of the field. Ideally, informal models can be refined into formal models, that can be executed to yield simulations, which allow to validate the coherence of the knowledge incorporated in the model, obtain predictions, and eventually deepen the understanding of the cell's behavior.

In this thesis, we study the modeling and simulation of gene expression. We restrict ourselves to bacteria, since these have been investigated more thoroughly over the last decades from the biological perspective. This facilitates modeling of systems of bacterial gene expression at the necessary precision for simulation. Even though simpler, the phenomena arising in bacterial gene regulation are relevant to higher organisms as well.

We follow the approach of Regev and Shapiro (2002) in using the stochastic π -calculus as a formal modeling language for biomolecular knowledge. The π -calculus is a fundamental language for the investigation of the behavior of concurrent actors, and the dynamics of their interactions. In the chemical metaphor, actors can be molecules and interactions chemical reactions. Milner, Parrow, and Walker (1992) designed the operators of the π -calculus to be highly expressive, even though abstract and minimalistic. The stochastic semantics of the π -calculus by Priami (1995) adds a notion of reaction speed, determining the temporal distribution of reaction time points.

In this thesis project, we start with concrete modeling case studies. This leads us to programming concepts such as concurrent objects, that motivate extensions of the stochastic π -calculus, our modeling language.

Lambda switch modeling study. We study transcriptional regulation at the λ switch (Ptashne, 2004). This prototypical bacterial example has for decades remained central to unraveling the principles of gene expression. Transcriptional regulation is a key aspect.

Previous quantitative models of transcription control at the λ switch are based on Shea and Ackers (1985). This class of approaches yields accurate predictions of the temporal evolution at the level of bacterial populations. They however disregard interactions between individual molecules, which determine the temporal dynamics of transcription control from a single gene. As a consequence, they lack the ability to predict the dynamic evolution of the molecular population within an individual bacterial cell.

In recent years, the experimental techniques for quantitative assessment of gene expression in single cells considerably advanced. New experimental results stimulate reflection by new modeling and simulation studies, taking into account the precise interactions of individual molecules, so that their temporal dynamics can be predicted. Our case study on transcription initiation at the lambda switch provides a first such model and the corresponding simulations. Besides distilling the actors and their interactions from the literature, the most demanding aspect consists in the accurate stochastic quantification of all reactions.

Modeling language and concepts. We capture the molecular-level control of transcription initiation at the λ switch as concurrent control in the stochastic π -calculus. Semaphores correspond to operator sites on DNA, where precisely one protein may bind, in mutual exclusion with RNAP's access to overlapping promoters. We show how to express cooperative enhancement of chemical reaction rates as modulation of function rates in the π -calculus.

Transcription and translation consist in iterated processing of the linear macromolecules DNA and mRNA, which can be seen as lists. It is convenient to model the elements of such lists as concurrent objects, so that object inheritance permits to infer models of DNA and mRNA from a common basic list model. Unfortunately however, it is not easy to express concurrent objects in the stochastic π -calculus. Vasconcelos and Tokoro (1993) solve this problem for the asynchronous π -calculus underlying the distributed programming language TyCO by proposing an extension by input patterns.

In this thesis, we present an extension of the stochastic π -calculus by input patterns so that it can express concurrent objects, and use it as modeling language for systems biology. Besides discovering the usefulness of input patterns for the synchronous π -calculus, the difficult part is to define a stochastic semantics in terms of continuous time Markov chains. The algorithm of Gillespie (1976) specifies the execution of such Markov chains, i.e. how to compute simulation traces for programs of the stochastic π -calculus. We show how to encode input patterns in the π -calculus without input patterns, and prove that the stochastic semantics is preserved.

Stochastic simulation. We use the BioSpi system for implementing and executing our models in the stochastic π -calculus with input patterns. This becomes possible due to our above encoding of input patterns. We conduct exhaustive simulations of both the λ switch control system, and transcription and translation. Our results are in quantitative agreement with experimental knowledge, and thus supports the appropriateness of the approach.

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CHAPTER 1

Introduction

The young field of systems biology seeks to aid the quantitative understanding of cellular biology. The term was coined by Ideker et al. (2001) and is meanwhile well established. Systems biology complements research in the established area of molecular biology, which through wet-lab experimentation yields detailed descriptions of biomolecules and their interactions in living cells (Alberts et al., 2002; Lodish, 2003). Systems biology aims to contribute to better understanding of the overall dynamics of living matter, that arises from the interaction of many components, and is only partially understood.

Modeling and simulation is an important branch of systems biology, and the domain to which this thesis subscribes. It is concerned with the formal modeling of the behavior of cellular systems, in terms of quantities and time. Such models should be executable, so that they yield simulations by which to validate the coherence of the integrated knowledge, and eventually predict the system's behavior, and its response to perturbations. A complementary branch of systems biology deals with the systematic acquisition of biological data through techniques that are high-throughput, quantitative, and large-scale. While these reveal less detail than more traditional manual experimentation, they enable rapid knowledge discovery.

Gene expression is the biological phenomenon addressed in this thesis

¹Systems biology is presented in recent textbooks by Alon (2006) and Palsson (2006), and article collections of Szallasi et al. (2006), Kitano (2001), and Bower and Bolouri (2001), where the latter not yet adopts this term.

(Lewin, 2003). Gene expression is the sophisticated multi-step transformation of hereditary information, statically encoded in DNA, into those biomolecules that carry out the cell's vital functions: proteins. Many aspects of the exploitation of genetic material remain intricate to elucidate. Numerous interdependent components contribute to gene expression, and virtually any intermediate of the activities they perform can be modulated. The dynamics arising from this control or regulation of gene expression (Davidson, 2006; Ptashne and Gann, 2002) rapidly surpasses intuitive understanding.

Bacteria play a fundamental role in biological research (Trun and Trempy, 2003). The knowledge gained through the study of bacterial systems often yields insights relevant to other kinds of cells, which refine and complement the observed mechanisms. This namely holds for gene expression and regulation. Their central mechanisms were discovered within the bacterium Escherichia coli (Jacob and Monod, 1961), and their principles understood through two prototypical systems: the lac operon and the λ switch (Müller-Hill, 1996; Ptashne, 2004). Gene regulation at this latter has for decades remained a fruitful research field (Gottesman, 1999), and keeps providing important new insights (Gottesman and Weisberg, 2004; Dodd et al., 2005; Oppenheim et al., 2005). The λ switch frequently serves for benchmarking simulation methods (Hasty et al., 2001).

Regev and Shapiro (2002) suggested to abstract biomolecular knowledge in terms of concurrent computation in the π -calculus of Milner, Parrow, and Walker (1992), and base quantitative simulations on it. For the purpose of simulation, Priami, Regev, Shapiro, and Silverman (2001) adapted the stochastic variant of the π -calculus of Priami (1995) to the well-established simulation algorithm of Gillespie (1976). This latter accurately gives rise to the temporal and quantitative dynamics of biochemical systems at the level of molecular interactions.

This proposal raised numerous questions. While cellular networks were shaped by evolution and exhibit properties whose origins are difficult to unravel, the situation in engineering is complementary. Complex computational systems are incrementally assembled from fully specified components in order to reach specific goals. Methodologies and strategies play an important role in the design of software systems. The π -calculus however does not ease systematic and structured model creation. Its means of expression are indeed restrained to the very essence of concurrent computation, for the sake of semantic precision. It should be considered as an assembler or machine code, as opposed to higher languages with built-in support for actual programing techniques. From a methodological perspective, this thesis seeks to remedy drawbacks in the development, understanding, extension and sharing of biological models based on the π -calculus approach.

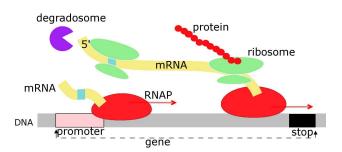


Figure 1.1: Overview of bacterial gene expression: decoding genes into proteins

1.1 Bacterial gene expression

Diverse activities co-exist in living cells. They ensure its vital functions, response to changes in the environment, allow the cell to fulfill its role in multicellular organisms, and transmit its hereditary material from one generation to the next.

Gene expression is a major cellular activity. Figure 1.1 sketches this transfer of hereditary information from the sequence encoded in the macromolecule DNA (grey strip) via mRNA (yellow strip) to proteins. Numerous enzymes contribute. In the first step of gene expression, RNA polymerase (short: RNAP²) locates a promoter site on DNA, which indicates the start of a gene. Several RNAP may proceed along the same gene at the same time, all transcribing the DNA nucleotide sequence into mRNA. While transcription continues, the mRNA becomes accessible to ribosomes that bind at a dedicated start site (blue), in order to build proteins from its information content. This is called translation. More of it can start as long as the degradosome has not yet accessed the mRNA's 5' end in order to degrade the transcript.

Summarizing, our overview of gene expression illustrated first aspects of coordination, competition, and simultaneity between the various actors. These soon give rise to intricate dependencies.

Regulation of gene expression. Cells use their genetic material to produce appropriate quantities of products at the right time. The principles of regulation were understood in bacterial systems (Müller-Hill, 1996; Ptashne, 2004), which still offer many insights. Gene expression is controlled within all phases, it is most effective however to regulate it early – before transcription starts. Many discrete molecular events contribute to this control of transcription.

²RNAP polymerizes RNA, hence its name

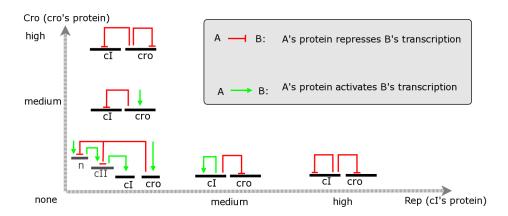


Figure 1.2: The regulatory patterns between the λ switch genes cI and cro reflect the available protein amounts

scription initiation that occurs at promoters, i.e. the DNA areas marking the start of a gene, colored in pink in Figure 1.1. Proteins find operator sites on DNA, that are located within or in the vicinity of promoters. They bind there, stick for a while (from seconds to hours), and eventually fall off. By their presence, they affect RNAP's interaction with the promoter.

The repertoire of molecular mechanisms for repression and activation of transcription initiation through DNA binding proteins is well identified in bacteria. In the simplest case, transcription is repressed by protein binding to an operator within the promoter. This excludes RNAP from promoter access; see Figure 1.6 on page 15. Activation conversely occurs through operator binding nearby, but outside the promoter. In this case the protein is beneficial to interactions between RNAP and the promoter, i.e. stability of binding and transcription initiation. Both activation and repression in bacteria necessitate only a couple of regulatory proteins, while in higher organisms several dozens are involved. In this thesis, we investigate fundamental mechanisms of repression and activation in bacteria, at the example of two promoters at the λ switch.

Regulatory patterns depend on protein quantities. Transcriptional regulation in bacteria relies on only few components, the interaction between these nonetheless soon challenges intuitive understanding. Consider the genes cI and cro, which determine the activity of the virus λ in an infected bacterial cell. These two genes are self-regulating as well as mutually regulating through the activity of their proteins, Rep and Cro.

The promoters of cI and cro are adjacent on DNA. They are controlled

by the same three DNA operators sites – yet in significantly different manners. Each combination of operator, Cro and Rep binding has a different specificity. All bindings are reversible, but higher specificity means that the binding is tighter, hence that the protein spends more time on the operator, before falling off. Note that higher specificity implies that fewer proteins are necessary to keep the operator filled. Depending on their position on DNA, the regulatory proteins influence interactions between RNAP and either promoter differently.

We visualize the regulatory influences at the λ switch in a diagrammatic notation in Figure 1.2. Directed arrows from A to B represent the regulatory influence of gene A's protein on the transcription of gene B. The arrowhead's shapes indicate whether the influence is repressive (T), or activating (triangle). Genes are represented as black horizontal bars. Note that arrows can point from one gene to itself, as well as to another. Arrows starting in the void indicate a gene's default activation status, in the absence of a regulatory signal.

If neither Cro nor Rep are available, transcription of the cro gene ensues; while in the same setting cI's transcription depends on the protein products of the genes cII and N. If cro wins, new λ viruses kill the host cell after a while. Otherwise, the bacterium is immunized. Once available, Rep proteins rapidly shut off cro's promoter, and up to intermediary concentrations activate transcription from their own promoter cI. At high concentrations, Rep represses its own promoter. In the absence of Rep, Cro proteins repress transcription from cI's promoter. Once many Cro proteins are available, they also repress their own expression.

Observing gene expression in real time. We report recent quantitative assessment of the temporal dynamics of gene expression in a single cell, that are of interest to the modeling work in this thesis.

Abbondanzieri et al. (2005) provide evidence that transcribing RNAP advances over the coding region of DNA in discrete steps of a length equivalent to that of a single base of DNA (3.7 Å). The one-step advancement hypothesis had remained under debate since proposed by von Heijne et al. (1977). It is well understood that each advance over a single nucleotide subsumes intermediary steps, in which RNAP reads the DNA sequence, and takes up the suitable material from the environment to reflect the appropriate nucleotide in the nascent mRNA. Figure 1.3 is also important to understand the timing of RNAP advancement. It visibly clarifies that in each step, a unique internal reaction limits RNAP in taking the next step. Assuming each forward step has constant probability to occur per unit time, RNAP's movement corre-

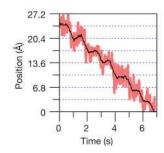


Figure 1.3: Observation of RNAP stepping over DNA

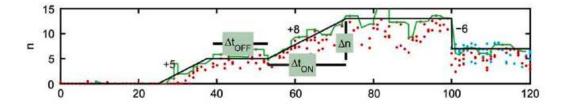


Figure 1.4: mRNA numbers (red points) produced from a single gene over time (in minutes)

sponds to a Poisson process, implying an *exponential distribution* of waiting times between steps (Manabe, 1981; Kampen, 2001).

Golding et al. (2005) tracked the dynamics of mRNA production from a single gene, transcribed from the strongly repressible bacterial promoter $P_{\rm lac/ara}$. This revealed that transcription can occur in quantal bursts, i.e. meaning that long phases of repression take turns with such in which transcription occurs. The former are annotated as $\Delta t_{\rm OFF}$, the latter as $\Delta t_{\rm ON}$ in Figure 1.4. The durations of the periods of inactivity are characterized by an exponential distribution. In each activity period, varying numbers of transcriptions occur, annotated as Δn .

Based on a wealth of recent experimental studies in single cells, Kou et al. (2005) discuss the kinetics of enzymatic reactions at the level of individual reactions. This embraces activities of the molecular machines of gene expression. The authors argue that the appropriate representation is in terms of probabilities for the enzyme to be in one among multiple states in its pathway. This is in contrast to the usual bulk reactions of biochemistry, where kinetics is expressed in terms of concentrations.

1.2 Concurrent modeling languages

Concurrent computation extends sequential computation by notions of concurrent actors, that may progress independently. Concurrent actors exchange information and resources by communication, and synchronize until enough resources and information are available. Actors may know each other or belong to private groups unknown to the external world.

Research on concurrent computation is traditionally motivated by applications within distributed networks, multi-tasking operating systems, parallel computers, and concurrent programming languages. Nondeterminism is unavoidable in concurrent computation. It arises once two actors compete for a resource, that is is only attributed to one. The omnipresence of nondeterminism renders concurrent systems notoriously difficult to analyze, model, and understand.

A number of formal languages were proposed to model concurrent systems. The earliest are Petri nets (Petri, 1962), a graphical language with states and actions reminiscent of finite automata. State charts are a more recent graphical formalism (Harel, 1987). Both found applications in biological modeling (Goss and Peccoud, 1998; Fisher et al., 2005). The calculus of communication systems (CCS) is a process algebra (Milner, 1980) preceding the π -calculus. It corresponds to the fragment of the π -calculus where all messages are void.

The π -calculus by Milner, Parrow, and Walker (1992) is a more recent language providing a purely syntactical notation for modeling concurrent computation on a high level of abstraction. Its syntax is built from a minimalistic set of operators that can be freely composed with each other. These operators include parallel composition, channel creation, expressions for channel communication, and possibly choice operators ³.

Even though minimalistic, the π -calculus is very expressive. Besides of many different aspects of concurrent control, it permits to express sequential computation in the λ -calculus, a Turing complete foundation of functional computation⁴. Two major variants of the π -calculus are to be distinguished following Palamidessi (2003). The asynchronous π -calculus is frequently studied in the context of distributed programming languages, where central-

³Choice operators are often omitted in asynchronous π -calculus dialects, since they are dispensable to nondeterminism, and often undesired in the context of concurrent programming languages. Choice operators are essential ingredients of the synchronous π -calculus though. Indeed, they are convenient constructs for modeling applications in systems biology.

⁴Beyond its enormous fundamental importance, the λ -calculus has also been used for modeling in biology (Fontana and Buss, 1996).

ized control is neither available nor expressible. The more expressive synchronous π -calculus is advantageous for modeling in systems biology, where the stochastic scheduler needs to be implemented by a centralized controller anyway.

Banâtre and Metayer (1986) proposed to base concurrent computation on the chemical metaphor, where molecules interact according to chemical reaction rules⁵. Berry and Boudol (1990) followed this idea in presenting a so called chemical abstract machine as alternative formalization of the π -calculus semantics. What this model lacks however, is a notion of reaction speed.

The stochastic π -calculus of Priami (1995) extends the synchronous π -calculus by this lacking notion of *time*. It associates stochastic parameters to all channels, which defines the speed of interaction on this channel. The stochastic parameter defines an exponential distribution of delays, until reactions happen. This idea dates back to the stochastic process algebra Pepa by Hillston (1995), that defines semantics in terms of continuous time Markov chains (CTMCs).

Modeling biochemical reactions in the stochastic π -calculus. Regev and Shapiro (2002) propose to apply formal languages of concurrency to model molecular networks in cellular biology. This approach is inverse to that of Berry and Boudol, i.e. to use the chemical metaphor to formalize languages for the description of concurrent computation.

The stochastic π -calculus is the language chosen by Regev and Shapiro. It offers the advantage that processes defined it can be executed by the simulation algorithm of Gillespie (1976). Due to its suitably defined stochastic semantics, the stochastic π -calculus of Priami, Regev, Shapiro, and Silverman (2001) becomes a formal modeling language yielding quantitative simulations.

An underlying idea in using the π -calculus for descriptions of chemical reactions is the *shifted perspective from rules to objects*, i.e. objects represent molecules of different species, nucleotides or whole segments of DNA and RNA. In chemistry's rule-based view, one enumerates the reaction rules for all objects present in a chemical solution. Taking the alternative perspective of the π -calculus, one independently states each object's reaction capabilities.

Let us illustrate the perspective shift at the example of Figure 1.5. We

⁵This work has led to the development of the Gamma programming language (Banâtre and Métayer, 1993; Banâtre et al., 2001, 2005). In the latter, a minimalistic model for chemical programming called γ_0 was proposed concomitantly with a comparison to the chemical abstract machine.

Figure 1.5: Defining chemical rules in the π -calculus: shifting the perspective from reaction rules to objects

consider two chemical reaction rules. The first is named \deg and describes the $\operatorname{degradation}$ of a protein of species P by an enzyme of species D. The reaction speed is defined as rate k_1 which is some positive real number. In terms of mesoscopic chemical kinetics, it characterizes an exponential distribution of waiting times between reactions specified by the rule \deg . The second rule is named \dim . It represents the complexation of two P proteins to a heterodimer of type P_2 . This reaction proceeds at rate k_2 .

The π -calculus specification in Figure 1.5(b) first introduces two public channel names deg and dim, assigned the stochastic rates k_1 and k_2 , respectively. Objects may use channel names to communicate, as walkie-talkie⁶ users must agree. The speed of communication acts is defined by the stochastic rates of the channel in use.

P objects may play three different roles, that correspond to the three occurrences of P as reactants in the rules of Figure 1.5(a). The π -calculus definition of process type P in Figure 1.5(b) renders these three roles as alternatives of a choice +:

- deg?().0: as second participant of rule deg, a P object may receive the dummy message over channel deg. As a consequence, it becomes the inert process 0;
- dim!().P₂: as first participant of rule dim, a P object may send a dummy message () over channel dim, and then continue as P₂;
- dim?().0: as second participant of rule dim, a P object may receive the dummy message over channel dim and disappear.

D objects may play only a single role, given there is a single occurrence of D as reactant of the chemical rules. This role is expressed by sending the

⁶or: two-way radio

dummy message on channel deg, once some P object is willing to receive it. In this case, the D object is re-incarnated as such, while the P object vanishes.

Two design decisions underly this encoding. Similarly to the order of participants in chemical reaction rules, they are somehow arbitrary:

- 1. First participants in chemical reactions always send, while second participants receive. Given that no true message is exchanged (so far), this design decision does not matter and could be inverted.
- 2. First participants always survive and continue as the product of the reaction, while second participants disappear. This design decision is arbitrary too, and could be inverted as well.

Chemical solutions are seen as multisets of objects. In the π -calculus, such multisets are expressed by parallel compositions of objects. The solution $P \mid P \mid D$ for instance may either reduce to $P_2 \mid D$ in one step, or to $P \mid D$, depending on which reaction rule is used.

Discussion. Regev formulates the above ideas in terms of modeling guidelines for systems biology. These guidelines are sufficient for modeling systems of chemical reactions, but leave a broad design space for cases in which rule application depends on fine grained control. As a consequence, models may rapidly become obfuscated. Model legibility often suffers from lacking discipline in nomenclature, e.g. for a set of processes representing the same biological entity in various scenarios. This limits the scalability of this modeling approach, and indeed only fairly small modeling tasks have been approached in practice so far.

To conclude the situation as this thesis started in 2003, one can say that the π -calculus approach to modeling systems biology remained impaired by lack of programming language concepts and programming techniques, both with respect to the design and the understandability of models. These problem quickly appeared with the case studies of this thesis, which therefore contributes to remedy the situation.

1.3 Contributions

We first present an extension of the stochastic π -calculus that supports a richer notion objects, with features known from object-oriented programming languages. In particular it explicits notions of functions, interfaces, and inheritance. We then discuss modeling and simulation studies within this π -calculus extension.

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1.3.1 Modeling language and concepts

The objects seen so far lack notions of persistent object identities and functions. This makes it impossible to distinguish different objects offering each the same functions, such as the many different building blocks of DNA. Let us consider a simpler example, with two promoters regulated in the same manner for different genes on the same DNA. Assume these promoters can be bound by RNA polymerase (RNAP) according to the following two chemical rules:

```
\begin{array}{lll} \mathsf{bind}_1\colon & \mathsf{PR\_free}_1 \,+\, \mathsf{RNAP} \,\to\, \mathsf{PR\_bound}_1 \\ \mathsf{bind}_2\colon & \mathsf{PR\_free}_2 \,+\, \mathsf{RNAP} \,\to\, \mathsf{PR\_bound}_2 \end{array}
```

As before, the activities of the two promoters can be expressed by two definitions in the π -calculus:

```
PR\_free_1 \triangleq bind_1?().PR\_bound_1 + ...

PR\_free_2 \triangleq bind_2?().PR\_bound_2 + ...
```

What is less nice here, is that both definitions are alike except for the identity, since both promoters do the same but at different places. Hence one might prefer having a unique definition, that is parameterized by the promoter's identity. It could be of the following form, where the channel **me** is universally quantified:

```
PR_{free}(me) \triangleq me?bind().PR_{bound}(me) + ...
```

Promoter identities are now distinguished by their channel names me, along which individual promoters receive function calls. All promoters offer a function bind that is addressed by the promoter's identity. Hence they provide the same interface, i.e. the same set of function names. Inheritance can be defined as the addition of new functions to objects.

Unfortunately however, function names are not available in the stochastic π -calculus (Priami et al., 2001), which motivates an extension. The idea of function names as input patterns in the π -calculus is not new, though. It was proposed by Vasconcelos and Tokoro (1993) in order to extend the asynchronous π -calculus with objects, and lays the foundation of the distributed programming language TyCO of Paulino et al. (2003). Note that objects can receive only such inputs, for which they provide a matching pattern. The test whether some pattern matches is closely tied to communication.

We present the stochastic π -calculus with input patterns that extends the synchronous stochastic π -calculus by input pattern with function names. The parametric promoter above is a first definition in that calculus. Besides discovering the usefulness of input patterns for the synchronous case, the difficult part is to define the stochastic semantics of this π -calculus.

Stochastic rates are now assigned to pairs of channel and function names. From the semantical perspective, programs in our stochastic π -calculus define continuous time Markov chains (CTMCs). The stochastic semantics for the π -calculus with input patterns that we propose defines an assignment of CTMCs to π -calculus programs. Our semantics copes with *instantaneous* reactions, i.e. calls to functions with infinite rates. These are necessary to deal with concurrent control between more than a pair of concurrent actors. The problem is to appropriately define the Markov chain of a process, under the assumption that there are no instantaneous loops. Previous work does either not define Markov chains explicitly (Priami et al., 2001; Phillips and Cardelli, 2006) so that correctness propositions can only be stated partially, or differently (Priami, 1995) which is less relevant to application in systems biology.

The essential benefit that our language offers to model building is the expression of concurrent objects with multiple profiles, i.e. multiple states with possibly different interfaces. We show how to define object extension by inheritance on a meta level. This representation style permits to accommodate precise information on quantitative and concurrent control, while retaining a maximal ease of notation, legibility, maintenance and extensibility.

We also show how to encode the stochastic π -calculus with input patterns back into the π -calculus without. We prove that our translation is correct, in that it preserves the Markov chains. Hence, existing simulation machines can be used to execute models formulated in our π -calculus with input patterns.

1.3.2 Lambda switch modeling studies

We investigate two cases in bacterial gene expression and regulation. First, we show how to model the control of transcription initiation at the λ switch promoters P_{RM} and P_{R} . Second, we present an general model of bacterial transcription and translation, that may be refined to numerous specific cases.

We express molecular actors in terms of concurrent objects in our stochastic π -calculus with input patterns, and regulatory mechanisms as concurrent control. It should be noted that semaphores appear all over. Each operator and promoter side forms a semaphore, since it can be bound by at most one protein or RNA polymerase. Another point is that we model coding regions of DNA and RNA as lists of nucleotides. Each nucleotide is an object, that can e.g. be rendered degradable by object inheritance, and leaves space for future refinement.

Our λ switch model substantially differs from previous work. We are more fine grained in that we explicitly render the discrete events in transcriptional regulation. These are abstracted away in kinetic models of gene

1.3 Contributions 13

regulation following the tradition of Shea and Ackers (1985), namely the major other models of the λ switch by Aurell et al. (2002) and Aurell and Sneppen (2002), as well as that of Arkin, Ross, and McAdams (1998). It is worthwhile emphasizing that this latter model only stochastically deals with gene expression beyond the point of initiation control, to which it applies the framework of Shea and Ackers.

More fine grained models may capture the level of observations enabled by recent experimental advances. Thus new methods of computational modeling and simulation are increasingly seeked. Independently of the present thesis, Saiz and Vilar (2006) propose a model that yields CTMC descriptions of events in transcription regulation at the λ switch.

Quantification of the models. We model the quantitative behavior by stochastic rates that determine the speed of all interactions in the system. Due to the high level of detail of our models, the literature provided only partial information, notably regarding the discrete events in transcription control at the λ switch, such as dimerization, binding, and quantitative control of interdependent events⁷.

One of the problems was to differentiate between forward and backward directions of reversible reactions, as DNA binding and dimerization of proteins. These are disregarded by continuous models, as that by Shea and Ackers of the λ switch. Albeit valid for general biochemistry, it is increasingly emphasized that this simplification reaches its limits in genetic networks (Fedoroff and Fontana, 2002). With respect to transcription control in an individual cell, it means to disregard essential intermediary stages, that can persist over minutes (Bryant and Ptashne, 2003; Halford et al., 2004), while typical time scales of biochemical systems range around fractions of seconds.

Cooperative enhancement. DNA-bound proteins can increase each other's specificity by adhesive contacts. Positive control of RNAP in transcription initiation boils down to modulate the speeds at which RNAP's possible interactions occur. We present a modeling technique for the stochas-

⁷ Useful new sources became available after finalization of our work in fall 2005 (Kuttler and Niehren, 2006): The highly valuable textbook by Sneppen and Zocchi (2005) covers the biophysical and quantitative aspects of gene regulation, including a chapter on the λ switch. Saiz and Vilar (2006) propose a full stochastic model of discrete events in transcriptional regulation at the λ switch, that is compatible with ours in that it gives rise to CTMCs (its scope is wider than ours, since it covers longe-range regulatory interactions on DNA). Golding et al. (2005) monitor mRNA production from the promoter P_{RM} at the λ switch in real time, and Kobiler et al. (2005) real-time protein levels in E. coli cells, during the decision between lysogeny and lysis upon infection by the λ virus.

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tic π -calculus to modulate the externally observable rate of communication. This technique applied to all other cases of biomolecular interactions we encountered, in which concurrent control affects reaction rates.

1.3.3 Stochastic simulation

We encoded our models in a format amenable to execution with the stochastic π -calculus simulator BioSpi, and conducted exhaustive simulations herein. This is enabled through our encoding of input patterns, since neither BioSpi nor SPiM support them as primitives⁸. For analysis of simulation traces and visualization of data, we developed tools in Perl and R (R Development Core Team, 2006).

In a first simulation study, we validate our models of transcription initiation control at the λ switch by reproducing well-established results from experiments and deterministic simulation. For this we summarize longitudinal observations of repressor binding to operators. Furthermore, at a greater level of detail, we report the activity of the promoter P_{RM} , varying the control by dimerization, quantities of repressor protein, and cooperative binding. Herein we illustrate the variability of results for series of simulation runs under equal conditions. Again, our results well reproduce the effects attributed to the various regulatory mechanisms.

In a second study, we simulate combined dynamics of bacterial transcription and translation. Here, we concentrate on the effect of translational bursting, that has been identified as a key to stochasticity in bacterial gene expression (Kaern et al., 2005; Raser and O'Shea, 2005). It arises from variations in the quantitative control of transcription initiation versus translation initiation. We consider it worthwhile mentioning that the representation of gene expression in the π -calculus approach of Blossey, Cardelli, and Phillips (2006) lacks the means to capture translational bursting. This is due to an atomic representation of gene expression, which disregards those details of quantitative control that our model emphasizes.

1.3.4 Modeling example

Figure 1.6 illustrates the concurrent control of a promoter by an overlapping operator. This DNA sites can respectively be bound by RNAP and the repressor protein Rep. Importantly, these bindings are mutually exclusive. In

⁸Our early models did neither use concurrent objects nor input patterns. Instead they relied on sophisticated protocols, that made these models difficult to understand, parametrize, and extend. Note also that the SPiM system was not available at that time.

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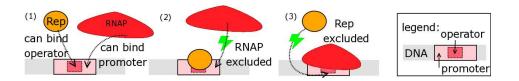


Figure 1.6: States of repressible promoter:(1) free, (2) blocked, (3) bound

```
module 'repressible promoter'
2
   public rnap with bind/1
3
   export Promoter with initiate / 0, unbind / 0, block / 0, free / 0
4
   define
   Promoter(me, op) \triangleq Promoter_free(me, op)
5
6
7
   Promoter_free(me, op) \triangleq
       rnap?bind(c).c!(me).Promoter_bound(me,op)
8
9
    + me?block().Promoter_blocked(me,op)
10
    + op!unblock(). Promoter_free(me, op)
11
   Promoter\_bound(me, op) \triangleq
12
       me?unbind().Promoter_free(me,op)
13
14
    + me?initiate().Promoter_free(me,op)
15
    + op!block().Promoter_bound(me,op)
16
17
   Promoter_blocked(me, op) \triangleq
       me?unblock().Promoter_free(me,op)
18
```

Figure 1.7: Repressible promoter as π -calculus object

setting (1) the promoter is not involved in any interaction, nor is the operator, hence we consider both as free. In (2) Rep's binding to overlapping operator site results in the promoter being blocked, while in (3) the promoter is bound by RNAP. We can similarly define states of the operator, RNAP and Rep.

Notably, the states free, blocked and bound determine the promoter's next possible interactions. In setting (1), binding can occur. In setting (2), Rep can unbind the operator, while the promoter may not accept RNAP's binding. In setting (3) the bound RNAP may either fall off DNA, or initiate transcription along it, while Rep's access to the operator is suspended.

Figure 1.7 lists the module 'repressible promoter'. It formally specifies this narrated behavior in our π -calculus, defining a concurrent object Pro-

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moter with three profiles. The export statement in line 3 declares the Promoter object delivered by the module. The keyword with documents that each Promoter provides the functions initiate and unbind for interaction with RNAP, and block versus unblock to keep the operator synchronized with the operator. Note we also declare the arities of functions. The module's core follows the keyword define. It provides four parametric process definition.

The first definition in line 5 defines how a Promoter object is created.

The remaining three definitions define the *profiles* of Promoter, each corresponding to one of the previously discussed states. Note that all profiles take two parameters. The dedicated channel me represents the object's constant *identity*, while the other parameter op grants access to the object representing the operator site.

Each profile is defined as *choice* between pattern inputs over me, and communication over other channels. Pattern input over me correspond to function invocations on the object at this channel. The acceptance of pattern input is determined by the object's current profile. Our π -calculus dialect refuses function calls on an object, aka pattern input over me, that do not match the current profile. This works by requiring communication not only to agree the names of channels, but also in the function symbol.

For instance, Promoter_blocked ignores unbind requests. It is only able to respond to a unblock invocation, see line 18.

As Promoter is bound, the abstraction of the visiting RNAP can call either function unbind or initiate, see lines 13 and 14. Promoter_bound also causes a transition of the operator to profile blocked, by calling the block on op, see line 15.

We last consider the profile free, in which a Promoter is created. It offers three interactions. Before explaining the first, we need to comment on line 2 of the module. It declares a public channel rnap, and associates it with pattern input of the unary bind. Channel rnap is used in the binding of a RNAP representative to Promoter_free, see line 8. Using this public channel allows initial RNAP-promoter binding to occur between any possible pair of molecular actors, in a many-to-many fashion known from concurrent scenarios. Upon binding, the Promoter extrudes its identifier channel me to the RNAP representative that contacted it. In doing so, Promoter uses the dedicated channel c it was passed in the preceding step 9.

Promoter_free has to other ways to interact, which both regard synchronizations with its sibling Operator at channel op. In line 9, the Operator causes Promoter's transition to the blocked profile. This occurs when we are

⁹Throughout this work we emulate function-call-and-return in the π -calculus as sketched in Milner (2004).

in scenario (2) from Figure 1.6, i.e. a repressor is bound to the operator, and the promoter representative must adjust to this state. The communication in line 10 is realized after Promoter's transition from profile bound to free. It corresponds to the adjustment of the operator representative, that accordingly switches from blocked to free.

1.4 Organization of this document

Part I introduces the biological material dealt with in this thesis: While Chapter 2 presents the overall mechanisms of transcription and translation, Chapter 3 details on transcriptional regulation at the λ switch.

Part II presents our methodological contribution. Its core consists in the stochastic π -calculus with input patterns in Chapter 4. We map it into CTMCs by its stochastic semantics, and we show an encoding allowing to rewrite programs such that they become executable with previously proposed stochastic π -calculus engines.

Chapter 5 introduces our notion of objects and a simple module system that is useful for later model building. These notions are illustrated at the example of various kinds of list, that constitute the basis for our later models of DNA and mRNA.

Chapter 6 proposes modeling techniques for concurrent objects expressed in our π -calculus, that may be useful beyond our own work.

Part III presents our modeling and simulation studies, based on the previously introduced concepts and biological background. Chapter 7 is devoted to the general mechanisms of transcription and translation, Chapter 8 to λ switch regulation.

Chapter 9 concludes.

1.5 Bibliographic note

Two thirds of the technical contributions in this thesis are published in international journals (Articles 1 and 2), the remaining third currently as a technical report (Article 3). Two further publications report early ideas, and survey related simulation frameworks.

Article 1. Céline Kuttler. Simulating bacterial transcription and translation in a stochastic pi calculus. In *Transactions on Computational Systems Biology VI*, volume 4220 of *LNCS*, pages 113–149. Springer 2006. Special issue of CMSB 2005.

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This journal article presents the modeling study on bacterial transcription and translation in the stochastic π -calculus with input patterns. It is covered by three chapters in this thesis: Chapter 2 presents the biological background. Chapter 5 elaborates on the notions of objects, inheritance, and modules; it also includes the discussion of lists as examples. Chapter 7 covers the π -calculus models of transcription and translation, and highlights some simulation results.

Article 2. Céline Kuttler and Joachim Niehren. Gene regulation in the pi calculus: Simulating cooperativity at the lambda switch. In *Transactions on Computational Systems Biology VII*, volume 4230 of *LNCS*, pages 24-55. Springer, 2006. Special issue of BioConcur 2004.

This journal publication presents the λ switch model in the original stochastic π -calculus. In Chapter 8 of this thesis, we simplify this model by reformulating it in the π -calculus with concurrent objects. Chapter 6 distills generic modeling techniques that are of major use to our λ switch model. Chapter 3 discusses the λ switch biology, basically following this paper. It complements with a rule-based representation, and relates its stochastic parameterization to that of our model in the π -calculus with objects.

Article 3. Céline Kuttler, Cédric Lhoussaine, and Joachim Niehren. A stochastic pi calculus for concurrent objects. Technical report, INRIA, 2006.

This technical report corresponds to Chapter 4.

Article 4. Denys Duchier and Céline Kuttler. Biomolecular agents as multi-behavioural concurrent objects. In *Proceedings of the First International Workshop on Methods and Tools for Coordinating Concurrent, Distributed and Mobile Systems*, volume 150 of *ENTCS*, pages 31–49, 2006.

This workshop paper contains early ideas on a new programming language with multi-profile objects and argues their advantage for modeling in systems biology. A formalization of this modeling language is still lacking, but much of the ideas can be expressed in the stochastic π -calculus with input patterns.

Article 5. Adelinde M. Uhrmacher and Céline Kuttler. Multi-level modeling in systems biology by discrete event approaches. it – Information Technology, 48(3):148–153, 2006.

This journal article compares the π -calculus with two discrete event modeling frameworks, currently used in systems biology: state charts of Harel (1987) and Devs proposed by Zeigler (1984).

1.6 Related work 19

1.6 Related work

In this section, we first discuss related work in the areas of formal languages inspired by the chemical metaphor and dedicated to biological modeling. We then sketch actual modeling and simulation studies carried out in π -calculi and some close relatives.

Further related work follows later, after setting up some biological background: studies in stochastic simulation of bacterial gene expression are discussed in Section 2.5, and on the the λ switch in Section 3.3.

1.6.1 Modeling languages

A number of alternative modeling languages have been proposed for systems biology.

BioCham. BioCham (Chabrier-Rivier et al., 2004, 2005) is a rule-based language for the representation of biomolecular systems, with a notation reminiscent of that of chemistry. It is well-suited to consider dynamics by distinguishing three levels of semantics: a boolean, one at concentrations level, and stochastic that allows for simulation. BioCham offers querying of model properties by formulae in the temporal logic CTL (Emerson, 1990), and model input via SBML (Hucka et al., 2003).

Computing with membranes. Membranes allow to structure space into distinct compartments, and are another basic notion that fits naturally with the chemical metaphor, and indeed, they are basic to the minimalistic chemical programming model γ_0 of Banâtre et al. (2005). Computing with membranes was promoted by Păun (2000), whose P-systems consist of nested membranes in which molecules interact. The ambient calculus of Cardelli and Gordon (2000) is another instance inspired by the π -calculus. Motivated by modeling needs in biology, it was succeeded by the bio-ambient calculus of Regev et al. (2004) and the brane calculus of Cardelli (2005).

Kappa calculus. The κ -calculus of Danos and Laneve (2004) aims to express the combinatorics between proteins. Its conceptional starting point is reminiscent of StochSim's by Morton-Firth and Bray (1998) (see page 41). In this view, multi-state molecules are sets of binary flags. Proteins in the κ -calculus are represented as a set of *sites*. The evolvable configurations of sites are termed *interfaces*; individual sites can be either free, hidden, or bound (by an edge to another protein's site).

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Beta binders. The β -binders formalism of Priami and Quaglia (2005) is a biologically motivated variation of the π -calculus. A leading desire is to eliminate the strict channel complementarity for interaction. Communication is enabled upon agreeing types, rather than names. It appears that composite β -binders are related to the interfaces of objects expressed in our π -calculus with pattern input, and that the operations of hiding and unhiding of β -binders correspond to profile transitions in multi-profile objects. In contrast to a driving point in the development of our calculus, β -binders do not allow to address a specific individual of a given species. A thorough discussion of the β -binders and our calculus with respect to biological modeling is planned for future work.

Pathway modeling language. Chang (2003) proposed the draft of a Pathway Modeling Language (PML), a high-level language that can be down-compiled to the π -calculus, suggesting it could yield models of more evident structure and modularization, that would be safer to compose.

Other languages. Ciocchetta and Priami (2006) propose a stochastic π -calculus with transactions, that permits atomic expressions of multiparticipant interactions.

Danos and Krivine (2003) propose CCS-R, a variant of the CCS calculus by Milner (1980). It explicitly supports reversible reactions frequently encountered in biomolecular networks. The language is further investigated in Danos and Krivine (2004) and Danos and Krivine (2005).

1.6.2 Modeling studies

A number of modeling case studies have been elaborated in the stochastic π -calculus or in stochastic process algebras.

Lymphocyte recruitment Lecca et al. (2004) examine lymphocyte recruitment in inflamed brain vessels with the stochastic π -calculus engine BioSpi. Their results are the first based on this approach to faithfully agree with experimental knowledge. Their model doesn't include use of the choice operator.

Metabolism Curti et al. (2005) and Chiarugi et al. (2006) examine the metabolic pathways of a hypothetic minimal bacterium, that they modeled in a fragment of the stochastic π -calculus, with synchronizations but devoid of message-passing and recursion/replication.

1.6 Related work 21

The observation of internal states was crucial to this study, which lead the authors to develop their own abstract π -calculus machine, based on SPiM that does not directly support this possibility.

FGF signaling pathways Tymchyshyn et al. (2006) examine the quantitative properties of the FGF signaling pathway through simulation in the stochastic π -calculus of Priami et al. (2001), making comprehensive use of its linguistic features. Independently of the π -calculus specification, they elaborate a CTMC description of the same model. It is analyzed by Heath et al. (2006) through CTMC probabilistic model checking, using the PRISM tool of Kwiatkowska et al. (2004). Kwiatkowska et al. (2006) thoroughly review the methodological toolset and related formalisms.

ERK signaling pathway Calder, Gilmore, and Hillston (2006) differ to the previous modeling studies in the view they adapt on the ERK signaling pathway: in addition to a molecule-centric model, they propose to make a correspondence between a subpathway and a process. They express this the process algebra PEPA, for which Hillston (1995) developed a mapping into CTMCs.

22 Introduction

Part I Bacterial Gene Expression

Transcription and Translation

In this chapter, we first overview the main activities during transcription and translation, contemporaneous events in gene expression, and interdependencies between its phases. Section 2.2 follows with a presentation of the details of transcription and translation at the level of molecular interactions. This constitutes the foundation for our later discrete event modeling. Section 2.3 presents particular cases of transcriptional organization in bacteria, that can have interesting impact on the quantitative patterns of gene expression. Section 2.4 discusses the quantitative parameters that control transcription, translation and mRNA decay - they are indispensable for stochastic simulation. We put an emphasis on parameter combinations leading to translational bursting, one of the major intrinsic origins of stochasticity in bacterial gene expression. Finally, in Section 2.5 we review modeling and simulation studies that influenced our own work.

2.1 Overview of genetic actors and activities

Each cell contains the complete hereditary information of an organism, that is transmitted from one cellular generation to the next. This information is encoded in a linear, double-stranded DNA macromolecule, that winds up to a helix. Each of the two strands of DNA contains a sequence over the four-letter alphabet of nucleotides $\{A, C, G, T\}$. The sequences on both strands are complementary, A faces T, while C faces G. A *gene* is a segment of one strand of DNA, with explicit begin and end delimiters. Its information content can

DNA
$$\longrightarrow$$
 m RNA \longrightarrow proteins transcription translation

Figure 2.1: The *central dogma of molecular biology* summarizes bacterial gene expression.

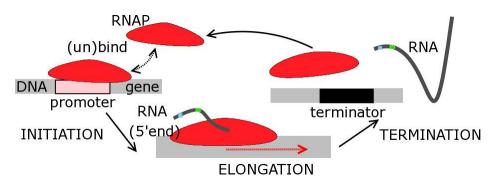


Figure 2.2: DNA processing by RNA polymerase (RNAP): promoter binding and initiation, transcript elongation, termination with release of RNA

be *transcribed* into a single-stranded RNA molecule, and *translated* for such RNA encoding proteins. Figure 2.1 summarizes these two phases of bacterial gene expression.

Transcription of a gene is carried out by RNA polymerase. RNAP assembles RNA molecules, that reflect the information content of the template DNA strand. Certain categories of transcripts have an immediate functional role in the cell. Messenger RNA (mRNA) acts as an information carrier. It is subject to two competing subsequent processing phases: translation into proteins and degradation.

Both transcription and translation follow a similar scheme of *three phases*, illustrated in Figure 2.2 for transcription:

Initiation. RNAP localizes its start point on DNA, a promoter sequence, where it reversibly binds. Upon successful initiation it opens the double-stranded DNA, making its information content accessible. RNAP reads out the first portion of the template DNA strand, assembles the 5' end of a new RNA molecule, and continues into elongation.

Elongation. RNAP translocates over DNA in discrete steps of one nu-

cleotide, and for each adds a complementary nucleotide to the growing transcript. Throughout elongation, RNAP maintains a tight contact to the growing extremity of the nascent RNA, as well as the template DNA strand.

Termination. RNAP unbinds from DNA and releases the transcript when it recognizes a *terminator* sequence.

Translation of mRNA into proteins is performed by *ribosomes*, the largest macromolecular complexes in the cell. Ribosomes read out the genetic code from mRNA in three-letter words (called *codons*), corresponding to amino acids, assemble these into growing sequences of amino acids, that subsequently fold into three-dimensional proteins.

mRNA decay. Besides carrying the code for proteins, a second decisive property of mRNA is its rapid degradation. Instability was indeed the definining feature as mRNA was discovered (Brenner et al., 1961; Gros et al., 1961). Degradation is accomplished by the degradosome, an ensemble encompassing several enzymes and their respective actions. With respect to translation, the decisive step is the degradosome's initial access to the 5' end of mRNA. Figure 2.3 illustrates its competion with ribosomal access for translation initiation. The reviews of Carpousis (2002) and Grunberg-Manago (1999) account for the full details of degradation, that may be covered by refinement of the formal model presented in this thesis.

Proteins are the most prominent active constituents of a cell. In brief, proteins carry out instructions that are hard-wired in DNA. They can be enzymes that catalyze reactions, receptors sitting on the cell's outer membrane and conferring information about the environment to the inside, signaling molecules that carry on information within the cell, transcription factors that control gene expression through binding to DNA, or others. All proteins are subject to degradation, with half-lives exceeding those of mRNA by far.

Concurrent features of gene expression. Many aspects of gene expression has a flavor of concurrency. The first is simultaneous processing of the same macromolecule by several molecular actors. The second are interdependencies, or *couplings*, between the different phases of gene expression, that are not yet visible in the simple scheme of Figure 2.1. The third is immediate competition for a resource, as the race for mRNA between ribosomes and the degradosome.

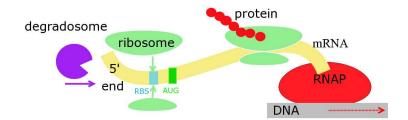


Figure 2.3: mRNA is subject to competing translation and degradation. The latter initiates at the 5' end, while the ribosome assembles on the nearby ribosomal binding site RBS. Actual translation begins with the start codon, here 'Aug'.

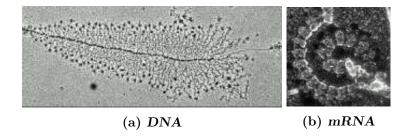


Figure 2.4: Simultaneous processing of DNA and mRNA (Alberts et al., 2002)

The macromolecules DNA and mRNA are typically processed by multiple actors at the same time. Bacterial genomes contain several thousand genes, many of which may undergo transcription at any instant. In addition, each gene can simultaneously be transcribed by several RNAP. Consider the structure reminiscent of a comb in Figure 2.4(a). The backbone is a DNA region encoding one gene. The comb's teeth are formed by nascent RNA transcripts. Althoughh we can not discern the RNAP themselves, the increasing lengths of transcripts indicates that transcription initiates at the left, and that elongation proceeds in left-to-right orientation ¹. The end point of transcription is easy to recognize: the non-coding stretch of DNA remains naked. Note that because transcription of this gene initiates with high efficiency, RNAP densely follow each other. Figure 2.4(b) shows the analogous phenomenon of queueing in translation. While the mRNA itself can not be seen, the visible blobs are ribosomes that rapidly follow each other.

¹These transcripts are not protein coding. Starting from their respective 5' ends, they gradually fold into three dimensional structures, which become ribosome constituents.

Coupling between phases of gene expression. Unlike in eukaryotes where they are separated in time and space, transcription and translation are contemporaneous in bacteria. While one end of an mRNA molecule is being elongated by RNAP, ribosomes start accessing the other. The coupling between transcription and translation can become very tight, and fulfill specific goals (discussed in Gowrishankar and Harinarayanan (2004)). Transcriptional attenuation is a regulatory mechanism in which transcription stops unless the growing mRNA is efficiently translated, as discovered by Yanofsky (1981).

The complexity of couplings dramatically increases in *eukaryotic cells*, as Orphanides and Reinberg (2002) and Maniatis and Need (2002) review. Recent system-level analysis by high-throughput methods reveal surprising aspects (Maciag et al., 2006).

2.2 Molecular events

In this section, we represent the molecular events in transcription, translation and mRNA decay in terms of chemical reactions. This representation is as general as possible. It does not intend to reflect any particular gene, but emphasizes the *core mechanisms* by which any gene is transcribed by RNAP, any mRNA processed by ribosomes in translation, or degraded.

The level of resolution with respect to the elongation mechanisms is that commonly adopted by stochastic models: each elongation step is considered as atomic, accounting for the unique rate-limiting step in the advance of the macromolecular machines RNAP and ribosome. It does not consider the internals of actually appending new elements to a nascent mRNA or protein. Quantitative descriptions of these are recent, e.g. Greive and von Hippel (2005).

2.2.1 DNA and transcription

Table 2.1 summarizes the discrete interactions between DNA and RNAP following the scheme of McClure (1985) for initiation, and McAdams and Arkin (1997) for elongation. It also comprises the parameters of quantitative control, necessary to reproduce the dynamics of transcription in stochastic simulation.

Reactions (2.2.1) to (2.2.3) represent the essential steps of transcription initiation: initial reversible binding of RNAP to the promoter (Prom), followed by transition to the open complex. The parameter k_{on} for binding to an arbitrary promoter in the binding reaction (2.2.1) subsumes the time

RNAP + Prom	$\longrightarrow_{k_{on}}$	$(Rnap \cdot Prom)_{closed}$	(2.2.1)
$(RNAP \cdot Prom)_{closed}$	$\longrightarrow_{k_{\mathit{off}}}$	Rnap + Prom	(2.2.2)
$(RNAP \cdot Prom)_{closed}$	$\longrightarrow_{k_{init}}$	$(RNAP \cdot Prom)_{open}$	(2.2.3)
$(RNAP \cdot Prom)_{open}$	$\longrightarrow_{k_{elong}}$	$Rnap \cdot Dna_1$	(2.2.4)
$\mathrm{Rnap}\cdot\mathrm{Dna}_n$	$\longrightarrow_{k_{elong}}$	$\text{RNAP} \cdot \text{DNA}_{n+1}$	(2.2.5)
$Rnap \cdot Dna_{terminator}$	$\rightarrow_{k_{elong}}$	$RNAP + DNA_{terminator}$	+ m Rna (2.2.6)

Table 2.1: Reaction rules for transcription

RNAP spends scanning DNA, until it recognizes and binds. At this point, promoter and RNAP form a *closed* complex, in which the two strands of DNA are firmly associated. RNAP may *unbind* without any further effect, see reaction (2.2.2). The stability of the closed complex is reflected by the promoter specific parameter k_{off} . In successful *initiation* RNAP unwinds the duplex DNA locally – we then reach the *open* complex (reaction (2.2.3)). The parameter k_{init} reflects the promoter specific efficiency of transcription initiation.

Elongation: After a successful transition to the open complex, RNAP starts to transcribe information content from DNA into RNA, at a first coding nucleotide (2.2.4). During elongation (2.2.5), it continues the synthesis of RNA complementary to the template DNA strand. The nucleotide wise advance of RNAP was experimentally confirmed by Abbondanzieri et al. (2005). These steps are separated by waiting times following an exponential distribution, determined by the parameter k_{elong} ².

Interesting details in elongation are that RNAP may stall, slow down and pause on certain sequences (Wagner, 2000). Also, the promoter becomes available for further binding only after RNAP has cleared the length of its own footprint (a few tens of nucleotides). This *promoter clearance* becomes rate-limiting at highly efficient promoters such as the one from Figure 2.4(a) ³

Termination can be summarized as follows. RNAP dissociates from DNA when recognizing a *terminator* sequence on the template strand. It then

² Note the reaction-base notation disregards the nascent mRNA.

³This aspect is incorporated in our executable models, yet not technically discussed in this thesis. For details, see (Hsu, 2002).

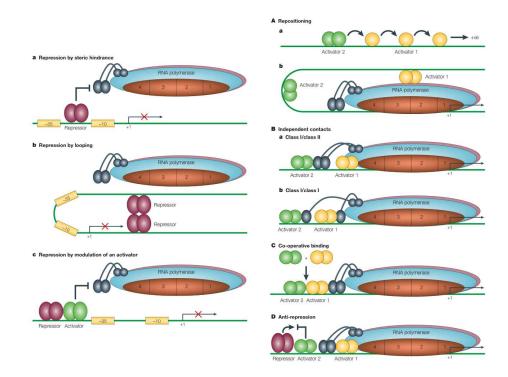


Figure 2.5: Control of bacterial promoters. Regulatory proteins apply as small catalog of molecular mechanisms when binding DNA for repression (left) and activation (right) of transcription initiation. From Browning and Busby (2004).

releases the completed transcript. Reaction (2.2.6) summarizes this *intrinsic* termination.

A regulatory detail not considered in this thesis is that under certain circumstances, small molecules can load on elongating RNAP, and cause it to overrun intrinsic terminators. This is referred to as *anti-termination*, and can be explained by a more detailed model of intrinsic termination. An alternative termination mechanism is called *rho-dependent*. In it, a small protein slides along the transcript starting from its 5' end, reaches RNAP and causes it to terminate. We will not cover this mechanism either, for details see Banerjee et al. (2006) and Henkin (2000),

Regulation of initiation: Bacteria apply various strategies to use their genetic material with great effectiveness, in the correct amount and at the appropriate time. Transcription initiation is controlled by DNA binding

```
Ribosome + mRNA_{RBS}
                                                     Ribosome \cdot mRNA_{RBS}
                                                                                           (2.2.7)
                                           \rightarrow_{k_{on}}
      Ribosome \cdot mRNA_{RBS}
                                          \longrightarrow_{k_{\mathit{off}}}
                                                     Ribosome + mRNA_{RBS}
                                                                                           (2.2.8)
      Ribosome \cdot mRNA_{RBS}
                                                                                           (2.2.9)
                                                     Ribosome \cdot mRNA<sub>1</sub>
                                          \rightarrow_{k_{init}}
          Ribosome \cdot mRNA_n
                                                     Ribosome \cdot mRNA<sub>n+1</sub>
                                                                                         (2.2.10)
                                           \rightarrow_{k_{elong}}
Ribosome \cdot mRNA_{terminator}
                                                     Ribosome + Protein
                                                                                         (2.2.11)
                                         \rightarrow_{k_{elong}}
                                                      +mRNA_{terminator}
Degradosome + mRNA_{RBS}
                                                     Degradosome · mRNA_{RB}(2.2.12)
                                           \rightarrow_{k_d}
```

Table 2.2: Reaction rules for translation and mRNA decay

proteins⁴. Repressors exclude RNAP from promoters by stable binding to overlapping sequences. Activators conversely attach in the vicinity of the promoter, and favor initiation by increasing the transition rate to the open complex k_{init} , or stabilize RNAP by lowering k_{off} .

The repertoire of regulatory interactions between proteins and bacterial DNA is actually small. Figure 2.5 illustrates essential molecular mechanisms of repression (left) and activation (right), depending on no more than two proteins.

In Chapter 3, we will detail on promoter repression by steric hindrance, depicted uppermost in the left column. It lead to the actual discovery ⁵ of gene regulation Jacob and Monod (1961), is the simplest mechanism of repression, and the most frequent. Steric hindrance is encountered at λ switch promoters, for which we develop π -calculus models in Chapter 8. These models refine the sketch from Section 1.3.4.

Among the mechanisms of activation, we will focus on cooperative binding of regulatory proteins, depicted as case (C) in the right column of Figure 2.5, and their positive control of RNAP. Cooperativity activates the λ switch promoter P_{RM} , and it is the key to transcription control in higher organisms (Müller-Hill, 2006; Ptashne, 2005).

2.2.2 mRNA, translation and degradation

Translation, the flow of mRNA encoded information into proteins, is again subdivided into initiation, (protein) elongation, and termination. Table 2.2 summarizes.

⁴Reviewed by Barnard et al. (2004) and Browning and Busby (2004).

⁵Awarded a Nobel prize in 1965.

Initiation. Reaction (2.2.7) represents the initial step of ribosome binding and assembly on a dedicated mRNA sequence, the ribosomal binding site. As depicted in Figure 2.3 on page 28, the RBS is located nearby the mRNA's 5' end. The ribosome may dissociate readily. The parameter k_{off} in reaction (2.2.8) reflects its stability of binding, that depends on the agreement with an ideal sequence mRNA. The abbreviation mRNARna_{RBS} in Table 2.2 refers to the 5' end of mRNA, including both the RBS and the start sequence, e.g. 'Aug' in Figure 2.3. The actual combination of RBS and start sequence determines the efficiency of translation initiation, see parameter k_{init} in reaction (2.2.9).

In elongation, the ribosome slides over mRNA, reads out information content and assembles a growing chain of amino acids. Unlike transcription that maps individual nucleotides, translation proceeds over mRNA in three letter words (codons), that each code for one amino acid. For simplification, it is however common practice in mathematical modeling to consider only the average elongation delay per mRNA nucleotide. It is accounted for by the parameter k_{elong} in equation (2.2.10). While illustrative comics of elongation are widespread in the biological literature as Alberts et al. (2002), the detailed internal functioning of ribosomes is only partially understood, see Frank and Agrawal (2000). Elongation ends as the ribosome reaches a dedicated terminator signal on mRNA (2.2.11). The protein is then released.

Degradation: Table 2.2 covers the initial step of degradation as reaction (2.2.12). After this, decay to proceeds with the same net orientation as translation. It hence does not affect translation that already initiatied. Note that this scheme approximates the *net* outcome of multiple degradation pathways in a phenomenological manner. For details, see Carrier and Keasling (1997), Grunberg-Manago (1999), and Steege (2000). For long, the detailed understanding of mRNA degradation lagged far behind that of other steps in gene expression, recent discoveries are reported by Carpousis (2002) and Regonesi et al. (2006).

2.3 Particular promoter arrangements

In this section we sketch specific cases in the arrangement of genes and promoters in bacterial genomes. They have important impact on expression patterns, and are difficult to explicitly represent in previous modeling approaches.

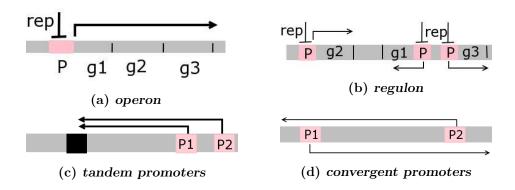


Figure 2.6: Particular promoter arrangements. Horizontal arrows indicate the orientation of transcription.

Operons are sequences of several genes, co-transcribed in one go from a common promoter. Figure 2.6(a) presents an example. Operons yield polycistronic mRNA molecules. Each mRNA segment called cistron corresponds to one gene, hence codes for a different protein. While decay initiates at the common 5' end as it does for monocistronic mRNA, translation is distinctly controlled across cistrons, each bearing their own ribosomal binding site and translation start signal. The translational efficiency across cistrons on the same mRNA can vary up to a factor of 1000 across cistrons (Ray and Pearson, 1974). Section 7.4.1 deals with modeling operons and polycistronic mRNA in our π -calculus with concurrent objects.

Regulons illustrated in Figure 2.6(b) are sets of genes, each transcribed from its individual promoter. The point that matters is that these promoters depend on the same regulatory signal. Assuming the signal reaches all promoters in this *regulon*, the genes are transcribed under the same circumstances.

In our illustration, the regulatory signal consists in repression by the same protein. Operons eliminate the need for multiple promoters. It appears interesting to compare the sensitivity of operons and regulators to a common regulatory signal, however we do not elaborate on this aspect in this thesis.

Tandem promoters are sketched in Figure 2.6(c). They lie close by on the same DNA strand, and control the transcription of the same gene(s). Tandem promoters offer two interesting aspects to fine tune expression levels. First, they can be activated independently, in response to different environmental signals. Second, the mRNA initiated from P2 is longer and thus contains

more information, compared to that from P1. The different 5' ends can have important consequences, since both translation and degradation initiate there. The longer transcript may contain a second ribosomal binding site, or translation start signal. It may be more resistant to decay due to secondary structures, into which its longer 5' end folds.

The fine-tuning of translation efficiency by transcripts of the same gene, initiated at alternative promoters is an interesting regulatory strategy. It is commonly applied by bacterial viruses as λ , that after infecting a bacterial cell, must take a decision to either enter their dormant state, or start multiplying at the expense of their host cell (Schmeissner et al., 1980). The most prominent example of alternative promoters however is ribosomal RNA genes in bacteria. These account for 90% of transcription in rapidly growing cells (Dennis et al., 2004; Paul et al., 2004). Beyond bacteria, alternative promoters are also relevant to gene regulation in higher organisms.

In humans, an interesting example is the control of alternative promoters for the cancer-inducing Epstein-Barr virus, see Thompson and Kurzrock (2004) and Young and Rickinson (2004). This virus infects over 90% of the world population. Its switch from the dormant to the cancer-inducing mode depends on the control of alternative promoters.

We will discuss the modeling of a tandem promoter in the π -calculus in Section 7.4.2, however not enter the details of parameterization and simulation.

Convergent promoters are the fourth promoter arrangement illustrated in Figure 2.6(d). The crucial point about convergent promoters arranged on opposing strands of DNA is that RNAP starting from them proceed over the two strands with converging orientations. However transcriptional traffic over double stranded DNA occurs on a *single lane*, two way street. Head-on collisions between two RNAP causes at least one participant to fall off DNA, releasing a truncated transcript. This suppressive influence is known as transcriptional interference, and can be used as a regulatory mechanism (Shearwin et al., 2005). This thesis only deals with single stranded DNA, leaving the treatment of the concurrent control of transcriptional interference in the π -calculus to future work.

2.4 Quantitative control

Cell-to-cell variability contronts biologists with intriguing questions. A frequent observation is that cells from a genetically identical population exhibit widely differing behavior, although being exposed to the same, precisely con-

parameter (reaction)	value	comment		
Transcription of DNA				
$k_{on} \text{ (in 2.2.1)}$	$0.1 \; \mathrm{sec^{-1}}$	binding: equally fast for all		
		promoters		
$\frac{k_{on}}{k_{off}}$ (in 2.2.1 and 2.2.2)	$10^6 \text{ to } 10^9$	unbinding: promoter specific		
$k_{init} \text{ (in 2.2.3)}$	$10^{-3} \text{ to } 10^{-1} \text{ sec}^{-1}$	initiation: promoter specific		
k_{elong} (in 2.2.5)	$\frac{1}{30} \sec^{-1}$	elongation speed: 30 nu-		
		cleotides/sec		
Repression				
repressors: $\frac{k_{on}}{k_{off}}$	$10^7 \text{ to } 10^{11}$	repressor binding may last be-		
i og		tween seconds and up to sev-		
		eral bacterial generations, de-		
		pending on operator		
Translation and degradation of mRNA				
	1 to 100	gene specific mean protein		
		crop per transcript, depending		
		on k_{off} , k_{init} and k_d		
$k_{elong} \text{ (in 2.2.10)}$	$\frac{1}{100} \text{sec}^{-1}$	elongation speed: 100 nu-		
		cleotides/sec		

Table 2.3: Quantitative control of gene expression. Reaction numbers refer to Tables 2.1 and 2.2.

trolled environment. Such differences may lead to visibly distinct behavior or appearance of the cells. In quantitative terms, they correspond to fluctuation of protein amounts, within a cell over time, as well as across cells in a population snapshot.

Part of the variability in gene expression originates from the inherently stochastic nature of the biochemical reactions, combined with low numbers of molecules in regulatory events (Sneppen and Zocchi, 2005). Other effects are due to the specific quantitative control for a given gene of interest, i.e. the efficiencies of transcription and translation initiation. Tables 2.1 and 2.2 listed the main parameters as reaction labels: k_{on} , k_{off} , k_{init} , k_{elong} , and k_d .

In this section we first consider value ranges for these parameters. We then discuss the impact of actual parameter combinations on the overall dynamics of gene expression, that can be considerable.

2.4.1 Parameter ranges

Table 2.3 reports some ranges of relevant values. The quantitative properties of promoters vary greatly. On some RNAP falls off the closed complex within fractions of seconds, while on others with favorable k_{off} parameter, it may remain stably bound for minutes. Transition to the open complex depends on the parameter k_{init} in reaction (2.2.3), at strong promoters it occurs within a second, while at weak ones after minutes. As a consequence, the frequency of transcription per gene varies from one per second (ribosomal RNA) to one per cell generation (certain regulatory proteins). RNAP elongates transcripts with an average rate of 30 nucleotides per second. With an average gene length of 1000 nucleotides, this combines to an average transcript elongation delay around 30 seconds.

We recall that RNAP's access to promoters can be hindered by repressor proteins, bound to DNA. A repressor protein can stick to highly specific operator sequences for several bacterial generations of each 30 min – 1 hour; while at less specific sequences it falls off within seconds.

Translation proceeds faster than transcription, such that the average time required for the translation of a protein from a mRNA is in the order of 10 seconds. Note that degradation can start before a first protein has been completed from an mRNA, and that a ribosome bound to the RBS protects mRNA from decay until it either unbinds or dissociates. As a consequence of degradation, average mRNA lifetimes range from few seconds to 30 minutes (Grunberg-Manago, 1999).

2.4.2 Translational bursting

The average number of proteins produced from a single mRNA is gene specific, typically ranges are between 1 and 100. It is important to consider the fluctuations of protein crops around these averages, for transcripts of the same gene. These depend on the outcome of the race between degradation and translation. When translation initiates efficiently, and the crop for the transcript is high, ribosomes queue on mRNA, and all proteins are released soon after transcript completion. With long spacings between transcriptions, this combines to translational bursts, i.e. rapid release of comparatively high numbers of proteins.

Only a minority of bacterial genes yield averages of fewer than 5 proteins per transcript, a value of 20 is rather normal – and burst sizes increase with

 $^{^6{}m This}$ is a considerable simplification of the quantitative details of individual steps in mRNA elongation. Greive and von Hippel (2005) review current methods of quantitative assessment.

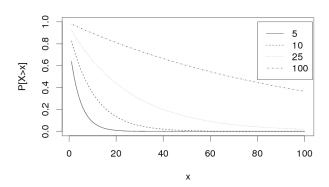


Figure 2.7: A geometric distribution characterizes the fluctuations around the mean crop of proteins per mRNA. P[X > x] for different mean values.

these means. Combined with the fact that most genes are only transcribed occasionally, translational bursting becomes prevalent. Figure 2.8 (left) on page 40 illustrates it. It contrasts the resulting dynamics at protein level for average crops per transcript of 10 proteins (up) with one of 1 (low). Importantly, in both cases the combination with transcriptional efficiencies yields the same *average* protein level.

Translational bursting significantly contributes to stochasticity in gene expression, which has attracted much attention in recent years, reviewed by Kaern et al. (2005), Paulsson (2005), and Raser and O'Shea (2005). It explains why two cells with identical genetic material, under the same conditions, can exhibit significantly variable individual behavior. The effects can propagate up to the level of population of cells, which are partitioned into sub-populations with externally distinct characteristics. While these consequences have been known for long, the origins have have only become observable recently through real time courses of levels in proteins and mRNA, as in the experiments of Kobiler et al. (2005) and Golding et al. (2005).

Geometric distribution. We consider the geometric distribution, that illuminates the increase of the stochastic variability tied to increasing average protein crops per transcript. Let p be the probability that translation succeeds in one round, over degradation that has a probability of (1-p). Considering several rounds of this race, the probability to produce x proteins from one transcript before it is degraded is given by $p^x(1-p)$: with a prob-

ability of p, translation succeeds for each of x rounds, and then degradation wins with the complementary probability of (1-p). This is a geometric distribution function, which is characterized by asymmetry and many large values. Figure 2.7 illustrates the complementary cumulative distribution function for geometric distributions with different mean values. It indicates the probability to obtain more than x transcripts from one transcript, P[X > x]. For example, if the mean crop per transcript is 10, 9% of the transcripts yield each over 25 proteins.

2.5 Related models

We report on studies of bacterial gene expression that our work draws from, dealing with modeling, simulation and experimental investigation. After this, we briefly sketch software packages for stochastic simulation, and comment on continuous modeling approaches.

Carrier and Keasling (1997) elucidated the relation between molecular actors in mRNA processing. Based on the prevalent narrative theories of prokaryotic mRNA, they developed a mechanistic model of discrete interactions between the various sets of enzymes contributing to degradation, and the initiation of translation by ribosomes. The authors performed simulations of the alternative models and tested their ability to reproduce dynamic effects known from wet lab experiments. We will follow their conceptional scheme in mRNA decay, that is rarely explicitly rendered by other models in the field.

McAdams and Arkin (1997) attracted wide attention with a scheme for simulation of gene expression. It combines a continuous model of transcription initiation in the tradition of Shea and Ackers (1985) with a stochastic account of transcript elongation and subsequent processing of mRNA (based on Gillespie's algorithm). We adhere to this conceptional scheme for the race between the initiation of translation versus degradation. Arkin, Ross, and McAdams (1998) applied this generic model to the initial decision between the lysogenic and lytic pathways bacteriophage lambda. We discuss points that we deem critical in their parameterization on page 52. Namely, they neglected the importance of distinct translational efficiencies, giving rise to differences in stochastic fluctuations in protein levels.

Kierzek, Zaim, and Zielenkiewicz (2001) systematically addressed this aspect, for bacterial gene expression in general. They clarified the contribution of translational efficiencies to noise at the protein level in stochastic simulation while systematically varying translation and transcription initiation frequencies.

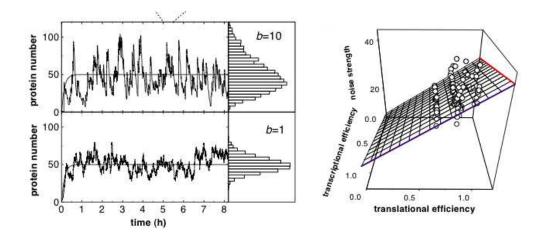


Figure 2.8: **Translational bursting.** The experiments of Ozbudak et al. (2002) confirmed the hypothesis consolidated through modeling and simulation, that efficiently translated transcripts together with rare transcription initiations are a major source of stochasticity in bacterial gene expression. (left) simulation data, (right) data points.

Ozbudak et al. (2002) confirmed Kierzek et al.'s predictions experimentally. They systematically varied single bases in the sequences of DNA determining transcription initiation efficiencies, and those transcribed into the translation initiation sequence (RBS) on mRNA. For these modified sequences, they quantified the resulting initiation efficiencies. In addition, they monitored the resulting dynamics at protein level for different combinations of promoter and RBS sequences. Their experimental observations support the proposal of Kierzek et al. (2001) that stochastic noise increases with the combination of high translational efficiency and rare transcription initiation. Figure 2.8 summarizes the observations of protein levels in silico (left) and vitro (right).

Software packages for stochastic simulation of gene expression While most of the above studies were performed with ad hoc implementations of algorithms for stochastic simulation, in recent years several dedicated software packages have been proposed.

STOCKS. Kierzek (2002) contributed a tool used for his own simulation studies, that executes chemical reaction rules specified in a reaction based syntax according to Gillespie's algorithm.

Dizzy. ⁷ This tool by Ramsey et al. (2005) and Orrell et al. (2005) implements current variants of Gillespie's algorithm of improved efficiency, for large-scale simulation of genetic networks. It includes explicit support for the multi-step reactions in transcription and translation, and reusable templates for the creation of large-scale models of regulatory dependencies between genes. Models are specified in a rule-based language via a graphical interface. The paper by Ramsey et al. (2005) includes a comprehensive overview of software packages for stochastic simulation.

STOCHSIM. Multi-state molecules are one of the central ideas realized in StochSim, a general purpose biochemical simulator described in Morton-Firth (1998) and Morton-Firth and Bray (1998). StochSim represents individual molecules interacting stochastically, however with time steps at even pace. Multi-state molecules possess a set of binary flags, indicating possible modifications as the presence of a smaller molecule.

BioNet. ⁸ For completeness we list the stochastic ODE solver of Adalsteinsson et al. (2004). It proved insightful through the recent simulation studies of Guido et al. (2006), dealing with the construction of a synthetic bacterial promoter.

Deterministic models. Continuous deterministic models have a decadelong tradition in chemistry, biochemistry, or physics. They are mostly represented in the unifying framework of differential reactions (Voit, 2000). By their design deterministic models abstract from the nondeterministic behavior of individual molecules. Their aim is to reproduce average behavior of systems with huge numbers of components, where discrete interactions may be disregarded. Although their predictive power with respect to detailed level as consider in our work is limited, such approaches have indeed proven insightful to gene expression, see e.g. Leloup and Goldbeter (1999), and von Dassow et al. (2000).

⁷http://magnet.systemsbiology.net/software/Dizzy

⁸http://x.amath.unc.edu/BioNetS

Transcription Regulation at the Lambda Switch

Bacteriophage λ is a virus which infects the bacterium *Escherichia coli*. Injecting its genome into the bacterial cell, two developmental pathways are possible, as illustrated in Figure 3.1. In lytic growth the viral genome uses the molecular machinery of the bacterial cell to produce new viruses and eventually burst the host. Alternatively, the viral genome gets integrated into the bacterial genome. Note the highlighted segment within the bacterial genome in Figure 3.1. The only viral protein expressed after the decision for lysogeny is the λ repressor. It represses the expression of all other viral genes. The host cell is now immune against further infections. Both the viral genome, and the immunity, are subsequently transmitted in a passive way. This state called *lysogeny* is extremely stable, and usually maintained for many bacterial generations. Spontaneous transitions from lysogeny to the state of lytic growth would occur about once every 5000 years for a single bacterial cell (Dodd et al., 2005). Taking into account that the bacterium divides into two daughter cells within less than an hour, the lysogenic state is extremely stable.

But surprisingly, upon an environmental signal the phage genome can efficiently become re-activated – this is called *induction*. Now, the bacterium switches from lysogeny into the phase of lytic growth. The viral genome is extracted from the host's, and uses the cell machinery to produce a fresh crop of viruses. This unavoidably leads to the *lysis*, or destruction of the host cell.

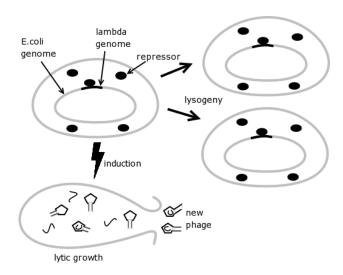


Figure 3.1: Two pathways of λ infected E.coli bacterium: lysogeny and lytic growth.

3.1 Molecular events

What happens during induction, as well as the maintenance of lysogeny, crucially depends on the control of transcription initiation within O_R , the right operator region of phage λ 's genome. O_R is commonly referred to as the λ switch.

The control of transcription initiation at the λ switch illustrates phenomena of cooperativity, which are increasingly important for gene regulation in higher forms of life (Ptashne and Gann, 2002). Cooperative enhancement of a reaction between two molecular actors means that its strength is enhanced by a third, otherwise independent actor. We will see two instances of cooperative enhancement at the λ switch: positive control and cooperative binding.

Genes and promoters: By the λ switch we refer to a segment of phage λ 's genome, that comprises the control regions for the genes cl and cro, illustrated Figure 3.2. Their transcription initiates at the promoters P_{RM} and P_R respectively, the transcripts are subsequently translated to the *proteins* Rep and Cro.

Cro and Rep proteins appear in two forms, as *dimers* and *monomers* which can be distinguished in Figure 3.4. When expressed they first appear as monomers. They can only bind to DNA after having associated pairwise. Dimers are unstable, unless bound to DNA they soon dissociate back to

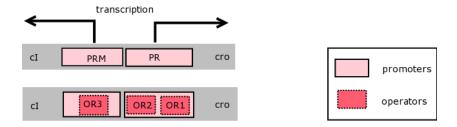


Figure 3.2: A spatial view of the λ switch, a segment of phage lambda's genome.

gene	protein	promoter			
cI	Rep	P_{RM} : promoter for synthesis of repressor during			
		maintenance of lysogeny			
cro	Cro	P_R : right promoter			

Figure 3.3: Genes, proteins, and promoters at the λ switch

monomers. The higher the protein concentration in the cell, the higher is the degree of dimerization.

In lysogeny, the regulatory network is characterized by a high number of Rep and negligible amount of Cro proteins; these frequencies are inverted during lytic growth. The environmental signal upon induction leads to a massive destruction of Rep proteins. $P_{\rm R}$ then becomes activated automatically, while transcription from $P_{\rm RM}$ ceases. These are consequences of the network controlling transcription initiation.

Repression of promoters by steric hindrance: The regulatory proteins Rep and Cro bind to the three neighboring operator regions O_{R1} , O_{R2} , and O_{R3} . By doing so, they control RNAP access to the promoters. As Figure 3.2 indicates O_{R1} and O_{R2} both overlap the promoter P_R , while O_{R3} lies within P_{RM} . A protein bound within a promoter blocks recognition of the promoter by RNAP. This principle is called steric hindrance. The typical constellations are sketched in Figure 3.4. Note that all bindings are reversible, i.e. the proteins dissociate from the DNA strand after some time. Similarly, RNAP frequently falls off a promoter without initiating transcription.

The maintenance of lysogeny depends on the presence of a sufficient amount of repressor, that is predominantly bound at O_{R1} and O_{R2} . This impedes RNAP binding to P_R . As a consequence, Cro and all other viral

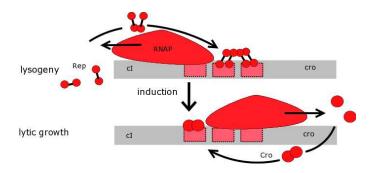


Figure 3.4: Network states during lysogeny and lytic growth. In lysogeny, Rep attached to either or both of the binding sites O_{R1} and O_{R2} blocks recognition of the promoter P_R by RNAP, and thus prevents transcription of the gene cro. At the same time, interactions between Rep at O_{R2} and RNAP at P_{RM} stimulate transcription of the gene cI, which allows for the production of new Rep.

genes are repressed.

Cooperative enhancement of repressor binding at O_{R2} : The intrinsic binding affinity of Rep for O_{R1} is tenfold higher than for O_{R2} and O_{R3} . Thus, Rep is more likely to be found at O_{R1} . Furthermore, Rep at O_{R1} significantly favors binding of another Rep to O_{R2} – this is what we call *cooperative binding*. One could say that the λ repressor at O_{R1} recruits another to O_{R2} (Ptashne and Gann, 2002).

Positive control of transcription initiation is needed for virtually all genes. It refers to the fact that RNAP bound to a promoter needs the help of regulatory proteins in order to successfully initiate transcription. At P_{RM} , RNAP's initiation frequency increases through a physical contact with Rep bound at O_{R2} . This second instance of cooperative enhancement, called *positive control*, is decisive for maintenance of the lysogenic state. Without it RNAP would rather fall off the inherently weak promoter P_{RM} than start to transcribe.

The production of Rep ceases once the available quantities fill the operator site site O_{R3} , in addition to O_{R1} and O_{R2} . At this point Rep inhibits its own production by steric hindrance of P_{RM} in a negative feedback loop.

Upon *induction*, the number of repressors rapidly decreases due to an external signal, so that O_{R1} and O_{R2} become more and more likely to remain vacant. Now polymerases find frequent opportunities to bind to P_R . As P_R

$$TF + O_{Ri} \quad k_{off} \rightleftharpoons^{k_{on}} \quad TF \cdot O_{Ri}$$

$$RNAP + P_{RM} \quad k_{off} \rightleftharpoons^{k_{on}} \quad (RNAP \cdot P_{RM})_{closed}$$

$$(RNAP \cdot P_{RM})_{closed} \quad \rightarrow_{k_{init}} \quad (RNAP \cdot P_{RM})_{open}$$

$$RNAP + P_{R} \quad k_{off} \rightleftharpoons^{k_{on}} \quad (RNAP \cdot P_{R})_{closed}$$

$$(3.1.1)$$

$$(RNAP \cdot P_{RM})_{closed} \quad (3.1.3)$$

$$(\text{RNAP} \cdot P_{\text{R}})_{\text{closed}} \longrightarrow_{k_{init}} (\text{RNAP} \cdot P_{\text{R}})_{\text{open}}$$
 (3.1.5)

Table 3.1: Reaction rules for protein-DNA interactions at the λ switch

is inherently a *strong promoter*, these bindings rapidly ensue transcription, followed by the production of Cro proteins.

3.2 Quantitative control

The stochastic π -calculus assumes rates that determine the speed of reactions. In this section, we discuss how to distill such rates from the literature. The resulting parameters are summarized in Table 3.2.

Table 3.1 summarizes the reactions for RNAP-promoter interactions, and protein binding to operators and at the λ switch, i.e. $TF \in \{Rep, Cro\}$ and $i \in \{1, 2, 3\}$. It is however not straightforward to include the mutual affections of these reactions. Table 3.2 explicits all side conditions.

In our system reversible binding reactions are frequent, such as by λ repressor to the operator O_{R1} :

$$Rep + O_{R1} \underset{k_{of}}{\rightleftharpoons}^{k_{on}} Rep \cdot O_{R1}$$
 (3.2.1)

This bidirectional reaction converges to an equilibrium, in which the number of reactants on both sides remains constant. The association constant k_{on} determines the speed of the association reaction. It measures the number of Rep-O_{R1}-pairs that form complexes per mol and second. For the case of regulatory proteins the association rate constant k_{on} has been experimentally determined – see Berg et al. (1981); Wagner (2000); Sneppen and Zocchi (2005). It is given by the net rate with which a protein locates its target site on DNA:

$$k_{on} = \frac{10^8}{\text{mol sec}}$$
 (3.2.2)

We assume this value for all combinations of proteins and operator sites ¹.

¹This constant exceeds three dimensional diffusion by two orders of magnitude, and subsumes a number of mechanisms of target site location by proteins. In its search process

reaction	rate	protein	site	condition	value	(channel,	reference
						function)	
	k_{on}	any	any	overlapping	0.098	pro,bind	(Berg et al., 1981; Wagner, 2000)
				promoter			
				vacant			
		Rep	O_{R1}		0.155	or1, timerRep	(Ackers et al., 1982)
		Rep	O_{R2}	no Rep at O _{R1}	3.99	or2, timer RepLow	(Ackers et al., 1982)
		Rep	O_{R2}	Rep at O_{R1}	0.155	or2,timerRepHigh	(Shea and Ackers, 1985)
				(cooperative			
				binding)			
(3.1.1)	k_{off}	Rep	O_{R3}		20.22	or3,timerRep	(Koblan and Ackers, 1992)
		Cro	O_{R1}		2.45	or1,timerCro	(Shea and Ackers, 1985)
		Cro	O_{R2}		2.45	or2,timerCro	(Shea and Ackers, 1985)
		Cro	O_{R3}		0.29	or3,timerCro	(Shea and Ackers, 1985)
(3.1.2)	k_{on}	RNAP	P_{RM}	O _{R3} vacant	0.098	rnap,bind	(Berg et al., 1981; Wagner, 2000)
	k_{off}	Rnap	P_{RM}		0.788	prm,unbind	(Li et al., 1997)
(3.1.3)	k_{init}	Rnap	P_{RM}	Rep at O_{R2}	0.086	prm,highTimer	(Li et al., 1997)
				(positive con-			
				trol)			
		RNAP	P_{RM}	no Rep at O_{R2}	0.005	prm,lowTimer	(Li et al., 1997)
(3.1.4)	k_{on}	RNAP	P_{R}	O_{R1} and O_{R2}	0.098	rnap,bind	(Berg et al., 1981; Wagner, 2000)
				vacant			
	k_{off}	RNAP	P_{R}		0.155	pr,unbind	(Hawley et al., 1985)
(3.1.5)	k_{init}	Rnap	P_{R}		0.05	pr,initiate	(Hawley et al., 1985)

The dissociation constant k_{off} specifies the speed of the de-complexation. It measures the proportion of complexes that is resolved per second. As we will see, for the case of Rep binding to O_{R1} we can assume it to be $k_{off} = \frac{0.155}{\text{sec}}$.

However, it is less obvious to infer such dissociation rates the literature. What is determined experimentally for such reactions is mostly Gibbs free energy ΔG – a notion from thermodynamics. The value of ΔG quantifies the effort necessary for decomplexation. In the concrete example of O_{R1} , Ackers et al. (1982) provide $\Delta G = -12.5 \frac{kcal}{mol}$. This energy is negative, reflecting that binding requires an effort by the environment, while unbinding happens voluntarily. Non cooperative binding of Rep at the weaker binding site O_{R2} yields a value of $\Delta G = -10.5 \frac{kcal}{mol}$, for O_{R3} we obtain $\Delta G = -9.5 \frac{kcal}{mol}$. Note that a smaller value indicates stronger binding, and that a difference of 1kcal ensues a tenfold difference in binding strength.

Gibbs free energy correlates with the equilibrium constant K_{eq} of the binding reaction, which expresses the quantities of unbound pairs Rep and O_{R1} compared to complexes $Rep \cdot O_{R1}$ in equilibrium. The relationship is expressed through the equation:

$$K_{eq} = \exp(\frac{-\Delta G}{R \cdot T}) \tag{3.2.3}$$

where $R=1.9872\frac{cal}{\text{mol Kelvin}}$ is the universal gas constant and T=310.15 Kelvin is the absolute temperature at which the experiments were performed (it corresponds to 37 Celsius).

The equilibrium constant K_{eq} represents the ratio of association and dissociation rate constants as shows the following kinetic equation:

$$K_{eq} = \frac{k_{on}}{k_{off}} \text{ mol} (3.2.4)$$

The experimental data on Gibbs energy together with equations (3.2.2), (3.2.3), and (3.2.4) are sufficient to compute the dissociation rate k_{off} by straightforward arithmetics².

The rate constants k_{on} and k_{off} we have met so far are macroscopic – as in chemical kinetics. They do not depend on the actual numbers of

$$\Delta G = -12.5 \cdot 10^3 \text{cal/mol}$$
 $K_{eq} = \exp^{-\Delta G/(R\ T)}$ $R = 1.9872 \text{ cal/(mol\ Kelvin)}$ $k_{on} = 10^8/(\text{mol\ sec})$ $K_{off} = k_{on}/K_{eq} \text{ mol}$

a protein first diffuses three-dimensionally through the cytoplasm, hits the DNA and subsequently slides along the DNA, rapidly scanning it for its specific site. A model explaining this has been proposed by Slutsky and Mirny (2004).

²The following set of equations determines the values of all rates for the example:

	ΔG	k_{off}	binding strength
O_{R1}	-12.5	0.155	strongest
O_{R2} (coop)	-12.5	0.155	
O_{R2} (isolated)	-10.5	3.99	
O_{R3}	-9.5	20.22	weakest

Figure 3.5: Parameters for λ repressor binding to the three operator sites

molecules, but on concentrations. Gillespie's algorithm, however, and thus the stochastic π -calculus use mesoscopic rate constants as their stochastic rates. These refer to actual numbers of molecules and are determined from their macroscopic counterparts as follows:

$$k_{on}^{meso} = \frac{k_a}{A \ V}, \qquad k_{off}^{meso} = k_{off},$$

where $A=6.023\cdot 10^{23}$ is Avogadro's number – i.e. number of molecules per mole – and $V=1.7\cdot 10^{-15}l$ is the E. coli cell volume. We need to divide by $A\cdot V$ for reactions involving two reactants, such as binding; for reactions that transform a single reactant as unbinding, the macroscopic and mesoscopic rates coincide. Note that we assume the cell volume to be constant while ignoring cell growth. Evaluating our equation yields the following final rates for the considered example reaction between O_{R1} and Rep:

$$k_{on}^{meso}=0.098/\sec \qquad k_{off}^{meso}=0.155/\sec$$

We can now quantify the effects of cooperative binding between repressors at O_{R1} and O_{R2} . Cooperativity adds a favorable term of $-2\frac{\text{kcal}}{\text{mol}}$ to the Gibbs binding energy of Rep at O_{R2} (Shea and Ackers, 1985) ³. Due to the exponential relation between free energies and equilibrium constants this massively strengthens the binding: the mesoscopic dissociation rate k_{off} for O_{R2} decreases from 3.99 to 0.155, the same value as for O_{R1} . Table 3.5 summarizes.

Finally, we need rates for transcription initiation, in which we follow the scheme of McClure (1985): After binding, the complex of RNAP and promoter P undergoes an irreversible transition from a closed state into an open one, in which the two strands of DNA have locally been separated. Then transcription proceeds.

$$\operatorname{RNAP} + P \rightleftharpoons^{K_{eq}} (\operatorname{RNAP} \cdot P)_{\operatorname{closed}} \rightarrow_{k_{init}} (\operatorname{RNAP} \cdot P)_{\operatorname{open}}$$
 (3.2.5)

 $^{^3}$ Cooperativity also has a helping effect to binding at O_{R1} , however we chose to neglect this in our model as the effect at O_{R2} predominates.

The k_{init} rates for the promoter P_R and P_{RM} can be found in Hawley et al. (1985) and Li et al. (1997). Positive control of RNAP by repressor binding at O_{R2} increases the k_{init} rate of P_{RM} roughly tenfold. Note that the dissociation rate of RNAP binding at P_{RM} is not affected, which distinguishes this mechanism from cooperative binding of regulatory proteins.

Throughout this paper we assume a constant RNAP concentration of $c = 30 \cdot 10^{-9}$ mol according to Shea and Ackers (1985). This corresponds to a population of circa 30 RNAP molecules via the simple calculation $\#RNAP = c \cdot V \cdot A = 30.7$, with A and V as above.

Finally, we assume the rate at which repressor monomers associate to dimers to be $0.025 \sec^{-1}(nM)^{-1}$ (mesoscopic: 0.048) while setting the dissociation rate to 0.5/sec following Bundschuh et al. (2003).

3.3 Related models

The λ switch might be the case of gene expression that is most frequently approached by modeling and simulation studies. The central questions addressed at a systems level are:

- How is the initial decision between lytic and lysogenic pathways determined, after infection?
- How is the lysogenic state maintained?

We review hallmark studies in modeling and simulation of bacteriophage λ , in chronological order. Note that the questions addressed by these models are distinct from ours, as well as the modeling frameworks applied. Also, covering a maximal number of existing models remains beyond our intention.

The first quantitative model of λ switch regulation through protein binding, to the best of our knowledge, is that of Ackers, Johnson, and Shea (1982). They started from experimental data of Johnson, Meyer, and Ptashne (1979) reporting the concentration of repressor required for half-saturation of operator sites, and converted these into a set of thermodynamic free energies. Ackers et al. derived the probability to find repressor proteins bound to the operator sites O_{R1} , O_{R2} and O_{R3} , distinguishing eight possible binding configurations. This allows to calculate the degrees of promoter repression, depending on repressor levels. Importantly, the model also allows to predict promoter repression under the assumption that repressors at O_{R1} and O_{R2} do not bind cooperatively. This data supported the view that would have been difficult to confirm experimentally, that cooperativity improves P_R repression in lysogeny.

Shea and Ackers (1985) extend this model, to include binding of RNAP to the promoters as well as Cro's to the operators. The number of possible configurations increases from 8 to 40 by the additional information. Importantly, in contrast to the previous, this model version is dynamic. It was used to predict the maintenance of lysogeny, and induction of the lytic pathway.

The model of McAdams and Shapiro (1995) was the first to follows λ 's dynamics from the moment the virus infects the host cell, through the decision between the lytic and lysogenic pathway. It does so in a *qualitative* manner, and concludes that detailed simulation of genetic mechanisms are necessary to model regulatory circuits quantitatively.

Arkin, Ross, and McAdams (1998) deal with the initial decision between the lysogenic and lytic pathways bacteriophage lambda in *quantitative* terms. This model integrates a promoter control model following Shea and Ackers (1985) with a stochastic account of transcript elongation and mRNA processing.

The next two studies deal with the maintenance of the lysogenic state. Aurell, Brown, Johanson, and Sneppen (2002) mathematically deal with the remarkable stability at which it is inherited from one bacterial genetics to the next. Their investigation includes experimental data of Little et al. (1999), that report robustness of the switch with respect to modifications of protein binding strengths to the operators O_{R1} , O_{R2} , O_{R3} . Aurell et al. conclude that the knowledge available at the time of their work does not yet allow to account for the experimentally observed stability, and thus appears incomplete. Aurell and Sneppen (2002) develop a generic framework for the investigation of the stability of epigenetic states (i.e. passing on lysogeny from one generation to the next), and apply it to λ .

Other models centering on *induction* were proposed by Chung and Stephanopoulos (1996), Tian and Burrage (2004), and Zhu, Yin, Hood, and Ao (2004), while Thomas et al. (1976) and Thieffry and Thomas (1995) dealt with the initial lysis-lysogeny decision in logical formalisms.

Discussion of parameterization in Arkin et al. (1998)

It is worthwhile mentioning that while the work of Arkin et al. was an important source of inspiration for our own model of transcription and translation, in what regards the parameterization of the λ model our choices widely differ from theirs. Regarding dimerization, we follow Bundschuh et al. (2003), who corrects the rates of Arkin et al. by a factor nano, i.e. nine orders of magnitude. Without this, it would not have been possible to simulate the dynamics of dimer formation and breakage. Regarding transcription control,

our parameter set developed in Section 3.2 is novel⁴; the level of resolution of Arkin et al. disregards those aspects that are of importance to us. Regarding protein decay, they assume repressor half-lives of 40 min. However to the best of our knowledge, the λ repressor is remarkably stable in the absence of the signal for induction. We follow Parsell et al. (1990) who report half-lives in time scales of 10 hours or more, i.e. repressor degradation is not relevant to our model since we consider shorter time scales⁵. Last it was a choice of this thesis not cover the quantitative control of translation for the λ proteins. However, we report that to the best of our knowledge, we identified important flaws in the parameter set of Arkin et al.. Their work assumes an average crop of 10 proteins for all transcripts, including those of the cI gene transcribed from P_{RM}. This clearly contradicts to the findings of Balakin et al. (1992) that this transcript belongs to a minority with unusual translation initiation properties, the so called *leaderless* mRNA. P_{RM} initiated cI transcripts lack a ribosomal binding sites, translation initiates directly on the start codon. This results in poor efficiency, yielding in average 1 protein per cI transcript. Ribosomal assembly on such transcripts follows a peculiar pathway, see Moll et al. (2002), Moll et al. (2004). It was previously not reported for bacterial mRNA- however exhibits parallels to translation initiation in archeal and eukaryotic cells. We deem these choices in parameterization to have important impact on the simulation results of Arkin et al., notably on the prediction of variability in protein levels.

⁴An similarly derived by Saiz and Vilar (2006).

⁵Degradation would importantly matter if considering induction of the lytic pathway.

Part II Modeling Language and Concepts

A Stochastic Pi Calculus with Input Patterns

The π -calculus by Milner, Parrow, and Walker (1992) is an expressive formal language for describing systems of concurrent actors and their interactions. It supports a minimalistic set of operators, describing concurrent systems on a high level of abstraction, while ignoring specific aspects of applications. The synchronous π -calculus is more expressive than the asynchronous π -calculus, in that it can express centralized control (Palamidessi, 2003). Distributed programming languages are the prototypical application of the asynchronous π -calculus, since no centralized control is available there.

The stochastic π -calculus of Priami (1995) adds a temporal perspective to the synchronous π -calculus. The speed of reaction x is specified by a stochastic parameter, that is assigned to channel x. Such parameters define exponential distributions of waiting times, associated with reactions on the channel. A one-step reduction based semantics¹ is given in Priami et al. (2001). This semantics can be implemented by the simulation algorithm of Gillespie (1976).

The two implementations available so far, SPiM (Phillips and Cardelli, 2006) and BioSpi (Priami et al., 2001), were already applied in a number of simulation cases studies in systems biology beside those presented in this thesis (Lecca et al., 2004; Blossey et al., 2006; Kwiatkowska et al., 2006). From the modeling perspective in systems biology, the minimality of the π -calculus is sometimes unfortunate. Objects help specifying the interfaces of

¹The alternative SOS style semantics was used in the original π -calculus (Milner et al., 1992) and in the original stochastic π -calculus (Priami, 1995).

concurrent actors, so that they can be refined by inheritance. This permits to add new functionality to concurrent actors, while remaining consistent with their previous interface.

The lack of object-oriented features in the asynchronous π -calculus was perceived early from the programming language perspective. Vasconcelos and Tokoro (1993) proposed a suitable extension of the asynchronous π -calculus to remedy the situation, that lead to the development of the TyCO programming language (Paulino et al., 2003). The main idea is to extend the asynchronous π -calculus by input patterns with function names, in order to define object-oriented programming abstractions.

In this chapter, we extend the stochastic π -calculus by input patterns with function names. In doing so, we are driven by the motivation to define notions of concurrent objects, that we introduce later in Chapter 5. These notions will be more general than those in TyCO, and are based on synchronous communication. This increase expressiveness is required for our modeling studies. Beside discovering the usefulness of input pattern for the synchronous π -calculus, the main contribution of this chapter is a *stochastic semantics* for the π -calculus with input patterns. It assigns stochastic rates to pairs of channel and function names. The challenge is to define the stochastic semantics such that it specifies a continuous time Markov chain for every process. Gillespie's algorithm allows to execute this Markov chain, i.e. to compute simulation traces.

Our semantics copes with *instantaneous* reactions. Again, the problem is to appropriately define the Markov chain of a process, under the assumption that there are no immediate loops. Previous work on the stochastic π -calculus does either not define Markov chains explicitly (Priami et al., 2001; Phillips and Cardelli, 2006) so that correctness propositions can only be stated partially, or differently (Priami, 1995) which is less relevant to applications in systems biology. Experiments with the existing implementations – SPiM–confirm a correct treatments nevertheless.

Finally, we show how to *encode* the stochastic π -calculus with input patterns back into the original stochastic π -calculus without. We prove that our translation is *correct*, in that it preserves Markov chains. Hence, existing simulation machines can be used to execute models formulated in our π -calculus with input patterns.

Outline. We present our π -calculus with input patterns (Section 4.1), recall continuous time Markov chains and relate them to chemical reaction (Section 4.2). The stochastic semantics of our π -calculus extension is presented in Section 4.3. We then show how to encode input patterns (Section 4.4). Finally we discuss yet another extension, one by higher-order definitions, that allows to express classes (Section 4.5). Chapter 5 separately

Processes	P	::=	$P_1 \mid P_2$	parallel composition
			new $x:\rho$. P	channel creation
			$C_1 + \ldots + C_n$	sum $(n \ge 0)$
			$A(\tilde{x})$	application
Guarded processes	C	::=	$x?f(\tilde{y}).P$	pattern input
			$x!f(\tilde{y}).P$	tuple output
Definitions	D	::=	$A(\tilde{y}) \triangleq P$	

Table 4.1: Syntax of the stochastic π -calculus with input patterns

discusses how to define different notions of concurrent objects.

4.1 The language

The vocabulary for constructing π -calculus expressions consists of an infinite set of channel names $\mathcal{N} = \{x, y, z, \ldots\}$, a set of process names A, and a set of function names $f \in \mathcal{F}$. The vocabulary fixes an arity for every process name A and for every function name f, that determines their numbers of parameters. Our vocabulary additionally comprises functions $\rho : \mathcal{F} \to]0, \infty]$ defining collections of stochastic rates associated to channels. If ρ is assigned to channel x and $f \in \mathcal{F}$ a function name then $\rho(f)$ is the rate of the pair (x, f).

The syntax of our π -calculus is defined in Table 4.1. We write \tilde{x} for finite, possibly empty sequences of channels x_1, \ldots, x_n where $n \geq 0$. Whenever we use tuples $f(\tilde{x})$ or terms $A(\tilde{x})$ we assume that the number of arguments (the length of \tilde{x}) is equal to the respective arity of f or A. Process expressions are ranged over by P. The only atomic expression (that cannot be decomposed into others) is the guarded choice of length n=0 that we write as $\mathbf{0}$. Expressions $P_1|P_2$ denote the parallel composition of processes P_1 and P_2 . A term $\mathbf{new}\ x:\rho$. P describes the introduction of a new channel x scoping over P; the rate function ρ fixes stochastic rates $\rho(f)$ for all pairs (x, f) where $f \in \mathscr{F}$. We can omit rate functions ρ in the declaration of a channel x if all reactions on x are instantaneous, i.e. $\rho(f) = \infty$ for all $f \in \mathscr{F}$. An expression $A(\tilde{x})$ applies the definition of a parametric process A with actual parameters \tilde{x} .

A sum of guarded processes $C_1 + \ldots + C_n$ offers a choice between $n \geq 0$ communication alternatives C_1, \ldots, C_n . A guarded input $x?f(\tilde{y})$ describes a communication act, ready to receive a tuple that is constructed by f over

```
fv(x?f(\tilde{y}).P) = \{x\} \cup (fv(P) - \{\tilde{y}\})
fv(P_1 \mid P_2) = fv(P_1) \cup fv(P_2)
fv(x!f(\tilde{y}).P) = \{x\} \cup fv(P) \cup \{\tilde{y}\}
fv(\mathbf{new} \ x:\rho. \ P) = fv(P) - \{x\}
fv(C_1 + \ldots + C_n) = fv(C_1) \cup \ldots \cup fv(C_n)
```

Table 4.2: Free variables

```
\begin{array}{rcl} (P_1|P_2)|P_3 & \equiv & P_1|(P_2|P_3) \\ & P_1|P_2 & \equiv & P_2|P_1 \\ \dots + C_1 + C_2 + \dots & \equiv & \dots + C_2 + C_1 + \dots \\ & P|\mathbf{0} & \equiv & P \\ & P_1 & \equiv & P_2 & \text{if } P_1 \equiv_{\alpha} P_2 \\ & \mathbf{new} \ x_1 : \rho_1. \ \mathbf{new} \ x_2 : \rho_2. \ P & \equiv & \mathbf{new} \ x_2 : \rho_2. \ \mathbf{new} \ x_1 : \rho_1. \ P & \text{if } x_1 \neq x_2 \\ & \mathbf{new} \ x : \rho. \ (P_1|P_2) & \equiv & P_1| \ \mathbf{new} \ x : \rho. \ P_2 & \text{if } x \notin fv(P_1) \end{array}
```

Table 4.3: Axioms of the structural congruence

x. The channels \tilde{y} in input guards serve as pattern variables; these are bound variables that are replaced by the channels received as input. An output guarded process $x!f(\tilde{y}).P$ describes a communication act willing to send tuple $f(\tilde{y})$ over channel x and continue as P.

A definition of parametric process has the form $A(\tilde{x}) \triangleq P$ where A is a process name with \tilde{x} as formal parameters (that is a sequence of bound channels). Note that P may contain free channel names besides the parameters in \tilde{x} , which is convenient for modeling. The full power of free variables in definitions, however, appears only when allowing for higher-order definitions. This requires a further extension of the calculus, discussed in Section 4.5. The set of free channel names for processes P and guarded processes C is formally defined by induction on the structure of such expressions in Table 4.2.

The operational semantics of the π -calculus, without stochastic aspects, is often defined in terms of a binary relation between expressions, called the (one step) reduction. We will later refine it to a ternary relation with stochastic labels. The definition relies on the usual structural congruence between expressions. Reduction steps can always be performed on arbitrary congruent expressions.

The *structural congruence* is the smallest relation induced by the axioms in Table 4.3. It identifies expressions modulo associativity and commutativity

Communication, choice, and pattern matching:

$$x!f(\tilde{y}).P_1 + \ldots \mid x?f(\tilde{z}).P_2 + \ldots \rightarrow P_1 \mid P_2[\tilde{z} \mapsto \tilde{y}]$$

if \tilde{z} free for \tilde{y} in P_2

Application of definitions:

$$A(\tilde{x}) \rightarrow P[\tilde{y} \mapsto \tilde{x}]$$
 if $A(\tilde{y}) \triangleq P$ in Δ , and \tilde{y} free for \tilde{x} in P

Context closure:

$$\frac{P \to P'}{\text{new } c:\rho. \ P \to \text{new } c:\rho. \ P'} \qquad \frac{P \to P'}{P \mid Q \to P' \mid Q}$$

Congruence closure:

$$\frac{P \equiv P' \quad P' \rightarrow Q' \quad Q \equiv Q'}{P \rightarrow Q}$$

Table 4.4: Reduction relation for a finite set of definitions Δ

of parallel composition, i.e. the order in $P_1|\dots|P_n$ does not matter, order independence of alternatives in sums, and scope extrusion. We also assume congruence of two processes that are α -convertible, i.e. one can be obtained from the other by renaming of bound names, without capturing free names. For a formal definition of α -conversion, we refer to Honda (1992).

Table 4.4 defines the reduction relation. The first axiom tells how to interpret choices; it comprises channel communication and pattern matching. It applies to two complementary matching alternatives in parallel choices, an output alternative $x!f(\tilde{y}).P_1$ willing to send a term $f(\tilde{y})$ and an input pattern $x!f(\tilde{z}).P_2$ on the same channel x; this pattern matches in that it is built using the same function symbol f. Reduction cancels all other alternatives, substitutes the pattern's variables \tilde{z} by the received channels \tilde{y} in the continuation P_2 of the input, and reduces the result in parallel with the continuation of the output P_1 .

Only matching tuples can be received over a channel. Other sending attempts suspend until a suitable input pattern becomes available. This fact proves extremely useful for concurrent modeling. Upon reception, tuples are immediately decomposed.

The application axiom unfolds one of the definitions of the parametric processes in a given set Δ . An application $A(\tilde{y})$ reduces in one step to definition P in which the formal parameters \tilde{y} were replaced by the actual parameters \tilde{x} . Parametric definitions may be recursive, e.g. A may occur in P. Reduction can be applied in arbitrary contexts, however not under choices or in definitions.

Syntactic sugar for polyadic input and output. The syntax of the stochastic π -calculus underling BioSpi is the same as ours, except for function names. We can express the constructs of BioSpi using dummy function names UNIT_i for all arities $i \geq 0$, and the following shortcuts for all sequences \tilde{y} of channel names of length i:

$$x?(\tilde{y}).P =_{\text{def}} x?(\text{UNIT}_i(\tilde{y})).P$$

 $x!(\tilde{y}).P =_{\text{def}} x!(\text{UNIT}_i(\tilde{y})).P$

Discussion on pattern matching. Input patterns as presented here are motivated by pattern matching in functional programming languages of the ML family. Pattern matching is the standard operation used there to decompose data structures containing value tuples.

In contrast, the input patterns presented here are closely tied to communication. A process can only receive tuples for which it provides a matching input pattern. Otherwise it refuses the communication offer, until it a change of state provides the required pattern.

Vasconcelos and Tokoro (1993) proposed input patterns for the asynchronous π -calculus ². They restrict sums to input patterns on the same channel $x?f_1(\tilde{y}_1) + \ldots + x?f_n(\tilde{y}_n)$. Outputs $x!f(\tilde{y})$.0 are asynchronous there; they have no continuation and cannot appear in proper sums. In our modeling work we will need mixed inputs and outputs, both over possibly different channels, all with their continuations.

Compared to the π -calculus with data terms of Baldamus, Parrow, and Victor (2005), the π -calculus presented here cannot pass arbitrary nested tuples around. One can only pass flat tuples $f(\tilde{y})$, and needs an f headed pattern in order to receive them.

Example. Semaphores control the access to shared resources in concurrent systems (Dijkstra, 1971). They are widespread in programming languages, operating systems, or distributed databases. A semaphore restricts the access to a resource to single user at a time. We consider simple semaphores with two states - free or bound. When free, they can become bound, and when bound they can become free. Importantly, a bound semaphore may not be bound a second time. Any binding attempt on a bound semaphore is suspended until the semaphore becomes free.

²Note that mutually recursive definitions were absent in the original proposal of Vasconcelos and Tokoro (1993) but have been added on the way to the distributed programming language TyCO (Paulino et al., 2003).

Consider the reduction sequence of the following process expression, of a bound semaphore, located at site s, in parallel with a bind request and a free request.

In a first step, the bound semaphore s unfolds its definition. This creates an input offer on s, able to receive a free message. Other messages cannot be received on s in this state, namely no bind requests. Hence, the site s cannot get bound a second time. Only after the free message was received, s is able to accept the next bind request, while becoming bound again.

4.2 Stochastic models

We recall foundations of continuous time Markov chains (CTMCs) with countably infinite state spaces. We then illustrate CTMCs for systems of chemical reaction rules.

4.2.1 Continuous time Markov chains (CTMCs)

We assume a countable set S called the *state space*. A continuous time stochastic process with states $q \in S$ is a family $\{X_t \mid t \in \mathbb{R}^+\}$ of random variables with values in S. These define probabilities $Pr(X_t \in S')$ for all subsets $S' \subseteq S$, i.e. the probability that the process is in some state of S' at time t.

A continuous time Markov chain (CTMC) is a continuous time stochastic process, with memoryless sojourn times for all states. More formally, a CTMC over S is a continuous time stochastic process $\{X_t \mid t \in \mathbb{R}^+\}$ with states in S, that satisfies the Markov property, i.e. for all $q_0, \ldots, q_{n+1} \in S$ and all time points $0 \le t_0 < \ldots < t_{n+1}$:

$$Pr(X_{t_{n+1}} = q_{n+1} \mid X_{t_n} = q_n, \dots, X_{t_0} = q_0) = Pr(X_{t_{n+1}} = q_{n+1} \mid X_{t_n} = q_n)$$

The probabilistic behavior of a CTMC is determined by the distribution of its initial states (at time 0) and its transition rates. The transition rate r from state q to state q' is a value that, according to Hermanns (2002), "scales as the (one step) transition probability between q and q' increases with time". We write $q \xrightarrow{r} q'$ in this case. For simplicity, we consider CTMCs with

a single initial state. These can be identified with a Markovian transition system $(S, (\xrightarrow{r})_{r \in R^+}, q_0)$ where $q_0 \in S$ is the initial state and $\xrightarrow{r} \subseteq S \times S$ are transition relations for all $r \in \mathbb{R}^+$, such that for all $q, q' \in S$ there exists at most one $r \in R^+$ satisfying $q \xrightarrow{r} q'$.

The stochastic time evolution of a CTMC can be computed by the first reaction method of Gillespie (1976) if each state permits only a finite number of transitions, as we assume in the sequel. At time 0 the process starts in state q_0 . Suppose that the process has moved to state q at time point t. Let $q \xrightarrow{r_i} q_i$ be all (finitely many) transitions starting in q. Draw delays $t_i > 0$ for all i from an exponential distribution with rate r_i . Draw with equal probability some j, with minimal t_j . Move to state q_j at time point $t + t_j$.

Gillespie's direct method equivalently³ determines the stochastic behavior of a CTMC. In state q at time t it first computes the delay until the next transition (called sojourn time), by drawing a number from the exponential distribution with rate $\downarrow s =_{\text{def}} \sum_{q \xrightarrow{r_i} q_i} r_i$. Next, we guess into which state to go. This can be done by drawing state q_j with probability $Pr(q \to q_j) =_{\text{def}} r_j / \sum_{q \xrightarrow{r'} q'} r'$ if $q \xrightarrow{r_j} q_j$ and 0 otherwise.

4.2.2 Chemical reactions

Systems of chemical reaction rules define CTMCs. This idea will guide our semantics. We start from a set of chemical species X, Y, Z and a set of chemical reaction rules of the following form⁴, where $r \in \mathbb{R}^+$:

$$X \mid Y \xrightarrow{r} Z_1 \mid \ldots \mid Z_k$$

Chemical solutions P are multisets of species, where each occurrence in the multiset represents a molecule of the species. Chemical rules as above apply as follows to a chemical solution P. Each pair of molecules of species X and Y can interact at rate r, yielding one molecule of each of the species Z_1, \ldots, Z_k . The solution obtained is $P - \{ \mid X, Y \mid \} \cup \{ \mid Z_1, \ldots, Z_k \mid \}$.

According to the *Chemical Law of Mass Action*, the speed of a chemical reaction in a solution is proportional to the number of possible interactions of its reactants in the solution. It is distributed exponentially, and defines a CTMC with the following transitions:

$$P \xrightarrow{n \cdot r} P - \{ \mid X, Y \mid \} \cup \{ \mid Z_1, \dots, Z_k \mid \}$$

³For proof, see Gillespie (1976).

⁴ The usual chemical notation would use the notation X + Y, while we reserve the + symbol as choice operator.

where

$$n = \begin{cases} \sharp(X \in P) \cdot \sharp(Y \in P) & \text{if } X \neq Y \\ 1/2 \cdot \sharp(X \in P) \cdot (\sharp(X \in P) - 1) & \text{else} \end{cases}$$

The above n corresponds to the number of distinct (X, Y) pairs. Note that a molecule may not react with itself.

4.3 Stochastic Semantics

We define the stochastic semantics of our π -calculus by associating a π -calculus process with a CTMC. The states of this Markov chain are the set of congruence classes of π -calculus processes with respect to the structural congruence. Note this set is countably infinite. The initial state for the CTMC of process P is the congruence class of $P_{/\equiv}$. What remains to be defined are the transition relations.

4.3.1 Transition relations

We first consider the fragment of the π -calculus without proper summation, parametric processes, infinite rates, and **new**-binders. The remaining processes are parallel compositions $C_1 \mid \ldots \mid C_n$. The structural congruence turns them into multisets of guarded processes, i.e. into chemical solutions whose species are guarded processes.

Suppose we know the rate functions $\varrho(x)$ for all channels x. The π -calculus with input patterns then defines the following chemical reaction rule:

$$x?f(\tilde{z}).Q_1 \mid x!f(\tilde{y}).Q_2 \xrightarrow{\varrho(x)(f)} Q_1[\tilde{z} \mapsto \tilde{y}] \mid Q_2$$

This defines a CTMC. For example, assume n molecules of a first species $x!f().P_1$ and m of another different one $x!f().P_2$, which all want to react with a single molecule of a third kind x?f().P. The Markovian transitions are:

$$|_{i=1}^{n} x! f().P_1 \mid |_{i=1}^{m} x! f().P_2 \mid x? f().P$$

$$n \cdot \rho(x)(f) \swarrow \qquad \qquad \searrow m \cdot \rho(x)(f)$$

$$|_{i=1}^{n-1} x! ().P_1 \mid |_{i=1}^{m} x! ().P_2 \mid P \qquad \qquad |_{i=1}^{n} x! ().A \mid |_{i=1}^{m-1} x! f().P_2 \mid P$$

The stochastic semantics for the general case is induced by the relations in Table 4.5. We define the transitions on arbitrary representations P of a congruence class that are prenex normal forms, in which bound variables are renamed apart. The rate function $\varrho(x)$ is then read off from the quantifier prefix in rule (NEW).

Labeled reduction steps

(APP)
$$\frac{P_{i_1} = A(\tilde{y}) \qquad A(\tilde{x}) \triangleq \mathbf{new} \ \widetilde{y:\rho}. \ Q \text{ in } \Delta }{|\underset{i=1}{^n} P_i \xrightarrow{\infty}_{i_1} \mathbf{new} \ \widetilde{y:\rho}. \ (Q[\tilde{x} \mapsto \tilde{y}] \mid |_{i=1,i\neq i_1}^n P_i)}$$
 where Q has no top-level \mathbf{new} -binders and $1 \leq i_1 \leq n$

(NEW)
$$\frac{P \xrightarrow{s} Q \qquad \varrho(x) = \rho}{\mathbf{new} \ \widetilde{x} : \rho. \ P \xrightarrow{s} \mathbf{new} \ \widetilde{x} : \rho. \ Q} \quad \text{where } s \in \mathbb{R}^+ \cup \{\infty\}, \ w \in \mathbb{N} \cup \mathbb{N}^4$$

Time consuming transitions $(r, r' \in \mathbb{R}^+, w \in \mathbb{N}^4)$

(SUM)
$$P \equiv P' \qquad r = \sum_{P' \xrightarrow{r'} Q' \equiv Q} r' \neq 0 \qquad \neg \exists R \exists w' \in \mathbb{N} \cup \mathbb{N}^4. \ P' \xrightarrow{\infty} R$$
$$P \xrightarrow{r} Q$$

Immediate transitions

(COUNT)
$$P \equiv P' \qquad n = \sharp \{w \in \mathbb{N} \cup \mathbb{N}^4 \mid P' \xrightarrow{\infty}_{w} Q' \equiv Q\} \neq 0$$
$$m = \sharp \{w \in \mathbb{N} \cup \mathbb{N}^4 \mid P' \xrightarrow{\infty}_{w} Q''\}$$
$$P \xrightarrow{\infty(n/m)} Q$$

Table 4.5: Timed transitions of the π -calculus with input patterns with respect to a set Δ of definitions in prenex normal form, and a global assignment ρ of channels to rate functions.

Time consuming transitions. We first discuss non-immediate transitions $P \xrightarrow{r} P'$ where $r \in \mathbb{R}^+$. These capture everything, except parametric process unfolding and invocation of functions of rate ∞ .

What remains from prenex normal forms after removing top-level **new**-binders are multisets of sums and applications. All applications must have been reduced before time consuming transitions apply, so we have a multiset of sums. Each sum is like a molecule, except that each of its choices offers

its own interactions.

In $x?f().\mathbf{0} + x?f().\mathbf{0} \mid x!f().\mathbf{0}$ for instance, there are two possible interactions with rate $\varrho(x)(f)$ leading to the same state. We can think of $x?f().\mathbf{0} + x?f().\mathbf{0}$ as a protein with two identical domains, complementary to one domain of some other protein represented by $x!f().\mathbf{0}$. The overall rate of the interaction thus doubles. Let $r = \varrho(x)(f)$:

$$x?f() \cdot 0 + x?f() \cdot 0 \mid x!f() \cdot 0 \xrightarrow{r} 0$$

 $x?f() \cdot 0 + x?f() \cdot 0 \mid x!f() \cdot 0 \xrightarrow{r} 0$

sums up to

$$x?f().0 + x?f().0 \mid x!f().0 \xrightarrow{2r} 0$$

Rule (COM) defines labeled reductions $P \xrightarrow[i_1,j_1,i_2,j_2]{r} Q$ that distinguishes communication actions with identical reactants and results, while using different occurrences of choice alternatives in sums. Those occurrences are identified by labels in \mathbb{N}^4 that specify the numbers of the reacting sums (i_1,i_2) and the reacting choices (j_1,j_2) . Rule (SUM) defines transitions $P \xrightarrow{r} Q$ by summing up all rates of all different interactions leading from P to Q. These relations are defined carefully, so that corresponding interactions in structurally congruent processes are not counted twice.

Immediate transitions. The stochastic semantics distinguishes time consuming transitions $P \xrightarrow{r} Q$ where $r \in \mathbb{R}^+$ from immediate ones $P \xrightarrow{\infty(p)} Q$, where $p \in [0, 1]$ is a probability. Rule (SUM) ensures that time consuming transitions apply only after all immediate have been reduced. In this case, all calls $A(\tilde{y})$ on top level must have been reduced before.

Immediate transitions can be licensed by communication (COM), or by applications of parametric process definitions (APP). Their labels are in $\mathbb{N} \cup \mathbb{N}^4$. The labeled reduction is independent of the choice of the prenex normal form.

Lemma 1 Let P and P' be in prenex normal form and $s \in \mathbb{R}^+ \cup \{\infty\}$. If $P \equiv P'$ and $P \xrightarrow[w]{s} Q$, then there exist $Q' \equiv Q$ and w' such that $P' \xrightarrow[w']{s} Q'$.

Proof. Straightforward.

We merge labeled immediate transitions with rule (COUNT). Although being immediate we want to associate probabilities, which characterize the number of immediate interactions leading to a common state with respect to the total number of enabled immediate interactions. For instance, let $\varrho(x)(f) = \infty$, in $x?f().P + x?f().P \mid x?f().Q \mid x!f().\mathbf{0}$ for some $P \not\equiv Q$. The associated probabilities reflect that 2 of 3 interactions lead to P, and 1 of 3 to Q:

$$x?f().P + x?f().P \mid x?f().Q \mid x!f().\mathbf{0} \xrightarrow{\infty(2/3)} P$$

 $x?f().P + x?f().P \mid x?f().Q \mid x!f().\mathbf{0} \xrightarrow{\infty(1/3)} Q$

Lemma 2 The following properties hold:

1.
$$\equiv \circ \xrightarrow{r} \circ \equiv \subset \xrightarrow{r}$$
,

$$2. \equiv \circ \xrightarrow{\infty(p)} \circ \equiv \subset \xrightarrow{\infty(p)},$$

3. if
$$P \xrightarrow{r} Q$$
 and $P \xrightarrow{r'} Q$ then $r = r'$,

4. if
$$P \xrightarrow{\infty(p_1)} Q$$
 and $P \xrightarrow{\infty(p_2)} Q$ then $p_1 = p_2$, and

5. for all
$$P: \sum_{P \xrightarrow{\infty(p)} Q} p = 1$$
.

Proof.

- 1. Let $P \equiv \circ \xrightarrow{r} \circ \equiv Q$, then there are P' and Q' such that $P \equiv P'$, $P' \xrightarrow{r} Q'$ and $Q' \equiv Q$. Since $P' \xrightarrow{r} Q'$ is necessarily inferred by (SUM), there is $P'' \equiv P'$ (1) such that $r = \sum_{P'' \xrightarrow{r'} Q'' \equiv Q'} r' \neq 0$ (2), and $\neg \exists R \exists w' \in \mathbb{N} \cup \mathbb{N}^4 . P'' \xrightarrow{\infty} R$ (3). From $P' \equiv P$ and (1), we have $P \equiv P''$ (1'), and by $Q' \equiv Q$ and (2) we have $r = \sum_{P'' \xrightarrow{r'} Q'' \equiv Q} r' \neq 0$ (2'). Then, by (1'), (2'), (3) and by (SUM), we conclude $P \xrightarrow{r} Q$.
- 2. Similar to the previous point, by rule (COUNT) and Lemma 1.
- 3. Suppose that $P \xrightarrow{r} Q$ and $P \xrightarrow{r'} Q$, then by rule (SUM), there are P_1 and P_2 such that $P_1 \equiv P \equiv P_2$ and $r = \sum_{P_1 \xrightarrow{r_1} Q_1 \equiv Q} r_1$ and $r' = \sum_{P_2 \xrightarrow{r_2} Q_2 \equiv Q} r_2$. However, by Lemma 1, there is $Q_1 \equiv Q$ such that $P_1 \xrightarrow{r} Q_1$ iff there is $Q_2 \equiv Q$ such that $P_2 \xrightarrow{r} Q_2$. Therefore, r = r'.
- 4. Similar to the previous point, using Lemma 1.

5. Assume, without loss of generality, that P is in prenex normal form. Let $\{Q_1,\ldots,Q_k\}$ be the set (up-to \equiv) of the possible (immediate) derivatives of P, that is satisfying $\forall i \in \{1,\ldots,k\}$ $P \xrightarrow{\infty(p_i)} Q_i$ and $i \neq j \Rightarrow Q_i \not\equiv Q_j$. Let $X = \{w \in \mathbb{N} \cup \mathbb{N}^4 \mid P \xrightarrow{\infty} Q''\}$ and $Y_i = \{w \in \mathbb{N} \cup \mathbb{N}^4 \mid P \xrightarrow{w} Q' \equiv Q_i\}$. It is clear that, $i \neq j \Rightarrow Y_i \cap Y_j = \emptyset$ (since $Q_i \not\equiv Q_j$) and $\bigcup_{1 \leq i \leq k} Y_i = X$. Therefore $\sum_{1 \leq i \leq k} \sharp Y_i = \sharp X$, and, since $p_i = \sharp Y_i/\sharp X$, $\sum_{1 \leq i \leq k} p_i = 1$.

4.3.2 CTMCs with immediate reactions

In the presence of immediate transitions, CTMCs with transitions $P \xrightarrow{r} Q$ alone do not capture the dynamics of π -calculus processes. Instead, we define sojourn times and the probabilities of state changes for all P, Q as follows:

$$\downarrow P = \begin{cases}
\infty & \text{if } P \xrightarrow{\infty(p)} Q, \\
\sum_{P \xrightarrow{r} Q} r & \text{otherwise.}
\end{cases}$$

$$Pr(P \to Q) = \begin{cases}
r/\sum_{P \xrightarrow{r'} Q'} r' & \text{if } P \xrightarrow{r} Q \\
p & \text{if } P \xrightarrow{\infty(p)} Q \\
0 & \text{otherwise.}
\end{cases}$$

We assume that a random variable X with exponential distribution of parameter ∞ is such that Pr(X=0)=1. We also define the probability of a sequence of reductions as: $Pr(Q_1 \to \cdots \to Q_n) = \prod_{1 \le i < n} Pr(Q_i \to Q_{i+1})$

We are now giving an interpretation of the reduction semantics with immediate transitions in terms of CTMCs for processes that can not exhibit infinite sequences of immediate transitions. Its transitions $P \stackrel{r}{\Longrightarrow} Q$ are defined in Table 4.6. The idea is quite similar to that of Bernardo et al. (1994): the transitions are obtained by integrating immediate transitions into time consuming transitions. An example for this transformation is as follows:

$$P \left\{ \begin{array}{ccc} \xrightarrow{r_1} & Q_1 \not\xrightarrow{\infty} & & \\ \frac{r_2}{\longrightarrow} & Q_2 \left\{ \begin{array}{ccc} \xrightarrow{\infty(p)} & Q_{21} \not\xrightarrow{\infty} & & \\ \frac{\infty(1-p)}{\longrightarrow} & Q_{22} \not\xrightarrow{\infty} & & \end{array} \right. & \text{becomes} & P \left\{ \begin{array}{ccc} \xrightarrow{r_1} & Q_1 \\ \xrightarrow{r_2 \cdot p} & Q_{21} \\ \xrightarrow{r_2 \cdot (1-p)} & Q_{22} \xrightarrow{\infty} & & \end{array} \right.$$

In general, a sequence of reductions $P \xrightarrow{r} P_1 \xrightarrow{\infty(p_1)} \dots P_n \xrightarrow{\infty(p_n)} Q \xrightarrow{p}$ reduces to $P \xrightarrow{p_1 \cdot \dots \cdot p_n \cdot r} Q$. However, we must beware of merging initially distinct

$$(\text{ELIM}_{1}) \quad \frac{P \xrightarrow{\infty} Q}{w} \quad n = \sharp \{w' \in \mathbb{N} \cup \mathbb{N}^{4} \mid P \xrightarrow{\infty} Q'\} \\ P \xrightarrow{\infty(1/n)} Q \\ (\text{ELIM}_{2}) \quad \frac{P \xrightarrow{r} Q}{w} \quad Q \xrightarrow{\infty(p_{1})} \dots \xrightarrow{\infty(p_{n})} Q_{n} \xrightarrow{\infty} \\ P \xrightarrow{p_{1} \dots p_{n} \cdot r} Q_{n} \\ (\text{ELIM}^{\text{sum}}) \quad P \equiv P' \qquad r = \sum_{P' \xrightarrow{r'} w_{1} \dots w_{n}} Q' \equiv Q \xrightarrow{r'} \\ P \xrightarrow{p} Q$$

Table 4.6: Elimination of immediate transitions and merging timed transitions

states. Indeed, in the previous example, if $Q_{22} \equiv Q_1$ then the CTMC should have transitions $P \stackrel{r_1+(1-p)r_2}{\Longrightarrow} Q_1$ and $P \stackrel{pr_2}{\Longrightarrow} Q_{21}$. In order to infer these transitions correctly, the elimination procedure defines labeled transitions $\stackrel{r}{\Longrightarrow}$ with labels $w \in (\mathbb{N} \cup \mathbb{N}^4)^*$ representing paths in the labeled derivation trees of $\stackrel{r}{\to}$.

Lemma 3 Let P and P' be in prenex normal form. If $P \equiv P'$ and $P \stackrel{r}{\Longrightarrow} Q$ (resp. $P \stackrel{\infty(p)}{\Longrightarrow} Q$), then there exists $Q' \equiv Q$ and w' such that $P' \stackrel{r}{\Longrightarrow} Q'$ (resp. $P' \stackrel{\infty(p)}{\Longrightarrow} Q'$).

Proof.

- 1. Suppose that $P \xrightarrow[w]{\infty(p)} Q$, by rule (ELIM₁), we have $P \xrightarrow[w]{\infty} Q$ and $p = 1/\sharp\{w_0 \in \mathbb{N} \cup \mathbb{N}^4 \mid P \xrightarrow[w_0]{\infty} R\}$. By Lemma 1, there exist w' and $Q' \equiv Q$ such that $P' \xrightarrow[w']{\infty} Q'$ and $\sharp\{w_0 \in \mathbb{N} \cup \mathbb{N}^4 \mid P \xrightarrow[w_0]{\infty} R\} = \sharp\{w'_0 \in \mathbb{N} \cup \mathbb{N}^4 \mid P \xrightarrow[w']{\infty} Q'\}$. Therefore, by (ELIM₁), we have $P' \xrightarrow[w']{\infty(p)} Q'$.
- 2. Suppose that $P \stackrel{r}{\Longrightarrow} Q$, by rule (ELIM₂), we have $P \stackrel{r_0}{\Longrightarrow} Q_0$ and $Q_0 \stackrel{\infty(p_1)}{\Longrightarrow} \cdots \stackrel{\infty(p_n)}{\Longrightarrow} Q_n = Q \stackrel{\infty}{\Longrightarrow} \text{were } r = p_1 \cdot \ldots \cdot p_n \cdot r_0$ and $w = w_0 w_1 \ldots w_n$. By Lemma 1, there exists $Q_0' \equiv Q_0$ such that

 $P' \xrightarrow{v_0} Q'_0$. Q'_0 is necessarily in prenex normal form, thus, by Lemma 1, there are $Q'_1 \equiv Q_1, \dots Q'_n = Q' \equiv Q$ all in prenex normal form such that $Q'_0 \xrightarrow{\infty(p_1)} \cdots \xrightarrow{\infty(p_n)} Q'_n \xrightarrow{\mathscr{P}}$. Therefore, by rule (ELIM₂), $P' \xrightarrow{r} Q' \equiv Q$ were $w' = w'_0 w'_1 \dots w'_n$.

Lemma 4 $\equiv \circ \xrightarrow{r} \circ \equiv \subseteq \xrightarrow{r}$ and if $P \xrightarrow{r} Q$ and $P \xrightarrow{r'} Q$ then r = r'.

Proof. Similar to the proof of Lemma 2 using Lemma 3.

Thus, for any P, such that $P \xrightarrow{\infty}$, $(\mathscr{P}_{/\equiv}, (\stackrel{r}{\Longrightarrow})_{r \in \mathbb{R}^+}, P_{/\equiv})$ is a Markovian transition system⁵ with sojourn time parameters and transition probabilities:

$$\Downarrow P = \sum_{P \xrightarrow{r} Q} r \quad \text{and} \quad Pr(P \Rightarrow Q) = \begin{cases} r/\sum_{P \xrightarrow{r'} Q'} r' & \text{if } P \xrightarrow{r} Q \\ 0 & \text{otherwise} \end{cases}$$

In order to show that this defines a Markovian model for the reduction semantics with immediate transitions, we show that the sojourn time parameters and the transition probabilities with respect to both $\stackrel{r}{\rightarrow}$ and $\stackrel{r}{\Longrightarrow}$ are identical. Since we are only interested in processes performing timed transitions (that is processes P such that $P \stackrel{\sim}{\nearrow}$), we define a suitable transition probability $Pr(P \twoheadrightarrow Q)$ for $P \stackrel{\sim}{\nearrow}$ and $Q \stackrel{\sim}{\nearrow}$, that is the probability to reach Q from P by a sequence of transitions made of one timed transition and possibly several intermediate immediate transitions. Formally, $Pr(P \twoheadrightarrow Q)$ is the sum of the probabilities of all such sequences:

$$Pr(P \to Q) = \sum_{P \xrightarrow{r} Q_1 \xrightarrow{\infty(p_1)} \dots Q_n \xrightarrow{\infty(p_n)} Q \xrightarrow{\infty}} Pr(P \to Q_1 \to \dots Q_n \to Q)$$

Theorem 1 If $P \not\xrightarrow{\sim}$ and if no infinite sequence of immediate transitions is reachable from P, then

- (Timed correctness) $\downarrow P = \Downarrow P$,
- (Probabilistic correctness) $Pr(P \rightarrow Q) = Pr(P \Rightarrow Q)$.

⁵For $P \xrightarrow{\infty}$ it suffices to start with a process $Q = x!f().\mathbf{0} \mid x?f().P$ such that $\varrho(x)(f) = 1$ in order to obtain a set of initial processes together with an initial probability distribution of those processes rather than a single initial process.

Proof.

• Timed correctness. First, note that for any P we have $\sum_{P \xrightarrow{w(p)} Q} p = 1.$ In order to show that $\downarrow P = \Downarrow P$, it is sufficient, by rules (SUM) and (ELIM^{sum}) to show that

$$\sum_{P \xrightarrow{r}_{w} Q} r = \sum_{P \xrightarrow{w} Q} r \tag{4.3.1}$$

We denote $P \xrightarrow[w]{\infty(p)}^n Q$ iff $m \leq n$ is the largest integer, such that there exists a sequence $P \xrightarrow[w_0]{\infty(p_1)} Q_1 \dots \xrightarrow[w_m]{\infty(p_m)} Q_m = Q$ and such that $p = p_1 \cdot \dots \cdot p_m$ and $w = w_1 \dots w_m$. It is clear that $P \xrightarrow[w]{r} Q$ iff $P \xrightarrow[w_0]{r'} Q \xrightarrow[w']{r} Q = 1$. Let n_0 be an integer such that for any P, Q and $n \geq n_0$, we have $P \xrightarrow[w']{r} Q$ iff $P \xrightarrow[w']{r} Q$. To prove 4.3.1, we essentially need to show that if $P \xrightarrow[w_0]{r} Q$, then for $w_1, \dots, w_k \in (\mathbb{N} \cup \mathbb{N}^4)^*$ and Q_1, \dots, Q_k be such that $w_i's$ are pairwise distinct and $P \xrightarrow[w_0]{r} Q_i$, then $\sum_{1 \leq i \leq k} r_i = r$. Indeed, we have $P \xrightarrow[w_0]{r} Q_i \xrightarrow[w_0]$

• Probabilistic correctness. For any P, $\sum_{P \stackrel{r'}{\Longrightarrow} Q} r' = \sum_{P \stackrel{r'}{\longrightarrow} Q} r'$ (1). We have $P \xrightarrow{\infty(p)} Q$, iff $\sum_{P \stackrel{p'}{\longrightarrow} Q' \equiv Q} p' = p$ (2). For any P and Q we have:

$$Pr(P \xrightarrow{r} Q_1 \xrightarrow{\infty(p_1)} \dots Q_n \xrightarrow{\infty(p_n)} Q_{n+1} \equiv Q \xrightarrow{\infty})$$

$$= (\sum_{P \xrightarrow{r'} Q'} r')^{-1} (r \cdot p_1 \cdot \dots \cdot p_n)$$

$$= (\sum_{P \xrightarrow{r'} Q'} r')^{-1} (r \cdot p_1 \cdot \dots \cdot p_n) \qquad \text{by (1)}$$

$$= (\sum_{P \xrightarrow{r'} Q'} r')^{-1} ((\sum_{P \xrightarrow{r'} Q' \equiv Q_1} r') \cdot \prod_{1 \le i \le n} \sum_{Q_i \xrightarrow{\infty(p_i)} Q' \equiv Q_{i+1}} p_i) \quad \text{by (2)}$$

$$= (\sum_{P \xrightarrow{r'} Q'} r')^{-1} (\sum_{P \xrightarrow{w_0} Q'_1 \xrightarrow{\infty(p_1)} \dots \xrightarrow{\infty(p_n)} Q'_{n+1} \equiv Q} r_0 \cdot p_1 \cdot \dots \cdot p_n)$$

$$= (\sum_{P \xrightarrow{r'} Q'} r')^{-1} (\sum_{P \xrightarrow{r'} Q} r')$$

Therefore, $Pr(P \rightarrow Q) = Pr(P \Rightarrow Q)$.

```
[\![x?f(\tilde{y}).P]\!] = x_f?(\tilde{y}_{\mathscr{F}}).[\![P]\!]
[\![P_1 \mid P_2]\!] = [\![P_1]\!] \mid [\![P_2]\!]
[\![x!f(\tilde{y}).P]\!] = x_f!(\tilde{y}_{\mathscr{F}}).[\![P]\!]
[\![\mathbf{new}\ x:\rho.\ P]\!] = \mathbf{new}\ x_{f_1}:\rho(f_1).\dots\mathbf{new}\ x_{f_n}:\rho(f_n).\ [\![P]\!]
[\![C_1 + \dots + C_n]\!] = [\![C_1]\!] + \dots + [\![C_n]\!]
[\![A(\tilde{y})]\!] = A(\tilde{y}_{\mathscr{F}})
[\![A(\tilde{x}) \triangleq P]\!] = A(\tilde{x}_{\mathscr{F}}) \triangleq [\![P]\!]
```

Table 4.7: Encoding of input patterns

4.4 Encoding input patterns

We now encode our π -calculus with input patterns back into the stochastic π -calculus. The latter can be identified as the special case with a unique function name per arity (we assume arities bounded by some max): $\mathscr{F}' = \{\text{UNIT}_i \mid 0 \le i \le max\}$. In what follows, we write UNIT instead of UNIT_i.

4.4.1 Translation

We assume a total ordering < on a finite set of function names \mathscr{F} . This means that \mathscr{F} has a unique representation $\mathscr{F} = \{f_1, \ldots, f_n\}$ with $f_1 < \ldots < f_n$. Our encoding uses channels names from the set $\mathscr{N} \times \mathscr{F}$. We denote elements (x, f) of this set by x_f . For each channel x we define a sequence of n channels $x_F uns$ as follows: $x_{\mathscr{F}} = x_{f_1}, \ldots, x_{f_n}$. Channels in the target language are associated a rate (that may be infinite) by means of the encoding of ϱ defined as $[\![\varrho]\!](x_f) = \varrho(x)(f)$. We write \tilde{x}, \tilde{y} for the concatenation of two sequences \tilde{x} and \tilde{y} . If $\tilde{x} = x_1, \ldots, x_n$ then we let $\tilde{x}_{\mathscr{F}} = x_{1\mathscr{F}}, \ldots, x_{n\mathscr{F}}$. The encoding is stated in Table 4.7.

Lemma 5 For all process P, P' with functions in \mathscr{F} and variables sequences \tilde{y}, \tilde{z} of the same length:

- 1. \tilde{y} is free for \tilde{z} in P if and only if $\tilde{y}_{\mathscr{F}}$ is free for $\tilde{z}_{\mathscr{F}}$ in $[\![P]\!]$.
- 2. $\llbracket P[\tilde{y} \mapsto \tilde{z}] \rrbracket = \llbracket P \rrbracket [\tilde{y}_{\mathscr{F}} \mapsto \tilde{z}_{\mathscr{F}}]$
- 3. If $[P] \equiv Q$ then there exists $R \in [Q]^{-1}$ such that $P \equiv Q$.

- 4. $P \equiv P'$ if and only if $\llbracket P \rrbracket \equiv \llbracket P' \rrbracket$.
- 5. P is in prenex normal form iff $\llbracket P \rrbracket$ is.

Proof.

- 1. By induction on the definition of freeness conditions.
- 2. By induction on the structure of P. Note that the lemma may fail for processes P with function symbols outside \mathscr{F} . As a counter example let $\mathscr{F} = \emptyset$ and consider $x ? f().\mathbf{0}[x \mapsto y]$
- 3. By induction on the structure of P.
- 4. By induction on derivations of $P \equiv P'$ resp. $[\![P]\!] \equiv [\![P']\!]$.
- 5. By induction on the structure of P.

The following theorem shows the correctness of our encoding. It allows us to run simulations of models expressed in our π -calculus with objects, via an implementation of the original stochastic π -calculus, as implemented in the SPiM system of Phillips and Cardelli (2006).

Theorem 2 The encoding defines a stochastic bisimulation: for all processes P, Q and finite sets of definitions Δ , and all rates $s \in \mathbb{R}^+ \cup \{\infty(p) \mid p \in]0, 1]\}$ it holds that $P \stackrel{s}{\to} Q$ relative to Δ if and only if $P \stackrel{s}{\to} Q$ relative to Δ .

The statement $P \xrightarrow{s} Q$ relative to Δ means that there exists some function $\varrho : \mathscr{N} \to \mathscr{F} \to (\mathbb{R}^+ \cup \{\infty\})$ such that $P \xrightarrow{s} Q$ relative to Δ and ϱ . The values $\varrho(x)$ will be the rate ρ assigned to x in the declaration (**new** $x : \rho$). It holds for all ρ and x that $\varrho(x) = \rho$ iff $[\![\varrho]\!](x_f) = \rho(f)$ for all $f \in \mathscr{F}$.

The statement $\llbracket P \rrbracket \xrightarrow{s} \llbracket Q \rrbracket$ relative to $\llbracket \Delta \rrbracket$ means that there exists some function $\varrho': \{x_f \mid f \in \mathscr{F}, x \in \mathscr{N}\} \to (\mathbb{R}^+ \cup \{\infty\})$ such that $\llbracket P \rrbracket \xrightarrow{s} \llbracket Q \rrbracket$ relative to $\llbracket \Delta \rrbracket$ and ϱ' . The situation differs in that there exists only a single function UNIT for all arities. Here, we are a little sloppy, in that we identify a constant function with its constant value, i.e., $\varrho'(x_f) = \varrho'(x_f)$ (UNIT).

4.4.2 Correctness proof

We prove a slightly stronger proposition than Theorem 2. We define a translation of functions $\varrho : \mathscr{N} \to \mathscr{F} \to (\mathbb{R}^+ \cup \{\infty\})$ to functions $\llbracket \varrho \rrbracket : \{x_f \mid f \in \mathscr{F}, x \in \mathscr{N}\}$ such that for all $x \in \mathscr{N}$ and $f \in \mathscr{F}$:

$$\llbracket \varrho \rrbracket(x_f) = \varrho(x)(f)$$

The translation is onto, i.e for all $\varrho': \{x_f \mid f \in \mathscr{F}, x \in \mathscr{N}\} \to (\mathbb{R}^+ \cup \{\infty\})$ there exists some $\varrho: \mathscr{N} \to \mathscr{F} \to (\mathbb{R}^+ \cup \{\infty\})$ such that $\varrho' = \llbracket \varrho \rrbracket$. Hence, the theorem follows if from the following proposition:

Proposition 1 $P \xrightarrow{s} Q$ with respect to Δ and ϱ iff $\llbracket P \rrbracket \xrightarrow{s} \llbracket Q \rrbracket$ with respect to $\llbracket \Delta \rrbracket$ and $\llbracket \varrho \rrbracket$.

We need some auxiliary lemmas, before we can show the proposition for infinite rates in Lemma 9 and for finite rates in Lemma 10. All of these Lemmas hold for all processes P, Q, Q' and definitions Δ with functions in \mathscr{F} , rates $s \in \mathbb{R}^+ \cup \{\infty\}$ or $r \in \mathbb{R}^+$, functions ϱ , labels $w \in \mathbb{N} \cup \mathbb{N}^4$, and probabilities $\varrho \in [0, 1]$. For convenience, we define

$$[\![\mathbf{new}\ y_1:\rho_1.\ \dots\ \mathbf{new}\ y_n:\rho_n]\!] = [\![\mathbf{new}\ y_1:\rho_1]\!]\dots[\![\mathbf{new}\ y_n:\rho_n]\!]$$
$$[\![\mathbf{new}\ y:\rho]\!] = \mathbf{new}\ y_{f_1}:\rho(f_1).\ \dots\ \mathbf{new}\ y_{f_n}:\rho(f_n).$$

Lemma 6 If $P \xrightarrow{s}_{w} Q$ with respect to Δ and ϱ then $\llbracket P \rrbracket \xrightarrow{s}_{w} \llbracket Q \rrbracket$ with respect to $\llbracket \Delta \rrbracket$ and $\llbracket \varrho \rrbracket$.

Proof. By rule induction. We need to consider the three rules (NEW), (APP), and (COM) by which to infer $P \xrightarrow{s} Q$.

• Rule (NEW). Suppose that **new** $x:\rho$. $P \xrightarrow[w]{s}$ **new** $x:\rho$. Q is inferred as follows:

$$\frac{P \xrightarrow{s} Q \qquad \varrho(x) = \rho}{\text{new } x : \rho. \ P \xrightarrow{s} \text{new } x : \rho. \ Q}$$

The induction hypothesis yields that $\llbracket P \rrbracket \xrightarrow{r} \llbracket Q \rrbracket$. As argued above, $\varrho(x) = \rho$ is equivalent to that $\llbracket \varrho \rrbracket(x_f) = \rho(f)$ for all $f \in \mathscr{F}$. We can thus infer $\llbracket \mathbf{new} \ x : \rho$. $P \rrbracket \xrightarrow{r} \llbracket \mathbf{new} \ x : \rho$. $Q \rrbracket$ by applying the (NEW) rule in an iterative manner:

$$\frac{\llbracket P \rrbracket \xrightarrow{s} \llbracket Q \rrbracket \qquad \varrho(x_{f_1}) = \llbracket \rho \rrbracket(f_1) \qquad \dots \qquad \llbracket \varrho \rrbracket(x_{f_n}) = \rho(f_n)}{\mathbf{new} \ x_{f_1} : \rho(f_1) \dots \mathbf{new} \ x_{f_n} : \rho(f_n) . \ \llbracket P \rrbracket \xrightarrow{s}_{w}} \\
\mathbf{new} \ x_{f_1} : \rho(f_1) \dots \mathbf{new} \ x_{f_n} : \rho(f_n) . \ \llbracket Q \rrbracket$$

• Rule (APP). In this case, the judgment has been derived as follows:

$$\frac{P_{i_1} = A(\tilde{y}) \qquad A(\tilde{x}) \triangleq \mathbf{new} \ \widetilde{y:\rho}. \ Q \text{ in } \Delta}{|\underset{i=1}{\overset{n}{\longrightarrow}} P_i \xrightarrow{\overset{\infty}{\longrightarrow}} \mathbf{new} \ \widetilde{y:\rho}. \ (Q[\tilde{x} \mapsto \tilde{y}] \mid |\underset{i=1, i \neq i_1}{\overset{n}{\longrightarrow}} P_i)}$$

By translation the following rule instance applies too:

$$\frac{\llbracket P_{i_1} \rrbracket = A(\widetilde{y}_{\mathscr{F}}) \qquad A(\widetilde{x}_{\mathscr{F}}) \triangleq \llbracket \mathbf{new} \ \widetilde{y} : \rho. \ Q \rrbracket \ \text{in} \ \llbracket \Delta \rrbracket}{|\underset{i=1}{\overset{n}{\longrightarrow}} \llbracket P_i \rrbracket \ \xrightarrow{\underset{i_1}{\longrightarrow}} \llbracket \mathbf{new} \ \widetilde{y} : \rho \rrbracket \ (\llbracket Q \rrbracket [\widetilde{x}_{\mathscr{F}} \mapsto \widetilde{y}_{\mathscr{F}}] \ | \ |_{i=1, i \neq i_1}^{n} \llbracket P_i \rrbracket)}$$

By Lemma 5, this is $[\![|_{i=1}^n P_i]\!] \xrightarrow{\infty} [\![\mathbf{new}\ \widetilde{y:\rho}.\ (Q[\widetilde{x} \mapsto \widetilde{y}] \mid |_{i=1,i\neq i_1}^n P_i)]\!].$

• rule (COM). The judgment has thus been inferred by an application of the communication rule:

$$\frac{C_{i_1}^{j_1} = x? f(\tilde{z}).\mathbf{new} \ \widetilde{x_1:\rho_1}. \ Q_1 \qquad C_{i_2}^{j_2} = x! f(\tilde{y}).\mathbf{new} \ \widetilde{x_2:\rho_2}. \ Q_2 }{ |_{i=1}^n +_{j=1}^{m_i} C_i^j \ \frac{\varrho(x)(f)}{i_1,j_1,i_2,j_2}} \left\{ \begin{array}{l} \mathbf{new} \ \widetilde{x_1:\rho_1}. \ \mathbf{new} \ \widetilde{x_2:\rho_2}. \\ (Q_1[\tilde{z} \mapsto \tilde{y}] \ | \ Q_2 \ | \ |_{i=1,i \neq i_1,i_2}^n +_{j=1}^{m_i} C_i^j) \end{array} \right.$$

We can then apply the communication rule as follows too:

Lemma 7 If $[\![P]\!] \xrightarrow{s}_w Q'$ with respect to $[\![\Delta]\!]$ and $[\![\varrho]\!]$ then exists $Q \in [\![Q']\!]^{-1}$ such that $P \xrightarrow{s}_w Q$ with respect to Δ and ϱ .

Proof. By rule induction. We need to consider the three rules (NEW), (APP), and (COM) by which to infer $[\![P]\!] \xrightarrow{s}_{w} Q'$ with respect to $[\![\Delta]\!]$ and $[\![\varrho]\!]$.

• Rule (NEW). In this case, the above judgment be inferred as follows:

$$\frac{\llbracket P_1 \rrbracket \xrightarrow{s} Q_1' \qquad \llbracket \varrho \rrbracket(x_{f_1}) = \rho(f_1) \qquad \dots \qquad \llbracket \varrho \rrbracket(x_{f_n}) = \rho(f_n)}{\llbracket P \rrbracket = \mathbf{new} \ x_{f_1} : \rho(f_1) \dots \mathbf{new} \ x_{f_n} : \rho(f_n) . \ \llbracket P_1 \rrbracket \xrightarrow{s}_{w}}$$

$$Q' = \mathbf{new} \ x_{f_1} : \rho(f_1) \dots \mathbf{new} \ x_{f_n} : \rho(f_n) . \ Q_1'$$

By induction hypothesis, there exists $Q_1 \in [\![Q_1']\!]^{-1}$ such that $P_1 \xrightarrow{s} Q_1$ with respect to Δ and ϱ . The hypotheses of the rule yield $\varrho(x) = \varrho$. We can thus apply the (NEW) rule as follows:

$$\frac{P_1 \xrightarrow{s} Q_1 \qquad \varrho(x) = \rho}{\text{new } x : \rho. \ P_1 \xrightarrow{s} \text{new } x : \rho. \ Q_1}$$

Lemma 6 shows that $[\![\mathbf{new}\ x:\rho.\ P_1]\!] \xrightarrow[w]{s} [\![\mathbf{new}\ x:\rho.\ Q_1]\!]$. This is equivalent to:

$$\llbracket P \rrbracket \xrightarrow{s} \mathbf{new} x_{f_1} : \rho(f_1). \dots \mathbf{new} x_{f_n} : \rho(f_n). \llbracket Q_1 \rrbracket = Q'$$

• Rule (APP). The judgment has in this case been inferred as follows:

$$\frac{\llbracket P_{i_1} \rrbracket = A(\tilde{y}_{\mathscr{F}}) \qquad A(\tilde{x}_{\mathscr{F}}) \triangleq \llbracket \mathbf{new} \ \widetilde{y} : \widetilde{\rho}. \ Q_1 \rrbracket \ \text{in} \ \llbracket \Delta \rrbracket}{\llbracket P \rrbracket = \mid_{i=1}^n \llbracket P_i \rrbracket \ \xrightarrow[i_1]{\infty} \ Q' = \llbracket \mathbf{new} \ \widetilde{y} : \widetilde{\rho} \rrbracket \ (\llbracket Q_1 \rrbracket [\tilde{x}_{\mathscr{F}} \mapsto \tilde{y}_{\mathscr{F}}] \mid \mid_{i=1, i \neq i_1}^n \llbracket P_i \rrbracket)}$$

By Lemma 5, we have $[\![Q_1]\!][\tilde{x}_{\mathscr{F}} \mapsto \tilde{y}_{\mathscr{F}}] = [\![Q_1[\tilde{x} \mapsto \tilde{y}]\!]]$. Hence, $Q' = [\![Q]\!]$ where $Q = \mathbf{new} \ \widetilde{y} : \rho$. $(Q_1[\tilde{x} \mapsto \tilde{y}] \mid |_{i=1, i \neq i_1}^n P_i)$. Furthermore, we can infer $P \xrightarrow[i_1]{\infty} Q$ as follows:

$$\frac{P_{i_1} = A(\tilde{y}) \qquad A(\tilde{x}) \triangleq \mathbf{new} \ \widetilde{y:\rho}. \ Q_1 \text{ in } \Delta}{P = \begin{vmatrix} n \\ i=1 \end{vmatrix} P_i \xrightarrow[i_1]{\infty} Q = \mathbf{new} \ \widetilde{y:\rho}. \ (Q_1[\tilde{x} \mapsto \tilde{y}] \mid |_{i=1, i \neq i_1}^n P_i)}$$

• Rule (COM). The judgment is now inferred as follows:

where $Q' = [\![\mathbf{new} \ \widetilde{x_1:\rho_1}]\!] [\![\mathbf{new} \ \widetilde{x_2:\rho_2}]\!] ([\![Q_1]\!] [\![\widetilde{z}_{\mathscr{F}} \mapsto \widetilde{y}_{\mathscr{F}}]\!] | [\![Q_2]\!] |$ $\mid_{i=1,i\neq i_1,i_2}^n +_{j=1}^{m_i} [\![C_i^j]\!])$. The substitution Lemma 5 yields equality between $[\![Q_1]\!] [\![\widetilde{z}_{\mathscr{F}} \mapsto \widetilde{y}_{\mathscr{F}}]\!]$ and $[\![Q_1[\![\widetilde{z} \mapsto \widetilde{y}]\!]]\!]$. Thus, $Q' = [\![Q]\!]$ where $Q = \mathbf{new} \ \widetilde{x_1:\rho_1}$. $\mathbf{new} \ \widetilde{x_2:\rho_2}$. $(Q_1[\![\widetilde{z} \mapsto \widetilde{y}]\!] | Q_2 | |_{i=1,i\neq i_1,i_2}^n +_{j=1}^{m_i} C_i^j)$. Hence, we can infer $P \xrightarrow[i_1,i_1,i_2,i_2]{\varrho(x)} Q$ as follows:

$$C_{i_{1}}^{j_{1}} = x?f(\tilde{z}).\mathbf{new} \ \widetilde{x_{1}:\rho_{1}}. \ Q_{1} \qquad C_{i_{2}}^{j_{2}} = x!f(\tilde{y}).\mathbf{new} \ \widetilde{x_{2}:\rho_{2}}. \ Q_{2}$$

$$\downarrow_{i=1}^{n} +_{j=1}^{m_{i}} C_{i}^{j} \quad \xrightarrow[i_{1},j_{1},i_{2},j_{2}]{\varrho(x)(f)}} \left\{ \begin{array}{l} \mathbf{new} \ \widetilde{x_{1}:\rho_{1}}. \ \mathbf{new} \ \widetilde{x_{2}:\rho_{2}}. \\ (Q_{1}[\tilde{z} \mapsto \tilde{y}] \mid Q_{2} \mid |_{i=1,i\neq i_{1},i_{2}}^{n_{i}} +_{j=1}^{m_{i}} C_{i}^{j}) \end{array} \right.$$

Lemma 8 $P \xrightarrow{s}_{w} Q$ with respect to Δ and ϱ iff $\llbracket P \rrbracket \xrightarrow{s}_{w} \llbracket Q \rrbracket$ with respect to $\llbracket \Delta \rrbracket$ and $\llbracket \varrho \rrbracket$.

Proof. The implication from the left to the right is shown by Lemma 6. For the converse assume $[\![P]\!] \stackrel{s}{\underset{w}{\longrightarrow}} [\![Q]\!]$ with respect to $[\![\Delta]\!]$ and $[\![\varrho]\!]$. By Lemma 7 there exists $R \in [\![\![Q]\!]\!]^{-1}$ such that $P \stackrel{s}{\underset{w}{\longrightarrow}} R$. Since $[\![\cdot]\!]$ is injective, it follows that R = Q so that $P \stackrel{s}{\underset{w}{\longrightarrow}} Q$.

Lemma 9 $P \xrightarrow{\infty(p)} Q$ with respect to Δ and ϱ iff $\llbracket P \rrbracket \xrightarrow{\infty(p)} \llbracket Q \rrbracket$ with respect to $\llbracket \Delta \rrbracket$ and $\llbracket \varrho \rrbracket$.

Proof.

'⇒' Judgments $P \xrightarrow{\infty(p)} Q$ with respect to Δ and ϱ are derived by rule (COUNT):

$$P \equiv P' \qquad n = \sharp \{ w \in \mathbb{N} \cup \mathbb{N}^4 \mid P' \xrightarrow{\infty} R' \equiv Q \} \neq 0$$

$$m = \sharp \{ w \in \mathbb{N} \cup \mathbb{N}^4 \mid P' \xrightarrow{w} R' \}$$

$$P \xrightarrow{\infty(n/n+m)} Q \qquad (4.4.1)$$

The corresponding judgment can be derived as follows by rule (COUNT):

To see this, we must show that $\exists R'.P' \xrightarrow{\infty} R' \equiv Q$ is equivalent to $\exists R. \llbracket P' \rrbracket \xrightarrow{\infty} R \equiv \llbracket Q \rrbracket$. This follows from Lemmas 6, 7 and 5.

'\(\infty\)' The judgment [P] $\xrightarrow{\infty(n/n+m)}$ [Q] must be inferred as follows:

Since $[\![P]\!] \equiv P_1$ we can apply Lemma 5 which yields the existence of $P' \in [\![P_1]\!]^{-1}$ such that $P \equiv P'$. With this P' the inference step (4.4.2) becomes valid, so that we can infer $P \xrightarrow{\infty(n/n+m)} Q$ with respect to Δ and ρ as in (4.4.1).

Lemma 10 $P \xrightarrow{r} Q$ with respect to Δ and ϱ iff $\llbracket P \rrbracket \xrightarrow{r} \llbracket Q \rrbracket$ with respect to $\llbracket \Delta \rrbracket$ and $\llbracket \varrho \rrbracket$.

Proof.

'⇒' The judgments $P \xrightarrow{\infty(p)} Q$ with respect to Δ and ϱ is inferred by rule (SUM).

$$P \equiv P' \qquad r = \sum_{\substack{P' \xrightarrow{r'} R' \equiv Q}} r' \neq 0 \qquad \neg \exists R'' \exists w'. \ P' \xrightarrow{\infty} R''$$

$$P \xrightarrow{r} Q \qquad (4.4.3)$$

The corresponding judgment can be inferred as follows:

To see this, we it is sufficient to show following two equivalences, which both follow from Lemmas 5, 6, and 7:

1.
$$\exists R'.P' \xrightarrow{r'}_{w} R' \equiv Q \text{ iff } \exists R. \llbracket P' \rrbracket \xrightarrow{r'}_{w} R \equiv \llbracket Q \rrbracket.$$

2.
$$\exists R'.P' \xrightarrow{\infty} R' \text{ iff } \exists R. \llbracket P' \rrbracket \xrightarrow{w} R.$$

'\(\infty\)' The judgment $[P] \xrightarrow{r} [Q]$ must be inferred as follows:

Since $\llbracket P \rrbracket \equiv P_1$, Lemma 5 yields the existence of $P' \in \llbracket P_1 \rrbracket^{-1}$ such that $P \equiv P'$. With this P' the inference step (4.4.4) becomes valid, so that we can infer $P \xrightarrow{r} Q$ with respect to Δ and ϱ as in (4.4.3).

Table 4.8: Syntax of the stochastic π -calculus with higher-order definitions and input patterns

4.5 Higher-order definitions

Our process definitions up to now are first-order, in that they need to be provided statically at compile time. We show how to render definitions higher-order, so that they may also be determined dynamically at run time. The definitions we obtain hereby are reminiscent of procedures in Mozart-Oz⁶ of Smolka (1995).

In a first-order setting, it is impossible to define classes of objects as functions which create objects. Rather, all objects must be defined statically. Dynamic values are passed as parameters during object invocation. The drawback of this programming style is that argument lists quickly reach a considerable length.

We obtain a simpler syntax by incorporating higher-order definitions into the π -calculus. The syntactic categories of names of channels x and parametric processes A are unified, same for the two syntactic categories of definitions D and processes P. Parametric definitions become replicated inputs and belong to the category of processes; definitions can be composed by parallel composition in order to build sets thereof.

The syntax of the extended π -calculus is listed in Table 4.8. It is built from an infinite set of channel names $\mathcal{N} = \{x, y, z, \ldots\}$, and a set of function names $f \in \mathcal{F}$. Note that definitions $x(\tilde{y}) \triangleq P$ are drawn from the same alphabet as channels. In the literature, they are often written as replicated inputs $!x?(\tilde{y}).P$. The fragment with higher-order definitions, yet no sums, was studied by Niehren (2000). It can express both the eager and the lazy λ -calculus.

The reduction semantics needs to be adapted in the application rule for

⁶http://www.mozart-oz.org

parametric processes, where the definitions become internal.

$$z(\tilde{x}) \mid z(\tilde{y}) \triangleq P \quad \rightarrow \quad P[\tilde{y} \mapsto \tilde{x}] \mid z(\tilde{y}) \triangleq P$$

if \tilde{y} free is for \tilde{x} in P. The stochastic semantics is not affected either, except for the application rule:

$$\frac{P_{i_1} = z(\tilde{y}) \qquad P_{i_2} = z(\tilde{x}) \triangleq \mathbf{new} \ \widetilde{y:\rho}. \ Q}{\begin{vmatrix} n \\ i=1 \end{vmatrix} P_i \xrightarrow{\infty} \mathbf{new} \ \widetilde{y:\rho}. \ (Q[\tilde{x} \mapsto \tilde{y}] \mid |_{i=1, i \neq i_1}^n P_i)}$$

where $1 \leq i_1, i_2 \leq n$ and Q contain no top-level **new**-binders. We illustrate the usefulness of higher-order definitions at the example of class definitions. Consider promoter objects with two profiles:

```
\begin{array}{ll} \mathsf{PR\_free}(\mathsf{me},\mathsf{op}) & \triangleq \mathsf{rnap?bind}().\,\mathsf{PR\_bound}(\mathsf{me},\mathsf{op}) + \dots \\ \mathsf{PR\_bound}(\mathsf{me},\mathsf{op}) & \triangleq \mathsf{me?free}().\,\mathsf{PR\_free}(\mathsf{me},\mathsf{op}) \\ & + \mathsf{op!block}().\,\mathsf{PR\_bound} + \dots \end{array}
```

Instead of threading identities me, one might want them to become global names, that are passed at object creation time. Promoter creation can then be defined as follows, assuming that all promoters start in free:

```
make_pr(me, op) \triangleq new pr_free. new pr_bound.
pr_free() \triangleq rnap?bind().pr_bound() + ... |
pr_bound() \triangleq me?free().pr_free()
+ op!block().pr_bound + ... |
pr_free()
```

With this we can create distinct promoters dynamically, by applying the definition of $make_pr$. We need to pass as arguments the actual name me_i of the object, and the name of its operator site op_i . The channel rnap can remain global.

```
make_pr(me_1, op_1) \mid make_pr(me_2, op_1)
```

We consider processes as erroneous if they use the same name for naming different definitions, i.e. if some x occurs in subexpressions of the following form: $x(\tilde{y}) \triangleq P \mid x(\tilde{y}') \triangleq P'$. Such errors can be excluded statically by syntax restrictions as in TyCO, or raise errors dynamically as in Mozart-Oz. The static way would be to introduce all definitions by recursive let-operators. This is generally sufficient; see for the above example:

```
\begin{array}{l} \mathsf{make\_pr}(\mathsf{me},\mathsf{op}) \triangleq \\ & \mathsf{letrec} \\ & \mathsf{pr\_free}() \triangleq \mathsf{rnap?bind}().\mathsf{pr\_bound}() + \dots \mid \\ & \mathsf{pr\_bound}() \triangleq \mathsf{me?free}().\mathsf{pr\_free}() \end{array}
```

```
+ op!block().pr_bound() + ... |
in
    pr_free()
end
```

Finally, let us note a second kind of type errors which may arise now, since we no longer fix the arity of defined names (in contrast to names of parametric processes before). These errors have the form $x(\tilde{z}) \mid x(\tilde{y}) \triangleq P$ where the lengths of \tilde{z} and \tilde{y} differ.

4.6 Summary

In this chapter, we have presented the stochastic π -calculus with input patterns. We have defined the stochastic semantics of processes in this calculus in terms of continuous time Markov chains. Our definition of these CTMCs is new, even for the case without input patterns, but it induces existing simulation machines. We have shown how to encode input patterns, so that their stochastic semantics in terms of CTMCs is preserved.

As we will see in the next chapter, input pattern permit to define object-oriented abstractions. These can greatly facilitate π -calculus based modeling and simulation for systems biology, as illustrated by the modeling studies in the remaining chapters.

Concurrent Objects and Modules

This chapter first introduces notions of concurrent objects in the stochastic π -calculus with input patterns. We then show how to define object extension on meta level, making use of suitable notions of inheritance. Objects with inheritance are among the central reasons for the extensibility of the model of transcription and translation presented in Chapter 7. Note that previous π -calculus based approaches to biomolecular modeling do not use object-orientation.

We consider different object notions with increasing expressiveness. Objects may be passive, active, or mixed, depending on whether they may send or receive messages, or both. They may use particular channels for different kinds of interactions, or may restrict themselves to a single channel, the object's identity. Multi-profile objects offer different interfaces in different states, while single-profile objects stick to a permanent interface.

The objects of the TyCO language are passive, interact on a single channel, and may have multiple profiles. In this context multi-profile objects are termed non-uniform, see Ravara and Vasconcelos (2000). The objects presented in our work are more general, in that they may comprise both active and passive aspects, and permit interactions on multiple channels.

The use of multi-profile concurrent objects for modeling in systems biology was originally proposed by Duchier and Kuttler (2006). At that time however nor formal language existed to express such objects. The addition of input patterns to the synchronous π -calculus solves this problem at the symbolic level, the definition of the stochastic semantics of the previous chapter solves the numeric question.

The purpose of inheritance is to extend objects with new functions. We define inheritance for multi-profile objects on meta-level, rather than expressing it within the π -calculus. We keep the notion of inheritance static, so that all extension operations can be compiled away; the result is an expression of the stochastic π -calculus. Richer dynamic notions of inheritance are left to future research.

We present a module system for defining multi-profile objects in the stochastic π -calculus, while using inheritance. Modules are collections of definitions; we use them to specify multi-profile objects or collections thereof. The module system is inspired by that of Mozart-Oz, except for the aspect of inheritance. This latter is in turn inspired by that of SML, except for typing aspects.

5.1 Multi-profile objects

Multi-profile objects are objects with multiple *states*, each of which may offer a distinct *interface*. An interface is the set of function names for which the object provides definitions.

In the stochastic π -calculus, we express classes Obj of multi-profile objects by a set of definitions, one per state. For all states p of the object, we assume a parametric process name Obj_p in order to name this profile of the object Obj. The class of a multi-profile object Obj with profiles $p_1, ..., p_n$ is defined by a collection of mutually recursive definitions of the following form:

An object of this class in some profile p_i is created by the application $Obj_p(\tilde{y})$. Single profile objects are a special case of multi-profile objects, where the number of profiles n equals 1.

Let us consider Semaphore objects as a first example. These are like rooms or sites, that can be occupied at most by a single visitor. We represent semaphores as objects with two profiles free and bound. Each Semaphore is given an identity by some channel name me. The state transitions of Semaphores are depicted in Figure 5.1. In state free, a Semaphore can only accept a bind message and become bound. In state bound a Semaphore can only receive a free message and become Semaphore_free. It crucially matters that Semaphore may not accept bind messages, while in the bound profile. We obtain this behavior with the definitions in Figure 5.2.

We call a multi-profile object passive if all guarded processes C_i^j in its

5.2 Inheritance 85

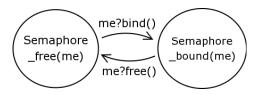


Figure 5.1: State transitions of a Semaphore

```
Semaphore\_free(me) \triangleq me?bind().Semaphore\_bound(me)

Semaphore\_bound(me) \triangleq me?free().Semaphore\_free(me)
```

Figure 5.2: Defining semaphores in the π -calculus as multi-profile objects

definitions are inputs, active if all of them are outputs, and mixed otherwise. In TyCO, all objects are passive and furthermore restricted to input on a same dedicated channel me, that identifies the object. In this case, all definitions have the following form:

$$Obj_p(me,\tilde{z}) \triangleq me?f_1(\tilde{x_1}).P_1 + ... + me?f_n(\tilde{x_n}).P_n$$

The symbols f_i name the functions offered by the object in that profile, and determine its *interface* or *type*.

5.2 Inheritance

In our modeling studies, we will frequently extend object classes by new functions. Our class specifications by inheritance can be compiled into ordinary π -calculus definitions.

Let us begin with single profile objects, considering the class **Obj** with the following definition:

$$Obj(\tilde{z}) \triangleq C_1 + \ldots + C_k$$

We extend the class Obj to Obj2 by adding new alternative behaviors:

Obj2 extends Obj
$$Obj2\left(\tilde{z}\right) \ \mbox{extended by} \ C_{k+1} \ + \ \ldots + \ C_{l}$$

This definition by inheritance can be resolved into a regular π -calculus definition as follows:

$$Obj2(\tilde{z}) \triangleq C_1 + \ldots + C_l [Obj \mapsto Obj2]$$

The substitution $[Obj \mapsto Obj2]$ denotes the renaming of all recursive calls to some Obj into recursive calls to Obj2. For multi-profile objects, the situation is somewhat more tedious. We consider some class Obj with n profiles:

We extend class Obj to Obj2 in the following manner:

This specification with inheritance is to be resolved into the following π -calculus definitions:

The substitution renames all recursive calls to profiles Obj_p_i into recursive calls to Obj_p_i for $1 \le i \le n$.

5.3 Module system

We present a module notation for the definition of multi-profile objects in the stochastic π -calculus, taking advantage of inheritance. This module system is inspired by that of Mozart-Oz (Roy, 2005), except for the aspect of inheritance. This latter is in turn inspired by the module system of SML except for typing aspects.

Basically, a module is a name for a *collection of definitions*. Such collections can be defined by importing definitions from other modules, or by inheritance from existing definitions. Modules export only distinguished definitions, while keeping others internal. Modules are self-contained, in that all names used in a module must be declared either in the module's header, or within the module itself. We provide some type annotations in module headers, aiming to improve legibility and facilitate the application of the contributed definitions.

As a first example, we turn the Semaphore definitions from Figure 5.2 into the module 'semaphore' in Figure 5.3. This module exports a unique process named Semaphore, with 0-ary function symbols bind and free. The definitions of Semaphore_free and Semaphore_bound remain internal to the module.

```
1 module 'semaphore'
2 export
3 Semaphore with bind/0, free/0
4 define
5 Semaphore(me) ≜ Semaphore_free(me)
6 Semaphore_free(me) ≜ me?bind().Semaphore_bound(me)
7 Semaphore_bound(me) ≜ me?free().Semaphore_free(me)
```

Figure 5.3: Semaphore module

Preamble. Modules start with a preamble, containing declarations and other statements, followed by definitions. The first line of the preamble defines the module's name.

```
module <module_name>
```

Module names are character strings. We discuss further preamble statements in the order they typically occur.

Public channels. Some objects communicate via public channels, which are neither part of their parameter list, nor locally created. We provide the following statements to declare such channels:

```
public <channel_name>
public <channel_name> with <type>
public <channel_name> as <channel_name>
public <channel_name> from <Table>
```

The first statement authorizes output on a public¹ channel, the second specifies the patterns locally defined objects may receive over some public channel. The third statement <public_channel> as < local_channel> is useful to address a public channel by another name, local to the module. The last declares channels introduced and assigned a stochastic parameterization in some table.

Import statements. Each module delivers material that can be re-used by other modules. We reserve the following statements for imports:

¹We use the alternative wordings *global* channel and *public*.

The first makes all exported definitions of the imported module available, while the second selects a few. The third allows to tag the component Object imported from module Othermodule, that we can address by the name Othermodule. Object. This is useful when importing definitions using the same name in different modules, or when extending on a definition from another module.

Rate function statements. We have not yet considered the parameterization of our objects, i.e. the rates determining the actual temporal behavior of interaction in the π -calculus. As introduced in Chapter 4 channels are associated with rate functions ρ upon creation (new x: ρ). These fix stochastic rates $\rho(f)$ for all pairs (x,f) where f are the patterns exchanged over channel x. We conveniently import such rate definitions into a module, defined in an external table, using the following statement:

```
rate <rho> from <Table>
```

Export statements. We specify the *interface* of defined objects by export statements.

```
export <definition_name> with <type>
export <definition_name>
```

In <type>, we list all input patterns an object may receive over its identifier channel me. Note that this does not reveal any internal detail of the object. For instance, it does not tell when input patterns may by received, which may depend on the current profile of an object. Note also that the export statement only fixes the arity of functions, yet not their stochastic parameterization.

We document inheritance relations at the level of export statements.

```
<definition_name> extends <Othermodule.Object> by <type>
<definition_name> extends <Othermodule.Object>
```

The first statement is used to signalize the addition of new pattern input over an object's identifier channel me, the second for new interaction potential using another channel.

Definitions. Finally, the keyword

define

delimits the end of the preamble. The module's definitions follow. Note that in the module's core part, we use

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```
module
            'persistent list'
1
2
   export
       Node with getNext/1, getValue/1, is Nil/1
3
4
       Nil
             with is Nil/1
5
   define
       Node (me, next, val) \triangleq
6
          me?getNext(c) .c!(next).Node(me,next,val)
7
8
        + me?getValue(c).c!(val).Node(me, next, val)
9
        + me?isNil(c).c!false().Node(me, next, val)
      Nil(me) \triangleq me?isNil(c).c!true().Nil(me)
10
```

Figure 5.4: Persistent list module

```
< definition\_name\_profile> \textbf{extended by } C_{k+1} + \ldots + C_{l} to detail on an extension, that in the preamble was announced as < definition\_name> \textbf{extends} < module\_name>.< \\ definition\_name>
```

Comments. Modules may comprise comment lines starting in the delimiter //, which must be repeated if the comment exceeds one line. In this document, for the sake of legibility we color comments in grey.

```
Nothing \triangleq 0 // this process has vanished!
```

5.4 Examples

We first present persistent lists as an example for single-profile objects, which we turn into degradable list by inheritance. As an example of multi-profile objects we then discuss persistent queuing lists, and render them degradable by inheritance.

5.4.1 Persistent lists

A list consists of a sequence of nodes, each with a successor next and a value val. We design the class Node with three parameters: me, next, and val. The successor of a list's last Node is represented by a dedicated Nil object. Interfaces of Node objects specified in Figure 5.4 export three unary functions: getNext, getValue, and isNil. The Nil object provides only the unary function isNil.

Consider a list [a,b] of length 2. It is represented by the parametric process List, using the module 'persistent list'.

```
module 'persistent list [a,b]' import Node Nil from 'persistent list' export List define  \text{List}(n_1) \triangleq \text{new } n_2 \colon \rho_{\text{plist}} \cdot \text{new } \text{nil} \colon \rho_{\text{plist}}.   \text{Node}(n_1, n_2, a) \mid \text{Node}(n_2, \text{nil}, b) \mid \text{Nil}(\text{nil})
```

We fix the stochastic behavior of persistent Node and Nil objects as follows:

```
\begin{array}{ll} \rho_{\mathsf{plist}}(\mathsf{getNext}){=}30 & \rho_{\mathsf{plist}}(\mathsf{getValue}){=}\infty \\ \rho_{\mathsf{plist}}(\mathsf{isNil}){=}\infty & \rho_{\mathsf{pnil}}(\mathsf{isNil}){=}\infty \end{array}
```

The rate function ρ_{plist} fixes the temporal behavior of the second node of the list, located at n_2 , ρ_{pnil} that of the Nil object. We illustrate list processing with a Walker. It traverses the list by querying each node for it successor via calling the function getNext, and stops after identifying Nil by its positive response to isNil.

```
 \begin{split} \text{Walker(node)} &\triangleq \\ \textbf{new} & c_1.\,\text{node!isNil(c_1)}\,. \\ & c_1?\,\text{true()}\,.0 \\ &+ c_1?\,\text{false()}\,. \\ & \textbf{new} & c_2.\,\text{node!getNext(c_2)}\,.c_2?(\,\text{next\,)}\,.\,\text{Walker(next\,)} \end{split}
```

Two notes about the Walker are in order.

First, it does not strictly adhere to our definition of object, since it uses a **new**-binder in front of a sum. More importantly, it is unclear how to define a useful notion of inheritance for Walker like processes, so that they they do different things while walking over a list. The same problem applies to all devices processing representatives of macromolecules (i.e., data structures) in Chapters 7 and 8: the abstractions of RNAP and ribosome proceed by calling functions that are offered by DNA and mRNA representatives.

The second point worthwhile stating regards the creation of new channels in this example. When emulating a function call in the π -calculus, we pass a fresh private channel on which the result comes back², in this case the Walker's c_1 and c_2 . Such channels are of infinite rate. Note that for channels not assigned any ρ upon creation, all interactions are instantaneous (see page 59).

After importing module 'persistent list [a,b]', we let the Walker run over an example list instantiated at channel n_1 :

²See (Milner, 2004).

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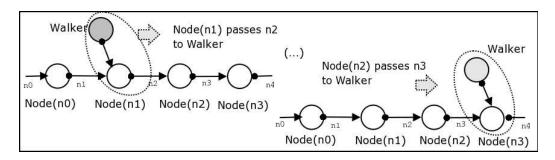


Figure 5.5: Walker stepping through a list; $Node(n_i, n_{i+1}, v_i)$ is here abbreviated as $Node(n_i)$.

Suppose the first node's identifier n_1 was introduced with the same rates ρ_{plist} . All calls to getNext functions are then associated with a stochastic rate of 30. This is the single parameter determining an exponential distribution of waiting times, i.e. the inverse of its mean. Our Walker hence traverses lists at an average speed of 30 nodes per second. Besides merely running down the list, the Walker does not perform any further action. This could be done by a Copier inspired by the Walker such that:

List
$$(n_1)$$
 | Copier $(n_1, n_2) \rightarrow^* List (n_1)$ | List (n_2)

While we leave the Copier's definition to the reader, we will later present our abstraction of RNAP for the related task of transcription from DNA into mRNA.

5.4.2 Degradable lists

We now illustrate object extension by deriving a degradable list variant from the previous, persistent one. The distinguishing feature is that degradable may be destroyed while processing.

The import statement in line 2 of their defining module (Figure 5.6) imports the specifications of Node and Nil from the module 'persistent lists', which it refers to as Plist. With this, Plist.Node and Plist.Nil denote the

```
'degradable list'
1
  module
2
  import Plist(Node, Nil) from 'persistent list'
3
  export
     Node extends Plist. Node by kill /0
4
5
           extends Plist.Nil
                                by kill/0
6
  define
7
     Node(me, val, next) extended by me? kill().0
8
      Nil(me) extended by me?kill().0
```

Figure 5.6: Degradable list module

respective objects of persistent lists, clearly distinguished from the corresponding objects in non-persistent lists. The export statement tells that this module provides definitions for Node and Nil. These objects provide the same functions as their analogs from the 'persistent list' module, and additionally kill of arity zero.

A non-persistent list [a,b] can now be built by the same definition as a persistent list [a,b]. The only difference is that we have to import module 'degradable list' instead of 'persistent list'. Destructing a non-persistent list is easy. A Killer proceeds like a Walker, except that it kills a Node before continuing with the next:

```
 \begin{array}{ll} \mbox{Killer(node)} \triangleq & \\ \mbox{new} & c_1.\,\mbox{node!isNil(c_1)}. \\ & c_1?\mbox{true()} & .\,\mbox{node!kill()}.0 \\ & + & c_1?\mbox{false()}.\mbox{new} & c_2.\,\mbox{node!getNext(c_2)}. & c_2?(\mbox{next)}. \\ & & \mbox{node!kill()}. & \mbox{Killer(next)} \end{array}
```

It is worthwhile observing that Walkers are able to traverse non-persistent lists, without changing their code. This is one of the main advantages of the object-oriented approach proposed in this work. Objects of non-persistent lists specialize those of persistent lists, so we can always replace the latter by the former. This would not hold for our model encoded in the biochemical stochastic π -calculus of Priami et al. (2001). We will discuss the reasons on page 94.

5.4.3 Queuing lists

The persistent and degradable lists presented so far can be traversed by several visitors at the same time, e.g. by a Walker and by a Reader. Each visitor proceeds over the nodes, and hereby draws waiting times independently of the others. This permits overtaking of one visitor by another, which is how-

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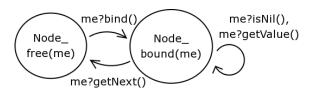


Figure 5.7: Transition diagram: persistent queuing list Node

```
'persistent queuing list'
1
   module
2
   export
       Node with getNext/1, getValue/1, isNil/1
3
4
       Nil
             with is Nil/1
5
       Node(me, next, val) \triangleq Node_free(me, next, val)
6
7
       Node_free(me, next, val) \triangleq
8
          me?bind().Node_bound(me, next, val)
9
       Node_bound(me, next, val) \triangleq
          me?getNext(c).next!bind().c!(next).
10
               Node_free (me, next, val)
11
12
        + me?getValue(c).c!(val).Node_bound(me, next, val)
13
        + me?isNil(c).c!false().Node_bound(me, next, val)
       Nil(me) \triangleq
14
15
          me?bind().Nil(me)
16
          me?isNil(c).c!true().Nil(me)
```

Figure 5.8: Persistent queuing list module

ever not possible in transcription of DNA, nor in translation of mRNA or its degradation.

We impose queuing on visitors of a persistent list by incorporating a semaphore style behavior, distinguishing free and bound. Figure 5.7 illustrates the transitions between these profiles of a Node, defined by the module 'persistent queuing list' in Figure 5.8. The functions exported on the interface can only be used when the Node is in profile bound. Note that the function bind is not exported outside the module, but can only be called on a node by its predecessor. This happens during the call of the getNext function, which is re-defined compared to our previous list module: Upon a getNext request a Node binds its successor - if necessary it waits - before passing over the reference next (line 10).

Note that before the Walker can operate on a persistent queuing list, we need to bind its first node:

```
'degradable queuing list'
  module
1
2
  import
3
      Plist (Node, Nil) from 'persistent queuing list'
4
  export
5
     Node extends Plist. Node by kill /0
           extends Plist. Nil
6
      Nil
                                by kill/0
7
8
      Node_free(me, next, val) extended by me?kill().0
9
      Nil(me) extended by me? kill().0
```

Figure 5.9: Degradable queuing list module

```
\begin{array}{c|cccc} \text{List(head)} & | & \text{head!bind().0} & | & \text{Walker(head)} \\ \rightarrow^* & \textbf{new} & \text{n}_1 : \rho_{\text{pqlist}} . \, \textbf{new} & \text{n}_2 : \rho_{\text{pqnil}} . & \text{Node\_free(head,n}_1,a) & | \\ & & \text{Node\_bound(n}_1, \text{n}_2,b) & | & \text{Nil(n}_2) & | & \text{Walker(n}_1) \\ \rightarrow^* & \dots \end{array}
```

A degradable queuing list can easily be obtained by inheritance, see Figure 5.9. Its members are equipped with a kill function for stepwise destruction. As for the Walker, the Killer remains functional starting on a bound first node.

5.5 Discussion: input patterns or protocols?

Let us discuss an alternative encoding of persistent nodes in the π -calculus. Instead of defining object interfaces by input patterns, we use smart handshake protocols. This works fine, but beyond poor legibility, it has the major inconvenience that inheritance gets out of reach.

Each function of Node_bound is now represented by a fresh name, which is created by the Node_free before profile switching. These names are passed from the nodes to the visitor following a handshake protocol illustrated in Figure 5.10. In a first step, the Node receives input some channel c over its me channel, knowing this is a binding request and that in step 2, it is supposed to return the channels associated with its interactions in the bound profile over channel c. The receiver in turn has precise knowledge on how to make subsequent use of these channels.

Let us now consider the *difference* between persistent and degradable node variants from a Visitor's perspective. Node extrudes one fresh private channels per possible interaction in step 2 of the protocol: getValue and getNext are extruded in either case, while only the degradable node passes kill. Visitors designed to interact with persistent Nodes can not be used on



Figure 5.10: Handshake protocol for Node binding in π -calculus without pattern input. Degradable and persistent nodes differ in their protocols since only the former creates and extrudes a kill channel in step 2.

degradable ones, in contrast to our previous Walker encoded in our object π -calculus on page 90.

The reason is the modified protocol. Hence if we wanted to design both Walkers and Killers for such lists in the π -calculus without pattern input, we would have to pass on the full channel set to both Walkers and Killers - even if the former never made use of kill.

The code spells out as follows for the *persistent* versions:

```
Node_free(me, next, val) \triangleq
       me?(c).// handshake step 1
           new getNext.new getValue.
           c!(getNext, getValue). // handshake step 2
           Node_bound (me, next, val, getNext, getValue)
    Node_bound(me, next, val, getNext, getValue) \triangleq
       getValue?(c).c!(val).
           Node_bound (me, next, val, getNext, getValue)
    + getNext?(c).c!(next).Node_free(me, next, val)
While for the degradable case, it is:
    Node_free(me, next, val, kill) \triangleq
       me?(c). // handshake step 1
           new getNext.new getValue.new kill_n.
           c!(getNext,getValue,kill_n). // handshake step 2
           Node_bound (me, next, val, getNext, getValue, kill_n)
    + kill?().0
    Node_bound(me, next, val, getNext, getValue, kill) \triangleq
       getValue?(c).c!(val).
           Node_bound (me, next, val, getNext, getValue, kill)
    + getNext?(c).c!(next).Node_free(me, next, val, kill)
```

Modeling Techniques

This chapter presents recurrent modeling techniques emanating from the modeling studies of Chapters 7 and 8. We illustrate these by artificial examples, focusing on elements of concurrent control that are indeed encountered in biological cases, but may also occur at other places.

These techniques address phenomena of many-to-many communication (Section 6.1), applied for multiple entry points to queuing lists (Section 6.2), overlapping sites with mutually exclusive binding (Section 6.3), where we develop a mechanism that is useful to other cases of mutual dependencies beyond pairs of actors. We introduce timers (Section 6.4), and show the application of these to the modulation of stochastic rates of object functions (Section 6.5). Our approach to these phenomena in novel to modeling in systems biology, since it heavily relies on multi-profile objects (beyond those of TyCO). Thus, our technical solutions could not easily be expressed in previous π -calculus dialects.

Several among these phenomena regard the stochastic behavior. Indeed, the stochastic semantics is essential to the correct treatment overlapping sites, and other examples. We must prevent events at one site, that would disregard the peer site's state. In our models, inconsistent states can indeed be reached, yet our stochastic semantics ensures that they may not be abused of. Inconsistent states are left by immediate transitions, which are executed prior to any time-consuming transitions that might abuse of it.

The avoidance of inconsistent intermediate states is a well-known practical issue, e.g. in distributed databases (Vossen and Weikum, 2001). The solution there is to introduce transactions, and by them to render sequences of

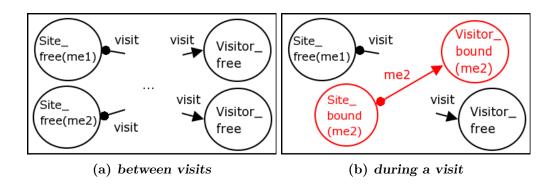


Figure 6.1: Many-to-many communication: at most one Visitor per Site.

actions atomic. Transactions for the π -calculus were proposed by Ciocchetta and Priami (2006). Fortunately, such heavier operations are not needed for the purpose of this thesis, thanks to our stochastic semantics with immediate transitions.

6.1 Many to many communication

Many-to-many communication over the same channel is inherently difficult, it requires not to mix up the messages of different partners.

Handshake protocols are the common technique to model many-to-many communication over the same channel in the π -calculus. As two actors establish a contact over this channel, they exchange a private channel, on which they subsequently continue their interaction. This private data exchange prohibits other concurrent actors from interfering.

We suggest a convenient alternative to handshaking for multi-profile objects. It applies to scenarios with many sites and visitors, where each site accepts at most one visitor at any time. Figure 6.1(a) illustrates the scenario without ongoing visits. We model sites and visitors as objects, assuming that Sites have unique identities me_i. During the initial interaction, a Site passes its identity to the Visitor, by communication over the public channel visit. Visitors can then invocate functions on the Site. This constellation during interaction is depicted in Figure 6.1(b).

The semaphore-type requirement that Sites accept maximally one Visitor at a time can be fulfilled as previously with semaphores, i.e. by state changes of multi-profile objects. A Site grants access to its identity only while in free state. As this occurs, it changes into a bound state. Once the Visitor leaves the Site, the latter becomes free again. Before leaving, the Visitor must discard any further access capabilities on the Site's identifier.

```
1
   public visit
2
   Site_free (me)
                    \triangleq visit!bind(me).Site_bound(me)
   Site\_bound(me) \triangleq me?unbind().Site\_free(me)
   Visitor_free() \triangleq visit?bind(site).Visitor_bound(site)
   Visitor\_bound(site) \triangleq site!unbind().Visitor\_free()
6
7
  new me_1. new me_2.
8
   Site_free(me_1)
                       Site_free (me_2)
   Visitor_free()
                    | Visitor_free()
```

Figure 6.2: Implementing scenario with 2 visitors and 2 sites

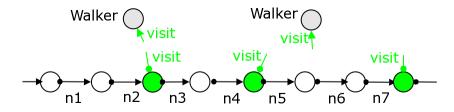


Figure 6.3: A list offering multiple entry points (green) to Walkers

The above scenario with each two Visitors and Sites is implemented in Figure 6.2. Note that Sites and Visitors may be enriched with further functions by inheritance.

In biological examples, many-to-many communication over global channels occurs between abstractions of RNAP and promoters in Section 7.1, in protein binding to operators modeled in Section 8.2, as well as in mRNA processing from Section 7.2.

6.2 Queuing lists with multiple entry points

Our next matter of interest is a list offering multiple points of entry, as illustrated in Figure 6.3. Each list Node can be visited by at most one Walker at the same time. Walkers can either come from the previous Node, or access the Node directly by using the public channel visit.

This is indeed a special case of the many-to-many scenario from Section 6.1. The Nodes in this list correspond to the previous Sites, the Walkers to Visitors. In contrast the previous setting, the sites are no longer independent, but part of a queuing list. This is because we want to prohibit a Walker from overtaking others, as appears when modeling RNA polymerases that

```
1
     QList(Node, Nil) from 'persistent queuing list'//Fig.5.8
2
3
   public
4
       visit
5
   export
       Node extends QList. Node // sends bind over visit
6
7
8
   define
9
       Node_free (me, next, val) extended by
10
           visit!bind(me).Node_bound(me, next, val)
       Walker() \triangleq Walker_free()
11
       Walker\_free() \triangleq visit?bind(n).Walker\_bound(n)
12
       Walker\_bound(n) \triangleq new c.
13
14
          me! getNext(c).c?(next).Walker_bound(next)
```

Figure 6.4: Implementing queuing lists with multiple entry points

transcribe through DNA, after starting at promoters.

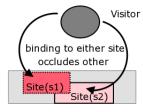
The implementation is listed in Figure 6.4. Nodes extend those of persistent queuing lists. The profile Node_free is extended by the capability to receive a visitor, as Site_free in Figure 6.2. Walker_free binds to a site in the same way as Visitor_free did before. But now, instead of being able to unbind, the walker needs to continue traversing the remaining list, similarly to the walker on page 90. It should be noted that multi-profile objects permit both mixed input and output, while using more than one interaction channel.

In our biological modeling, multiple entry points to lists are useful for several cases. One are tandem promoters, dealt with in Section 7.4.2. The abstraction of the mRNA transcribed there applies a solution developed for internal ribosomal binding sites, transcribed within polycistronic mRNA from operons (Figure 7.11).

6.3 Overlapping sites

We next model overlapping sites at s_1 and s_2 which may not receive visitors simultaneously, as illustrated in Figure 6.5(a). Whenever either of them is bound, the other becomes blocked. We must carefully prohibit inconsistent configurations in which the Site at s_1 is bound while that at s_2 is free, or vice versa.

In our models, inconsistent states can indeed be reached, yet may not be abused. We always provide immediate transitions leaving inconsistent con-



$Site(s_1,s_2)$	$Site(s_2,s_1)$	interaction	delay
free	free	$s_1.bind()$	timed
bound	free	s_2 .block()	immediate
bound	blocked	$s_1.unbind()$	timed
free	blocked	$s_2.unblock()$	immediate
free	free		

(b) Sample trajectory

Figure 6.5: Overlapping sites at s_1 and s_2

figurations. Their execution precedes any time-consuming transitions that might abuse it. The higher priority of immediate transitions is enforced by rule (SUM) of the stochastic semantics of our π -calculus in Table 4.5.

One possible state trajectory is given in Figure 6.5(b). Initially, we assume a parallel composition of each two Site_free and Visitor_free. The first parameter of a Site refers to its identity, and the second to its peer's:

$$Site_free(s_1, s_2) \mid Site_free(s_2, s_1) \mid Visitor_free \mid Visitor_free$$

The first reduction is an application s_1 .bind() which we assume time consuming. With some finite rate r we enter an inconsistent configuration:

```
\xrightarrow{r} Site_bound(s<sub>1</sub>,s<sub>2</sub>) | Site_free(s<sub>2</sub>,s<sub>1</sub>) | Visitor_free | Visitor_bound(s<sub>1</sub>)
```

Now comes the trick. $Site_free(s_2,s_1)$ has a choice between a time consuming transition through function $s_2.bind()$ (with the $Visitor_free$), and an immediate one by function $s_2.block()$ for which $Site_bound(s_1,s_2)$ acts as counterpart. The priority given to immediate transitions in our semantics ensures that only the latter function is applied:

Thus, it is impossible to enter an erroneous configuration in which both Sites are bound at the same time:

```
\stackrel{\eta}{\rightarrow} \text{Site\_bound}(s_1, s_2) \mid \text{Site\_bound}(s_2, s_1) \\ \mid \text{Visitor\_bound}(s_1) \mid \text{Visitor\_bound}(s_2)
```

An implementation of Site objects with these three profiles is listed in Figure 6.6. The first two profiles free and bound are analogous to the previous Semaphore's. The third profile blocked accounts for mutual exclusion of site inhibition. To complete the example, we provide an implementation of visitors in Figure 6.7.

```
module 'overlapping sites'
1
2
   export
       Site with bind /0, unbind /0
3
4
   define
       Site(me, other) \triangleq Site_free(me, other)
5
6
7
       Site_free(me, other) \triangleq
          me?bind().Site_bound(me, other) // timed
8
        + me?block().Site_blocked(me, other)
9
                                                 // immediate
10
        + other!unblock(). Site_free(me, other) // immediate
11
       Site_bound(me, other) \triangleq
12
          me?unbind().Site_free(me, other) // timed
13
        + other!block().Site_bound(me, other) // immediate
14
15
16
       Site_blocked(me, other) \triangleq
          me?unblock().Site_free(me, other) // immediate
17
```

Figure 6.6: Module 'overlapping sites'

```
module 'visitors of overlapping sites'
1
2
   public s_1 s_2
3
   export
4
       Visitor with bind/0, unbind/0
5
   define
       Visitor() \triangleq Visitor_free()
6
7
       Visitor_free()≜
8
          s_1! bind (). Visitor_bound (s_1)
9
        + s_2! bind(). Visitor_bound(s_2)
10
11
12
       Visitor\_bound(site) \triangleq site!unbind().Visitor\_free()
```

Figure 6.7: Visitor module

6.4 Timers 103

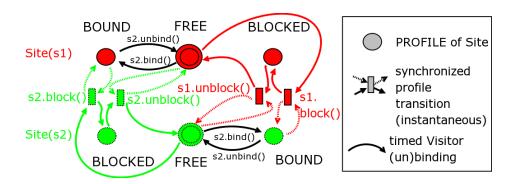


Figure 6.8: Transitions of overlapping sites at s_1 and s_2 in Petri net style

```
1
   module
             'timer (f_1, \ldots, f_n)'
2
   export
3
        Timer
4
   define
5
        Timer(c) \triangleq
6
            c!f<sub>1</sub>().Timer(c)
7
8
         + c!f_n().Timer(c)
```

Figure 6.9: Module 'timer($f_1,...,f_n$)'

Figure 6.8 illustrates the synchronized state transitions of the pair of objects $Site(s_1,s_2)$ and $Site(s_2,s_1)$. Colored transitions are due to calls of immediate functions block and unblock, and pass through the boxed synchronization points. Black edges denote timed interaction with the Visitor, not included in the illustration for the sake of clarity.

6.4 Timers

Timers proposed by Regev (2002) catalyze activities involving a single entity. When such are modeled in the π -calculus, due to its binary interaction paradigm these reactions nevertheless require some partner. An elementary timer on channel ${\bf c}$ sends the void message to ${\bf c}$, whenever it is requested. We will use a somewhat more powerful Timers for multi-profile objects, instantiated at channel ${\bf c}$. Such timers defined in Figure 6.9 provide co-actions ${\bf f}_i$ requested by alternative profiles. A first significant use case for these Timer processes, that can trigger actions with different rates depending on the function name, is shown in the following. The construction will also

```
1 module 'elementary timer'
2 export Timer
3 define
4 Timer(c) ≜ c!().Timer(c)
```

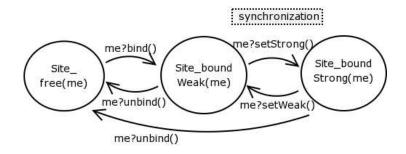


Figure 6.10: Transitions of Site with unbind function of mutable rate

demonstrate its versatility when modeling transcription regulation at the λ switch in Chapter 8.

6.5 Mutable rates

It is sometimes wishful to modify the stochastic rate of an object's function f. Achieving this is however not evident, since the function rates are determined upon creation of the object's identifier channel, by means of the associated ρ .

The alternative to rate modification would be to introduce a new function f', performing the same activity as the original f yet with a different rate. This would come at the expense of affecting the object's interface, require any interaction partners to know when to invocate which among f and f'. We favor as solution preserving the object's interface.

We illustrate our technique at the example of a Site, where as usual visitors may come and go. While binding itself occurs at a fixed rate, the stability of the bound state is mutable, i.e the response rate to calls to function unbind depends on some external condition. Figure 6.10 illustrates. Both Site_boundWeak and Site_boundStrong offer the unbind. Site is synchronized with an external partner, that via calls of its functions setStrong and setWeak may enforce profile adjustments. The trick is now simple: while unbind itself is immediate, its externally experienced rate is determined by timed internal

6.5 Mutable rates 105

```
module 'Site with mutable unbinding rate'
1
2
   import
       Timer from 'timer(weakTimer, strongTimer)//Fig.6.9
3
4
   export
              with bind /1, unbind /0, setWeak /0, setStrong /0
5
       Site
6
   define
7
       Site(me) \triangleq Site_free(me) \mid Timer(me)
8
       Site\_free(me) \triangleq me?bind(c).c!(me).Site\_boundWeak(me)
9
10
       Site_boundWeak(me) \triangleq
11
         me?weakTimer().me?unbind().Site_free(me)
12
13
       + me?setStrong().Site_boundStrong(me)
14
       Site_boundStrong(me) \triangleq
15
         me?strongTimer().me?unbind().Site_free(me)
16
17
       + me?setWeak().Site_boundWeak(me)
```

Figure 6.11: Site with unbind function of mutable rate

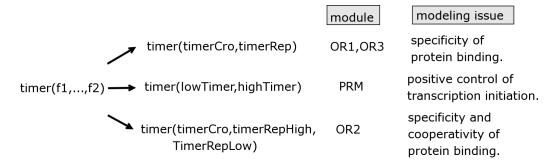


Figure 6.12: Module dependencies when using 'timer(f1,...,fn)'

communication with a tailored Timer.

The complete definition is given in Figure 6.11. We obtain the desired temporal behavior with a suitable choice of timed versus immediate function rates, such as:

```
bind \mapsto 1, strong Timer \mapsto 1, weak Timer \mapsto 10, set Strong \mapsto \infty, set Weak \mapsto \infty unbind \mapsto \infty.
```

Notice that the mechanism for switching between Site_boundWeak and Site_boundStrong depends on immediate functions, and is reminiscent of that

for overlapping sites from Section 6.3.

In our biological modeling studies, the combination of Timers with immediate profile synchronizations from Section 6.3 will prove to deal with: *specificity* between proteins and DNA operator sites, *cooperative* binding of proteins on distinct DNA operator sites, and *positive control* of transcription initiation. Figure 6.12 illustrates the module dependencies, when dealing with specific biological modeling issues.

Part III Modeling and Simulation Studies

CHAPTER 7

Transcription and Translation

This chapter is dedicated to our models of bacterial transcription and translation in the stochastic π -calculus with pattern input, and stochastic simulation based on these. Our design of biological model components benefits from the toolset introduced in the previous chapters. Objects with multiple profiles are essential to our modeling. The re-use of functionalities from existing components, i.e. object extension, greatly facilitates the development of our biological abstractions.

Abstracting macromolecules. In Section 7.1 we develop abstractions of RNAP and DNA. To deal with DNA, we introduce three different multi-profile objects sketched in Figure 7.1: Promoter, Nucleotide, and Terminator. Two among these objects provide functionalities ascribed sequences as a whole – promoters and terminators. In contrast, we represent individual coding nucleotides, again as objects. These abstraction levels are distinguished by

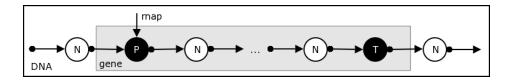


Figure 7.1: The DNA Module defines the objects Promoter, Nucleotide, Terminator, here abbreviated as P, N, and T respectively

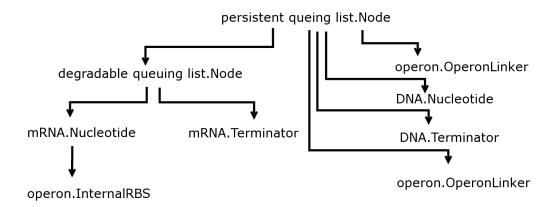


Figure 7.2: Module dependencies and inheritance

coloring in Figure 7.1. Our switching between abstraction levels follows the reaction-based representation in Table 2.1, which as previously discussed (see Section 2.5) constitutes the core of related stochastic models of gene expression. Our abstraction of mRNA in Section 7.2 follows similar rough lines.

Extending on lists. Figure 7.2 overviews how in this chaper, we extend the available list variants: we base models of DNA on persistent queuing lists, and those of mRNA on their degradable extension. For promoters, we initially present a stand-alone abstraction. It is later refined to comprise the functionalities of a DNA nucleotide representative. As such it may smoothly combine with a predecessor **Nucleotide**, as illustrated in Figure 7.1. To certain biological cases, this aspect matters, while for the simulation of others it may be disregarded.

Chapter outline. After introducing our generic models of DNA and mRNA, we provide suitable ρ definitions for the stochastic parameterization of our objects in Section 7.3. To illustrate how our models can accommodate further biological information, in Section 7.4 we refine our genetic library to special cases of transcriptional organization in bacteria, as introduced in Section 2.3. To keep the balance, in Section 7.5 we discuss open challenges to the coverage of further regulatory mechanisms within our framework. Last but not least, we move on to the simulation of the combined dynamics of bacterial transcription and translation in Section 7.6. We namely investigate the effect of translational bursting.

reaction	Rnap in	line in	sends	to DNA	line in
in	profile	Fig 7.4		representa-	Fig.7.6
Tab. 2.1				tive	
				Promoter	
(2.2.1)	_free	7	bind	_free	15
(2.2.2)	_closed	9	unbind	_closed	17
(2.2.3)	_closed	10	initiate	_closed	18
(2.2.4)	_open	12	startTranscript	_open	21
(2.2.5)	_elongating	17	elongate	Nucleotide	27
				$_{ extstyle }$ bound	
(2.2.6)	_elongating	16	terminate	Terminator	32
				$_{ m _}$ bound	

Figure 7.3: Relating the reaction-based view of transcription to interactions between π -calculus objects

7.1 DNA and transcription

Figure 7.3 summarizes our mapping of the reaction-based view from Table 2.1 on communication between concurrent π -calculus objects: interactions between RNAP and promoter sequences on DNA during initiation as sketched in reactions (2.2.1) to (2.2.4), transcript *elongation* in steps of one DNA nucleotide from reaction (2.2.5), and *termination* on terminator DNA sequences, i.e. reaction (2.2.6).

Let us precede the discussion of the components with a comment on a central design choice. In our model, we want to explicit the growth of the transcript, that is not represented in the reaction-based view. Recall that RNA is assembled on DNA by RNAP. In the π -calculus model, the transcript representative must be spawned by one among these. We attribute the task to the DNA representative, which by its sequence determines the information content of the transcript. Due to this choice, our representative of RNAP is simpler to explain than those of DNA.

Abstraction of RNAP. Rnap has four profiles introduced in Figure 7.4: free, closed, open, transcribing. The first three deal with transcription initiation – they have corresponding Promoter profiles. The fourth covers elongation, and roughly resembles our previous Walker. We first consider formation of the closed promoter complex, i.e. binding of RNAP to some promoter as summarized by reaction (2.2.1): Rnap_free invocates bind over the global

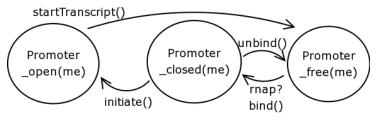
```
'RNAP'
 1
    module
 2
    public rnap
 3
    export Rnap
 4
    define
     Rnap ≜ Rnap_free
 5
     Rnap_free ≜
 6
 7
         new c.rnap!bind(c).c?(prom).Rnap_closed(prom)
 8
     Rnap\_closed(prom) \triangleq
         prom!unbind().Rnap_free
 9
      + prom!initiate().Rnap_open(prom)
10
     Rnap_open(prom)\triangleq new c<sub>1</sub>.new c<sub>2</sub>.
11
12
          prom! start Transcript (c_1) . c_1 ? (rna).
          prom!getNext(c_2).c_2?(dna).
13
14
          Rnap_elongating (dna, rna)
15
     Rnap_{-}elongating(dna, rna) \triangleq new c_1.dna!isTerm(c_1).
          c<sub>1</sub>?true().dna!terminate(rna).Rnap_free
16
17
       + c_1? false (). new c_2. dna! elongate (rna, c_2).
                c_2?(rna_nxt).
18
19
               new c_3. dna! getNext(c_3). c_3?(dna_nxt).
20
               Rnap_elongating(dna_nxt,rna_nxt)
```

Figure 7.4: RNAP module

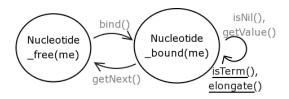
channel rnap (line 7).¹ It waits for satisfaction by a Promoter, that is nondeterministically selected among several available in profile free, and extrudes its me channel. As the bind interaction succeeds, Rnap and Promoter switch to their closed profiles. They now jointly represent the closed promoter complex. As such they can interact over Promoter's shared me channel, by the competing functions unbind and initiate. The race between these is controlled by the rates k_{off} in reaction (2.2.2) and k_{init} in reaction (2.2.3), which enter the model over the ρ function that quantifies the Promoter's channel me. Unbinding without transcription initiation is straightforward. It causes transitions from closed to free (line 9). If conversely initiate succeeds, both switch to their open profile (line 10). Transcription subsequently launches upon a startTranscript call, reflecting reaction (2.2.4). Promoter_open creates the first transcript segment, and returns a reference to its growing end rna. Rnap_open continues as elongating, using rna and the second parameter dna, that it obtains by a getNext call (line 13).

Rnap_elongating traverses the DNA representative, calling elongate on each

¹See Section 6.1 for establishment of a private connection over a global channel in a many-to-many setting.



(a) Transition diagram: Promoter



(b) Transition diagram: Nucleotide. The functions with shaded labels are inherited from a persistent queuing list Node, the underlined are new.

Figure 7.5: DNA abstraction: profile transitions

Nucleotide over its extruded me channelo, see line 17. This accounts for reaction (2.2.5). Recall that we left it to the abstraction of DNA to actually create that of mRNA, upon these calls of function elongate. After reaching the Terminator, Rnap returns to free (line 16), while the Terminator actually completes and releases the transcript. This behavior corresponds to reaction (2.2.6). Notice that the recycling of Rnap objects differs from the behaviour of the previous Walker, that terminates as 0 reaching the end of a list.

Abstraction of DNA. Our module 'DNA' in Figure 7.6 provides the complementary actions to Rnap. Promoter implements the access control to genes, with three profiles analogous to those of Rnap: Promoter_free is dual to Rnap_free, and so forth. Transcription ensues once both Rnap and Promoter are open. As a result of a startTranscript call (line 12), Promoter_open spawns a RBS abstracting the first chunk of the transcript, and returns the channel rna pointing to its growing end to Rnap_open. The transition to Promoter_free is caused by Rnap_open's following call to getNext.

Both Nucleotide and Terminator extend on the persistent queuing Node. Rnap distinguishes them via isTerm queries, determining whether elongation should cease: Nucleotide returns false, whereas Terminator returns true. When calling elongate, Rnap sends a reference rna to the transcript's growing end.

```
module 'DNA('your favorite protein')'
1
2
   public
3
       rnap with bind /1
   import
4
     List (Node, Nil) from 'persistent queuing list'//Fig 5.8
5
     Mrna(Node, Terminator, RBS) from 'mRNA('your favorite
6
        protein ') '// Fig 7.8
7
          \rho_{\rm rna}, \rho_{\rm rbs} from 'Table 7.1'
   rate
8
   export
9
      Promoter with
                        unbind / 0, initiate / 0, start Transcript / 1
      Nucleotide extends List. Node by isTerm /1, elongate /2
10
      Terminator extends List. Node by isTerm / 1, terminate / 1
11
12
   define
      Promoter(me, next) \triangleq Promoter\_free(me, next)
13
      Promoter_free (me, next)
14
         rnap?bind(c).c!(me).Promoter_closed(me, next)
15
      Promoter\_closed(me, next) \triangleq
16
         me?unbind().Promoter_free(me, next)
17
18
       + me?initiate().Promoter_open(me, next)
19
      Promoter_open (me, next)
20
         new me_2: \rho_{rbs}. new rna: \rho_{rna}.
21
         me? start Transcript (c_1) \cdot c_1! (rna).
22
         me?getNext(c_2).c_2!(next).
23
             Promoter_free (me, next) | Mrna. RBS (me<sub>2</sub>, rna)
24
      Nucleotide_bound(me, next, v) extended by
25
26
         me?isTerm(c).c!false().Nucleotide_bound(me, next, v)
27
       + me?elongate(Rna,c). new rna_nxt:\rho_{rna}. c!(rna_nxt).
28
         Nucleotide_bound (me, next, v)
29
         Mrna. Nucleotide(rna,rna_nxt,v')
30
      Terminator_bound(me, next, v) extended by
         me?isTerm(c).c!true().Terminator_bound(me, next, v)
31
32
       + me?terminate(rna).new last:\rho_{rna}.
33
         Terminator_bound (me, next, v)
34
          | Mrna. Terminator(rna, last, v') | List. Nil(last)
```

Figure 7.6: DNA module

The DNA Nucleotide appends a Nucleotide of complementary content (for simplification indicated by v') imported from the 'mRNA' module. It returns the new growing extremity rna_nxt to Rnap. The hybrid Terminator completes the nascent transcript with an mRNA. Terminator, followed by a Nil.

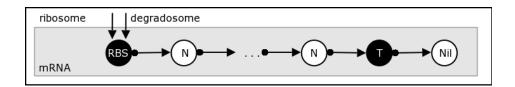


Figure 7.7: mRNA abstraction comprising processes RBS, Nucleotide, and Terminator. The latter two (here N and T) are based on the module 'degradable queuing list'. Note that the mRNA representative actually ends in a Nil object.

7.2 mRNA, translation and degradation

We base our model of mRNA on the module 'degradable queuing list' (Figure 5.9 on page 94). This accounts for two biologically relevant properties via object inheritance: the molecule's *unstable* character, and the *queuing* of the ribosomes and degradosomes processing it. Similarly as we did for DNA, we assemble mRNA from three components at different levels of abstraction illustrated in Figure 7.7. Different than in DNA processing, we do not explicity track the growth of the nascent transript while the abstraction of the translating ribosome proceeds along mRNA.

RBS. The two-profile RBS defined in Figure 7.8 represents the 5' end of mRNA, including the ribosomal binding site and the translation start signal. It implements the co-transcriptional race between translation and degradation. Decay initiates over the global channel degradosome in the free profile: after RBS has passed the reference to its successor (that it sends to profile bound) it becomes the inert process $\bf 0$ in line 15. If alternatively a Ribosome binds over the global channel ribosome, it causes a switch from RBS_free to RBS_bound (line 16). Similarly to the unstable intermediate on promoters, two interactions unbind (line 19) and initiate (line 18) become possible, reflecting reactions (2.2.8) and (2.2.9) in Table 2.2. Their quantitative behavior is fixed as usual by the ρ function associated with the RBS's me channel. We will give sample values in the following section.

Ribosome. In discussing translation elongation, we first consider the ribosome representative specified in Figure 7.9. Similarly as Rnap, it advances over individual Nucleotides of mRNA, while calling their elongate function in line 16. This accounts for reaction (2.2.10) in Table 2.2. Notice that elongate on mRNA takes no parameter, in contrast to that of DNA propagating the

```
module 'mRNA('your favorite protein')'
1
2
   public
3
       ribosome with bind /1
4
       degradosome with bind /1
5
   import
    List (Node, Nil) from 'degradable queuing list'//Fig5.9
6
    Protein from 'your favorite protein'
8
   export
9
      RBS with init /1, unbind /0
10
       Nucleotide extends List. Node by isTerm / 1, elongate / 0
       Terminator extends List. Node by isTerm / 1, terminate / 0
11
12
   define
13
      RBS(me, next) \triangleq RBS_free(me, next)
       RBS_free(me, next) \triangleq
14
          degradosome?bind(c).next!bind().c!(next).0
15
       + ribosome?bind(c).c!(me).RBS_bound(me, next)
16
      RBS_bound(me, next) \triangleq
17
          me?init(c).next!bind().c!(next).RBS_free(me,next)
18
       + me?unbind().RBS_free(me, next)
19
20
21
       Nucleotide_bound(me, next, val) extended by
          me?isTerm(c).c!false().Nucleotide_bound(me, next, v)
22
23
       + me?elongate(). Nucleotide_bound(me, next, v)
24
       Terminator_bound (me, next, val) extended by
25
26
          me?isTerm(c).c!true().Terminator(me)
       + me?terminate().
27
           Terminator_bound(me, next, val) | Protein
28
```

Figure 7.8: mRNA module

reference to the transcript's growing end. That is because our abstraction of translation disregards the actual assembly of a sequence of amino acids (which however may be covered by further refinement).

Reaching the Terminator the full protein representative is spawn via function terminate called by Ribsome_elongating in line 14. This corresponds to reaction (2.2.11).

Nucleotide and **Terminator.** Nucleotide objects propagate both translation and degradation, where the latter occurs via the function kill inherited

```
module
            'ribosome'
1
2
    public ribosome
              Ribosome
3
   export
4
   define
5
       Ribosome() \triangleq Ribosome_free()
       Ribosome_free() \triangleq
6
           ribosome!bind(c).c?(rna). Ribosome_bound(rna)
7
       Ribosome_bound(rna) \triangleq new c.
8
           rna!init(c).c?(next).Ribosome_elongating(next)
9
10
        + rna!unbind().Ribosome_free()
        Ribosome_elongating(rna) \triangleq
11
12
                 c_1.rna!isTerm(c_1)
13
                c_1?true().
14
                    rna!terminate().Ribosome_free()
15
              c<sub>1</sub>?false().
16
                    rna!elongate().
17
                   new c_2 \cdot rna! get Next (c_2) \cdot c_2? (next).
                    Ribosome_elongating(next)
18
```

Figure 7.9: Ribosome module

from a degradable queuing nodes. The Ribosome uses the inherited function getNext to step through the mRNA representative in translation; it stops on the Terminator due to its positive response to isTerm. The function elongate (line 27) that Ribosome calls remains without effect in this basic Nucleotide model.

Degradosome. The degradosome specification in Figure 7.10 is straightforward: after gaining access to the RBS, it stepwise destructs the whole mRNA, calling getNext (line 12) and kill (line 13) on each of its Nucleotides. Degradation stops at the end of the transcript (line 11) - note this occurs on Nil, not on the Terminator as does translation, by using functions isNil rather than isTerm. This distinction will prove useful when dealing with polycistronic mRNA. Another point worthwhile stating is that the propagation of decay is not covered by the reaction based view in Table 2.2.

Proteins. Proteins have many functions in the cell, that are not covered in this chapter. The only point we mention beyond their expression is their limited lifetime, reflected by a kill function for the degradation of Proteins of a certain type identified by prot:

```
1
   module 'degradosome'
   public degradosome
   export Degradosome
3
4
   define
    Degradosome() \triangleq Degradosome_free()
5
    Degradosome_free() \triangleq new c.
6
        degradosome!bind(c).c?(rna).Degradosome_working(rna)
7
8
9
    Degradosome_working(rna) \triangleq
       new b.rna!isNil(b).
10
          b?true() .rna!kill().Degradosome_free
11
12
       + b?false().new c.rna!getNext(c).c?(next).
13
             rna! kill(). Degradosome_working(next)
```

Figure 7.10: Degradosome module

channel	$ ho_{\mathbf{channel}}(\mathbf{function})$	quantifies
rnap	$\rho_{\mathrm{rnap}}(bind){=}0.1$	Rnap access to promoters over
		global channel
prom	$ ho_{ m prom}({\sf initiate}){=}0.1$	Rnap interaction with individual
		Promoter
	$ ho_{ m prom}({\sf unbind}){=}0.1$	
dna	$\rho_{\rm dna}({\sf getNext}){=}30$	Rnap's interaction with individual
		Nucleotide and Terminator of DNA
ribosome	$\rho_{ m ribosome}({\sf bind}){=}1$	Ribosome's initial access to RBS
degradosome	$ ho_{ m degradosome}({\sf bind}){=}0.1$	Degradosome's access to RBS
rbs	$ ho_{ m rbs}({\sf init}){=}0.5$	Ribosome's interaction with a RBS
	$ ho_{ m rbs}({\sf unbind}){=}2.25$	
rna	$ ho_{ m rna}({\sf getNext}) = 100$	Ribosome's and Degradosome's in-
		teraction with mRNA Nucleotide
		and Terminator
protein	$\rho_{\mathrm{protein}}(kill) = 0.002$	protein degradation

Table 7.1: ρ definitions for transcription, translation and mRNA decay

```
Protein \triangleq prot?kill().0
```

```
module 'operon'
   public ribosome with bind /1
         \rho_{\mathsf{rna}} from 'Table 7.1'
3
4
    List (Node) from 'persistent queuing list' // Fig. 5.8
5
    Mrna(Nucleotide, Terminator, RBS) from 'mRNA' // Fig. 7.8
6
7
    OperonLinker extends List.Node by isTerm/1, elongate/2
8
    InternalRBS extends Mrna. Nucleotide
9
10
    OperonLinker_free (me, next, v) \triangleq List. Node (me, next, v)
11
    OperonLinker_bound(me, next, v) extended by
12
13
        me?isTerm(c).c!false().OperonLinker(me, next, v)
     + me?elongate(rna,c).
14
          new rna_nxt:\rho_{rna}. new_rna_nxt2:\rho_{rna}.c!(rna_nxt2).
15
16
          OperonLinker_bound (me, next, v)
17
            Mrna. Terminator (rna, rna_nxt)
          InternalRBS(rna_nxt,rna_nxt2)
18
    InternalRBS (me, next, v) ≜ InternalRBS_free (me, next, v)
19
    InternalRBS_free (me, next, v) extended by
20
21
     + ribosome?bind(c).c!(me).InternalRBS_bound(me, next, v)
    InternalRBS_bound (me, next, v) ≜Mrna. RBS_bound (me, next, v)
22
```

Figure 7.11: Operon module

7.3 Parameterization

Table 7.1 gives sample values of the ρ function attributing rates to functions for transcription and translation. Functions not associated with a rate are instantaneous. Recall that each object is identified by its **me** channel, over which its function are invocated. This allows to associate method calls on different objects of the same class with distinct rates, as notably useful for initiation rates on promoters or ribosomal binding sites.

7.4 Particular promoter arrangements

We extend our components to cover particular promoter arrangements introduced in Section 2.3 on page 33.

7.4.1 Operons and polycistronic mRna

We devote a module to operons, and the polycistronic mRNA transcribed from them (Figure 7.11). It defines the processes OperonLinker and InternalRBS, that can be used in abstactions of DNA and mRNA respectively. OperonLinker is used to connect two genes that are co-transcribed within an operon. The interface it offers to Rnap_elongating is that of a regular Nucleotide on DNA, namely functions is Term in line 13, and elongate in line 14. This second is of particular interest: it spawns a transcript that comprises a mRNA Terminator, on which translation of the first protein stops (line 17), combined with an InternalRBS (spawn in line 18). On this latter, translation of the second protein may initiate – yet not degradation. Initial binding of the Ribosome occurs as on a regular RBS, via the global channel ribosome (line 21) while decay propagation is inherited from a regular mRNA Nucleotide. Ribosome unbinding and translation initiation are inherited from a regular RBS object in profile bound.

We can assemble an Operon after importing the previous modules. For better legibility we omit channel creations and parameterization.

```
\begin{array}{lll} \mathsf{Operon} & \triangleq \\ & \mathsf{Dna} \text{. Promoter} \\ & |_{i=1}^{\mathsf{length}(\mathsf{gene}\ 1)} & \mathsf{Dna} \text{. Nucleotide} & | & \mathsf{OperonLinker} \\ & |_{i=1}^{\mathsf{length}(\mathsf{gene}\ 2)} & \mathsf{Dna} \text{. Nucleotide} & | & \mathsf{Dna} \text{. Terminator} \end{array}
```

The transcription of our operon yields polycistronic mRNA coding for two different proteins², which are translated with distinct efficiencies (depending on the ρ function of RBS's me). Notice that translation of the first cistron ceases on the first terminator, while propagation continues over it.

```
\begin{array}{lll} {\sf PolycistronicMrna} & \triangleq \\ {\sf Mrna.RBS} & \mid_{i=1}^{{\sf length(gene~1)}} & {\sf Mrna.Nucleotide} \mid {\sf Mrna.Terminator} \\ \mid & {\sf InternaIRBS} & \mid_{i=1}^{{\sf length(gene~2)}} & {\sf Mrna.Nucleotide} \\ \mid & {\sf Mrna.Terminator} \mid & {\sf Node.Nil} \end{array}
```

When composing the operon in parallel with the molecular machines of transcription, translation, and mRNA decay, we obtain the following reduction sequence:

```
Operon | Rnap | Ribosome | Degradosome \rightarrow^* Operon | Rnap | Ribosome | Degradosome | PolycistronicMrna \rightarrow^* Operon | Rnap | Ribosome | Degradosome \mid \stackrel{n}{i=1} ProteinA \mid \stackrel{m}{i=1} ProteinB
```

² Notice the convenient parametricity of our module 'mRNA' in proteins.

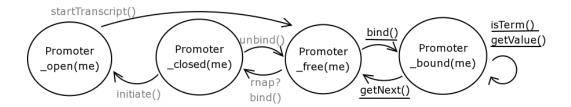


Figure 7.12: Transitions of tandem promoter. Underlined functions extend on those of the corresponding profiles of a DNA Promoter.

Eventually, the polycistronic mRNA has been transcribed, has yielded distinct numbers n and m of A and B proteins, and been degraded.

7.4.2 Tandem promoter

Let us now consider promoters arranged in a tandem, illustrated in Figure 2.6(c) on page 34. The interesting question lies in the representation of the *internal* promoter, over which transcription proceeds after it has initiated at the outer. Figure 7.13 presents the profile transitions of the tandem promoter as a stochastic π -calculus object, specified in Figure 7.13.

Promoter_free allows for binding of RNAP, and transcription initiation, as inherited from a regular promoter. The profile bound, that is not present for the previous promoter abstraction, offers RNAP_elongating the same interface as a regular Nucleotide from the 'DNA' module³. It is entered as RNAP_elongationg is about to leave the preceding Nucleotide, relying on the usual binding mechanism for queuing nodes: a call of function bind in line 10, triggered by RNAP's call of getNext on the predecessor nucleotide. In Promoter_bound the interesting point is the function elongate in line 15. Upon its call the transcript is appended a new element, offering translation initiation, but only propagation of decay. We previously designed an element of this functionality for transcripts resulting from operons: InternalRBS.

Promoter clearance. One of our simplifications so far is that a Promoter becomes available for new Rnap_free immediately upon after initiation, when switching to free. In reality RNAP clears its footprint stepwise, inducing a possibly limiting delay for highly efficient promoters, as those depicted in Figure 2.4(a). The model can be extended with an additional profile to reflect this synchronization, delaying the return to profile free until Rnap has

³It would fully do so by offering an additional function isNil, present in a persistent queing list node.

```
module 'tandem promoter'
1
2
   import
3
      P(Promoter) from 'DNA' // see Figure 7.6
       InternalRBS from 'operon'
                                    // see Figure 7.11
4
5
   rate \rho_{\rm rna} from 'Table 7.1'
6
   export
       Promoter extends P. Promoter by bind/0, is Term/1,
7
          getNext/1, elongate/2
8
   define
9
    Promoter_free (me, next) extended by
10
       + me?bind().Promoter_bound(me, next)
11
12
     Promoter\_bound(me, next) \triangleq
         me?isTerm(c).c!false().Promoter_bound(me, next)
13
      + me?getNext(c).next!bind().c!next.Promoter_free(me,
14
          next)
15
      + me?elongate(rna,c).new rna_nxt:\rho_{rna}.c!(rna_nxt).
          Promoter_bound (me, next) | Internal RBS (rna, rna_nxt)
16
```

Figure 7.13: Tandem promoter module

moved far enough. We included this is in our implementation, used for the simulations in Section 7.6.

7.5 Discussion: challenges in modeling

The integration of more biological detail can become increasingly challenging, namely when it comes to cover aspects related to secondary structures of mRNA (intrinsic termination of transcription, transcriptional attenuation), and two-way traffic on DNA and mRNA.

Attenuation of transcription. Consider the regulatory mechanism of transcriptional attenuation. In this case, transcription termination is determined by the efficiency at which translation proceeds over the nascent transcript. The crucial detail is that intrinsic termination depends on more than mere recognition of a terminator sequence. Terminator sequences actually comprise two sub-sequences with different effects. The first codes for an mRNA sequence that quickly forms a stable secondary structure, called hairpin. It is followed by a DNA sequence on which RNAP stalls. Both factors contribute to destabilize elongating RNAP, allowing the transcript below

its footprint to partly dissociate from the template strand. RNAP eventually falls off DNA. In transcriptional attenuation, the formation of the mRNA secondary structured is impaired by ribosomes that translate the mRNA portion forming the hairpin with sufficient efficiency. RNAP recovers from its speed loss and continues transcription over the terminator. Capturing this would require more elaborate mechanisms of concurrent control than so far, specifically regarding RNAP's dependency on the last chunk of mRNA assembled.

Antitermination of transcription on intrinsic terminators is related to attenuation. Regarding certain cases one could satisfyingly deal with it, while covering less detail than required for attenuation. The simplest strategy would be to introduce an additional profile antiterminated for RNAP, which continues over terminator signals. Transition to this profile would be triggered by interaction of Rnap_elongating with regulatory proteins.

Two-way traffic occurs both on DNA and mRNA. The concurrent control supported so far can not yet account for traffic problems on double-stranded DNA (one of two RNAP falls off after a head-on collision), nor for details of mRNA decay. So far we only realized queuing control on single stranded macromolecules, which are processed in one direction. Our model of mRNA decay is phenomenological, a detailed one would cover the initial step of decay, in which the transcript is cleaved by one member of the degrado-some proceeding with the same orientation as transcription, and subsequent decomposition of isolated mRNA chunks by another enzyme in opposite direction.

7.6 Simulation of translational bursting

In this section we present simulations obtained from our model components with the BioSpi tool (Priami et al., 2001), after encoding input patterns within the stochastic π -calculus. Our focus lies on the effect of translational bursting introduced in page 37. We hence compare the dynamics of unregulated expression of a single gene under variation of two crucial parameters. The underlying model is that of a single gene comprising 1000 nucleotides, its transcription into mRNA, and subsequent translation and degradation. As experimentally confirmed by Ozbudak et al. (2002), the variation of transcription of translation initiation parameters leads to significant differences in expression patterns. These would not appear in continuous deterministic simulation, which nevertheless yield comparable average expression levels, nor can they be reproduced by one step models of gene expression as that of

Blossey, Cardelli, and Phillips (2006). Our parameter combinations are the following:

- (a) In the setting we refer to as *bursty*, the promoter yields rare transcription initiations (k_{init} of 0.01). This is combined with efficient translation (k_{init} of 1).
- (b) The *smooth* setting inverts the parameters: transcription initiates more frequently $(k_{init} \text{ of } 0.1)$, while translation initiation is rarer $(k_{init} \text{ of } 0.1)$.

The mRNA and protein decay rates are the same for both settings, 0.1 and 0.002 respectively. They are taken from Ozbudak et al. (2002) as the above parameters, and the number of RNAP, ribosomes and degradosomes. We executed both combinations for 7 hours of simulated time.

Figure 7.14 reports a representative run for each of the two settings. The left curve in Figure 7.14(a) displays the evolution of the protein level over time for an execution of the bursty combination. The protein level fluctuates strongly around an average of 55, marked by a horizontal line. The fourth hour exhibits the strongest variability: after it has almost emptied, the protein pool replenishes rapidly to a maximal level around 140. We provide a summary of the protein levels observed over the whole simulation period by the histogram to the right of Figure 7.14(a). Here the simulated time is divided into equally long intervals. The bars indicate by their height how often a given number of proteins (labeled on the horizontal axis) is observed.

Simulations based on the *smooth* setting have a clearly distinct behavior, as shows Figure 7.14(b) where the protein level only weakly fluctuates around an average of 46^4 . The histogram confirms that the distribution is pronouncedly narrowed compared with the previous setting.

An alternative interpretation of the histograms is as population snapshots, with respect to the expression level of a given protein. In this view the height of the bars indicate the fraction of the population with a certain protein level. This shows how for the setting bursty, the variability propagates from the time course within an individual cell, up to population heterogeneity; while for the setting smooth the population remains considerably more homogeneous.

In the following table we adopt another perspective on the same data. The second column reports the mean protein crop per transcript, which averages to 10 for setting *bursty*. New transcripts appear about every 100 seconds (3rd column). This explains the drops observed in Figure 7.14(a)

⁴When averaging over many simulation runs, both settings yield the same average protein level.

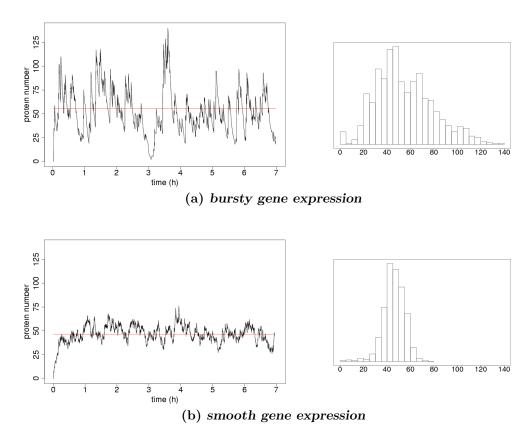


Figure 7.14: Basal expression of a single gene under parameter variation, yielding average protein crops per mRNA: (a) 10, (b) 1. Left: time course of protein numbers, right: histogram of protein number over the simulated period.

over periods in which the effect of protein degradation surpasses that of expression. Setting *smooth* behaves differently. It yields approximately one protein per transcript, fresh transcripts become available every 10 seconds, and both together result in weak fluctuations. Note that while the total number of transcriptions for setting *smooth* almost tenfold exceeds that of *bursty* (4th column), the total number of protein produced differ far less across the two settings (5th column):

setting	proteins	avg. spacing be-	total	total
	per tran-	tween transcript	transcrip-	transla-
	script	initiations	tions	tions
bursty	≈ 10	$\approx 100 \text{ sec}$	250	2725
smooth	≈ 1	$\approx 10 \text{ sec}$	2318	2338

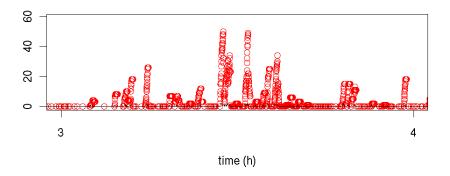


Figure 7.15: Concurrent translation of mRNA by multiple ribosomes during simulation from Figure 7.14(a).

Origin of translational bursting. We could not yet observe the origin of the strong bursts in protein numbers in Figure 7.14(a). This motivates further inspection of setting bursty's simulation data. Figure 7.15 displays the numbers of translating ribosomes (circles) within the fourth hour of the simulation period, in which the protein pool empties, and then rapidly replenishes to the maximum. While the number of full mRNA molecules a never times exceeds two (data not shown), these are simultaneously processed by up to 50 ribosomes. As discussed page 37 the strongest bursts in protein levels occur when for a mRNA, the number of translations by far exceeds the average. The column-reminiscent peaks mark transcripts yielding exceptionally high protein crops; this is in agreement with a geometric distribution.

The circles forming the bottom line may first appear peculiar. They can be explained as follows. For setting bursty new transcriptions are completed every 100 seconds. However, recall that nascent transcripts are translated co-transcriptionally. This means that whenever some RNAP is producing a transcript (which takes around 100 seconds), one or more ribosomes closely follow it on the nascent mRNA. Hence the bottom line reflects that there is virtually always some coupled transcription and concomitant translation going on.

CHAPTER 8

Transcription Regulation at the Lambda Switch

The discussion in the previous chapter considered only basal gene expression. The expression of any actual gene is however subject to regulation. This chapter is dedicated to modeling transcription initiation control at the λ switch in our stochastic π -calculus with concurrent objects, and validation of this model through simulation with the BioSpi engine. We will cover the details of regulatory interactions described in Chapter 3, involving the two promoters P_{RM} and P_R , the three operator regions on DNA controlling them, and the regulatory proteins Cro and λ repressor. In modeling transcriptional regulation at the λ switch, we make large use of the modeling techniques from Chapter 6.

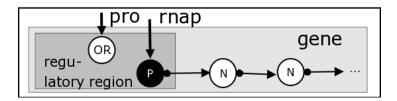


Figure 8.1: Sketch of regulatory region

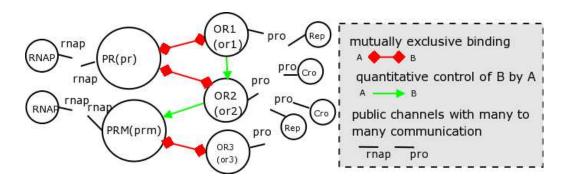


Figure 8.2: Molecular population and regulatory interactions

8.1 Overview

Before presenting the comprehensive model of the λ switch, we discuss modeling techniques for isolated aspects. Let us begin with a promoter, that is subject to control by one DNA operator region to which proteins bind. The outline of its π -calculus model in Figure 8.1, does not yet specify the actual mechanism regulating transcription initiation. Negative control would mean mutually exclusive access relation between the promoter and operator region. This can be covered by the mutual exclusion mechanism introduced in Section 6.3. Alternatively the gene may be positively controlled: RNAP's transcription initiation frequency could increase through the presence of a regulatory protein at the operator (not overlapping the promoter, but located in its vicinity). This would in a stochastic π -calculus model be reflected by adjustment of the promoter's initiate rate, based on the mechanism from Section 6.5

Population members and interaction topology. Let us now consider more detail to incorporate into our model. Figure 8.2 summarizes the λ switches' population: the operators OR1, OR2, and OR3 can be bound by the regulatory proteins Cro and Rep— in our model this occurs over the global channel pro. The promoters PRM and PR can be bound by RNAP via channel rnap. These two bindings occur in a many-to-many fashion using the mechanism from Section 6.1. Our model introduces the following profiles. Operator representatives can be free, rep, cro, or blocked. Promoter PR complements the profiles introduced in Section 7.1, where we did not yet consider repression, by a blocked profile. PRM additionally replaces the RNAP-bound profile closed by two others, in oder to distinguish the efficiency

8.1 Overview 129

	O_{R1}	O_{R2}	O_{R3}	P_{R}	P_{RM}
protein specific unbinding rate					
mutual exclusion					
quantitative control of other					
quantitatively controlled by other					

Figure 8.3: Summary: interactions and dependencies at the λ switch

of transcription initiation at high or low level, depending on OR2's binding state.

Concurrent control. We distinguishing two types of edges that indicate relations between operators and promoters.¹ Red edges represent mutual exclusion relations between population members. Each such edge yields four functions, for blocking and unblocking of the respective molecular actors. We introduce mnemonic names. For instance, the red edge between PRM and OR3 will be realized by OR3's function blockedByPrm, PRM's blockedByOr3, and two functions for the reverse actions of unblocking. All these basically rely on the mutual exclusion mechanism from Section 6.3.

Green edges indicate quantitative control of reactions, i.e. cooperative binding of the λ repressor protein to O_{R2} and O_{R1} , and positive control of transcription initiation frequency at P_{RM} . We here instantiate the mechanism for rate adjustment from Section 6.5, i.e. for up- and downregulating OR2's unbind rate and that of PRM's initiate. Figure 8.3 summarizes the mechanisms observed for the various members of the population. Each entry is realized as an object function in our model.

Promoters. Summarizing, the abstractions of the λ switch promoters P_R and P_{RM} extend on the generic Promoter from the module 'DNA' (see Figure 7.6) as follows. They are repressible by the operators overlapping them. Modeling this relies on the mutual exclusion mechanism from Section 6.3. In addition, the efficiency of transcription initiation at PRM increases as Repressor is bound to OR2. For this, we instantiate the technique introduced in Section 6.5. Notice that we could, in principle, obtain the model of PR by extension from the generic one, since all necessary operations represent additional input patterns in the respective profiles. Regarding PRM, we would need to rewrite some more, in order to distinguish the transcription

¹Each of these edges replaces an *update channel* in the topology of our earlier stochastic π -calculus model (Kuttler and Niehren, 2006).

²The only real obstacle would be to separately fix the ρ of the RBs representative.

```
1 Protein_free ≜
2 new c.pro!bind(c).c?(or).Protein_bound(or)
3 Protein_bound(or) ≜ or!unbind().Protein_free
4 
5 OR_free(me) ≜ pro?bind(c).c!(me).OR_bound(me)
6 OR_bound(me) ≜ me?unbind().OR_free(me)
```

Figure 8.4: Many-to-many docking of proteins to DNA operator sites.

initiation levels. For the sake of presentation, in this document we however spell out the complete 'PRM' and 'PR' modules.

Operator regions. Throughout this chapter we will incrementally refine models of *operator regions* on DNA to include all required aspects. Let us start with the minimal version, that is analogous to the previous Site from Figure 6.2 (page 99). The OR defined in Figure 8.4 offers many-to-many binding to proteins over a global channel pro while in profile free, and subsequent communication over its private channel while bound.

Let us relate this π -calculus model to the chemical reaction in Table 3.1, page 47. The communication on channel pro corresponds to the forward direction in reaction (3.1.1). The offer pro?bind made by the process OR_f ree (line 5) accounts for the participation of molecule OR, that of process $Protein_f$ ree in line 2 to that of the transcription factor TF.

Upon binding, Protein obtains the OR's identifier channel, over which it later invocates function unbind (lines 3 and 6)

Specificity of operator protein pairs. Proteins specifically attach to DNA, i.e. with a stability reflecting their match with the operator region's sequence: the same protein can bind more or less stably to different regions; while at the same site, the binding of different proteins can vary in strength. We introduced a technique to modify a function's apparent rate in Section 6.5. Here we use the same strategy to build an abstraction of an operator region offering a uniform unbind function to any protein attached, while adjusting its *rate* to the actual protein. The operator's profile name explicitly reflects this information.

Figure 8.5 lists this module 'OR with specificity'. In order to select the appropriate unbinding rate, the site identifies the protein upon binding, see lines 10–11. We therefore introduce an explicit profile OR_switching, exposing two functions specCro and specRep. These are requested by the proteins Cro

8.1 Overview 131

```
module 'OR with specificity'
2
    public pro with bind/1
3
   export
      OR with unbind / 0, specCro / 0, specRep / 0
4
5
6
    define
7
       OR(me) \triangleq OR_free(me) \mid Timer(me)
8
       OR_{free}(me) \triangleq pro?bind(c).c!(me).OR_{switching}(me)
       OR_switching(me) \triangleq
9
           me?specCro().OR_cro(me)
10
        + me?specRep().OR_rep(me)
11
       OR\_cro(me) \triangleq me?timerCro().me?unbind().OR\_free(me)
12
       OR_{rep}(me) \triangleq me?timerRep().me?unbind().OR_free(me)
13
       Timer(c)≜
14
15
           c!timerCro().Timer(c)
16
        + c!timerRep().Timer(c)
```

Figure 8.5: Operator adjusting its unbinding rate to proteins Cro and Rep

and Rep binding the operator, thus identifying themselves and causing the operator's continuation in the appropriate bound profile.³

Repressor protein. Figure 8.6 specifies the abstraction of the λ repressor protein, that as a dimer regulates the λ switch through binding to the sites O_{R1} , O_{R2} , and O_{R3} . Rep_dimer binds DNA through many-to-many communication over pro, hereby identifying itself to operators by calling the function specRep. For completeness the module also includes dimerization of the monomeric form. We omit a statement in the module that would be used to create and export a population Rep_monomers of a given size, together with one timer providing co-actions on lam_undimerize.

Our following discussion of the λ switch constituents proceeds from the simpler O_{R3} (with only a mutual exclusion edge in the above population diagram), to the other operator regions and promoters with refined control

³A note on the possibility of *unspecific* protein binding. Our Operator_switching could additionally offer a function unspecific, and proteins could request this upon binding, as an alternative to their respective specific functions. The problem is that such a solution does not yet combine with our semantics, in which alternative (instantaneous) choices are resolved non-deterministically. It would however work if choices between instantaneous alternatives were worked through sequentially, until the first match is found. An alternative would consist in an explicit conditional statement with *otherwise*, as offered by the BioSpi tool.

```
1
   module 'lambda repressor'
2
   public pro,lam_undimerize,lam_dimerize
3
   export Rep_monomer
   define
4
5
      Rep_monomer ≜
6
          lam_dimerize!().Rep_dimer
       + lam_dimerize?(c).0
7
       Rep_dimer \triangleq new c.
8
          pro!bind(c).c?(or).or!specRep().Rep_bound(or)
9
       + lam_undimerize?().Rep_monomer | Rep_monomer
10
11
       Rep_bound(or) \triangleq or!unbind().Rep_dimer
```

Figure 8.6: Module 'lambda repressor'

mechanism (see their increasing connective).

Parameterization. Figure 8.7 gives an overview of the functions offered by our objects (identified by the channels of corresponding names), together with their parameterization which is based on Table 3.2 on page 48. We would like to emphasize the crucial importance of the functions with infinite stochastic rates, which are executed without advance of the simulation clock.

8.1 Overview 133

channel	$ ho_{ m channel}({\sf function})$	
rnap	$\rho_{\text{rnap}}(bind) = 0.098$	
prm	$ ho_{ m prm}({\sf initiate}){=}\infty$	$\rho_{prm}(unbind) = 0.788$
	$\rho_{prm}(highTimer) = 0.086$	$\rho_{prm}(lowTimer) {=} 0.005$
	$\rho_{prm}(getNext) = 30$	$\rho_{prm}(startTranscript){=}30$
	$ ho_{prm}(freedByOr3) = \infty$	$ ho_{prm}(blockedByOr3) = \infty$
	$ ho_{\sf prm}({\sf raisedByOr2}) = \infty$	$ ho_{prm}(resetByOr2) = \infty$
pr	$ ho_{ m pr}({\sf initiate}){=}0.05$	$ ho_{ m pr}({\sf unbind}){=}0.155$
	$ ho_{pr}(freedByOr2) = \infty$	$ ho_{pr}(blockedByOr2) = \infty$
	$ ho_{pr}(freedByOr1) = \infty$	$ ho_{ m pr}({ m blockedByOr1})=\infty$
pro	$\rho_{\mathrm{pro}}(bind) = 0.098$	
or1	$ ho_{or1}(unbind) = \infty$	
	$\rho_{or1}(timerRep){=}0.155$	$\rho_{or1}(timerCro){=}2.45$
	$ ho_{or1}(specRep){=}\infty$	$ ho_{or1}(specCro){=}\infty$
	$ ho_{or1}(freedByPr) = \infty$	$ ho_{or1}(blockedByPr){=}\infty$
or2	$ ho_{or2}(unbind) = \infty$	$ ho_{ m or2}({ m timerRepHigh}){=}0.155$
	$\rho_{\text{or2}}(\text{timerRepLow})=3.99$	$\rho_{or2}(timerCro){=}2.45$
	$ ho_{or2}(specRep){=}\infty$	$ ho_{or2}(specCro){=}\infty$
	$\rho_{or2}(freedByPr) = \infty$	$ ho_{or2}(blockedByPr){=}\infty$
	$ ho_{or2}(raisedByOr1) = \infty$	$ ho_{or2}(resetByOr1){=}\infty$
or3	$ ho_{or3}(unbind) = \infty$	
	$\rho_{\text{or3}}(\text{timerRep})=20.22$	$\rho_{\text{or3}}(\text{timerCro}) = 0.29$
	$\rho_{or3}(specRep) = \infty$	$\rho_{or3}(specCro) = \infty$
	$\rho_{or3}(freedByPrm) = \infty$	$ ho_{or3}(blockedByPrm){=}\infty$
lam_dimerize	$\rho_{lam_dimerize} = 0.048$	
lam_undimerize	$ ho_{lam_undimerize} = 0.5$	

Figure 8.7: Public channels of the λ switch model and their ρ definitions

```
'OR3'
1
   module
2
   public pro with bind /1, or 3 as me, prm
3
   import
       Timer from 'timer(timerCro,timerRep)' // see Fig.6.9
4
5
   export OR3 with unbind / 0, specCro / 0, specRep / 0,
       blockedbyPrm / 0, freedByPrm / 0
6
   define
7
      OR3 \triangleq OR3_free \mid Timer(me)
       OR3_free ≜
8
          pro?bind(c).c!(me).
9
10
             me?specCro().OR3_cro
           + me?specRep().OR3_rep
11
       + me?blockedByPrm().OR3_blocked
12
       + prm!freedByOr3().OR3_free
13
       OR3_rep ≜
14
          me?timerRep().me?unbind().OR3_free
15
       + prm!blockedByOr3().OR3_rep
16
       OR3_cro ≜
17
          me?timerCro().me?unbind().OR3_free
18
19
       + prm!blockedByOr3().OR3_cro
20
       OR3_blocked ≜
          me?freedByPrm().OR3_free
21
```

Figure 8.8: O_{R3} module

8.2 Model components

We now specify the abstractions of our three operator sites and two promoters at the λ switch.

8.2.1 Abstraction of O_{R3}

We consider the abstraction of the site O_{R3} , that overlaps with the promoter P_{RM} and thus determines repression of the cI gene. It is the least complicated component of the λ switch, as indicated by the smaller number of edges interconnecting it, in the population overview of Figure 8.2. It nonetheless integrates the mechanism of specific binding for the proteins Rep and Cro.

Protein binding via the global channel pro occurs in the usual many-to-many manner, introduced in Section 6.1. Identification of the protein type occurs on the fly in lines 10-11, as introduced by the generic operator in Figure 8.5. Profile OR_free offers two other interactions: Line 12 accepts pat-

```
module 'OR1'
2
   public pro with bind /1, pr, or2, or1 as me
3
   import
       Timer from 'timer(timerCro, timerRep)' // Fig. 6.9
4
5
   export OR1 with unbind / 0, specCro / 0, specRep / 0,
       freedByPr/0, blockedByPr/0
6
7
   define
8
      OR1 \triangleq OR1_free \mid Timer(me)
       OR1_free ≜
9
          pro?bind(c).c!(me).
10
              me?specCro().OR1_cro
11
12
            + me?specRep().OR1_rep
       + or2!resetByOr1().OR1_free
13
       + pr!freedByOr1().OR1_free
14
       OR1_cro ≜
15
          me?timerCro().me?unbind().OR1_free
16
       + pr!blockedByOr1().OR1_cro
17
       OR1_{rep} \triangleq
18
          me?timerRep().me?unbind().OR1_free
19
20
       + or2!raisedByOr1().OR1_rep
21
       + pr!blockedByOr1().OR1_rep
22
       OR1_blocked ≜
          me?freedByPr().OR1_free
23
```

Figure 8.9: O_{R1} module

tern input matching blockedByPrm, this corresponds to become occluded and is performed by PRM residing in some bound profile. As a consequence, PR switches to its blocked profile. In line 13, OR3_free releases a block on PRM by calling its freeByOr3. This is performed instantaneously upon becoming free. This mutual exclusion with $P_{\rm RM}$ relies on the technique introduced in the module 'Overlapping Space' from Section 6.3. Note that loops of free/block calls without advance of the simulation are excluded, under the assumption of an appropriate stochastic parameterization. In such, all communications are instantaneous, except for calls of bind over the global channel pro, and unbind over the operator's identifier.

8.2.2 Abstraction of O_{R1}

 O_{R1} exhibits only a single feature not yet present at O_{R3} , beyond mutual exclusion with P_R and specific protein binding. It quantitatively controls the

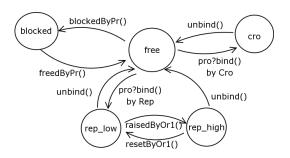


Figure 8.10: Transitions of OR2

binding rate of the λ repressor protein at O_{R2} , as symbolized by a green edge in Figure 8.2. In order to reflect this, our model OR1_rep calls the function raisedByOr1 on OR2, see line 20 in Figure 8.9. The reverse reaction occurs once the repressor protein has left, see OR1_free's call of resetByOr1 on OR2 in line 13. We discuss OR2's responses to these function calls in the following section.

8.2.3 Abstraction of O_{R2}

 O_{R2} is the most demanding λ switch component from the modeling point of view, since it combines all control aspects as reported in Figure 8.3. We summarize the state transition of OR2 in Figure 8.10 and list its specification in Figure 8.11.

Specific protein binding. Docking of regulatory proteins occurs in the usual fashion in profile free, line 12. Note that all three protein-bound profiles offer the unbind function. The timing of this latter relies on the complementary action of a tailored Timer, created from module 'timer(f1,...,fn)'.

Cooperative repressor binding with OR1. Note that as a repressor protein binds, OR2 initially switches to rep_low, regardless of the possible presence of another repressor at the O_{R1} representative. Figure 8.10 summarizes what happens next. A transition to OR2_rep_high ensues instantaneously by OR1_rep, calling raisedByOr1 in its line 29. O_{R2} 's profile for cooperative binding rep_high is left in line 29, because OR1 becomes free, or in line 28 upon local unbinding of repressor.

Positive control of initiation at PRM. OR2 exerts positive control of transcription initiation by calling raisedByOr2 over PRM's identifier

channel prm. It does so in profile rep_low (line 25), as well as rep_high (lines 30).

Mutual exclusion of binding with PR. In all three protein bound profiles, OR2 inhibits PR by calling blockeByOr2 (lines 20, 24, and 31).

```
1
   module 'OR2'
2
   public pro with bind /1, or 2 as me, prm, pr
3
    Timer from 'timer(timerRepHigh, timerRepLow, timerCro)'
4
5
       // see Fig. 6.9
6
   export
7
     OR2 with
                  unbind /0, specCro /0, specRep /0,
     blockedByPr/0, freedByPr/0, raisedByOr1/0, resetByOr1/0
8
9
      OR2 \triangleq OR2_free \mid Timer(me)
10
      OR2_free ≜
11
      + pro ?bind(c).c!(me).
12
             me?specCro().OR2_cro
13
           + me?specRep().OR2_rep_low
14
15
      + pr!freedByOr().OR2_free
16
      + prm!resetByOr2().OR2_free
      + me?blockedByPr().OR2_blocked
17
18
      OR2_cro ≜
          me?timerCro().me?unbind().OR2_free
19
20
       + pr!blockedByOr2().OR2_cro
       OR2_{rep_low} \triangleq
21
22
          me?timerRepLow().me?unbind().OR2_free
23
       + me?raisedByOr1().OR2_rep_high
24
       + pr!blockedByOr2().OR2_rep_low
       + prm!raisedByOr2().OR2_rep_low
25
26
       OR2_rep_high ≜
27
          me?timerRepHigh().
28
             me?unbind().OR2_free
       + me?resetByOr1().OR2_rep_low
29
30
       + prm!raisedByOr2().OR2_rep_high
       + pr!blockedByOr2().OR2_rep_high
31
32
       OR2\_blocked \triangleq me?freedByPr().OR2\_free
```

Figure 8.11: O_{R2} module

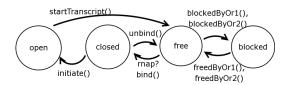


Figure 8.12: Transitions of PR

8.2.4 Abstraction of P_R

The abstractions of two λ switch promoters P_R and P_{RM} resemble that of the generic model in Figure 7.6, while adding their distinct features. The specialty of PR is to depend on a more intricate mutual exclusion mechanism than PRM. We need to cope with mutual exclusion with *both* operator regions O_{R1} and O_{R2} . Each of these is covered by our usual mechanism from Figure 8.13 on page 139, i.e. by dedicated functions for blocking and reversing the block.

It is worthwhile attention is that both representatives OR1 and OR2 send PR_blocked to PR_free as themselves become free upon protein unbinding. In this case however, the respectively other operator forces PR back to blocked instantaneously if itself is still bound by some protein: OR1 ensures this in lines 17 and 21, see Figure 8.9. For OR2 listed in Figure 8.11 see lines 20 (in profile cro), in profiles rep_low and rep_high lines 24 and 31. These multiple dependencies are not evident from PR's isolated transition diagram in Figure 8.12.

8.2.5 Abstraction of P_{RM}

Last but not least, we move to the abstraction of P_{RM} . There is one significant difference to consider, compared to P_R : positive control of transcription initiation. RNAP switches between two alternative rates for its function initiate, reflecting the presence of a repressor protein at O_{R2} .

Our model in Figure 8.14 deals with this quantitative control in the previously introduced manner. It maintains the interface, i.e. the functions offered to the RNAP representative while varying the initiation rate. As previously the technical solution consists in introducing alternative profiles for the RNAP bound state, PRM_low and PRM_high. In both the externally apparent rate of function initiate is internally determined by a Timer. Switching between the two profiles is subject to concurrent control by OR2, via invocations of the instantaneous functions raisedByOr2 (line 22) and resetByOr2 (line 28).

```
module 'PR'
1
2
   public rnap with bind /1, pr as me,
       cro_gene as next, or1, or2
3

ho_{\mathsf{rbs\_pr}} , 
ho_{\mathsf{rna}} from 'Table 7.1'
4
   import RBS from module 'mRNA' // Fig7.8
6
   export PR with blockedByOr1/0, freedByOr1/0,
7
       blockedByOr2/0, freedByOr2/0, unbind/0, initiate/1,
8
       free / 1, start Transcript / 1
9
   define
10
       PR \triangleq PR_free
       PR_free ≜
11
12
          rnap?bind(c).c!(me).PR_closed
13
       + me?blockedByOr2().PR_blocked
14
       + me?blockedByOr1().PR_blocked
15
       + or1!freedByPr().PR_free
       + or2!freedByPr().PR_free
16
17
       PR_blocked ≜
18
19
          me?freedByOr1().PR_free
20
       + me?freedByOr2().PR_free
21
       PR_closed \triangleq
22
23
           me?unbind().PR_free
24
        + me?initiate().PR_open
        + or1!blockedByPr().PR_closed
25
26
        + or2!blockedByPr().PR_closed
27
       PR_open ≜
28
29
          new rbs_pr: \rho_{\text{rbs\_pr}}. new rna: \rho_{\text{rna}}.
         me?startTranscript(c).c!(rna).
30
31
         me?getNext(c_2).c_2!(next).
32
             PR_free | RBS(rbs_pr,rna)
```

Figure 8.13: P_R module

```
1
   module 'PRM'
2
   public rnap with bind /1, prm as me,
       cl_gene as next, or2, or3
3
   rate \rho_{\text{rbs\_prm}}, \rho_{\text{rna}} from 'Table 7.1'
4
   import
5
6
    RBS from module 'mRNA' // Fig 7.8
7
    Timer from 'timer(lowTimer, highTimer)' //Fig. 6.9
   export PRM with getNext/0, unbind/0, initiate/1,
9
       startTranscript /1, freedByOr3 /0, blockedByOr3 /0,
10
       raisedByOr2/0, resetByOr2/0
   define
11
      PRM \triangleq PRM_{vacant} \mid Timer(me)
12
13
14
       PRM_free ≜
          me?blockedByOr3().PRM_blocked
15
16
       + or3!freedByPrm().PRM_free
17
       + rnap?bind(c).c!(me).PRM_low
18
       PRM low ≜
19
20
         me?lowTimer().me?initiate().PRM_open
       + me?unbind().PRM_free
21
22
       + me?raisedByOr2().PRM_high
       + or3!blockedByPrm().PRM_low
23
24
       PRM_high ≜
25
26
         me?highTimer().me?initiate(c).PRM_open
27
       + me?unbind().PRM_free
28
       + me?resetByOr2().PRM_low
29
       + or3!blockedByPrm().PRM_high
30
       PRM_open ≜
31
32
          new rbs_prm: \rho_{\text{rbs\_prm}}. new rna: \rho_{\text{rna}}.
          me?startTranscript(c).c!(rna).
33
          me?getNext(c_2).c_2!(next).
34
35
              PRM_free | RBS(rbs_prm, rna)
36
37
       PRM_blocked \triangleq
          me?freedByOr3().PRM_free
38
```

Figure 8.14: P_{RM} module

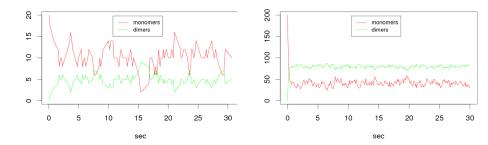


Figure 8.15: Dynamics of formation and breakage of λ repressor dimers over 30 simulated seconds, starting from 20 monomers (left) or 200 (right)

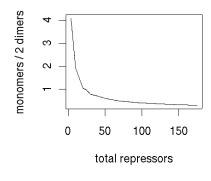


Figure 8.16: Shift of concentration dependent equilibrium between monomers and dimers

8.3 Simulation and discussion

We next validate our π -calculus model of the dynamics at the λ switch by exhaustive stochastic simulation. These are performed by execution with the BioSpi system (Priami et al., 2001).

Given its complexity, it does not make sense to directly simulationg the complete system. We use a sequence of models of distinguished subsystems in order to evaluate the different components independently. From the software engineering perspective, this allows to to successively validate the components. During our own work, the bottom-up approach to simulation was central to the establishment of a faithful set of stochastic parameters. From the biological standpoint, it is a current practice to isolate subsystems in order to observe their aspects as independently as possibly. The π -calculus programming approach is advantageous in that perspective, in that it allows to freely design and compose subsystems of interest.

It is a particular concern of ours to perform simulations of subsystems that can be clearly related to existing knowledge, either experimental or from established other simulation studies. Our strategy is incremental and bottom up. First we present simulations of repressor dimerization. We continue with binding of the protein Rep to DNA, and the impact of dimerization on binding patterns and cooperative interaction between Rep on DNA. Finally we investigate interactions between RNAP, the promoter $P_{\rm RM}$, and Rep's positive control thereof. The control of transcription initiation from $P_{\rm RM}$ is highly relevant. It has been subject to a number of theoretical and experimental studies as those of Baek et al. (2003), Bakk (2005) Li et al. (1997), Shea and Ackers (1985). The key to repression of this promoter has recently been revealed (Dodd et al., 2001). The model presented in this thesis may be extended to cover it in the future.

8.3.1 Dynamics of dimer formation and breakage

The essential point about repressor dimerization is the concentration dependent equilibrium (Ptashne, 2004). Figure 8.15 visualizes the dynamics of dimerization, starting with different numbers of monomers, as declared in Figure 8.17. When launched with 20 monomers, such a system tends to-

```
public lam_undimerize, lam_dimerize from 'Table 8.7'
import
'lambda repressor' // see Figure 8.6
Timer from 'elementary timer' // see page 104
define
| __i^n Rep_monomer | Timer(lam_undimerize)
```

Figure 8.17: Setup: simulating dimerization starting from n repressor monomers

wards a mean setting in which around around half the total repressors can be found as monomers, while the others are present as dimers. Note that in this case, one observes strong fluctuations (see Figure 8.15 left). Only a rough quarter of initially 200 monomers are present as such in average, while around 75% are dimer-bound - with less important fluctuations. The *shift* of the equilibrium towards dimers becomes more obvious as we plot the average ratio of repressors present as monomers to that of dimer-bound ones over a long time range for various total repressor amounts, see Figure 8.16.

Figure 8.18: Binding to isolated operator sites, assuming 100 repressor monomers.

	ΔG	mean	bound
		sojourn	
O_{R1}	-12.5	6.4	96 %
$ m O_{R2}$	-10.5	0.25	46 %
O_{R3}	-9.5	0.05	15~%

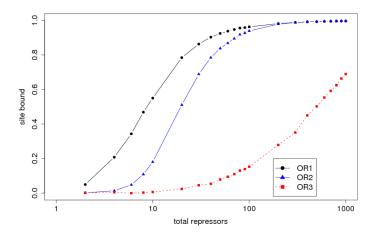


Figure 8.19: Occupancy of sites O_{R1} , O_{R2} and O_{R3} in the presence of dimerization and cooperative binding. Each point represents the relative occupancy of a site over 5000 simulated seconds, for some total repressor number. In a lysogen, one can expect 100-200 total repressors.

```
public pro, or;, lam_dimerize, lam_undimerize //i \in \{1,2,3\}' import

'lambda repressor' // see Figure 8.6

OR from 'OR with specificity' // see Figure 8.5

Timer from 'elementary timer' // see page 104

rate \rho_{\text{ori}} from 'Table 8.7'

define

OR(or;) |_{k=1}^n Rep_dimer | Timer(lam_undimerize)
```

Figure 8.20: Setup: simulating repressor binding to isolated operator O_{Ri}

8.3.2 Repressor interactions with and on DNA

We now consider the binding of repressor dimers to operator sites on DNA. The set up in Figure 8.20 permits to simulate site O_{R1} and n repressor dimers that can reversibly attach to it, or dissociate back to monomers: By adjustment of ρ_{ori} (unbind) we can simulate binding to the *isolated* sites O_{R1} , O_{R2} and O_{R3} . Figure 8.18 summarizes the corresponding simulations, emphasizing the impact of different binding site site affinities. Recall from Section 3.2 that a smaller value of the Gibbs free energy ΔG indicates a stronger binding, hence a higher saturation of the site.

We make two corresponding observations. The complex of repressor and operator site is most stable at O_{R1} , where we observe an average sojourn time of Rep of 6.4 seconds (this value is the mean of an exponential distribution not shown here). This is consistent with reports of Ptashne (2004) that binding of repressor to O_{R1} persists in the order of up to 10 seconds. For O_{R2} and O_{R3} less favorable ΔG s lead to drastic drops of complex stability.

The effect is also visible when considering not individual binding events, but average behavior. For a given concentration and a long time scale, O_{R1} is better saturated with repressor than any of the other sites. The last column in Table 8.18 reports the fraction of time the respective sites are bound when 100 Rep are included and dimerization activated. With respect to promoter control, these results show that P_{RM} is not yet efficiently repressed (via O_{R3} binding), based on the knowledge that our model integrates, neither at lysogenic repressor concentrations, nor when exceeding this level tenfold 4 .

⁴In this light, the relevance of the quantitative predictions of repression of the cI gene, of Blossey, Cardelli, and Phillips (2006), encompassed by a representation of the system of Guet et al. (2002) appear questionable.

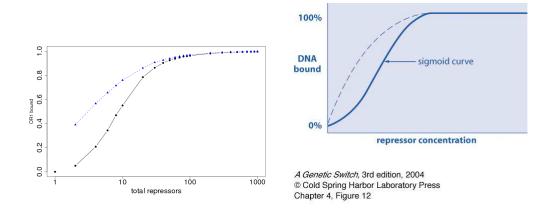


Figure 8.21: Occupancy of isolated operator region O_{R1} as a function of repressor concentration and dimerization. Our results (left), benchmark from Ptashne (2004) (right). Dashed lines: all repressors are found as dimers regardless of concentration. Solid lines: dimerization of repressors is included, hence the concentration-dependent equilibrium affects the binding curve.

Synopsis: repressor binding to the three operator sites

Figure 8.19 shows the saturation of sites O_{R1} , O_{R2} and O_{R3} as they arise in our simulations of the λ switch when both repressor dimerization and cooperative repressor binding between O_{R1} and O_{R2} are enabled. Each of the curves summarizes a series of experiments for varying Rep levels. Before discussing the full system, we investigate the underlying components and mechanisms one by one.

Dimerization sharpens response at O_{R1}

Figure 8.21 (left) illustrates the saturation of O_{R1} as a function of repressor level. Each of the two curves summarizes a series of experiments. For the solid line dimerization is enabled, i.e. only part of the total repressors are present as dimers and thus able to bind the operator. The dashed line assumes that dimers are stable at all concentrations, meaning that 100% of total repressors are found as dimers regardless of the concentration⁵. The horizontal axis indicates the number of total repressors on a logarithmic scale, while the vertical axis gives the relative occupancy of O_{R1} . Each data point represents the relative occupancy of O_{R1} for an experiment simulating the full dynamics of docking to DNA with or without dimerization over 5000

⁵We eliminate communication over the undimerization channel in the module 'lambda repressor', by commenting out the corresponding line in Figure 8.20.

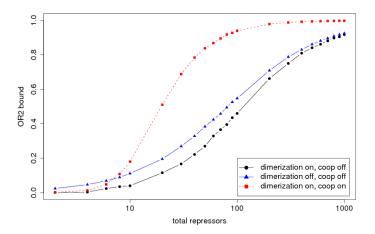


Figure 8.22: Occupancy of site O_{R2} , as a function of repressor level, dimerization and cooperativity. We consider *isolated* O_{R2} for the curves 'with'/'without' dimerization, and a system comprising both O_{R1} and O_{R2} for the curve O_{R2} , coop and dimerization'. Because at very low concentrations, binding occurs mainly at O_{R1} , the cooperative advantage only becomes visible at a certain level.

seconds.

Over this time scale, we can relate our results based on a stochastic discrete event approach to other's from deterministic continuous models, which compute only averages: one sees both qualitative and quantitative agreement with results⁶ reported in Ptashne (2004), reproduced in Figure 8.21 (right). Dimerization has the effect to change the shape of the binding curve, namely to give a sharper response in terms of site occupancy as the amount of repressor increases.

Superimposing dimerization and cooperative binding at O_{R2}

Figure 8.22 summarizes how the second operator site fills with Rep for three scenarios. The dashed curve illustrates binding to O_{R2} in presence of O_{R1} , cooperative binding⁷ and dimerization. We contrast this with binding to the isolated O_{R2} with and without dimerization. Note that the effect of dimerization is far less pronounced at an isolated O_{R2} than it was O_{R1} , where

⁶Simulations by Keith Shearwin.

⁷Technically, we eliminate cooperative binding by commenting out the corresponding lines in the definition of either module 'OR2', or 'OR1'.

dimerization lead to a sharp increase of sensitivity in the lower concentration range. This can be explained because the isolated weaker O_{R2} only fills notably at higher Rep concentrations, when the equilibrium is heavily biased toward dimers. However, now the combined effect of cooperativity and dimerization becomes prominent. Recall that binding at O_{R2} is cooperatively strengthened as O_{R1} is placed next to it. As can be seen from the dashed curve in Figure 8.22 the predominant cause of O_{R2} 's saturation at lysogenic repressor concentration levels is cooperative binding with O_{R1} . This cooperativity propagates O_{R1} 's stronger sensitivity to O_{R2} .

Negative auto-regulation of Rep at O_{R3}

Our results on Rep binding to the third operator O_{R3} are included in Figure 8.19. The binding curve is again based on the observation of the isolated operator, under variation of repressor level while disregarding interfering traffic between RNAP and P_{RM} . The most striking effect when comparing the binding curve with the other operators' is that the site fills to a significantly lower degree. It reaches around 30% when 200 repressors are included in the simulation. Even with an amount of 1000 repressors the isolated O_{R3} remains unsaturated. As we will report later the saturation further decreases to 4% as RNAP docking to P_{RM} interferes.

These results agree with recent experimental findings. Dodd et al. (2001) have demonstrated that an additional layer of cooperativity is needed for effective repression of P_{RM} at lysogenic repressor concentrations. Révet et al. (1999) first observed a long-range DNA loop between the right operator and another distal region in λ 's genome. As was subsequently understood, this loop is stabilized by an assembly of eight repressor proteins, in which the two repressor dimers cooperatively bound to O_{R1} and O_{R2} participate. They cooperatively interact with another repressor tetramer bound to λ 's left operator region O_L - while looping the DNA between the two regions. The large assembly further stabilizes all participants. More importantly, it juxtaposes O_{R3} with a third site at the left operator, O_{L3} . This allows for cooperative binding of repressor at O_{R3} and O_{L3} .

This additional level of cooperativity is a recent finding and not, as yet, fully characterized. However its importance is clearly described by Vilar and Saiz (2005). It allows to repress P_{RM} and maintain a low level of Rep, that is not yet ensured by binding to O_{R3} alone. Thus in a bacterium hosting phage λ , the lysogenic repressor concentration never surpasses a range allowing to return to the level in which O_{R1} and O_{R2} can be vacated. This is the key to induction back from lysogeny to the state of lytic growth (Dodd et al., 2004).

```
'PRM activity with n repressors'
1
2
   public rnap, pro, or1, or2, or3, pr, prm, cl_gene,
3
       lam_dimerize, lam_undimerize from 'Table 8.7'
4
   import 'lambda repressor', 'PRM',
       'OR1','OR2','OR3','RNAP','Timer'
5
6
   define
7
              OR2 | OR3 | PRM | Timer(lam_undimerize)
      OR1
                              \begin{vmatrix} 30 \\ i=1 \end{vmatrix} RNAP
8
              Rep_monomer
        |_{i=1}^{n}
```

Figure 8.23: Setup: simulating the activity of $P_{\rm RM}$ in the presence of n repressor monomers

8.3.3 Monitoring the activity of P_{RM}

We further widen the scope of the model, by adding P_{RM} and RNAP to the three operator sites and repressors simulated so far (see Figure 8.23). We study this system over 20 minutes simulated time, comparable with the life span of an individual bacterium. This allows to observe the occupancy patterns of both P_{RM} and the operators, as well as the initiation of transcription for the cI gene. We first consider the impact of varying repressor levels in a model including the essential cooperative features - dimerization, cooperative repressor binding and positive control of transcription initiation. Next we perturb our model and study the consequences.

Table 8.1 summarizes a series of simulations. For each set-up we indicate the number of repressors included, and whether cooperative binding and positive control are enabled. Each line of the table summarizes one simulation run, for which we report the following quantities:

- absolute number of transcription initiations from $P_{\rm RM}$ observed. This should be related to the theoretical upper bound of 103, estimated form $P_{\rm RM}$'s maximal rate of 0.086 initiations per second and the simulated time of 1200 seconds.
- absolute time that RNAP is bound to P_{RM} (in sec),
- absolute time P_{RM} is repressed as a consequence of Rep binding to O_{R3} (in sec),
- vacancy of P_{RM} (in sec),
- occupancy of O_{R2} by repressor (in sec).

coop	pos	Rep	transcription	RNAP	P_{RM}	P_{RM}	Rep
	ctrl		initiations	at P_{RM}	repressed		at O_{R2}
			from P_{RM}	(sec)	(sec)	(sec)	(sec)
			58	873	46	280	1111
			76	870	46	279	1120
		100	71	873	46	279	1120
			58	889	44	266	1110
			74	903	43	253	1111
			67	901	19	281	990
on	on	50	69	921	14	265	985
			70	899	18	283	972
			46	917	5	278	728
		25	52	929	5	266	730
			51	922	5	273	727
			19	927	< 1	272	305
		10	26	932	< 1	267	323
			28	922	< 1	277	300
			38	886	41	273	570
off	on	100	35	867	45	285	587
			31	890	43	267	575
			5	899	41	260	1108
on	off	100	6	915	39	246	1118
			4	898	44	258	1101

Table 8.1: Simulation runs over 1200 seconds: P_{RM} activity (absolute number of transcription initiations). Values are in units of simulated seconds for the following columns: P_{RM} repression, P_{RM} vacancy, and occupancy of O_{R2} by Rep. First block: results for varied repressor levels when both cooperative repressor binding and positive control are enabled. Second and third block: simulation results under elimination of either of the two mechanisms, for a level of 100 repressors.

To begin with, we mimic the system's behavior under *lysogenic repressor* concentrations with 100 repressors. The first block in Table 8.1 summarizes five executions of our model. For all runs P_{RM} is bound by RNAP in approximately 70 % of the time, P_{RM} is inhibited via competing Rep binding to O_{R3} for 4 % of the time, and otherwise vacant. The second operator site O_{R2} is bound by Rep around 92 % of the time for all five runs. The numbers of transcription initiations range between 58 and 76. Note that the variability of this figure is significantly higher than that of any other considered.

The actual number of transcript initiations from $P_{\rm RM}$ in a single lysogenic bacterium is difficult to determine experimentally. For long a precise level was deemed necessary for the maintenance of lysogeny (Johnson et al., 1981). This was rectified by recent experiments of Back, Svenningsen, Eisen, Sneppen, and Brown (2003) showing that repressor levels varies widely from cell to cell. This phenomenon is known as transcriptional noise. Our result are in agreement with an estimated average number of transcripts per cell cycle of 70.

Reactions to partial and near-total Rep depletion:

Our next step is to preserve the system's essential characteristics - dimerization, positive control and cooperative binding - but to thin out the repressor pool. In the remainder of Table 8.1's first block we report the outcomes of each three simulations with 50, 25 and 10 total repressors.

The primary effect is that saturation of O_{R2} drops nonlinearly. This has important secondary effects on transcription initiation from P_{RM} . A first reduction to 50 repressors de-represses P_{RM} and seems to favor initiation, at least in these runs. As a reaction to further depletion transcription visibly reduces, while the actual P_{RM} saturation by RNAP increases: in the presence of 10 repressors, initiations drop to around a third of those seen with 50 repressors. This should be related to the increasing vacancy of O_{R2} . It gives a first impression of how the system of positive auto-regulation breaks down.

Examining this question in detail seems promising for two reasons. First, the λ switch is known to be extremely robust. It needs to cope with transient fluctuations of Rep level. Nevertheless, *induction* relies on the system's ability to escape from the lysogenic state when repressor falls below a critical threshold. Recall that as both O_{R1} and O_{R2} are vacated, P_{RM} 's antagonist P_R becomes likely to take over. A detailed investigation remains beyond the scope of this thesis.

The impact of cooperative repressor binding

on P_{RM} activity is another point of interest. After we have observed its immediate impact at O_{R2} , we move on to a larger perspective. We perturb our π -calculus model by lowering the cooperative dissociation rate of Rep at O_{R2} to the basal one. This lowers O_{R2} 's saturation to half the previous amount, see Table 8.1 (second block, last column). And it has consequences for RNAP at P_{RM} . The binding itself is not lowered - our simulations even indicate a slightly higher promoter saturation. Nevertheless, the number of transcription initiations drops to half that of the wild type.

Impact of positive control

We last eliminated the positive control of transcription initiation in our model. This is reached by setting the parameter for promoted transcription the basal one, i.e. $\rho_{prm}(highTimer) = \rho_{prm}(lowTimer) = 0.005$. Our resulting in silico experiments are summarized in the last block in Table 8.1. The number of initiations in presence of 100 total repressors dramatically decreases from an average of 67 in the initial system to an average of 5. All the while, immediate RNAP bindings as well as all other features are not affected, when compared to the original setting. This underlines the importance of positive control.

This simulation scenario was motivated by wet lab experiments with modified λ repressors. These mutants bind cooperatively but fail to stimulate transcription. As Hawley and McClure (1983) reported the λ switch was no longer functional. Our simulation outcomes seem in rough agreement with this, even though we can not directly compare the results. Michalowski and Little (2005) suggested that positive auto-regulation may be a dispensable feature altogether. They experimentally observed that the λ switch remains functional if positive control is eliminated, but at the same time P_{RM} 's intrinsic initiation rate k_f increased.

Conclusion

We followed the approach of Regev (2002) in using the stochastic π -calculus as a modeling language yielding simulation in systems biology. Our driving question was how well the stochastic π -calculus lends itself to modeling gene expression and regulation. It motivated us to investigate bacterial gene expressions through two larger case studies.

Our experience soon showed that the pure stochastic π -calculus lacks many useful programming language concepts. As a bottleneck we identified difficulties to create object-oriented abstractions. This motivated us to augment the stochastic π -calculus with input patterns, that render appropriate object-oriented abstractions available. The main difficulty was to define the stochastic semantics. We proposed a module system atop the stochastic π -calculus with input patterns, that provides a syntax for specifying objects in the π -calculus while using inheritance.

Based on these contributions, we performed two modeling case studies: transcription initiation at the λ switch, and bacterial transcription and translation. Both confirmed the appropriateness and conciseness of our new modeling language. We proved that this language can be compiled into the original stochastic π -calculus. This in turn enabled us to implement and test our models within the BioSpi system. Based on this we have conducted exhausting simulations with excellent results.

In future work, it remains to design a new simulation system directly implementing the new modeling language. Open questions are on remain on how to integrate higher-order definitions and dynamic notions of inheritance.

On the modeling side, the largest remaining challenge is to tackle simu-

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lation questions of interest for experimentalists, beyond bacteriology. Phenomena as DNA looping at the λ switch are of particular interest, due to their fundamental relevance to eukaryotic gene regulation.

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