



study of the three-dimensional extension  
two-dimensional numerical modeling and  
Microwave imaging of buried objects:

Ph.D. thesis

Ioannis ALIFERIS



Microwave imaging of buried objects:  
two-dimensional numerical modeling and  
study of the three-dimensional extension

Ph.D. thesis

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# Jointly supervised Ph.D.: Greece – France

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- ▼ Laboratoire d'Électronique,  
Antennes et Télécommunications  
UMR CNRS 6071  
Université de Nice – Sophia Antipolis, France

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*Greek State Scholarship Foundation (IKY)*



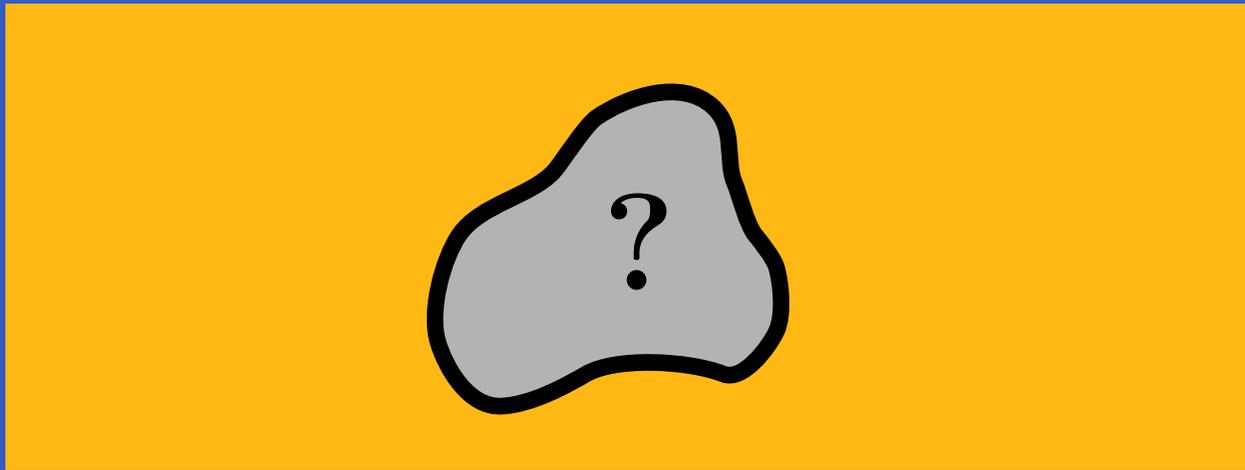
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# Microwave imaging of buried objects

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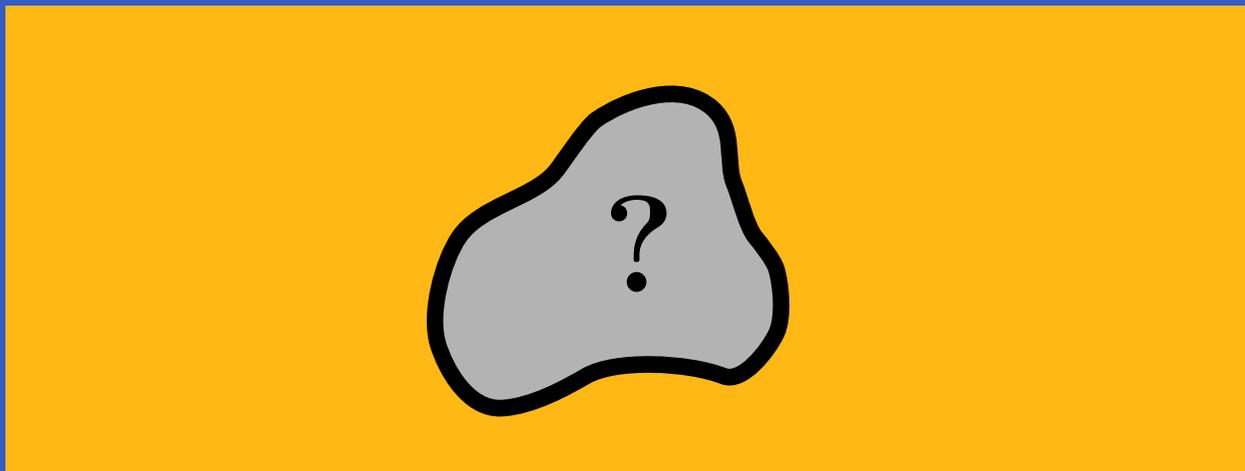


# Microwave imaging of buried objects



▼ Incident/Scattered field  $\xrightarrow{\text{find}}$  object  $(\epsilon_r, \sigma)$

# Microwave imaging of buried objects



- ▼ Incident/Scattered field  $\xrightarrow{find}$  object  $(\epsilon_r, \sigma)$
- ▼ Limited aspect data

# Microwave imaging of buried objects



- ▼ Incident/Scattered field  $\xrightarrow{\text{find}}$  object  $(\epsilon_r, \sigma)$
- ▼ Limited aspect data
- ▼ Multifrequency, multiview, multistatic

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# Iterative algorithm

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# Iterative algorithm

$E^{(i)}$

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# Iterative algorithm

$$E_{\text{ref}}^{(s)}$$

$$E^{(i)}$$



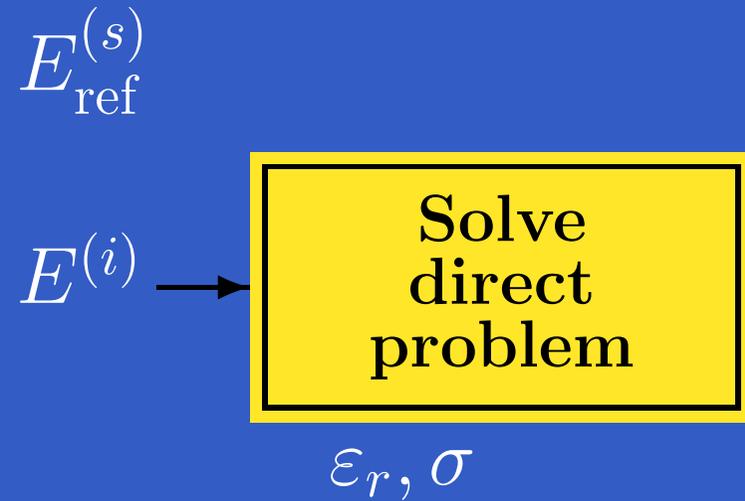
# Iterative algorithm

$$E_{\text{ref}}^{(s)}$$

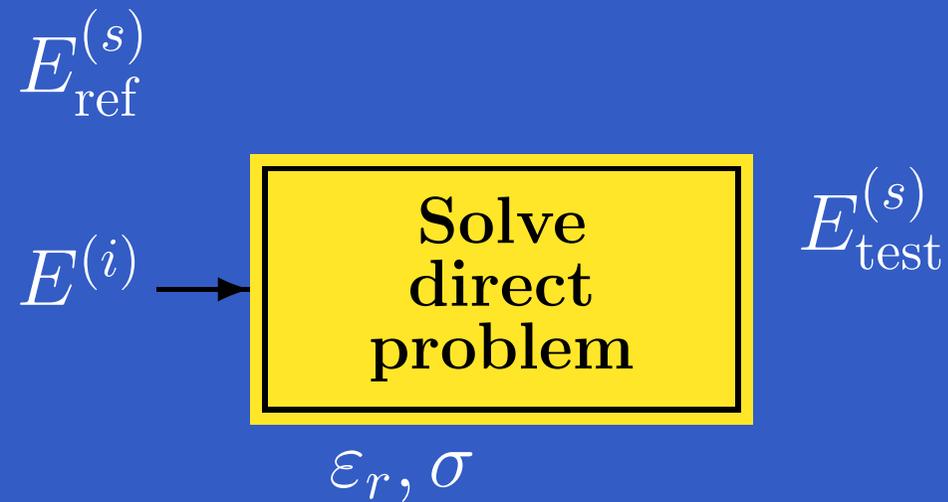
$$E^{(i)}$$

$$\epsilon_r, \sigma$$

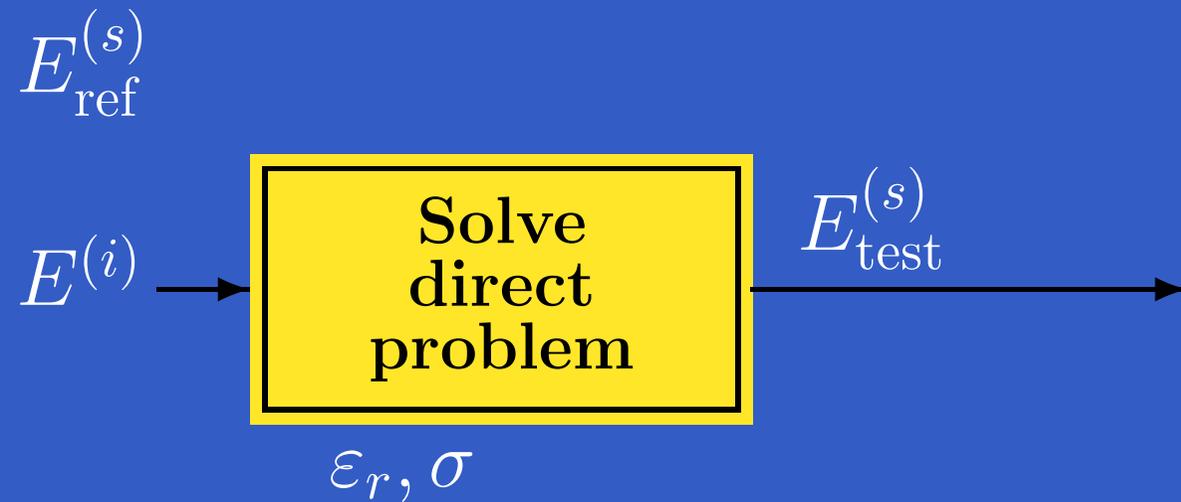
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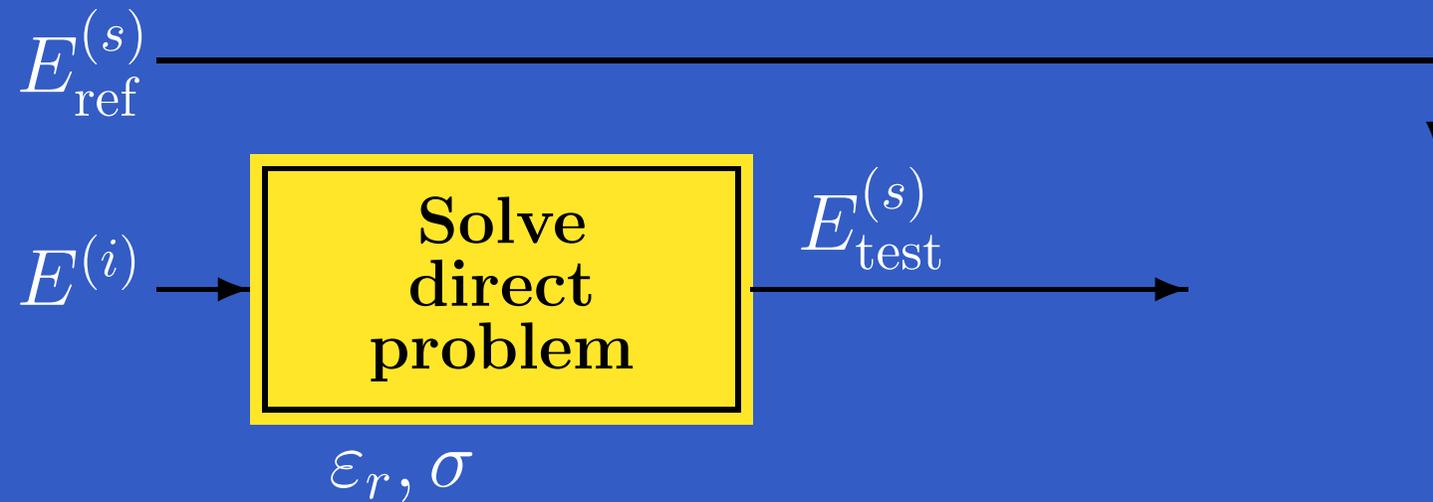
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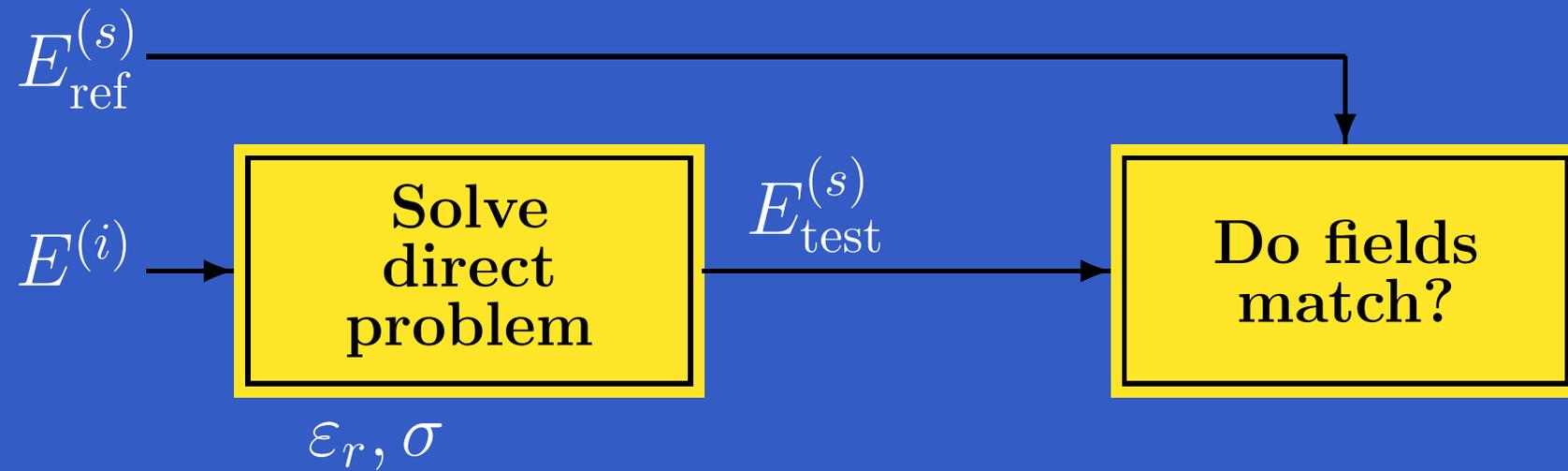
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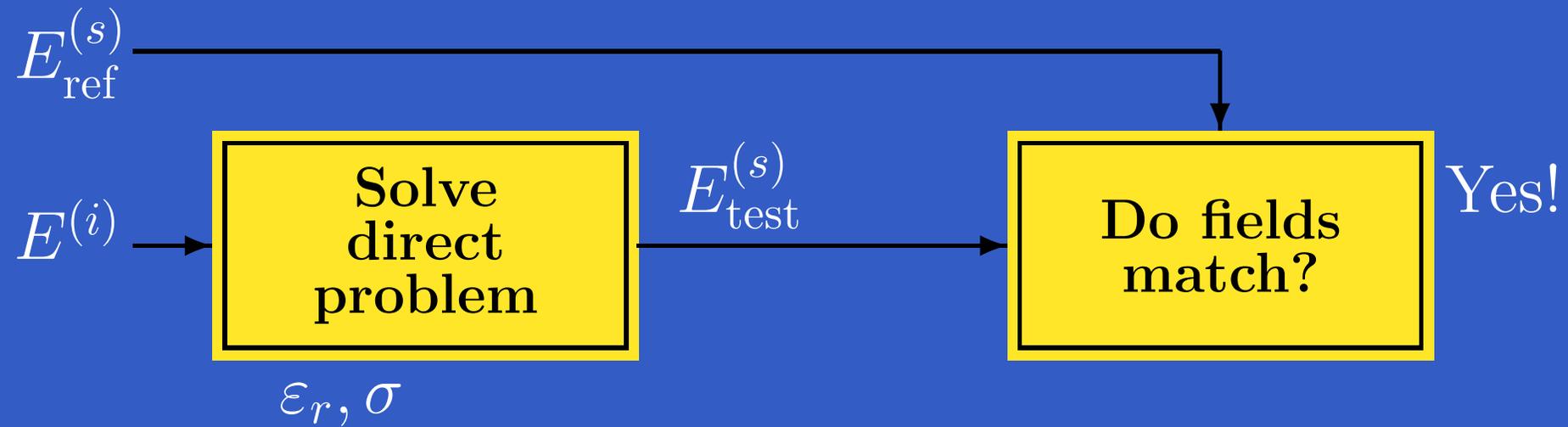
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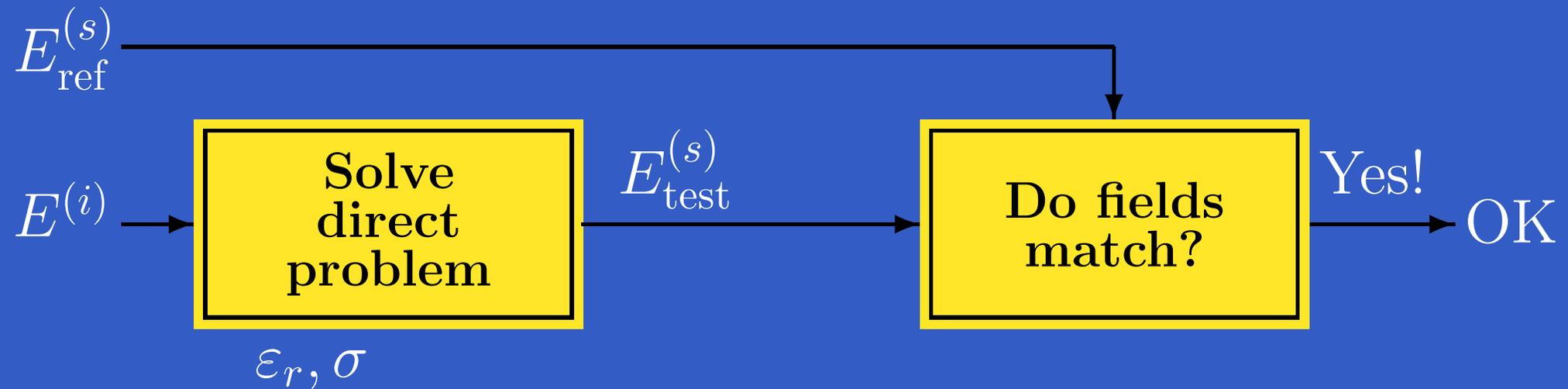
# Iterative algorithm



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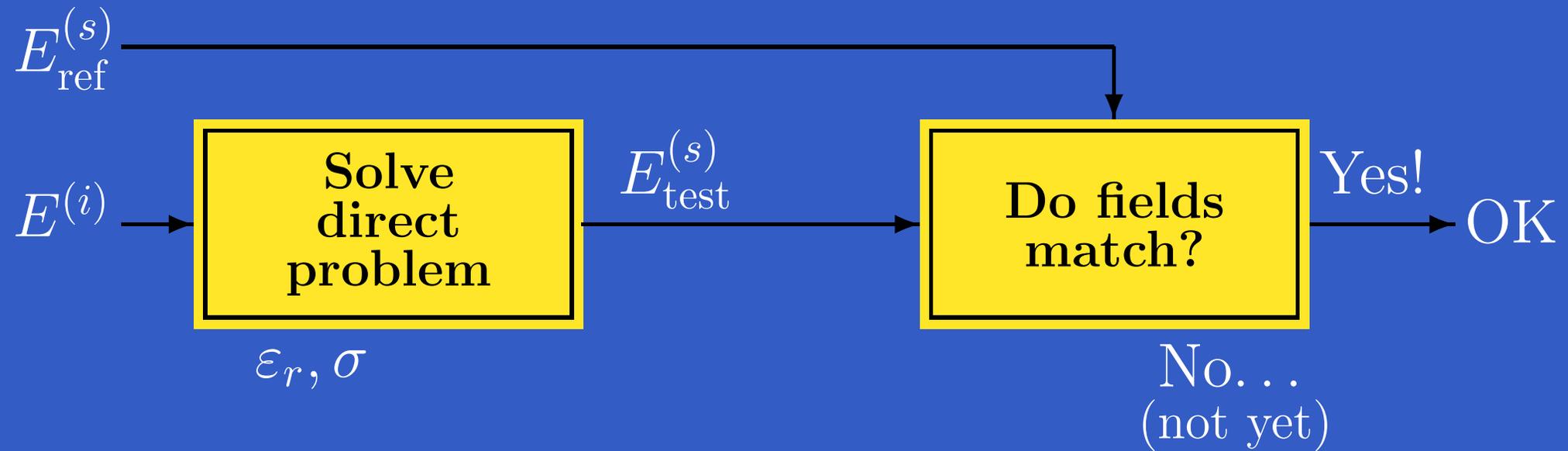


# Iterative algorithm

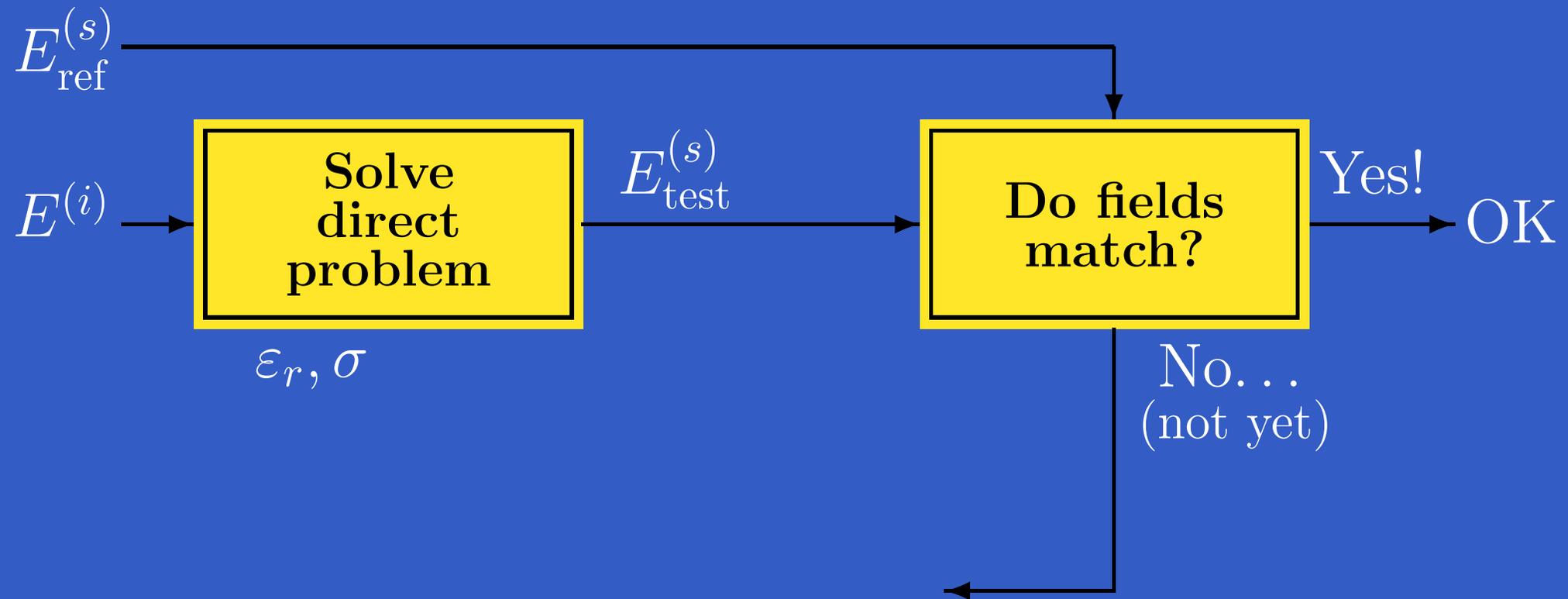




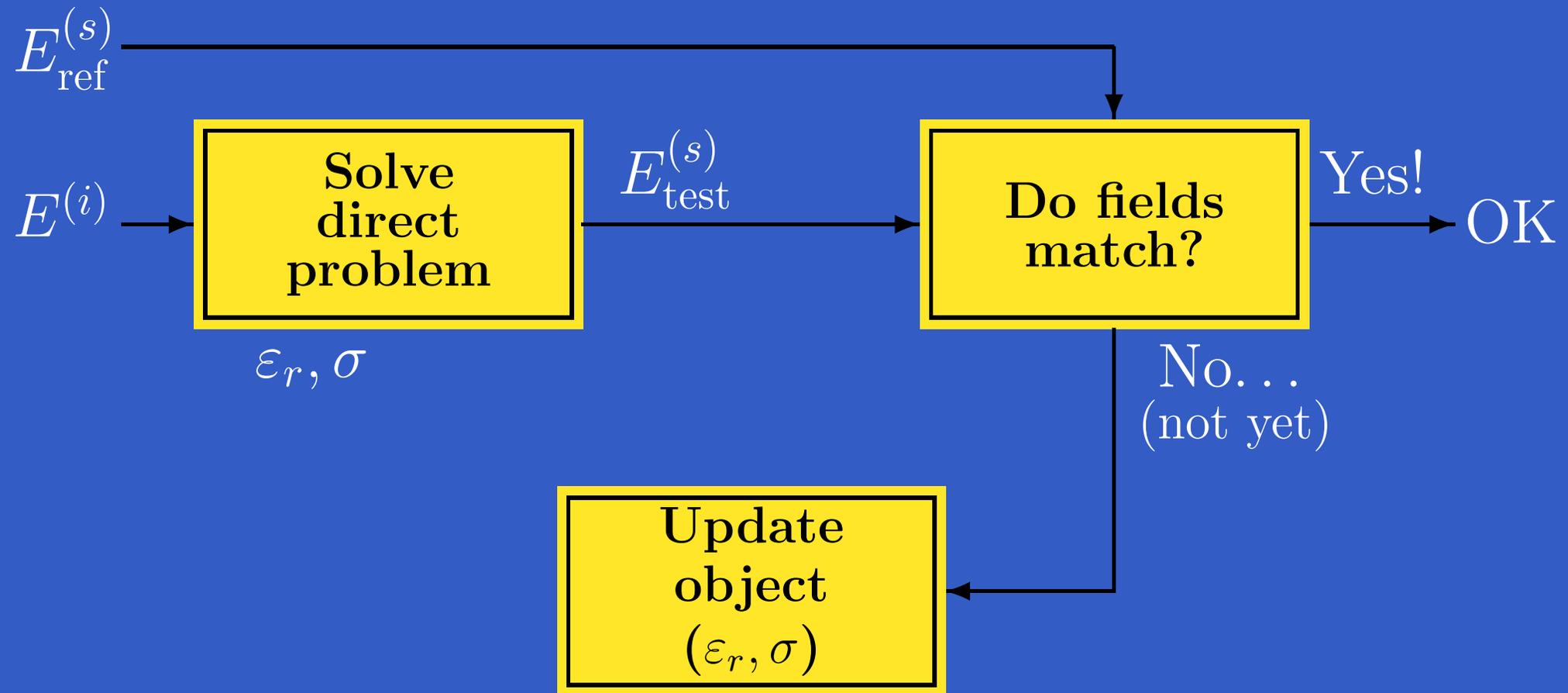
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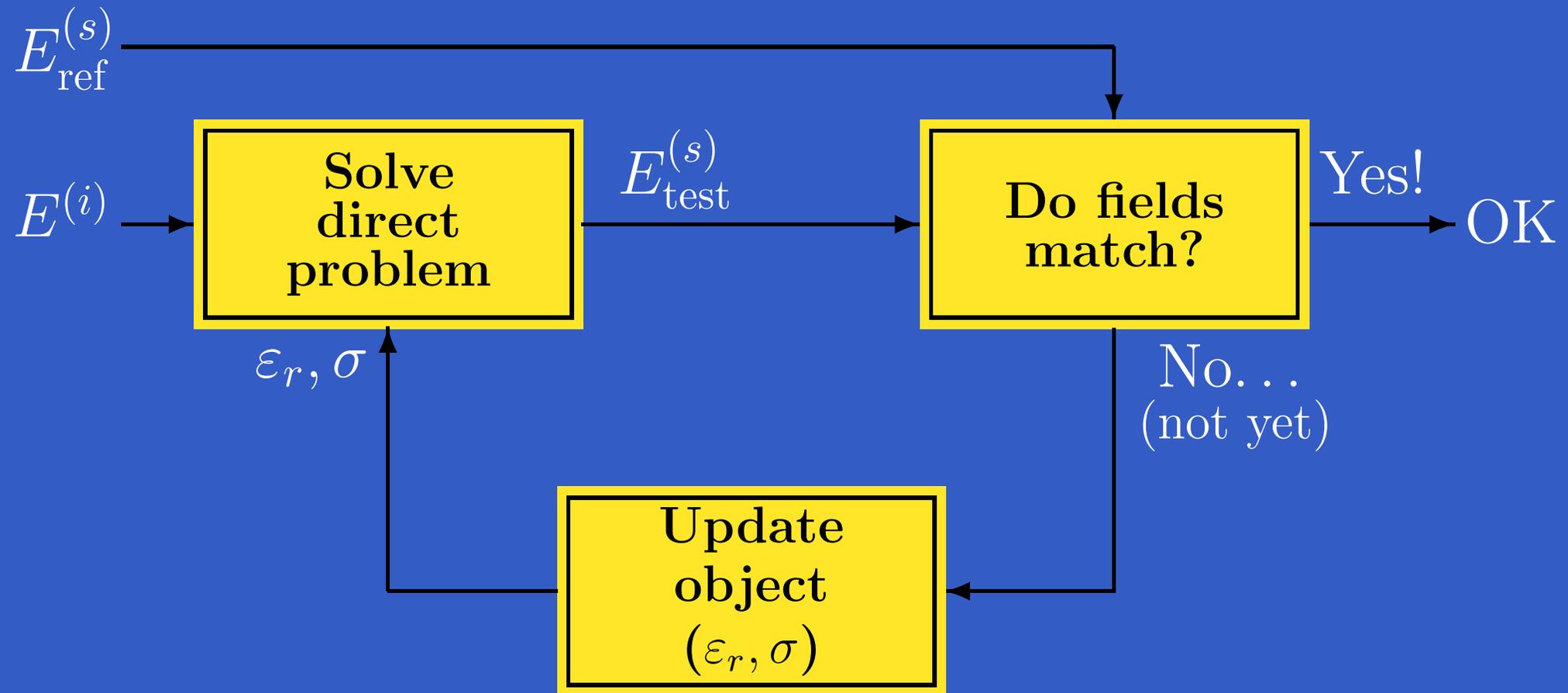
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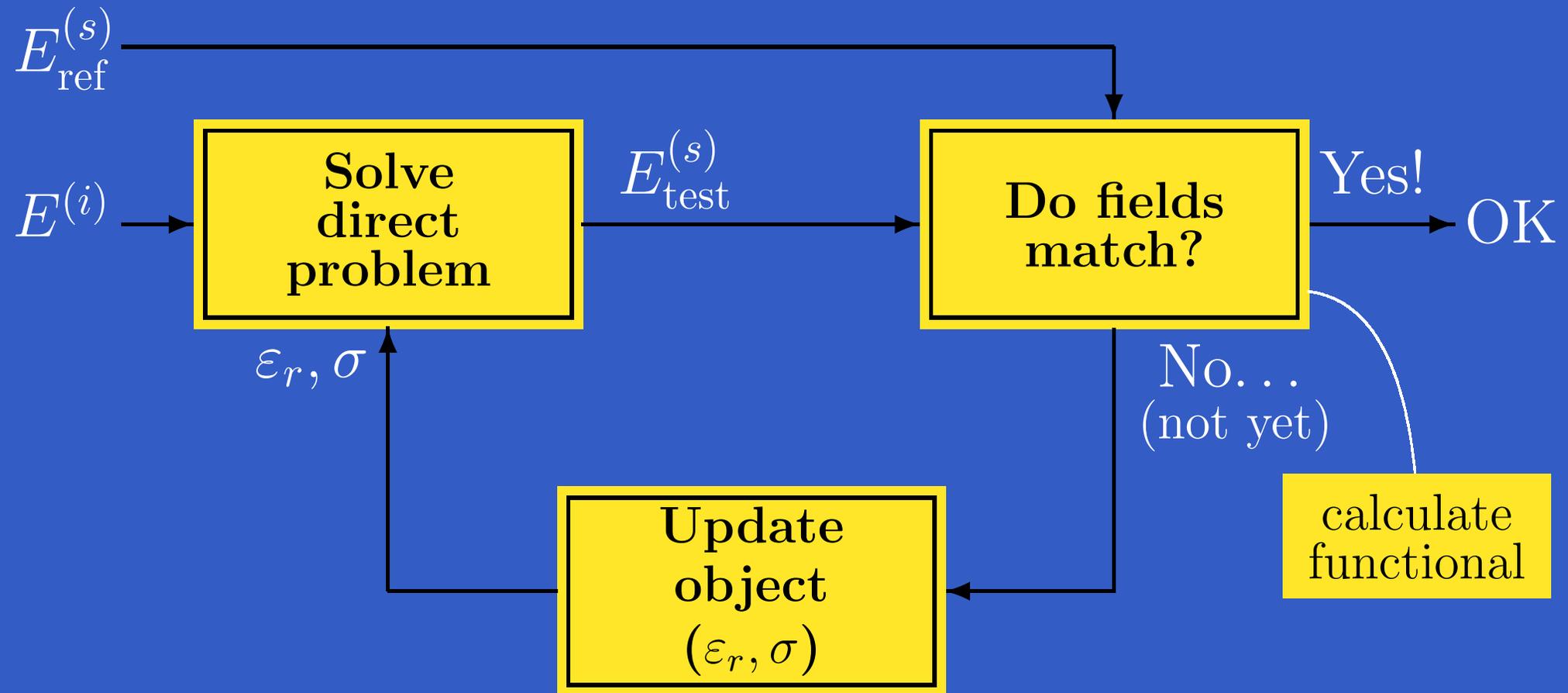
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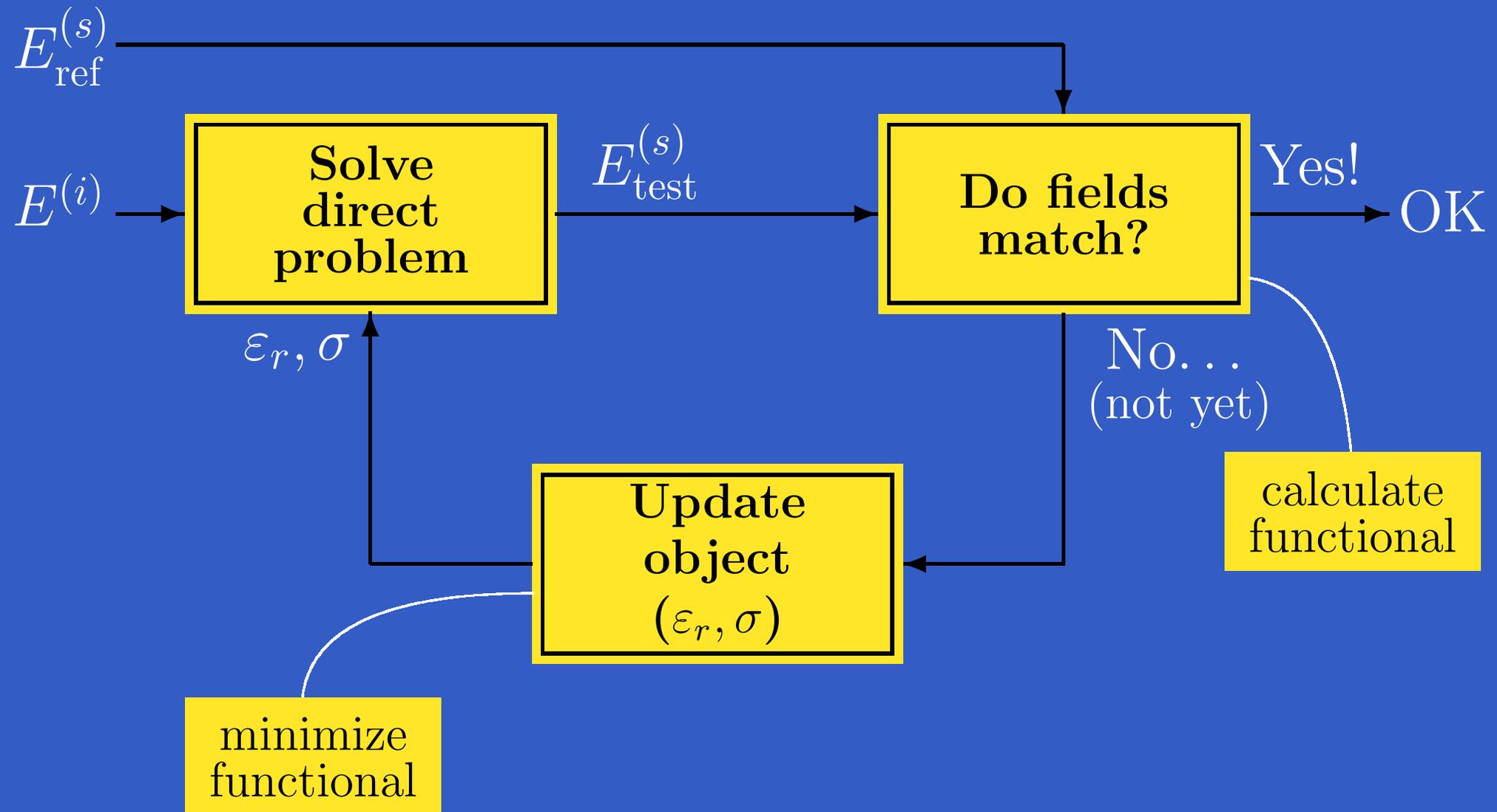
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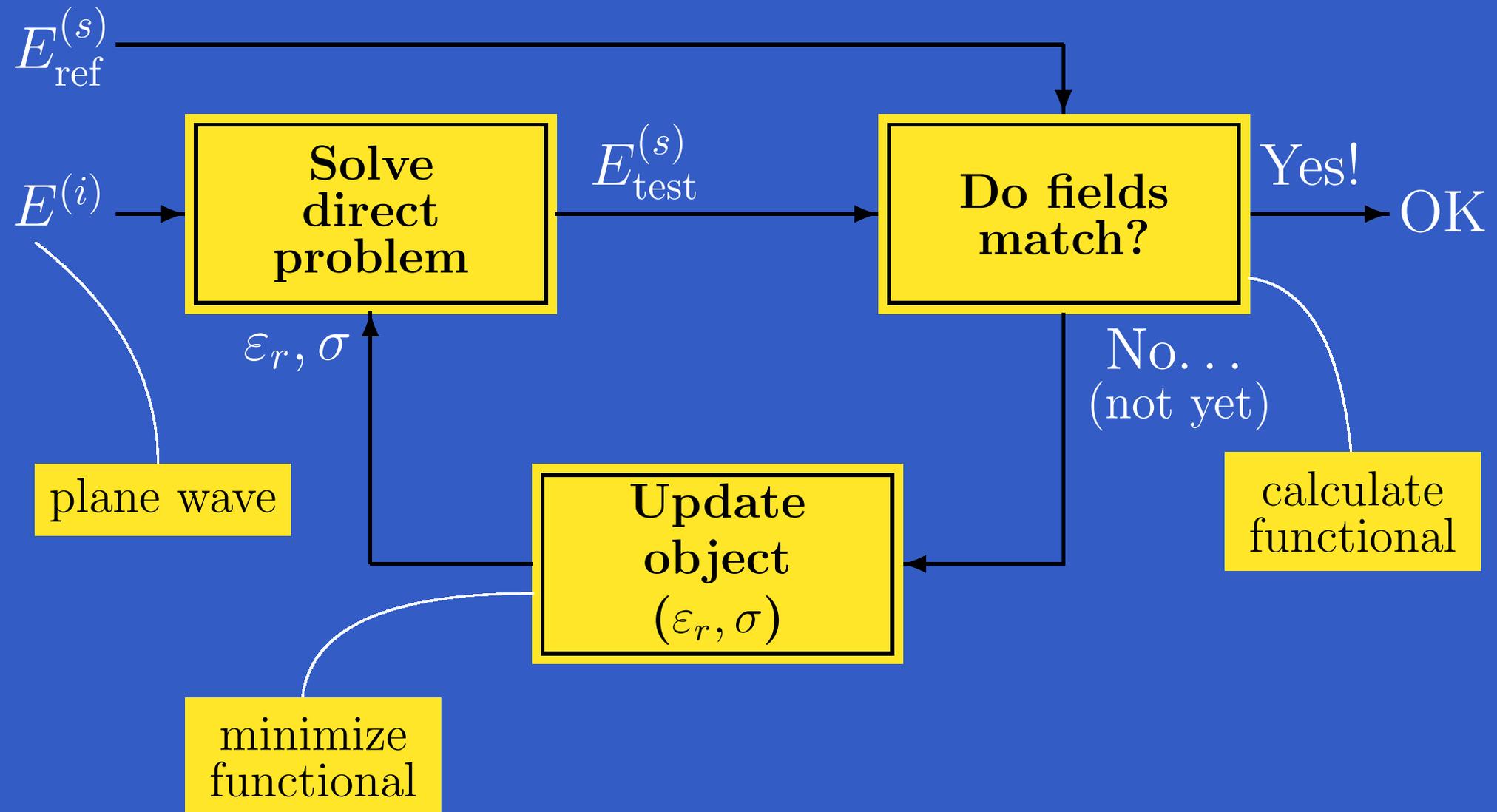
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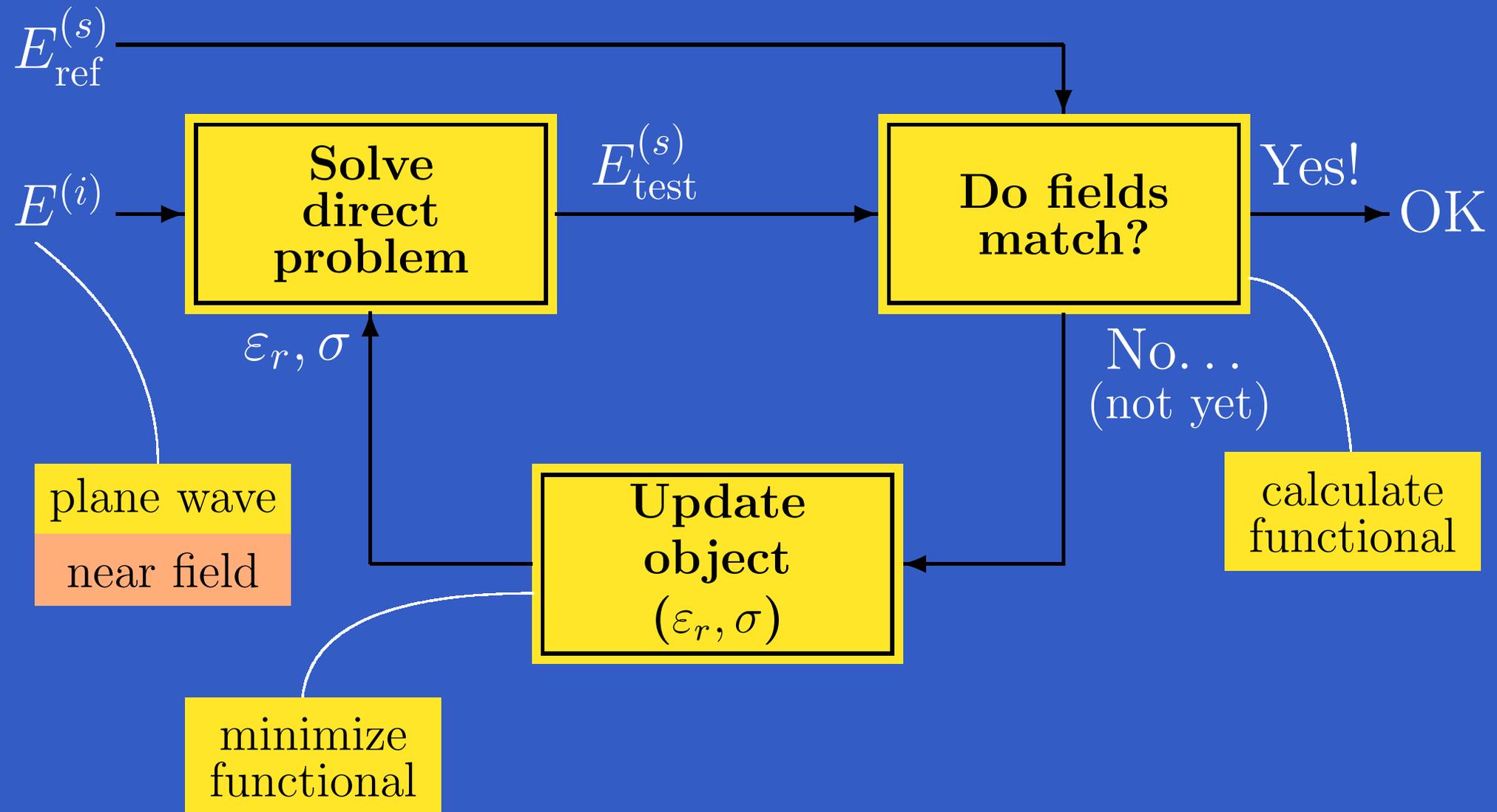
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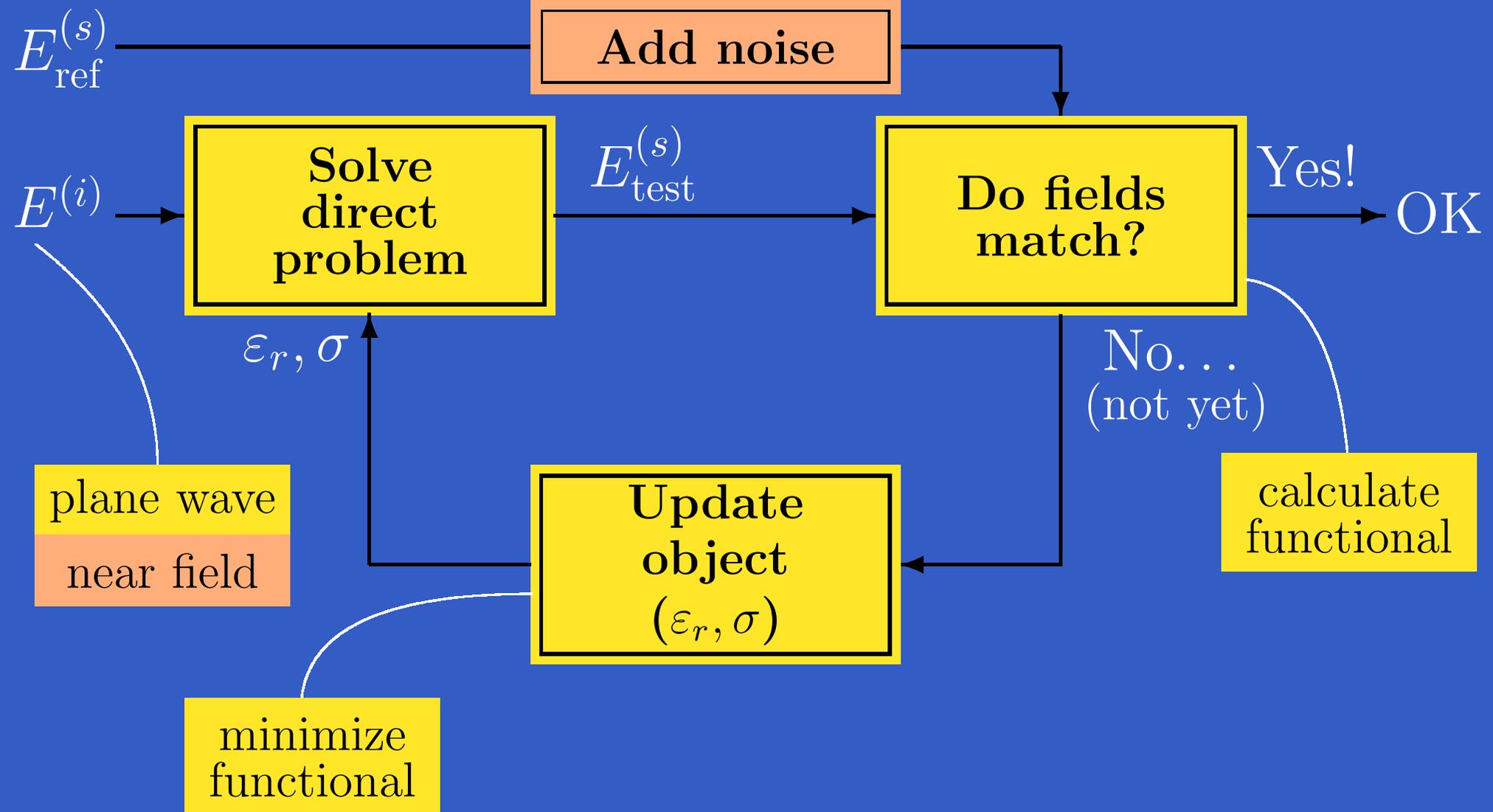


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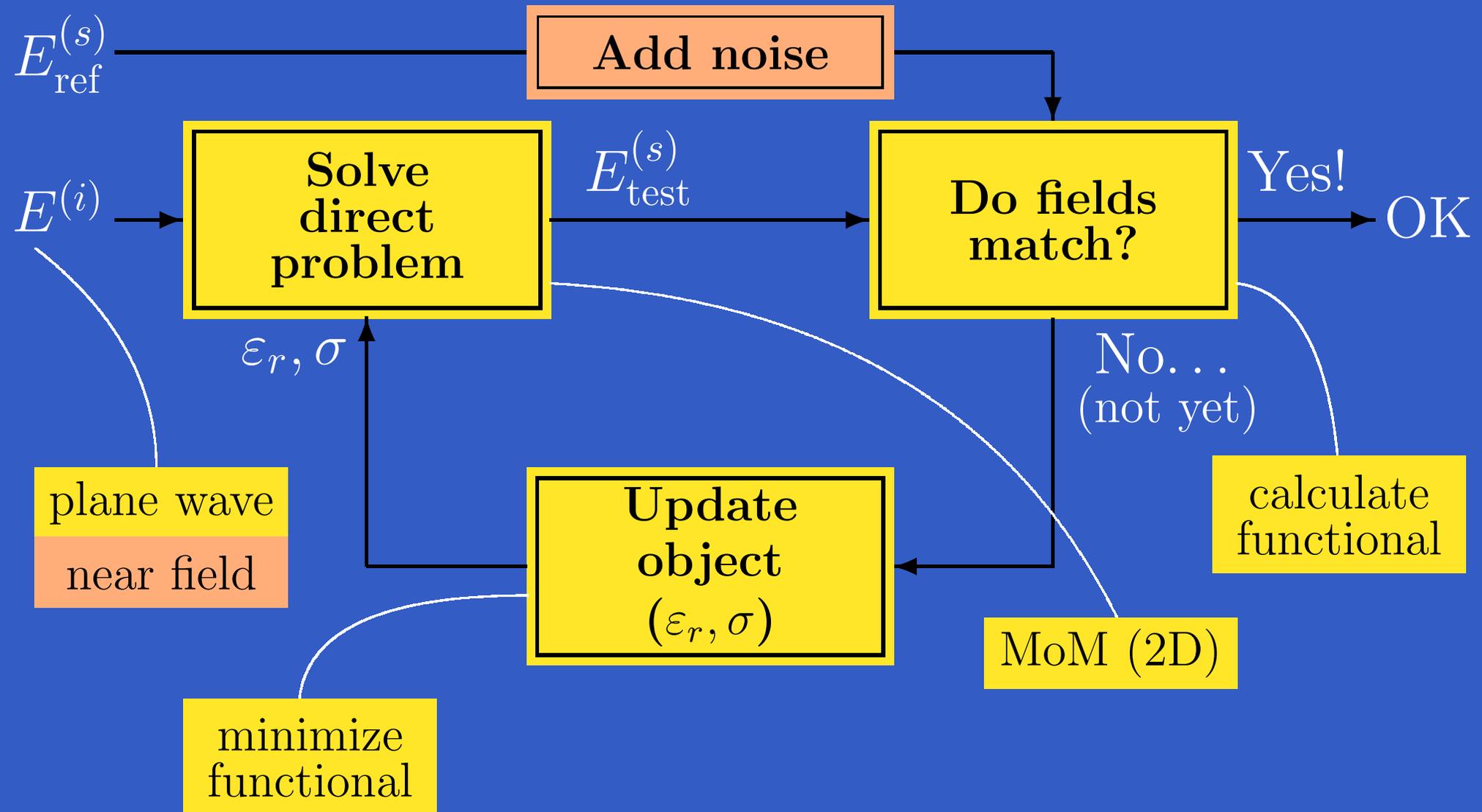




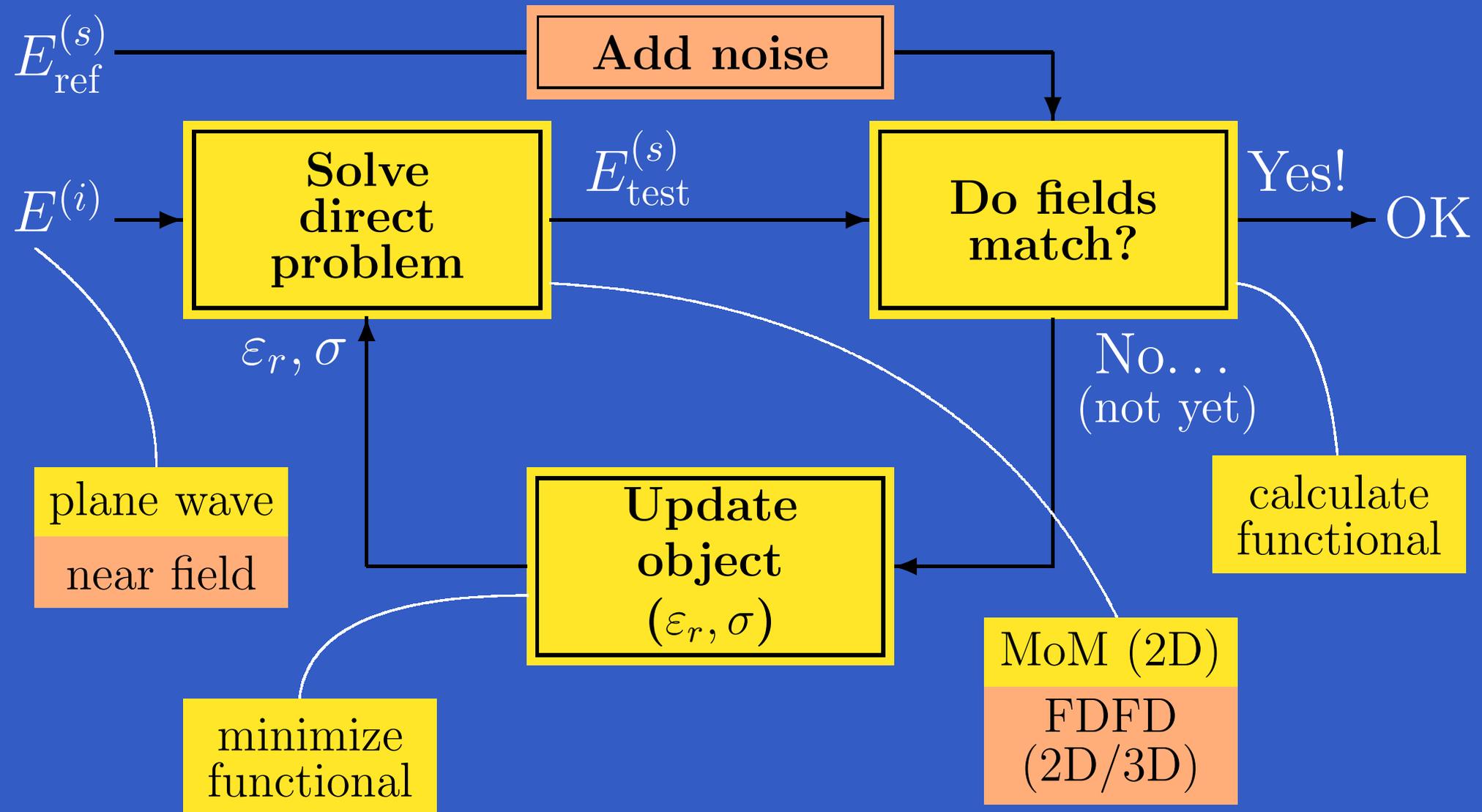
# Iterative algorithm



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# Iterative algorithm



# Two-dimensional numerical modeling

# Contents I

- ▼ Microwave tomography
- ▼ Extensions
- ▼ Numerical results

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## Direct problem

- ▼ Transverse magnetic (TM) polarization

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- ▼ Electric field integral equation (EFIE)

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- ▼ Method of moments (pulse basis, point matching)



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$$\left. \begin{aligned} \mathbf{e}^{(i)} &= (\mathbf{I}_{N_c} - \mathbf{G}^0 \mathbf{C}) \mathbf{e} \\ \mathbf{e}^{(s)} &= \mathbf{G}^R \mathbf{C} \mathbf{e} \end{aligned} \right\}$$

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$$\mathbf{C} = \text{diag}(\boldsymbol{\varepsilon}_r(\omega)) - j \frac{\text{diag}(\boldsymbol{\sigma}(\omega))}{\omega \varepsilon_0} - \left( \frac{\varepsilon_{N_L}(\omega)}{\varepsilon_0} - j \frac{\sigma_{N_L}(\omega)}{\omega \varepsilon_0} \right) \mathbf{I}_{N_c}$$

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# Inverse problem (1/2)

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▼ Cost functional:

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$$J(\boldsymbol{\varepsilon}_r, \boldsymbol{\sigma}) \triangleq \sum_{f=1}^{N_F} \sum_{s=1}^{N_S} \|\mathbf{r}_{f,s}(\boldsymbol{\varepsilon}_r, \boldsymbol{\sigma})\|_{L_M}^2$$

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## Inverse problem (1/2)

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## Inverse problem (1/2)

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$$J(\boldsymbol{\varepsilon}_r, \boldsymbol{\sigma}) \triangleq \sum_{f=1}^{N_F} \sum_{s=1}^{N_S} \|\mathbf{r}_{f,s}(\boldsymbol{\varepsilon}_r, \boldsymbol{\sigma})\|_{L_M}^2$$

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### ▼ Iterative minimization (biconjugate gradient)

$$\boldsymbol{\varepsilon}_r^{k+1} = \boldsymbol{\varepsilon}_r^k + \alpha_{\boldsymbol{\varepsilon}_r}^k \boldsymbol{\eta}_{\boldsymbol{\varepsilon}_r}^k \quad \boldsymbol{\sigma}^{k+1} = \boldsymbol{\sigma}^k + \alpha_{\boldsymbol{\sigma}}^k \boldsymbol{\eta}_{\boldsymbol{\sigma}}^k$$

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## Inverse problem (2/2)

### ▼ Ill-posed problem

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  - ▶ Smooth *below* threshold



## Inverse problem (2/2)

### ▼ Ill-posed problem

- ▶ Existence?
- ▶ Unicity?
- ▶ Stability?

### ▼ Edge-preserving regularization

- ▶ Piece-wise constant profile
- ▶ Smooth *below* threshold

$$\zeta_{\varepsilon_r}^2 \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} \phi \left( \frac{\|(\nabla \varepsilon_r)_{i,j}\|}{\delta_{\varepsilon_r}} \right) + \zeta_{\sigma}^2 \sum_{i=1}^{N_x} \sum_{j=1}^{N_y} \phi \left( \frac{\|(\nabla \sigma)_{i,j}\|}{\delta_{\sigma}} \right)$$

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# Emitting antenna modeling

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# Emitting antenna modeling

× Plane wave

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# Emitting antenna modeling

- ✗ Plane wave
- ✓ Simulated incident field

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- ▼ SR3D, France Telecom Research Center, La Turbie

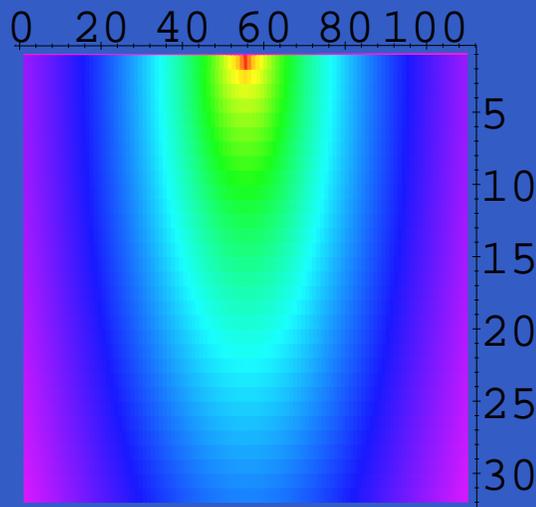
# Emitting antenna modeling

- ✗ Plane wave
- ✓ Simulated incident field
- ▼ SR3D, France Telecom Research Center, La Turbie  
Bow-tie antenna (cells of  $2.5 \times 2.5 \text{ cm}^2$ ):

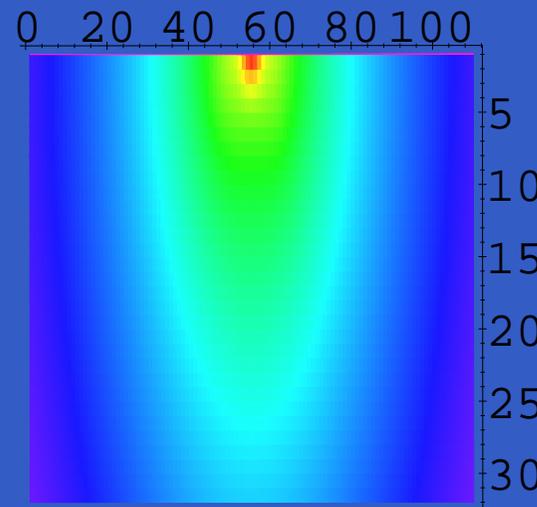
# Emitting antenna modeling

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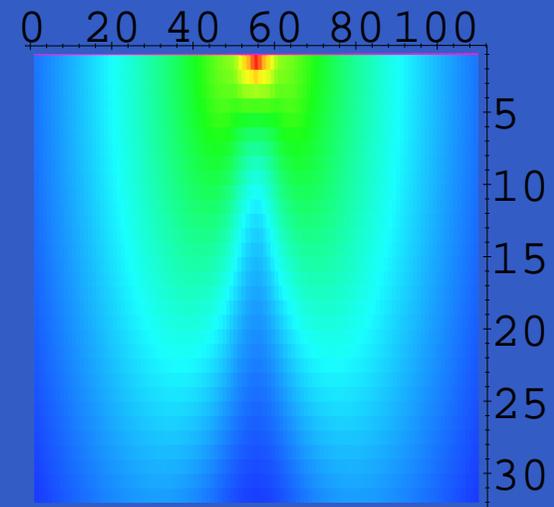
Bow-tie antenna (cells of  $2.5 \times 2.5 \text{ cm}^2$ ):



0.3 GHz



0.8 GHz



1.3 GHz

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# Measurement noise modeling



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# Measurement noise modeling

- ▼ White, Gaussian, zero mean

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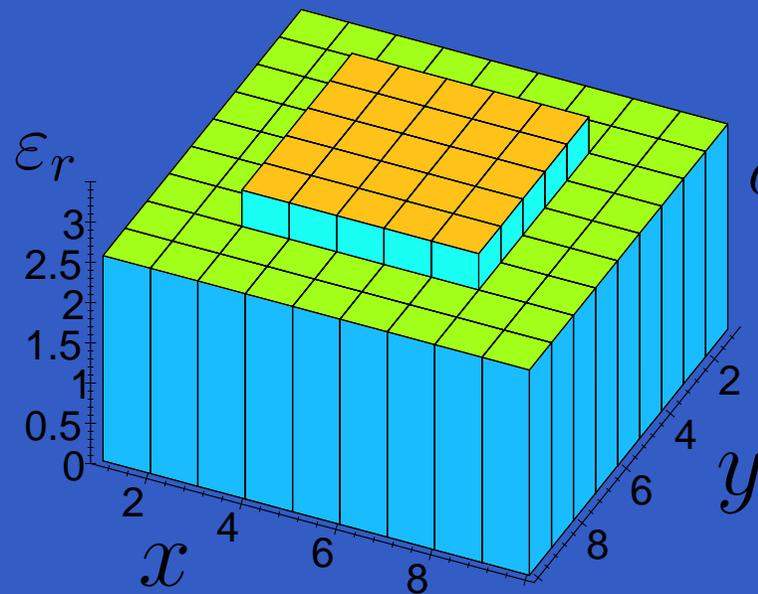
- ▼ White, Gaussian, zero mean
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- ▼ Fix SNR; choose  $\sigma$  for each frequency/emitter

$$E_{\text{signal}} = \frac{1}{N_M} \sum_{i=1}^{N_M} \text{Re} \left[ \left( \mathbf{e}_{\mathbf{f},\mathbf{s}}^{(\mathbf{s})} \right)_i \right]^2 \quad \text{real part}$$

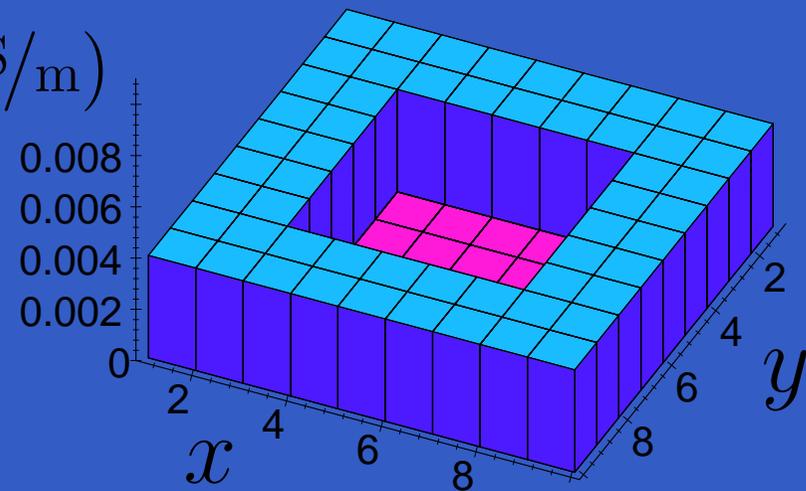
$$E_{\text{signal}} = \frac{1}{N_M} \sum_{i=1}^{N_M} \text{Im} \left[ \left( \mathbf{e}_{\mathbf{f},\mathbf{s}}^{(\mathbf{s})} \right)_i \right]^2 \quad \text{imaginary part}$$

$$E_{\text{noise}} = \sigma^2$$

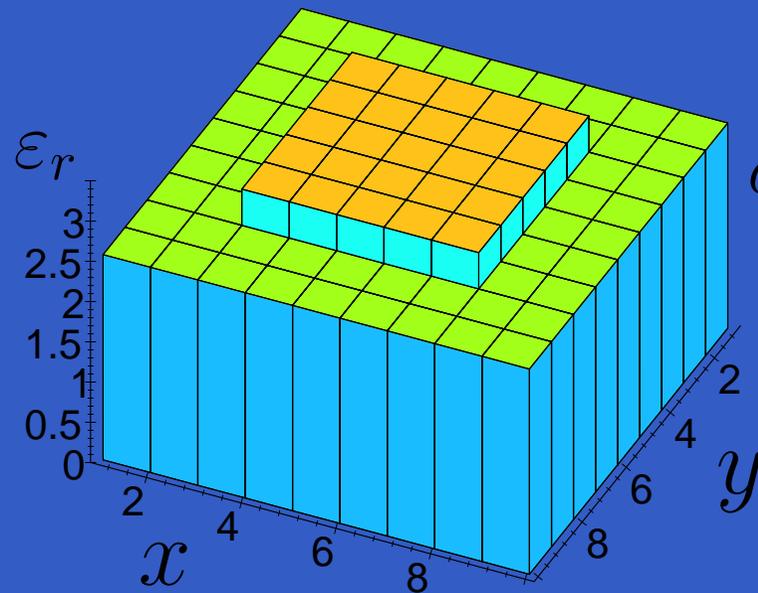
# Test suite: the real object



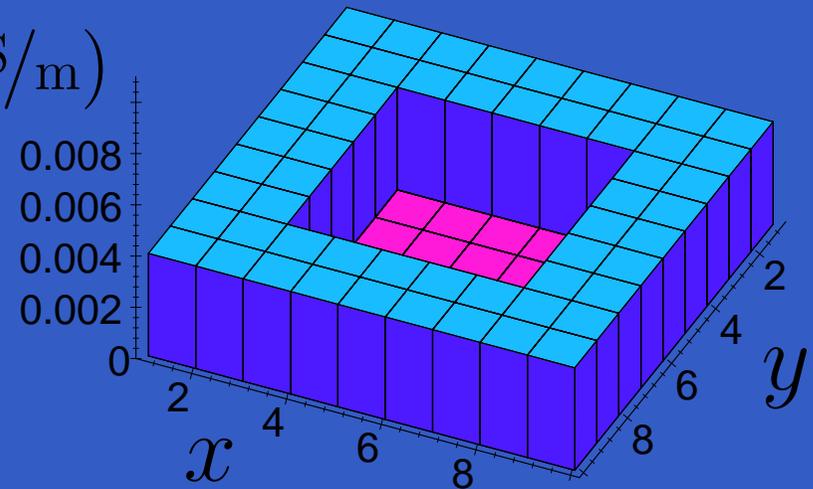
$\sigma$  (S/m)



# Test suite: the real object

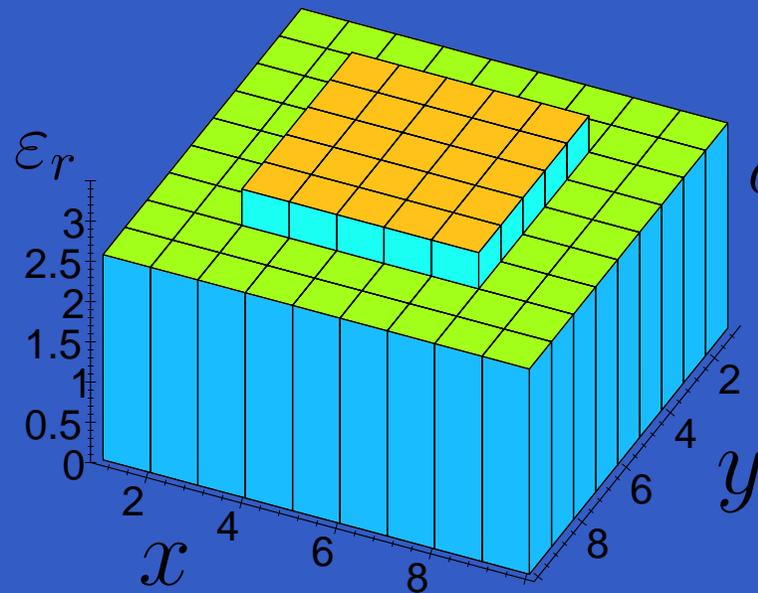


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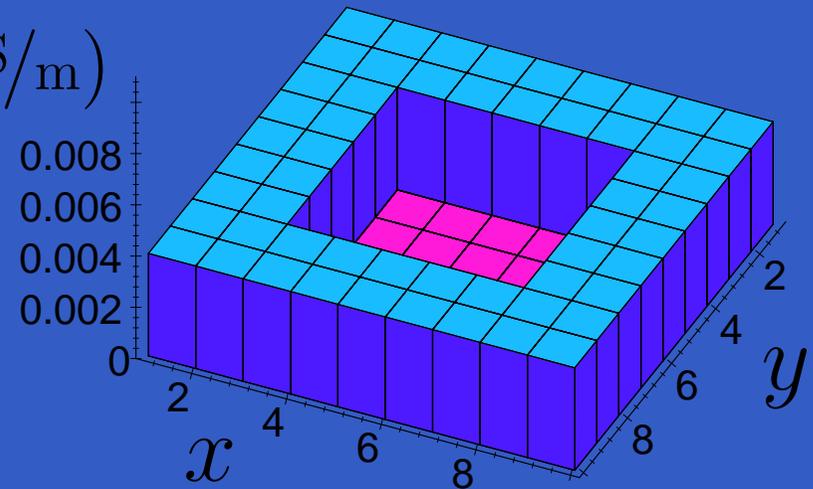


▼  $\epsilon_r = 3, \sigma = 0$ ; ext:  $\epsilon_r = 2.55, \sigma = 4 \cdot 10^{-3} \text{ S/m}$

# Test suite: the real object

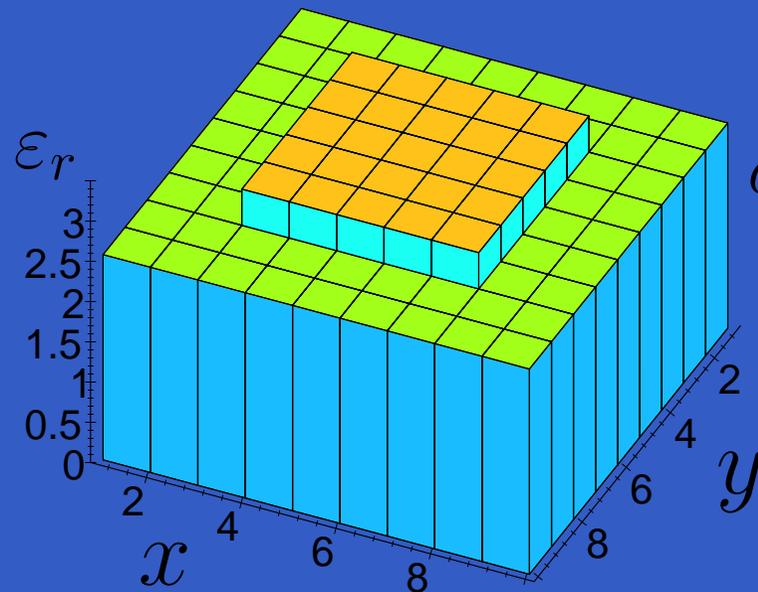


$\sigma$  (S/m)

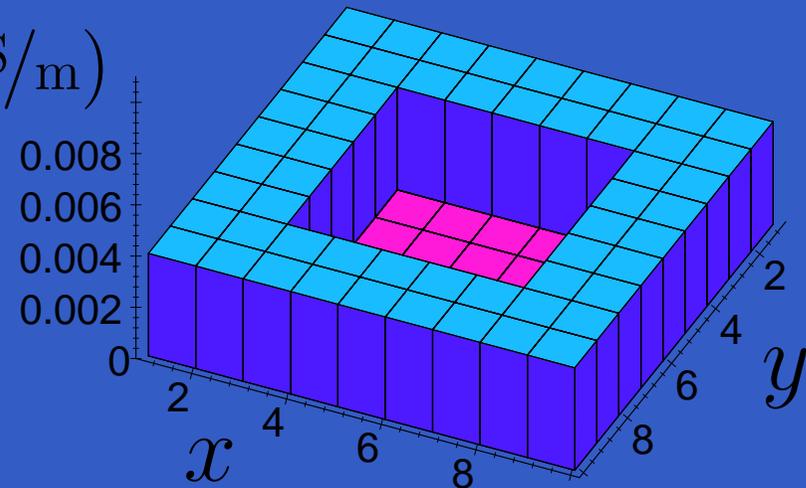


- ▼  $\epsilon_r = 3, \sigma = 0$ ; ext:  $\epsilon_r = 2.55, \sigma = 4 \cdot 10^{-3} \text{ S/m}$
- ▼  $L_x = L_y = 22.5 \text{ cm}, h_d = 23.75 \text{ cm}, \Delta_x = \Delta_y = 2.5 \text{ cm}$

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$\sigma$  (S/m)



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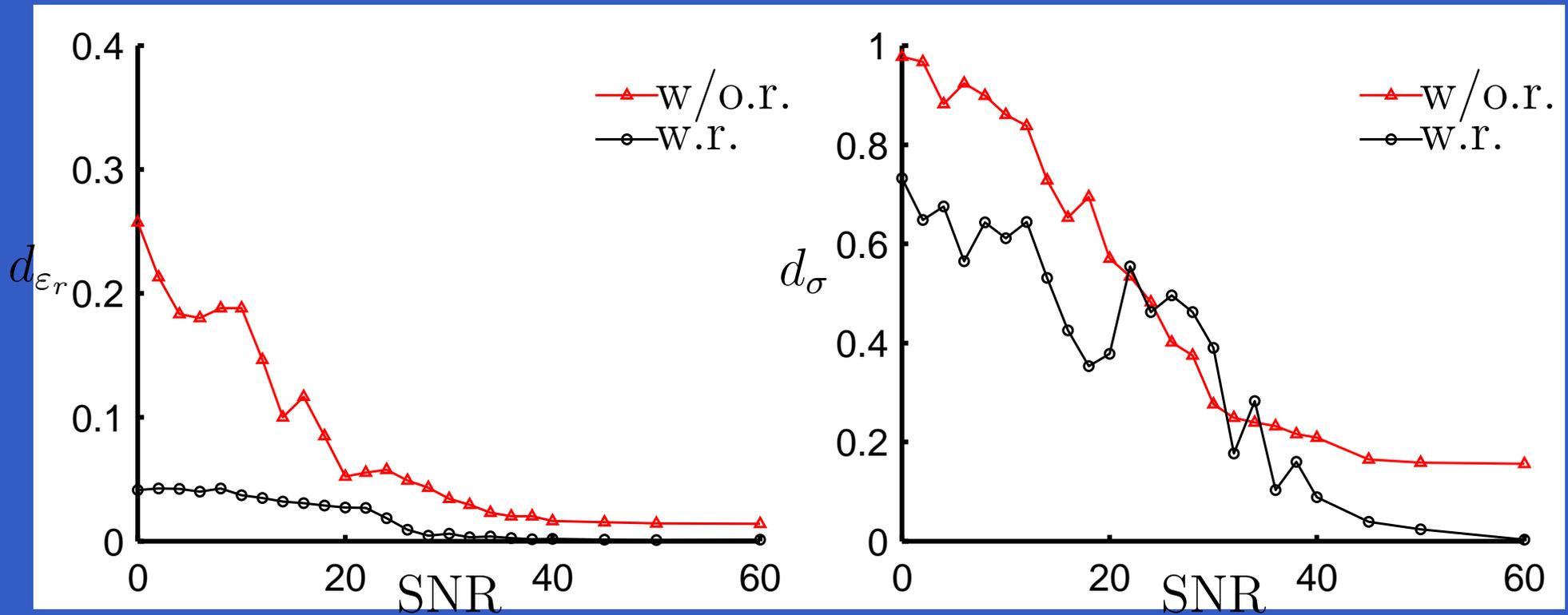
▼  $L_x = L_y = 22.5$  cm,  $h_d = 23.75$  cm,  $\Delta_x = \Delta_y = 2.5$  cm

$$d_{\epsilon_r} \triangleq \frac{\|\epsilon_r - \epsilon_r^d\|}{\|\epsilon_r^d\|}$$

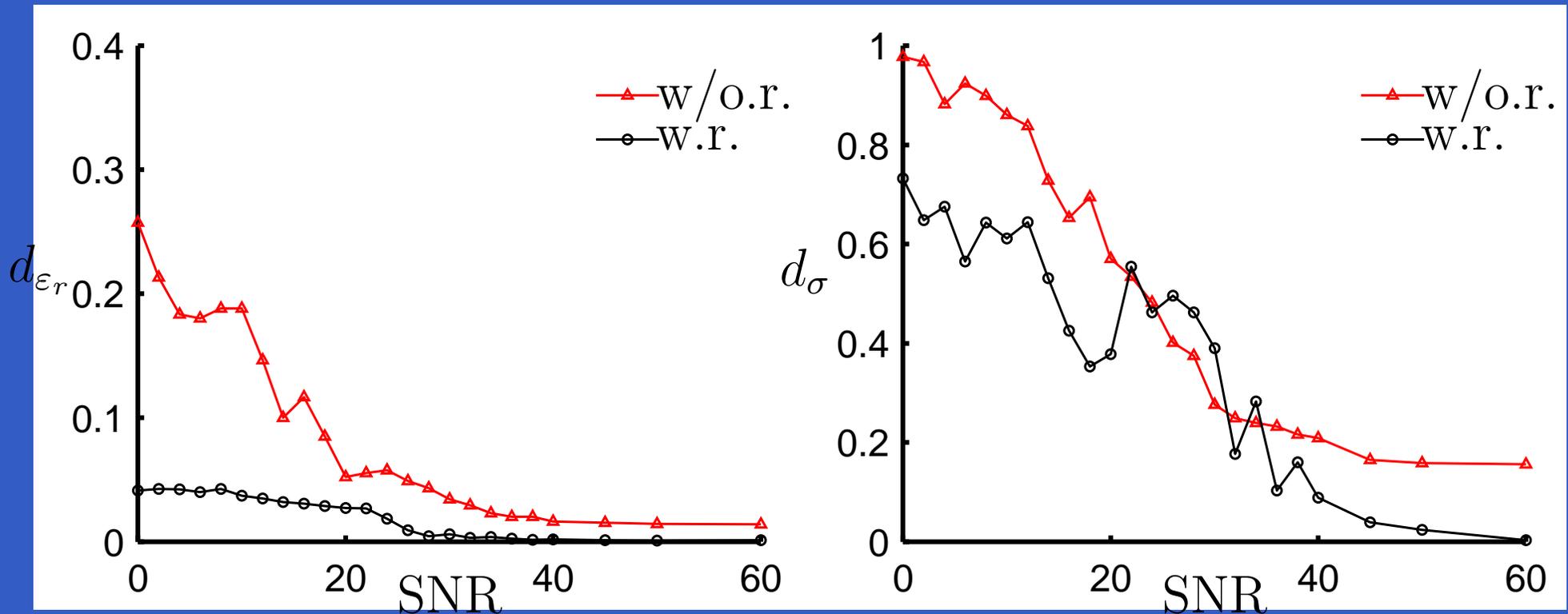
$$d_{\sigma} \triangleq \frac{\|\sigma_r - \sigma_r^d\|}{\|\sigma_r^d\|}$$



# Robustness to noise (1/3)



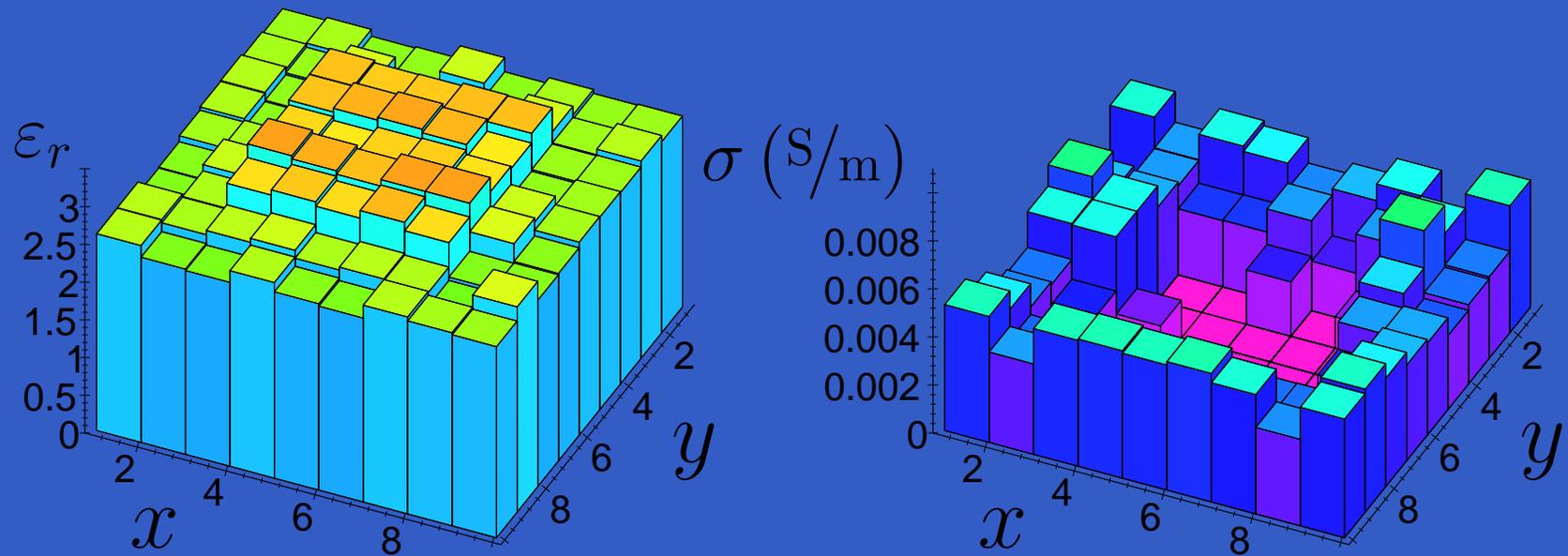
# Robustness to noise (1/3)



✓ Permittivity

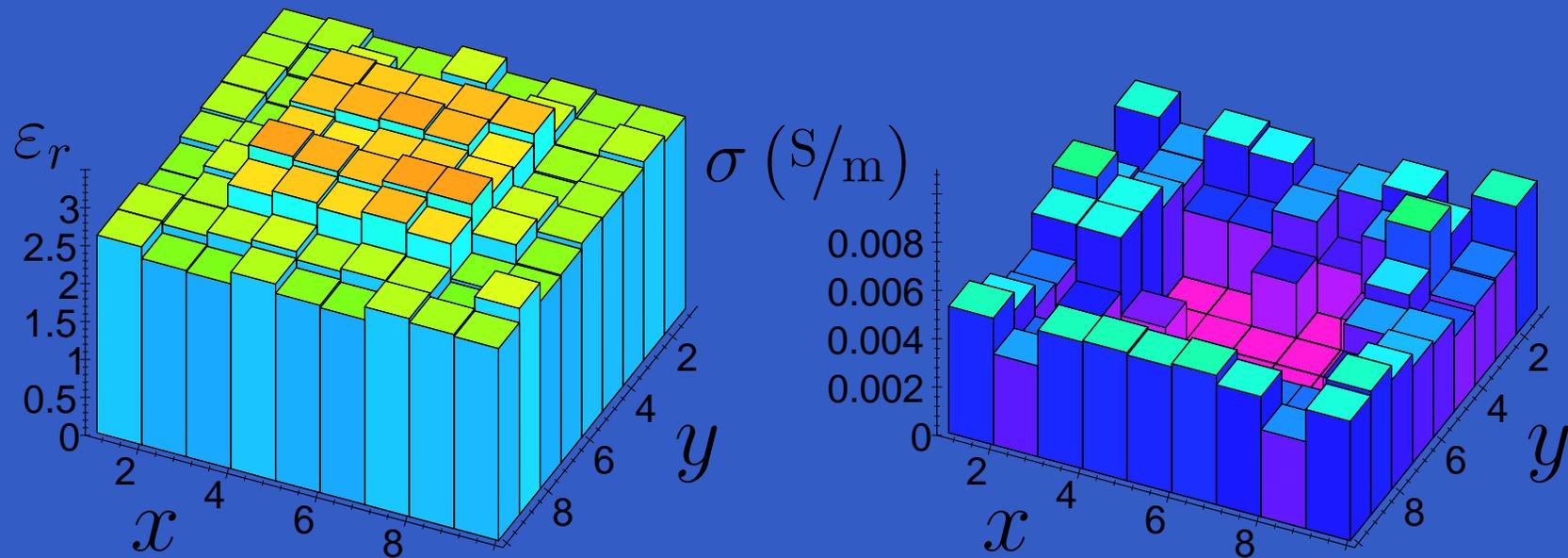
✗ Conductivity

# Robustness to noise (2/3)



SNR = 30 dB, without regularization

# Robustness to noise (2/3)



SNR = 30 dB, without regularization

$$L_M = 1.5 \text{ m}$$

$$N_M = 21$$

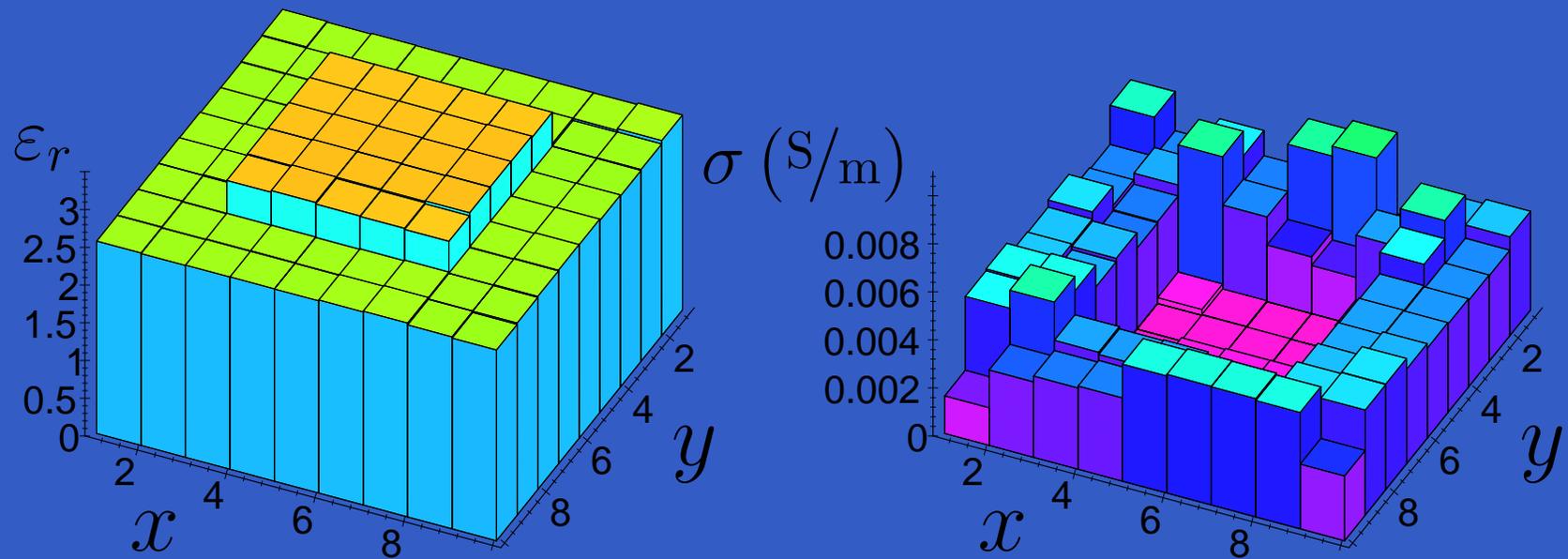
$$\Delta_M = 7.5 \text{ cm}$$

$$f_{\min} = 0.3 \text{ GHz}$$

$$f_{\max} = 1.3 \text{ GHz}$$

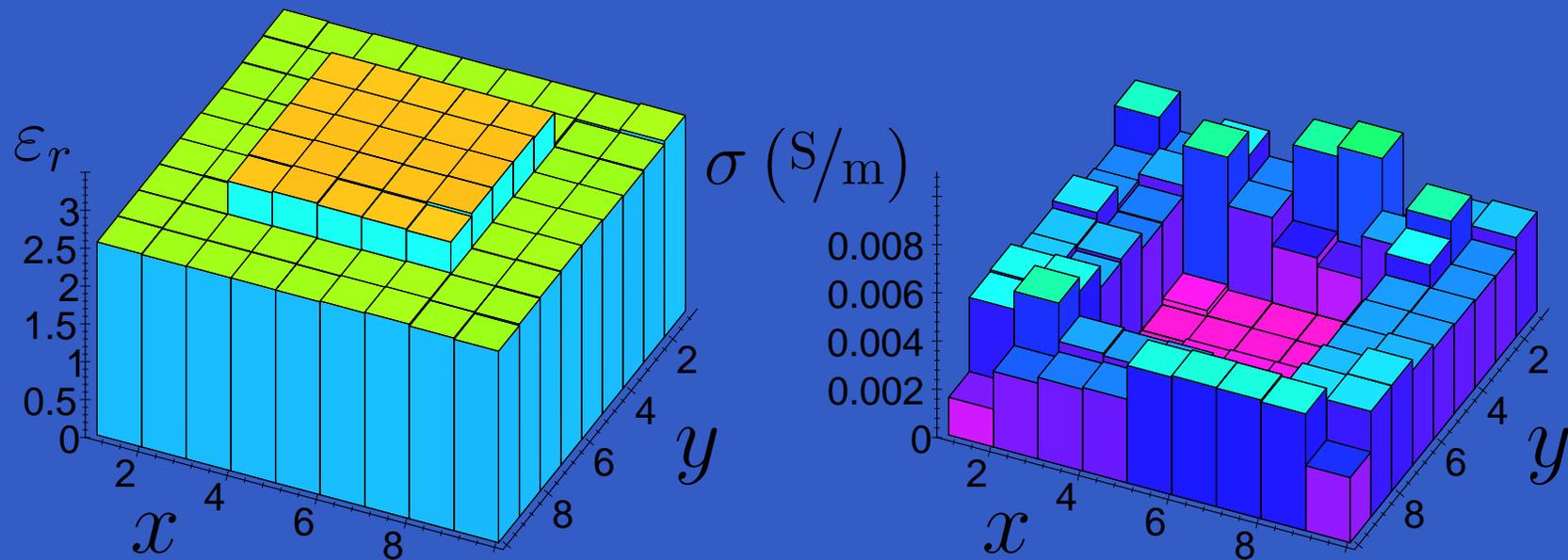
$$N_F = 3$$

# Robustness to noise (3/3)



SNR = 30 dB, *with regularization*

# Robustness to noise (3/3)



SNR = 30 dB, *with regularization*

$$\zeta_{\epsilon_r} = 10^{-2}$$

$$\zeta_{\sigma} = 10^{-3}$$

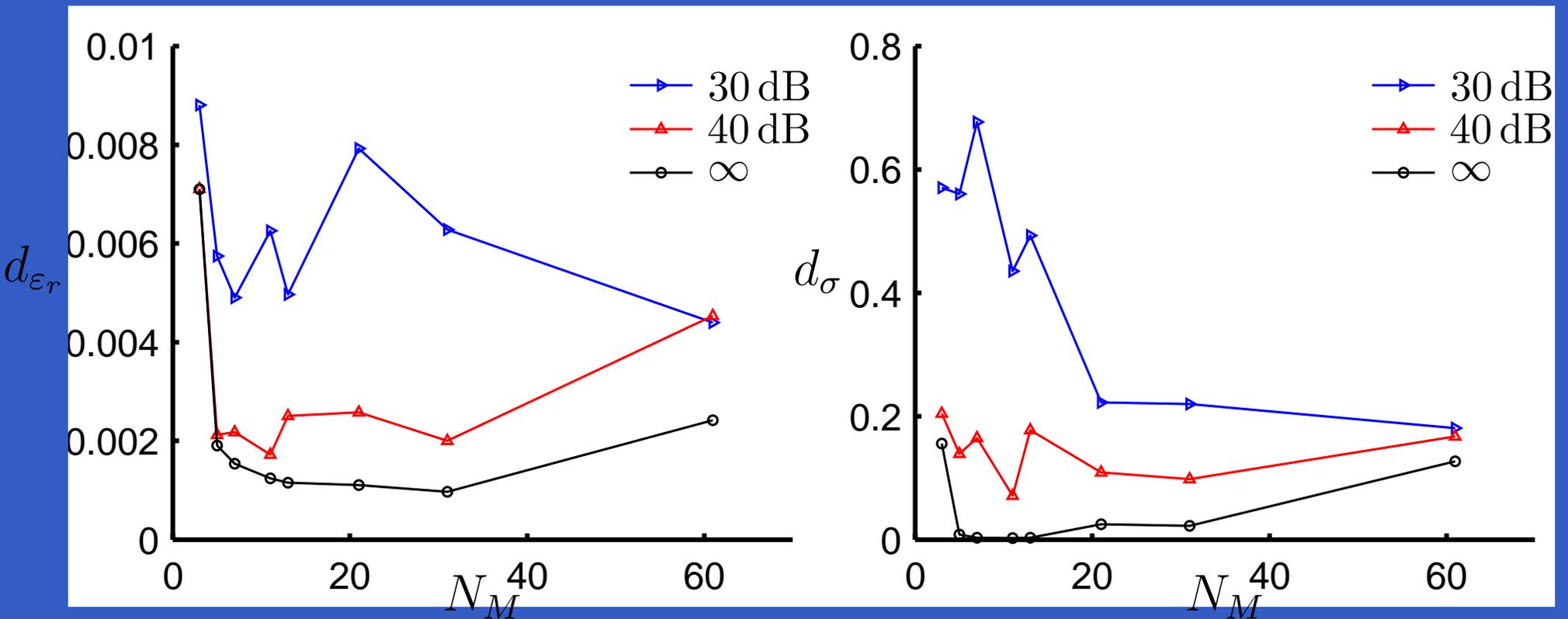
$$\phi(\cdot) = \phi_{gc}(\cdot)$$

$$\delta_{\epsilon_r} = 0.4$$

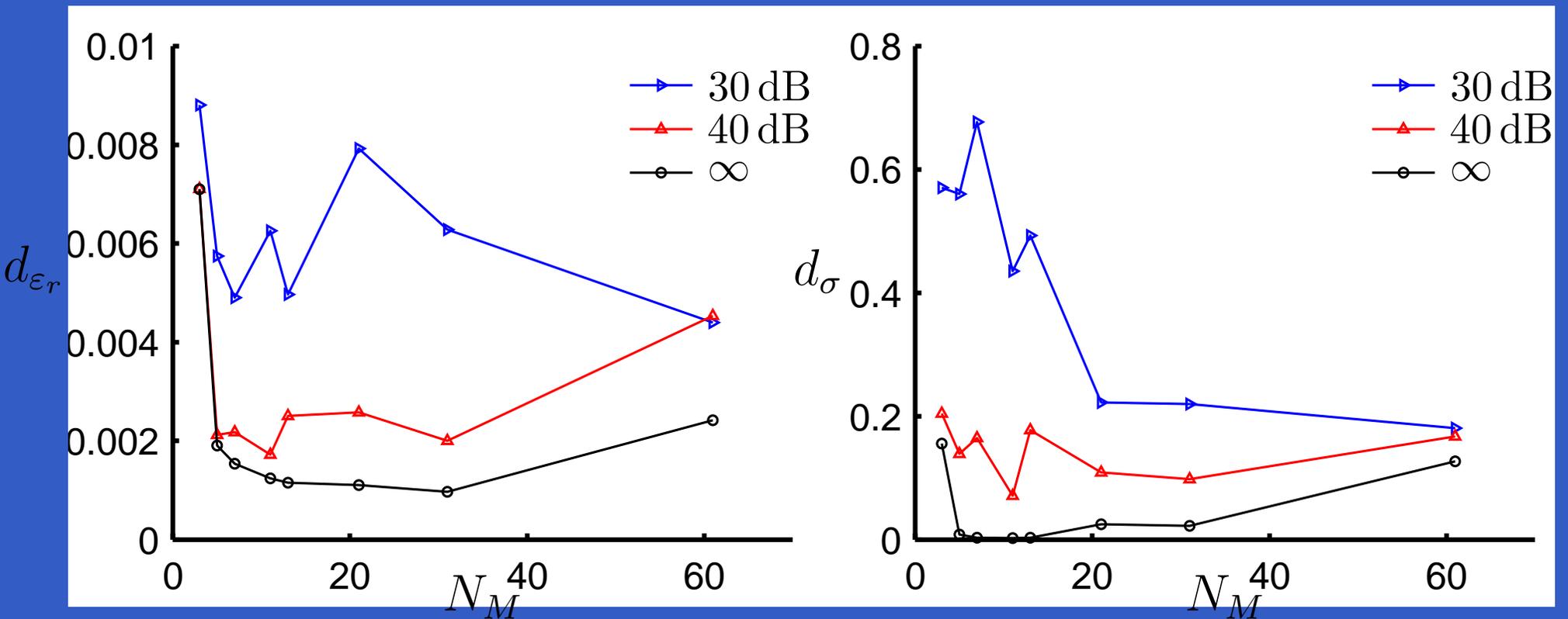
$$\delta_{\sigma} = 1.25 \cdot 10^{-3}$$

$$N_{\text{int}} = 10$$

# Number of measurement points



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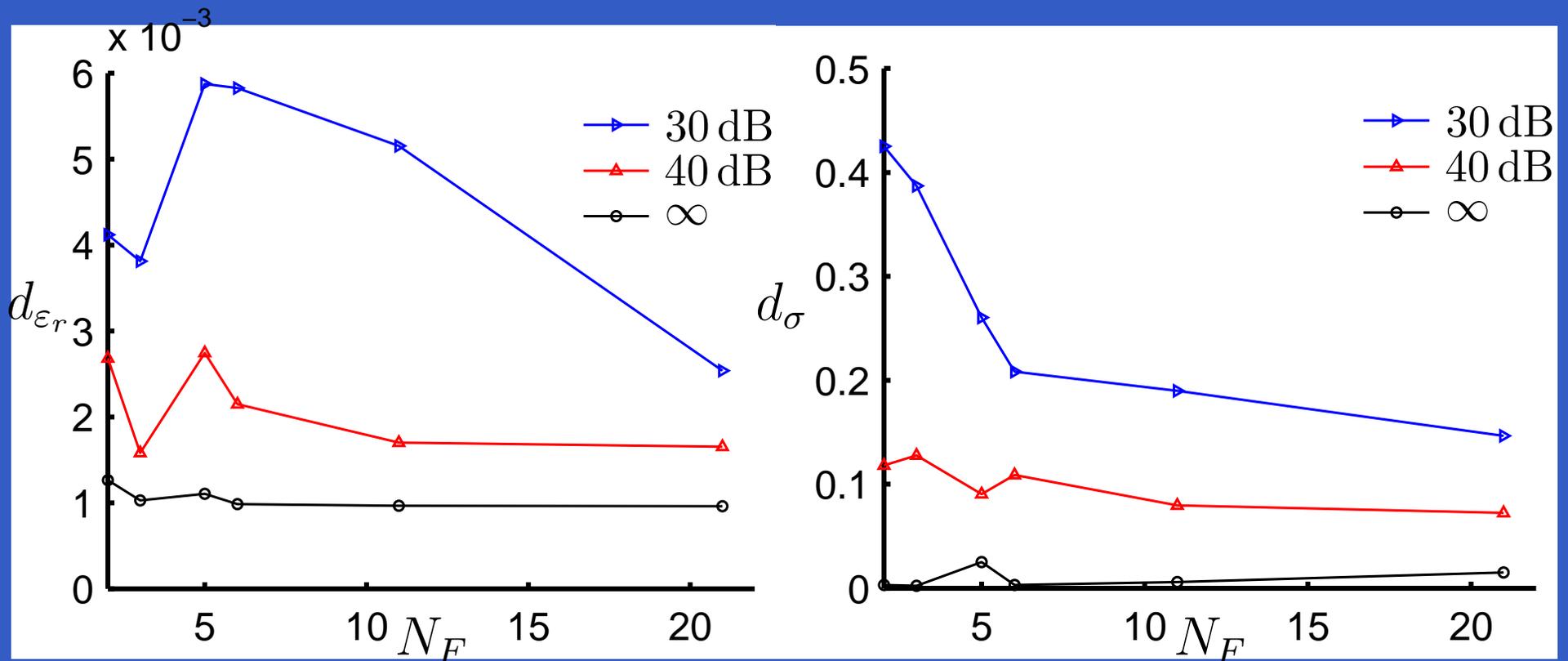


$(N_F = 5)$

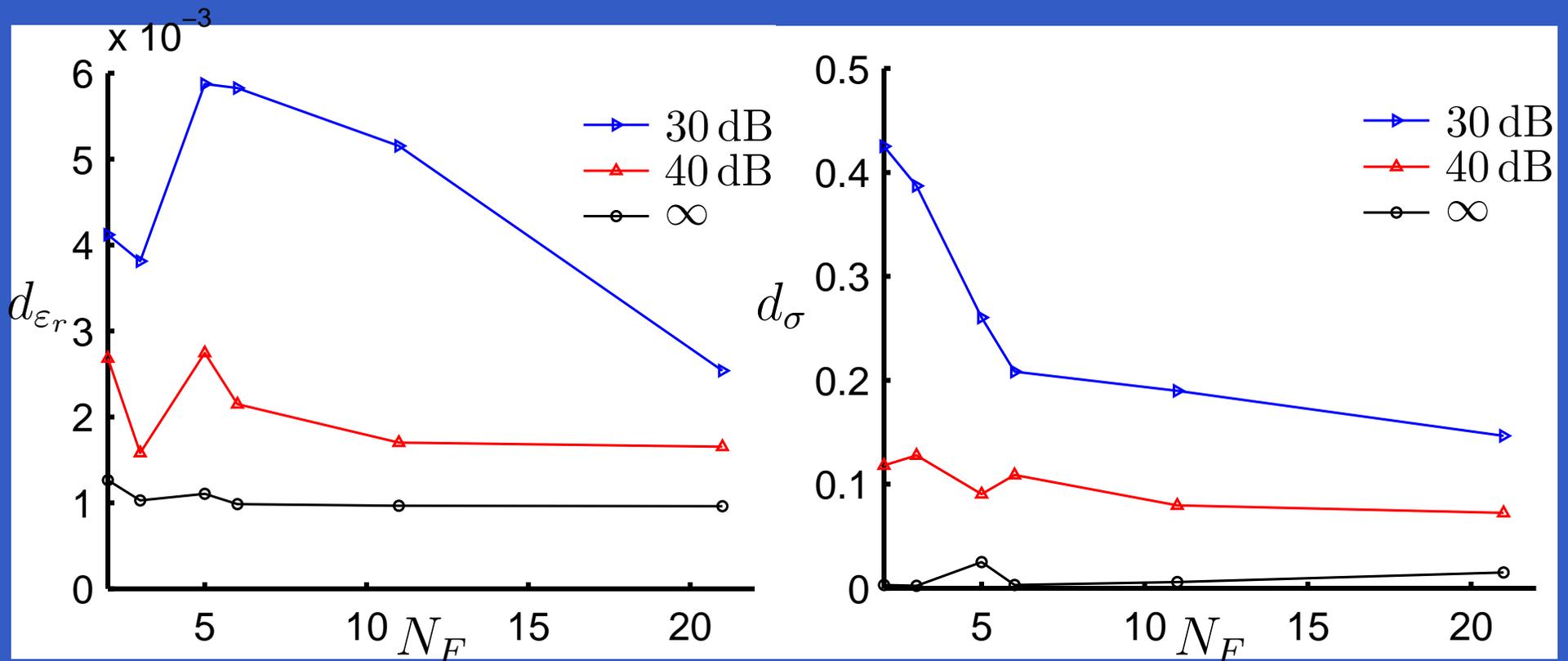
$N_M \rightarrow 21$



# Number of frequencies

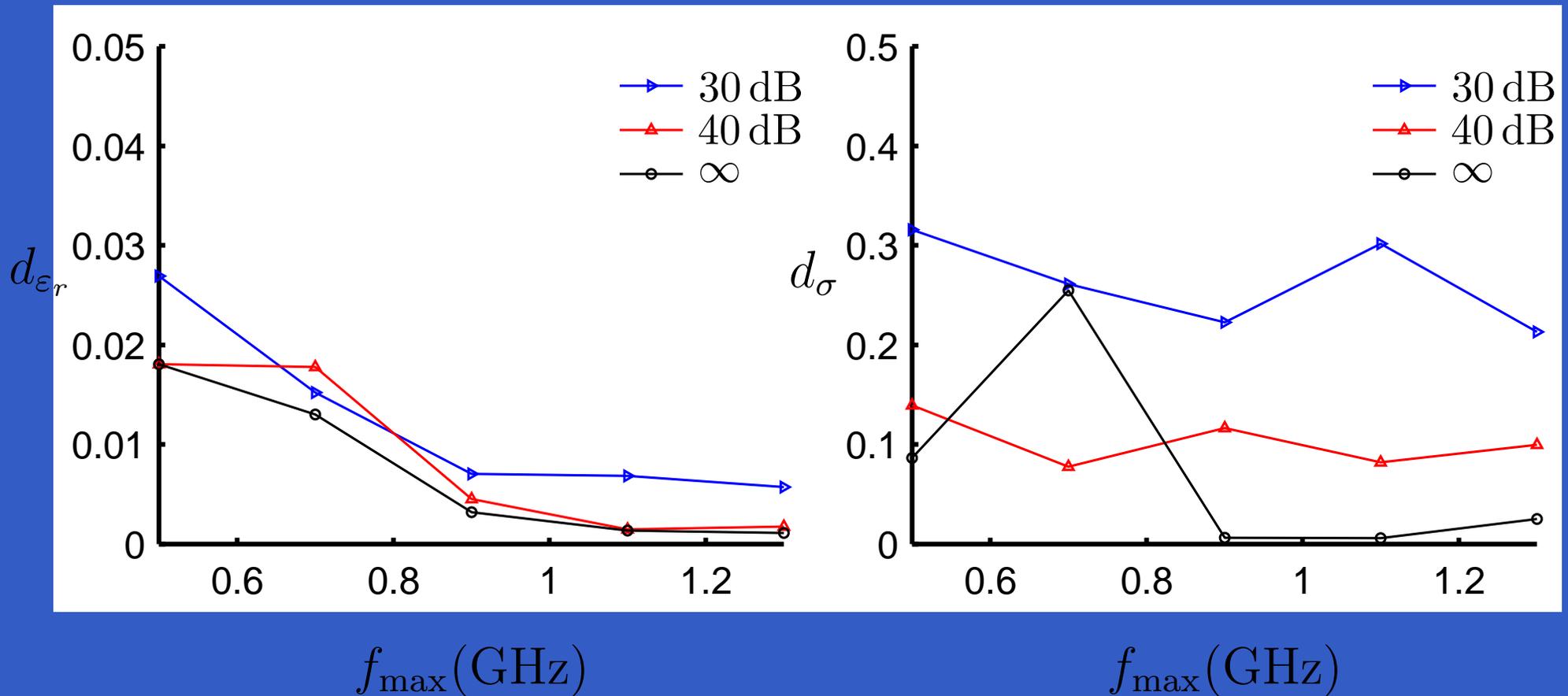


# Number of frequencies

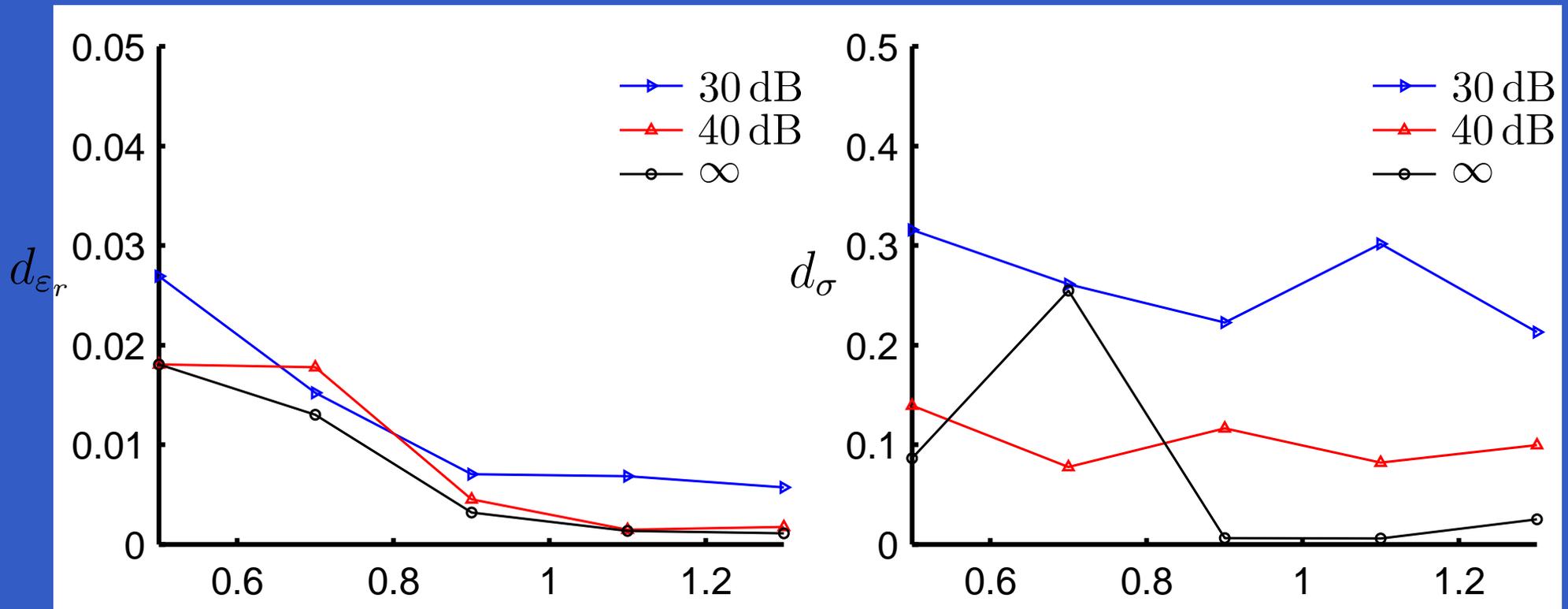


$N_F \rightarrow 5$

# Stretch frequency band



# Stretch frequency band



$f_{\max}$  (GHz) ( $N_F = 5$ )

$f_{\max}$  (GHz)

$f_{\max} \rightarrow 1.3$  GHz

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# Conclusions

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## ▼ Robustness to noise

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- ▼ Frequencies used:
  - ▶ Wide band
  - ▶ Low: localization

# Conclusions

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- ▼ Optimum number of emitting/measurement points
- ▼ Frequencies used:
  - ▶ Wide band
  - ▶ Low: localization
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# Conclusions

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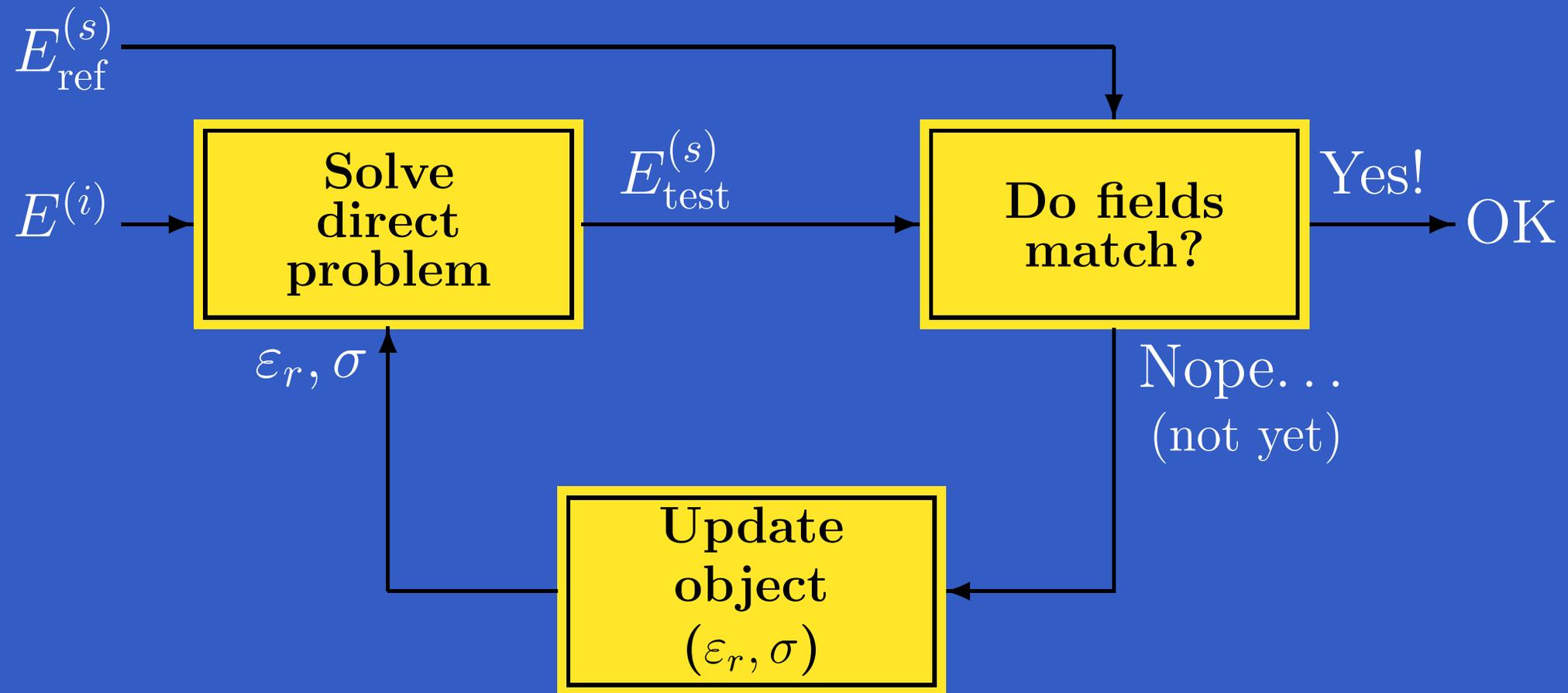
# Study of the three-dimensional extension

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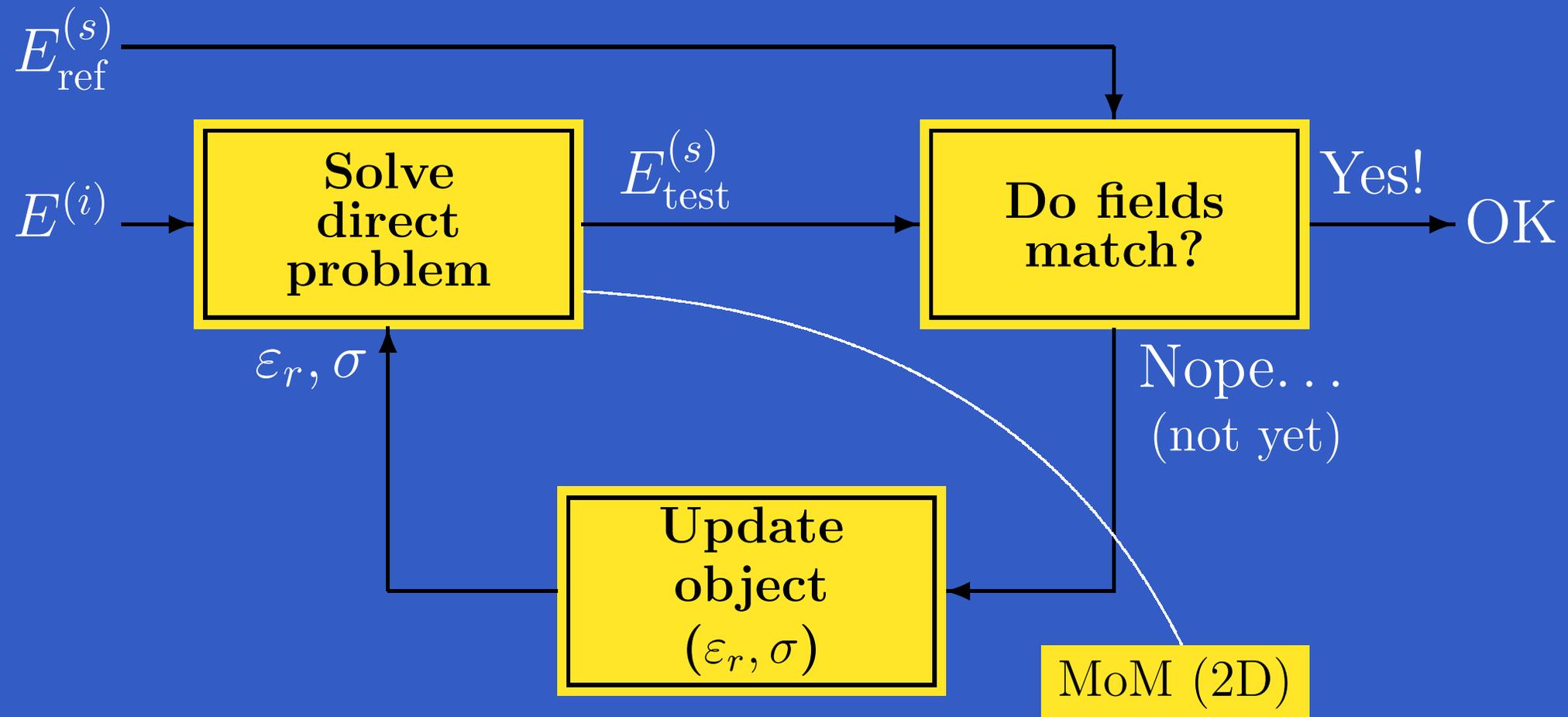
# Iterative algorithm (again)



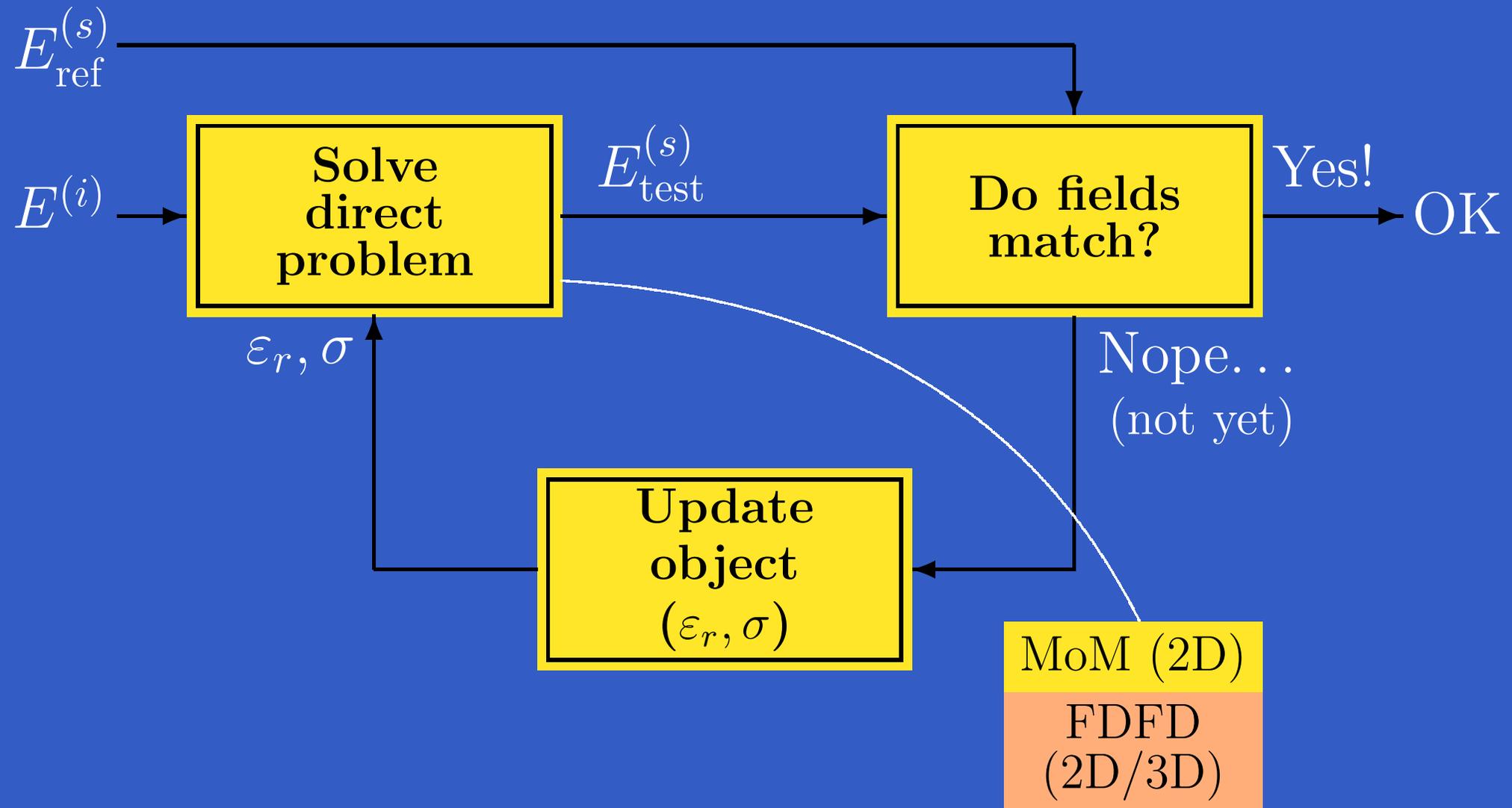
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# Iterative algorithm (again)



# Contents II

- ▼ Direct problem
- ▼ Finite-Difference Frequency-Domain method
- ▼ Numerical results

# Total field equations

$$\nabla \cdot (\bar{\epsilon} \cdot \mathbf{E}) = \rho$$

$$\nabla \cdot (\bar{\mu} \cdot \mathbf{H}) = \tau$$

$$\nabla \times \mathbf{E} = -j\omega\bar{\dot{\mu}} \cdot \mathbf{H} - \mathbf{M}$$

$$\nabla \times \mathbf{H} = j\omega\bar{\dot{\epsilon}} \cdot \mathbf{E} + \mathbf{J}$$

with

$$\bar{\dot{\mu}} = \bar{\mu} - j\frac{\bar{\sigma}^*}{\omega}, \quad \bar{\dot{\epsilon}} = \bar{\epsilon} - j\frac{\bar{\sigma}}{\omega}$$

# Scattered field equations

$$\mathbf{E} = \mathbf{E}^{(i)} + \mathbf{E}^{(s)}$$

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$$\nabla \cdot (\bar{\epsilon} \cdot \mathbf{E}^{(s)}) = \rho^{(ind)} + \rho^{(s)}$$

$$\nabla \cdot (\bar{\mu} \cdot \mathbf{H}^{(s)}) = \tau^{(ind)} + \tau^{(s)}$$

$$\nabla \times \mathbf{E}^{(s)} = -j\omega \bar{\mu} \cdot \mathbf{H}^{(s)} - \mathbf{M}^{(ind)} - \mathbf{M}^{(s)}$$

$$\nabla \times \mathbf{H}^{(s)} = j\omega \bar{\epsilon} \cdot \mathbf{E}^{(s)} + \mathbf{J}^{(ind)} + \mathbf{J}^{(s)}$$



# Definition of charge densities

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Induced from incident field:

$$\mathbf{J}^{(ind)} \triangleq \mathbf{j} \omega (\bar{\boldsymbol{\epsilon}} - \bar{\boldsymbol{\epsilon}}_{(b)}) \cdot \mathbf{E}^{(i)} = \mathbf{j} \omega \bar{\mathbf{C}}_{(e)} \cdot \mathbf{E}^{(i)}$$

$$\mathbf{M}^{(ind)} \triangleq \mathbf{j} \omega (\bar{\boldsymbol{\mu}} - \bar{\boldsymbol{\mu}}_{(b)}) \cdot \mathbf{H}^{(i)} = \mathbf{j} \omega \bar{\mathbf{C}}_{(m)} \cdot \mathbf{H}^{(i)}$$

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- ✓ Equivalence between total / scattered field equations
- ✓ Uniform treatment of electromagnetic problems
- ✓ Pure scattered field formulation

## Finite-difference frequency-domain (1/2)

- ▼ Spatial derivatives  $\longrightarrow$  finite differences

$$\left. \frac{\partial f}{\partial x_i} \right|_{\mathbf{x}_0} = \frac{f(\mathbf{x}_0 + h\mathbf{e}_i) - f(\mathbf{x}_0 - h\mathbf{e}_i)}{2h} + \mathcal{O}(h^2)$$

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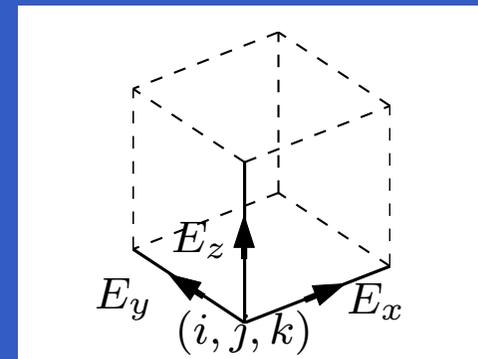
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- ▼ Uniform cubic grid

$$E_x^{i,j,k} = E_x|_{i+\frac{1}{2},j,k} \quad H_x^{i,j,k} = H_x|_{i,j+\frac{1}{2},k+\frac{1}{2}}$$

$$E_y^{i,j,k} = E_y|_{i,j+\frac{1}{2},k} \quad H_y^{i,j,k} = H_y|_{i+\frac{1}{2},j,k+\frac{1}{2}}$$

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with

$$\langle \varepsilon_{xx}^{i,j,k} \rangle \triangleq \frac{1}{4} \left( \varepsilon_{xx}^{i,j,k} + \varepsilon_{xx}^{i,j-1,k} + \varepsilon_{xx}^{i,j-1,k-1} + \varepsilon_{xx}^{i,j,k-1} \right)$$

$$\langle \mu_{xx}^{i,j,k} \rangle \triangleq \frac{1}{2} \left( \mu_{xx}^{i,j,k} + \mu_{xx}^{i-1,j,k} \right)$$

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$$\mathbf{A}_h \mathbf{h} = j\omega \text{diag}(\langle \dot{\epsilon} \rangle) \mathbf{e} + \mathbf{j} \quad , \quad \mathbf{A}_h = \mathbf{A}_e^T$$

## Discretized wave equation (1/3)

The two matrix equations yield:

$$\begin{aligned} [\mathbf{A}_e^T \text{diag}(\langle \dot{\boldsymbol{\mu}} \rangle)^{-1} \mathbf{A}_e - \omega^2 \text{diag}(\langle \dot{\boldsymbol{\epsilon}} \rangle)] \mathbf{e} = \\ - \mathbf{j} \omega \mathbf{j} - \mathbf{A}_e^T \text{diag}(\langle \dot{\boldsymbol{\mu}} \rangle)^{-1} \mathbf{m} \end{aligned}$$

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Compare with the continuous case:

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Add gradient of Gauss' law  $\nabla \nabla \cdot (\bar{\boldsymbol{\epsilon}} \cdot \mathbf{E}) = \nabla (\rho + \rho^{(ind)})$   
in discretized form:

$$\mathbf{A}_g \text{diag}(\langle \boldsymbol{\epsilon} \rangle) \mathbf{e} = -\mathbf{A}_g \text{diag}(\langle \mathbf{c}_\epsilon \rangle) \mathbf{e}^i - \mathbf{A}_\rho \langle \rho \rangle$$

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$\mathbf{V}_e, \mathbf{V}_m, \mathbf{V}_\rho$ : averaging matrices, e.g.  $\langle \epsilon \rangle = \mathbf{V}_e \epsilon$

## Discretized wave equation (3/3)

- ▼ Closed-geometry and radiation problems

$$\mathbf{x} = \mathbf{e}$$

$$\mathbf{b} = -\left(\mathbf{j}\omega\mathbf{j} + \mathbf{A}_e^T \text{diag}(\mathbf{V}_m \dot{\boldsymbol{\mu}})^{-1} \mathbf{m} + \mathbf{A}_\rho \mathbf{V}_\rho \boldsymbol{\rho}\right)$$

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- ▼ Scattering problems

$$\mathbf{x} = \mathbf{e}^s$$

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# Enforce boundary conditions

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$$\mathbf{A}' = \mathbf{I}_{VMC} + \mathbf{I}_{VMC} \mathbf{A} \mathbf{I}_C \quad \mathbf{b}' = \mathbf{I}_{VMC} \mathbf{b} - \mathbf{I}_V \mathbf{I}_M^i \mathbf{e}^i + \mathbf{v}$$

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$$\mathbf{A}'_{\text{g}} = \mathbf{I}_{\text{M}_n \text{C}_n} \mathbf{A}_{\text{g}}$$

$$\mathbf{A}'_{\rho} = \mathbf{I}_{\text{M}_n \text{C}_n} \mathbf{A}_{\rho}$$

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$$\mathbf{A}'_{\mathbf{g}} = \mathbf{I}_{\mathbf{M}_n \mathbf{C}_n} \mathbf{A}_{\mathbf{g}}$$

$$\mathbf{A}'_{\rho} = \mathbf{I}_{\mathbf{M}_n \mathbf{C}_n} \mathbf{A}_{\rho}$$

▼ Condensed system

## Enforce boundary conditions

- ▼ Perfect electric conductor ( $\epsilon, \parallel$ ):  $x_n = 0$  or  $x_n = -e_n^i$
- ▼ Applied voltage:  $x_n = v_n$

$$\mathbf{A}' = \mathbf{I}_{\overline{\mathbf{VMC}}} + \mathbf{I}_{\mathbf{VMC}} \mathbf{A} \mathbf{I}_{\mathbf{C}} \quad \mathbf{b}' = \mathbf{I}_{\mathbf{VMC}} \mathbf{b} - \mathbf{I}_{\mathbf{V}} \mathbf{I}_{\overline{\mathbf{M}}} \mathbf{e}^i + \mathbf{v}$$

- ▼ No Gauss  $\perp$  PEC

$$\mathbf{A}'_{\mathbf{g}} = \mathbf{I}_{\mathbf{M}_n \mathbf{C}_n} \mathbf{A}_{\mathbf{g}}$$

$$\mathbf{A}'_{\rho} = \mathbf{I}_{\mathbf{M}_n \mathbf{C}_n} \mathbf{A}_{\rho}$$

- ▼ Condensed system

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & 1 & 0 \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$



## Enforce boundary conditions

- ▼ Perfect electric conductor ( $\epsilon, \parallel$ ):  $x_n = 0$  or  $x_n = -e_n^i$
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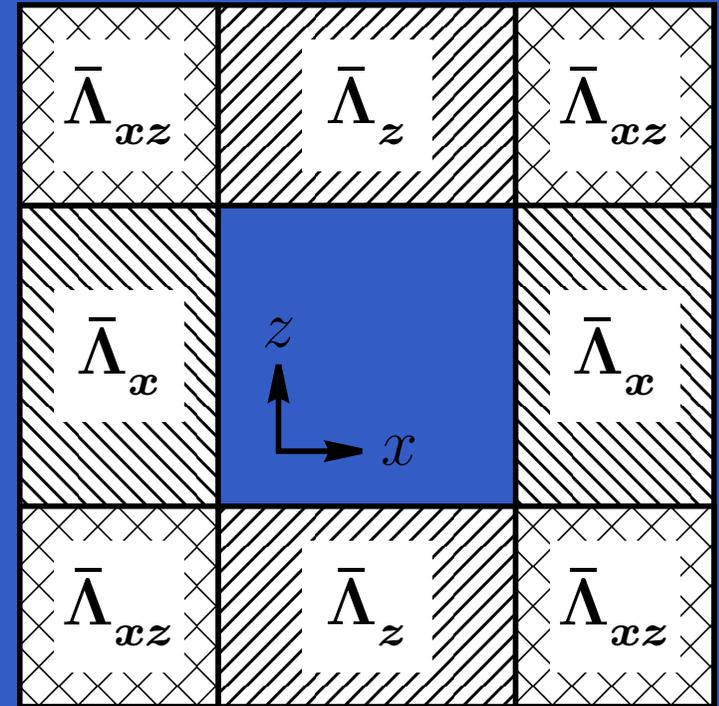
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$$x_2 = b_2$$

# Perfectly Matched Layers

$$\bar{\epsilon}_{\text{PML}} = \bar{\epsilon} \cdot \bar{\Lambda}_x$$
$$\bar{\mu}_{\text{PML}} = \bar{\mu} \cdot \bar{\Lambda}_x$$

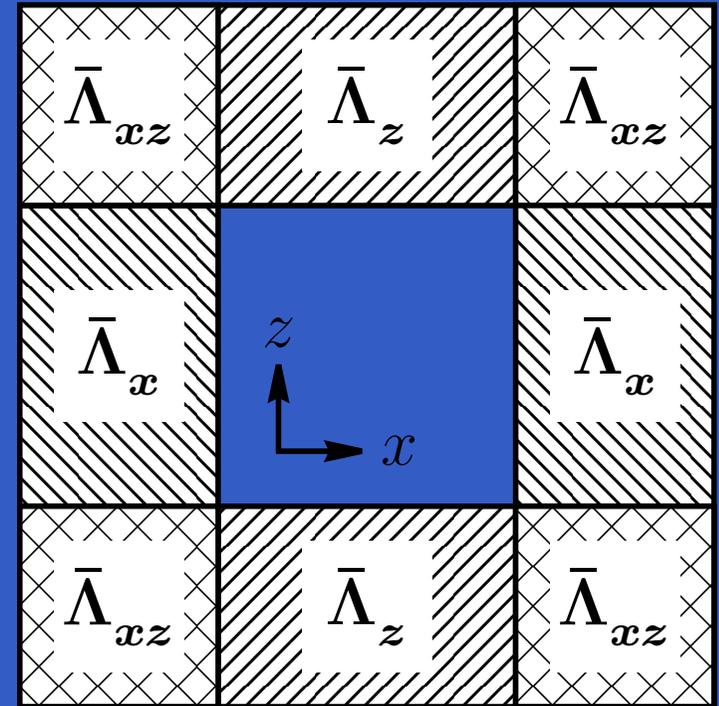


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$$\bar{\Lambda}_x = \begin{bmatrix} 1/s_x & 0 & 0 \\ 0 & s_x & 0 \\ 0 & 0 & s_x \end{bmatrix}$$

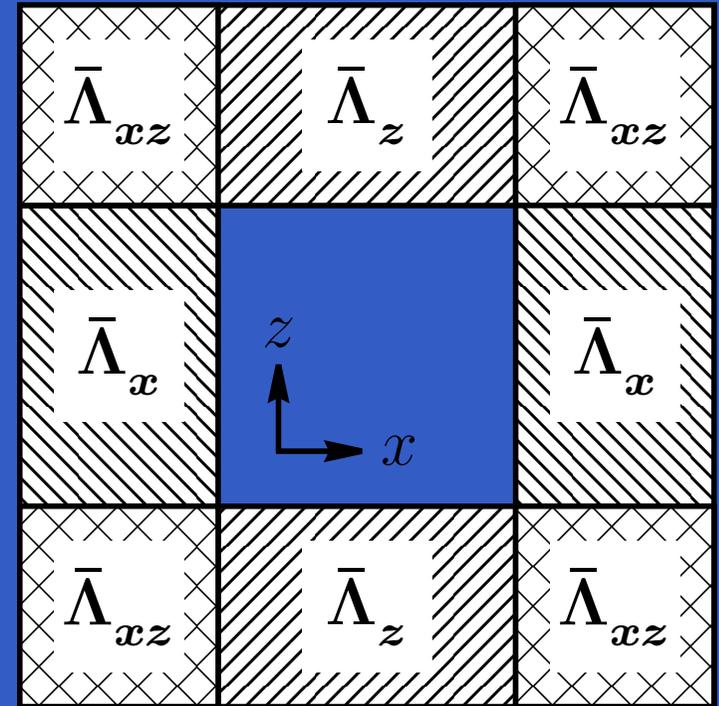


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$$s_x = \kappa_x - j \frac{\sigma_x}{\omega \epsilon_0}, \quad \kappa_x \geq 1, \quad \sigma_x \geq 0$$

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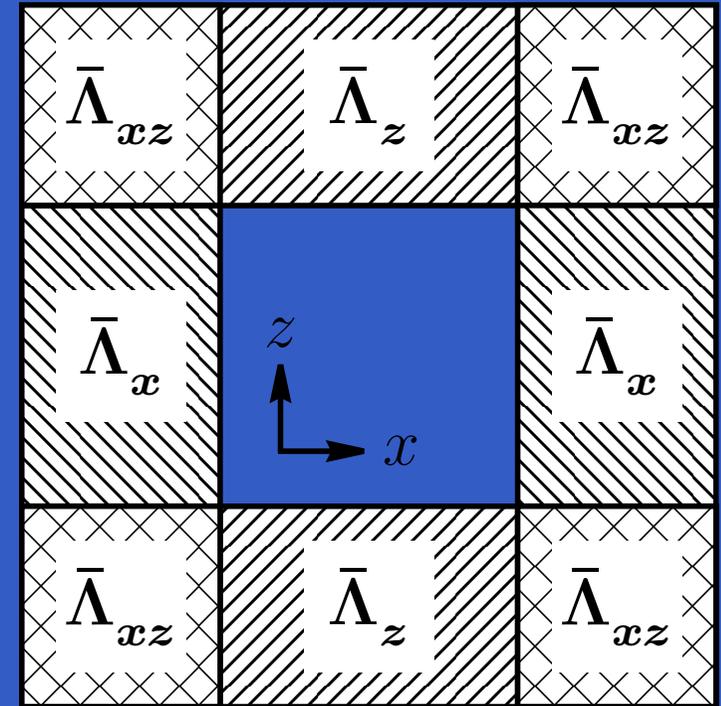
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# Near- to Far-Field Transform

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# Near- to Far-Field Transform

$r'$  near-field point

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- 

# Near- to Far-Field Transform

$r$  far-field (observation) point  
 $r'$  near-field point



# Near- to Far-Field Transform

- $\psi$  any rectangular component of  $\mathbf{E}$  or  $\mathbf{H}$
- $\mathbf{r}$  far-field (observation) point
- $\mathbf{r}'$  near-field point

# Near- to Far-Field Transform

Kirchhoff integral:

$$\psi(\mathbf{r}) = -\frac{1}{4\pi} \oint_S \frac{e^{-jkR}}{R} \left[ \frac{\partial \psi(\mathbf{r}')}{\partial \eta'} - \left( jk + \frac{1}{R} \right) \frac{1}{R} \hat{\boldsymbol{\eta}}' \cdot \mathbf{R} \psi(\mathbf{r}') \right] d\mathbf{r}'$$

$\psi$  any rectangular component of  $\mathbf{E}$  or  $\mathbf{H}$

$\mathbf{r}$  far-field (observation) point

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$$\mathbf{R} = \mathbf{r} - \mathbf{r}', \quad R = |\mathbf{R}|, \quad k = \omega \sqrt{\mu_0 \epsilon_0}$$

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▼  $\oint_S$  →  $\sum_n \sum_m w_{nm} \dots$  4th order 2D integration

## Near- to Far-Field Transform: Validation (1/6)

Radiation of an elementary dipole (far-field):

$$E_r(r, \theta, \phi) \approx 0, \quad E_\theta(r, \theta, \phi) \sim \sin\theta, \quad E_\phi(r, \theta, \phi) = 0$$

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$$\mathbf{e}_\theta = \left( E_\theta(\theta = 5^\circ) \ E_\theta(\theta = 10^\circ) \ \cdots \ E_\theta(\theta = 175^\circ) \right)^T$$

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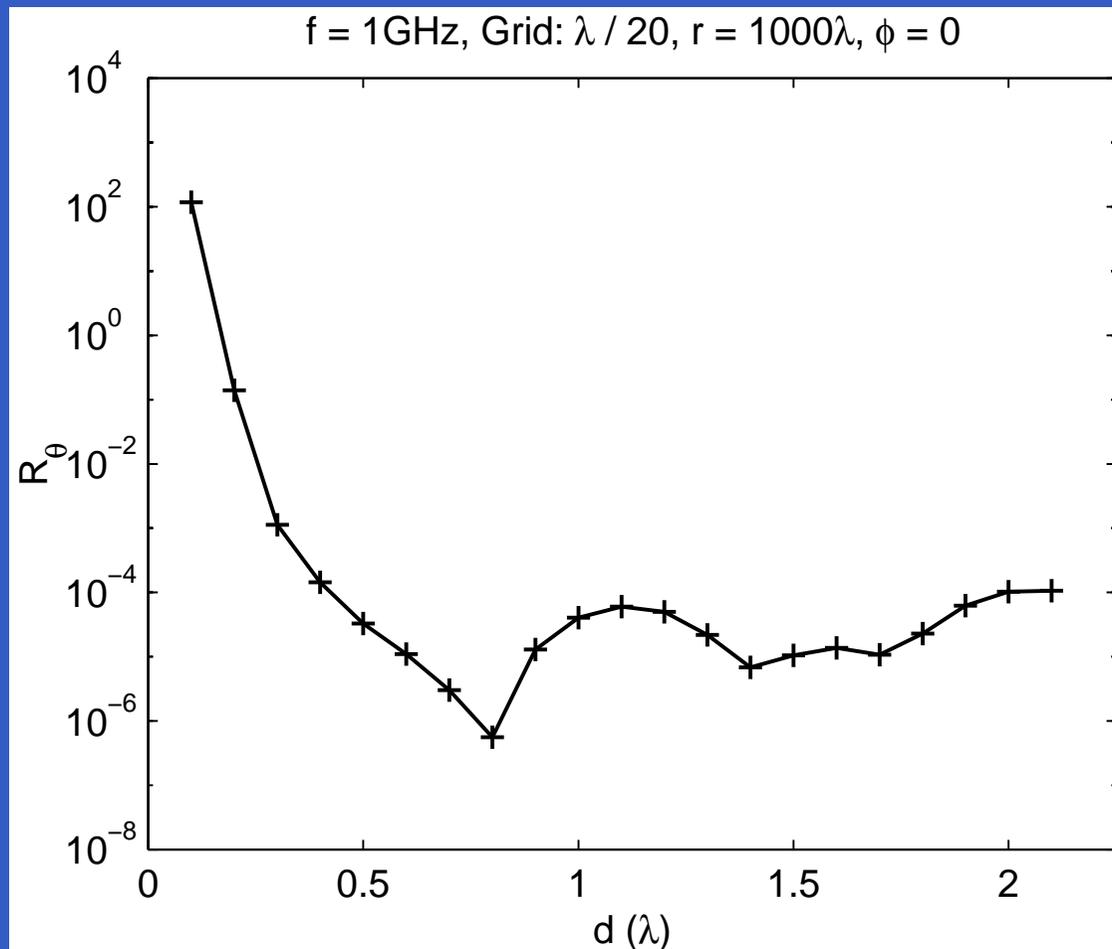
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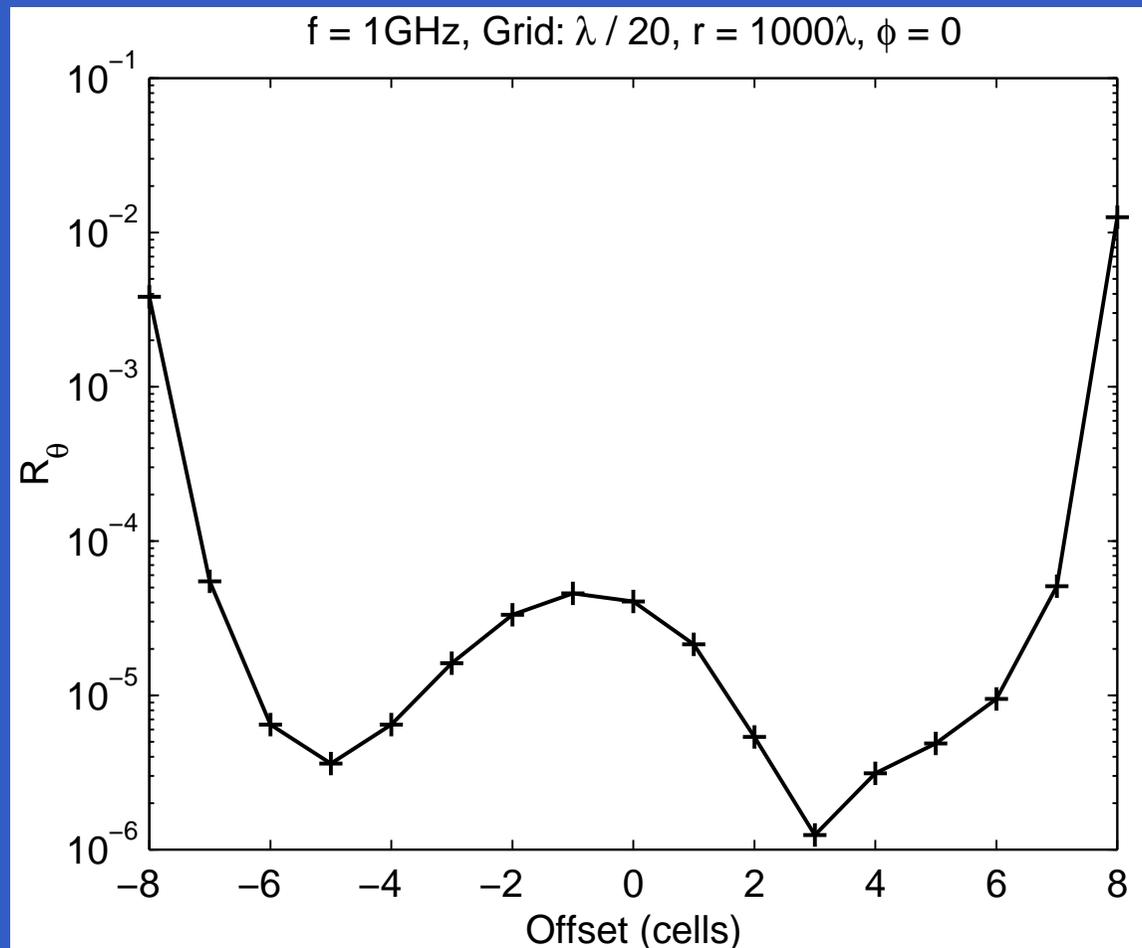
# Near- to Far-Field Transform: Validation (2/6)

Size of the integration cube



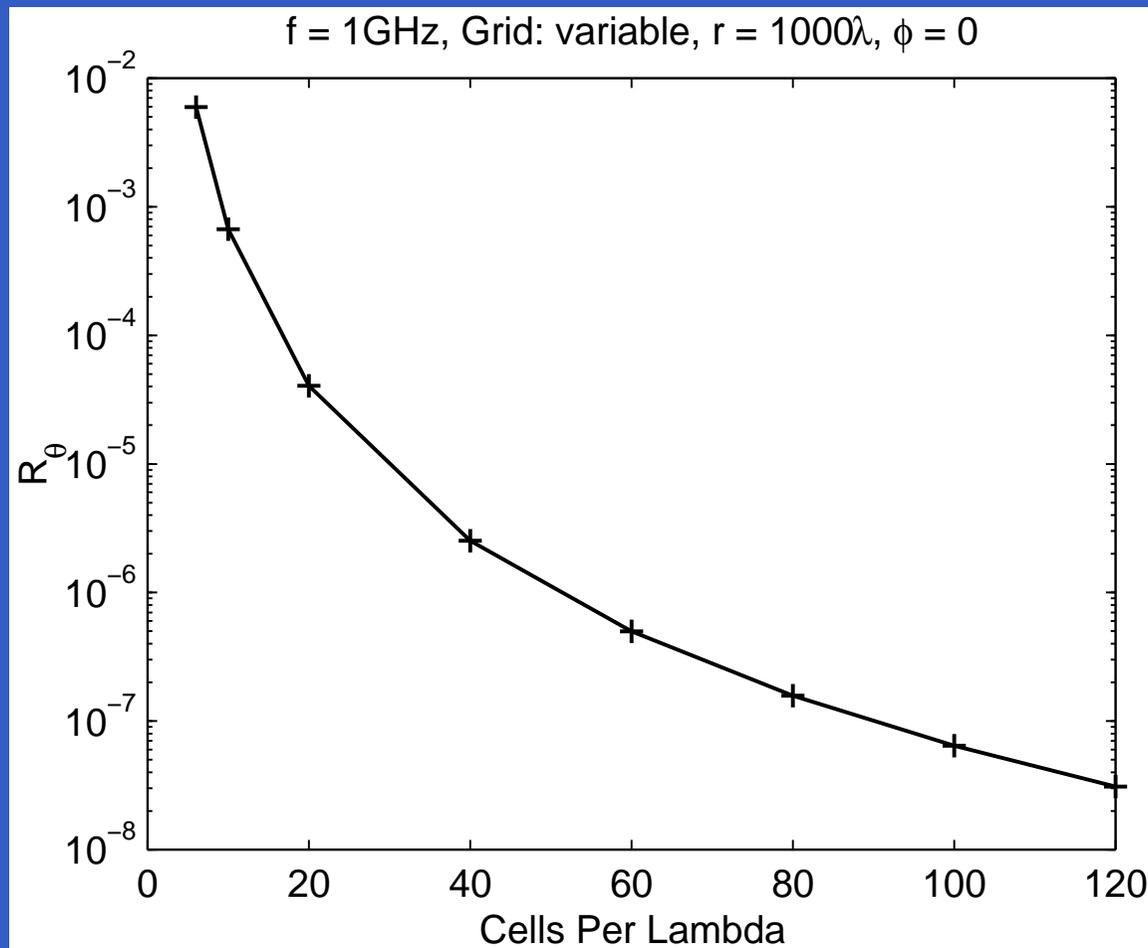
# Near- to Far-Field Transform: Validation (3/6)

Position of the integration cube



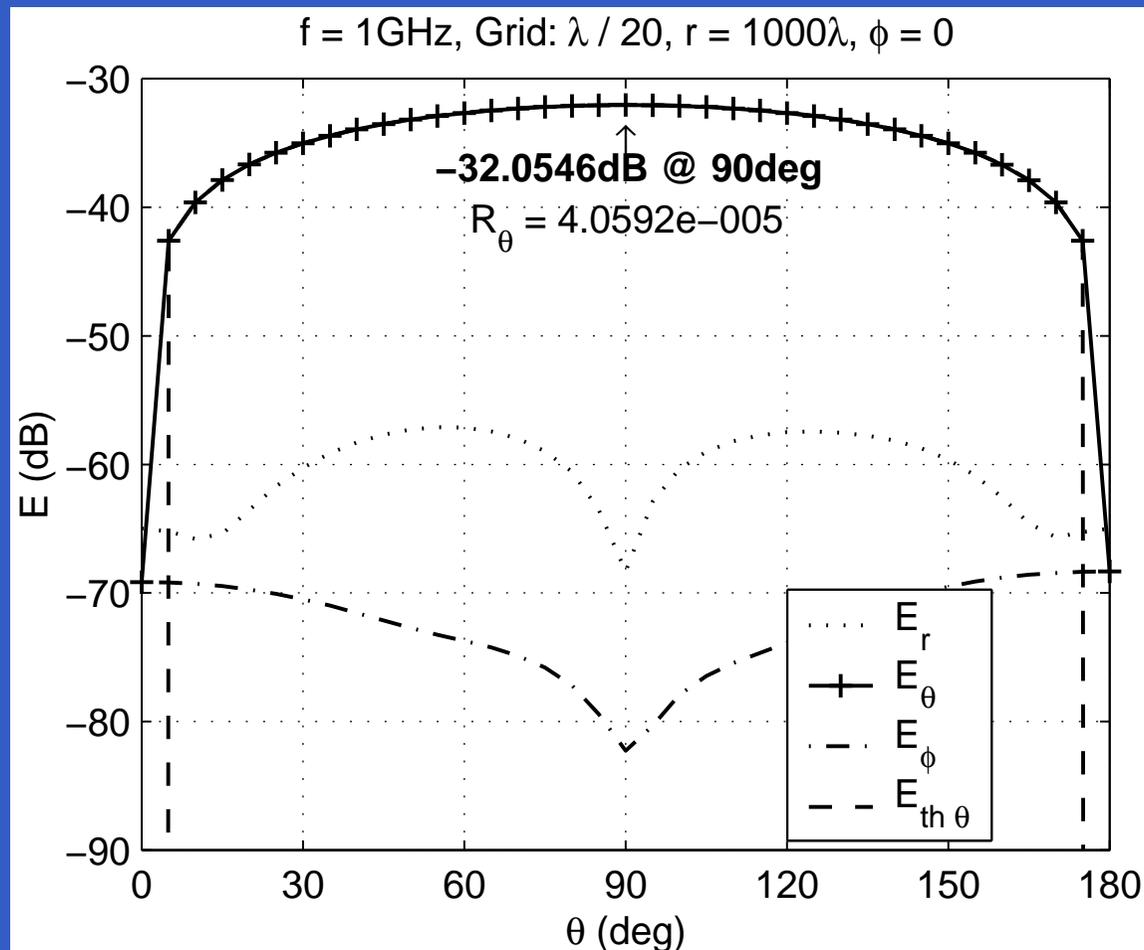
# Near- to Far-Field Transform: Validation (4/6)

## Coarseness of the discretization grid



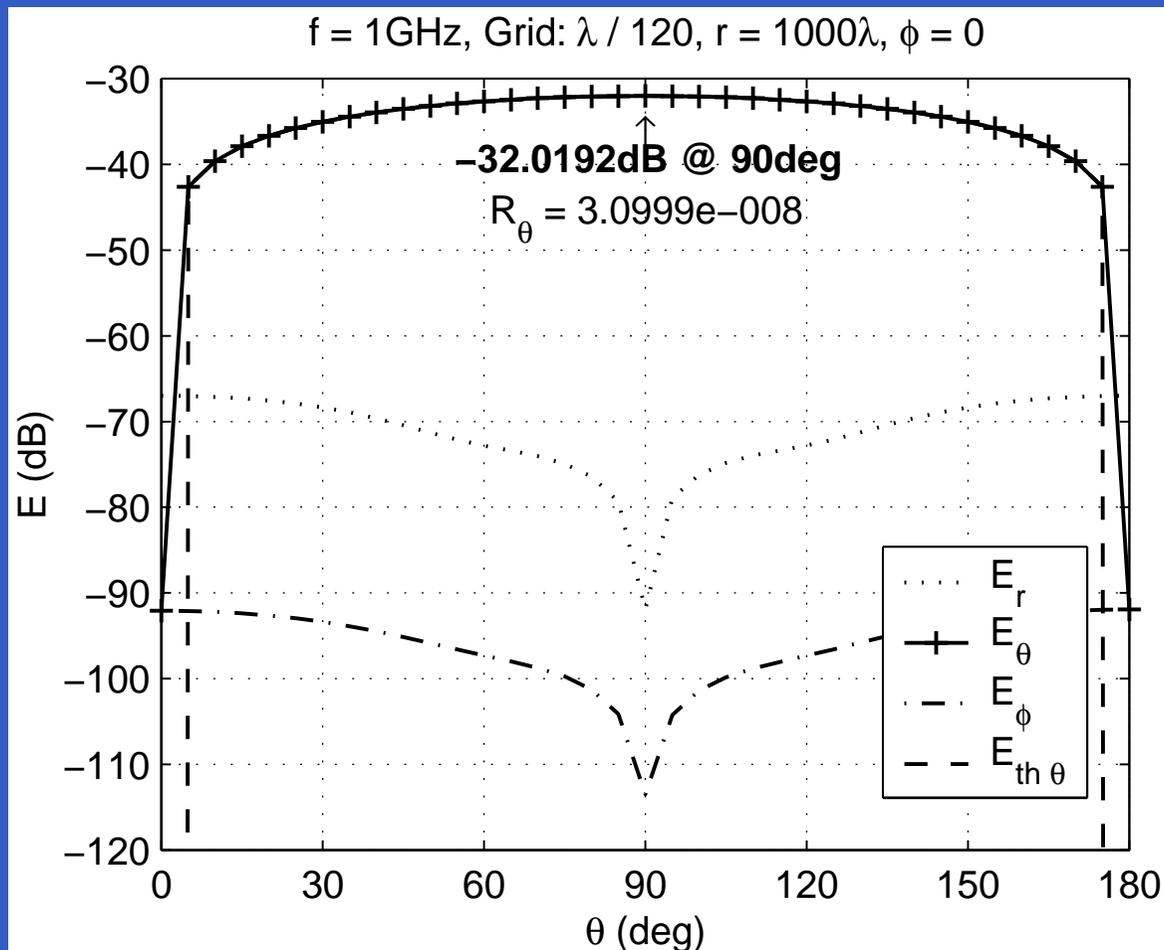
# Near- to Far-Field Transform: Validation (5/6)

Grid:  $\lambda/20$



# Near- to Far-Field Transform: Validation (6/6)

Grid:  $\lambda/120$



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# FDFD: numerical results

Closed-geometry problems

Open-geometry problems



# FDFD: numerical results

Closed-geometry problems:

- ▼ 2D: waveguide modes
- ▼ 3D: cavity modes

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- ▼ 3D: elementary dipole

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▼  $\mathbf{e} \in \text{nullspace } \mathbf{A}$

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BICGSTAB, GMRES

# FDFD: numerical results

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Open-geometry problems:

- ▼ 3D: elementary dipole

▼  $\mathbf{Ae} = \mathbf{b}$  (sparse)

▼ iterative methods:  
BICGSTAB, GMRES

▼ preconditioning:  
diagonal, LU, ILU

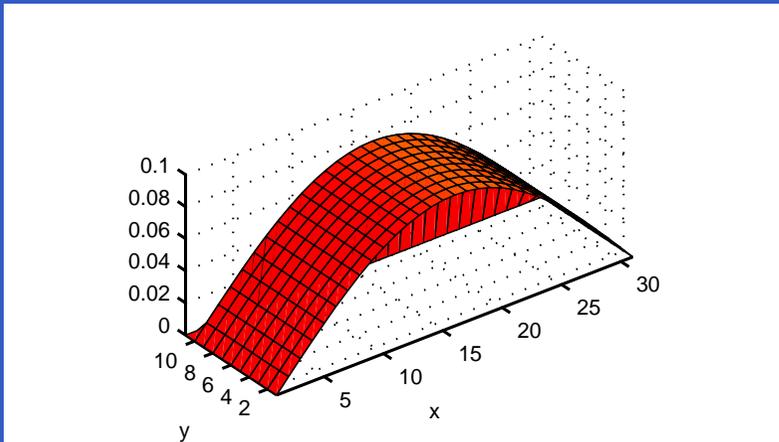


# Waveguide modes

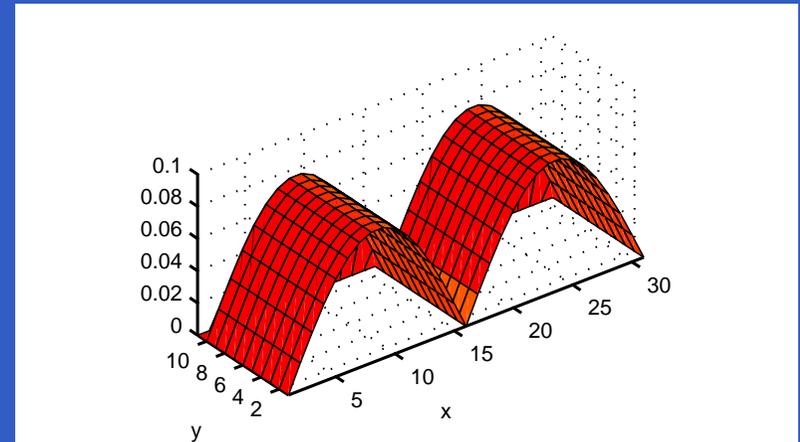
- ▼ Dimensions:  $a/b = 3$
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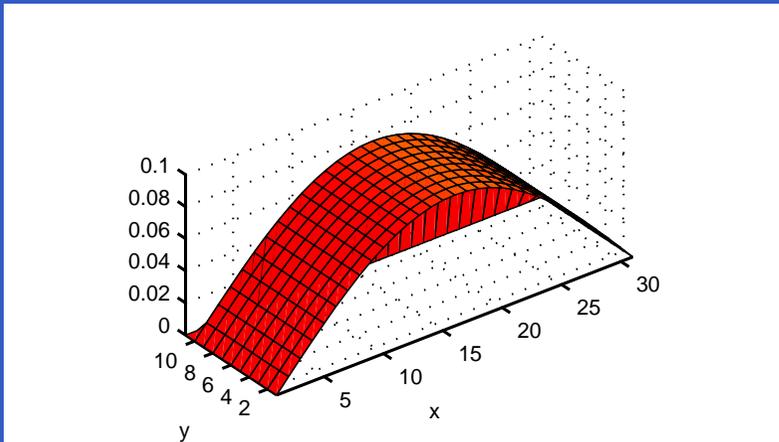
$E_y$  for  $TE_{10}^z$



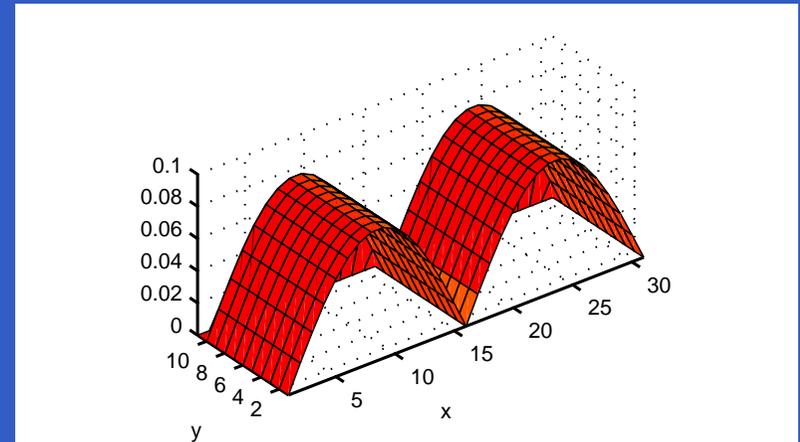
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$E_y$  for  $TE_{10}^z$



$E_y$  for  $TE_{20}^z$

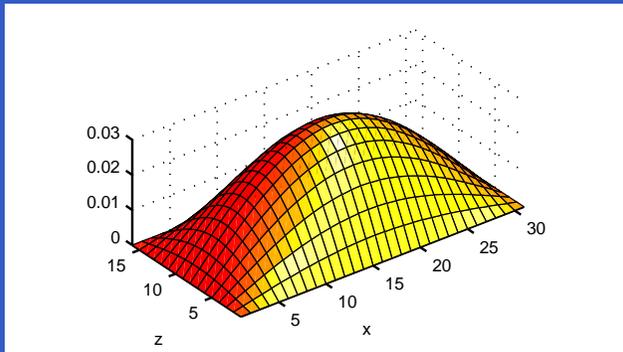
✓  $\|\mathbf{e}_{\text{num}}\| = 1, \quad \|\mathbf{e}_{\text{th}} - \mathbf{e}_{\text{num}}\| \approx 10^{-14}$

# Cavity modes

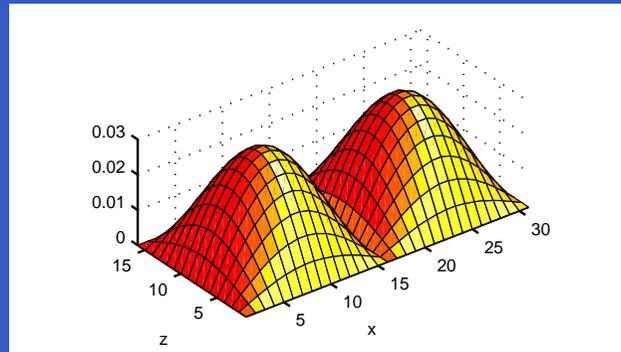
- ▼ Dimensions:  $a/b = 3$ ,  $a/c = 2$
- ▼ Non-degenerate modes:  $TE_{101}^z$  (1 GHz),  $TE_{201}^z$ ,  $TM_{110}^z$
- ▼ Cells:  $N_x = 31$ ,  $N_y = 11$ ,  $N_z = 16$

# Cavity modes

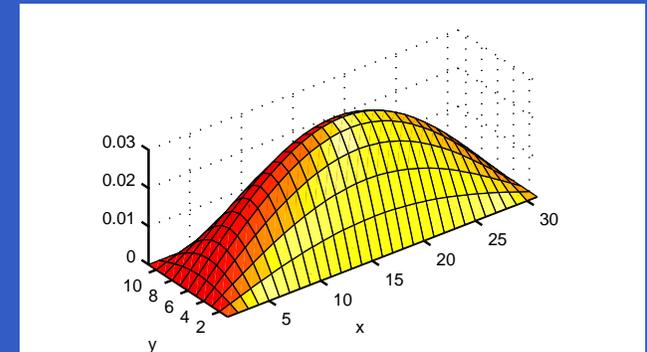
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$E_y$  for  $TE_{101}^z$



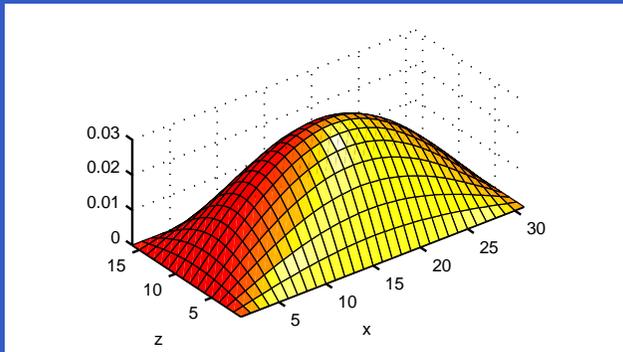
$E_y$  for  $TE_{201}^z$



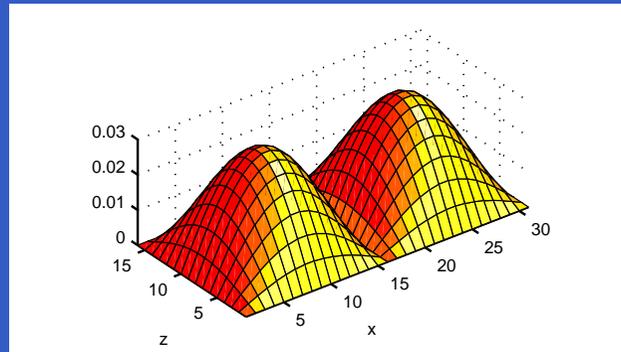
$E_z$  for  $TM_{110}^z$

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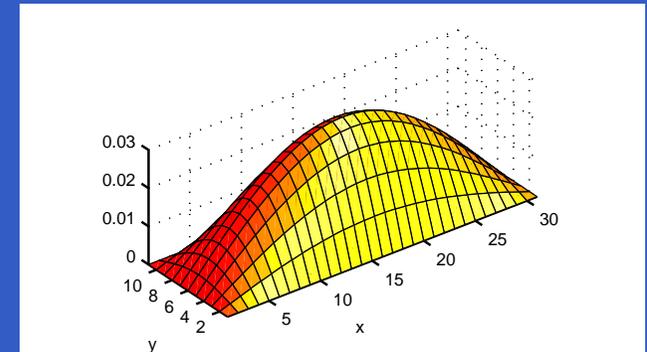
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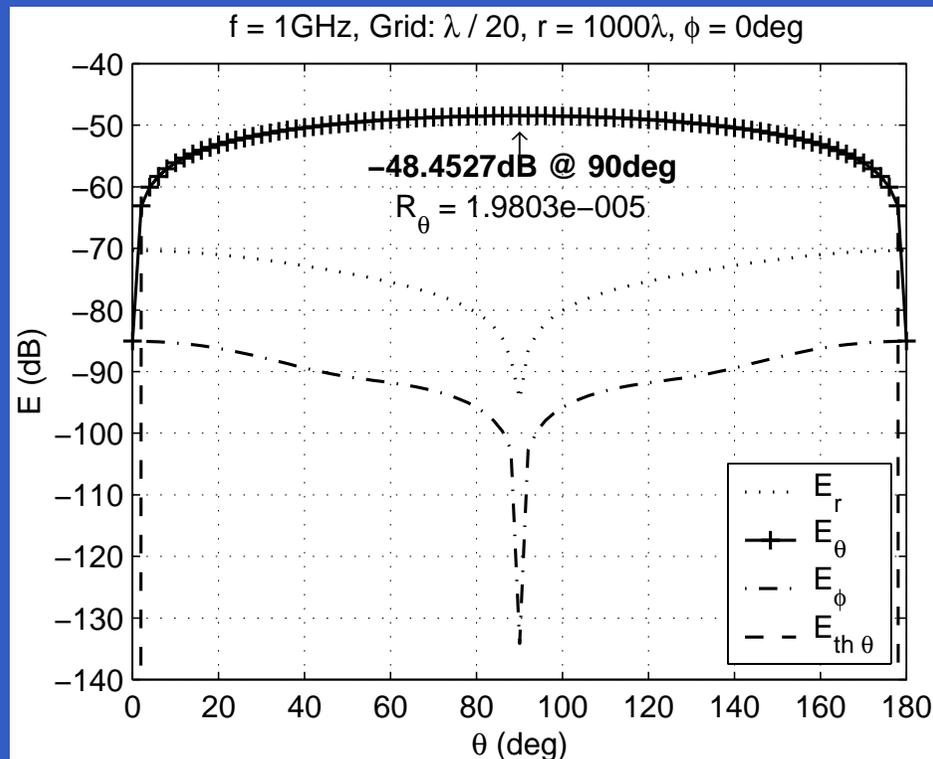
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# Elementary dipole radiation

- ▼ Electric current  $\mathbf{J}(z) = \hat{z}$  at a single cell (1 GHz)
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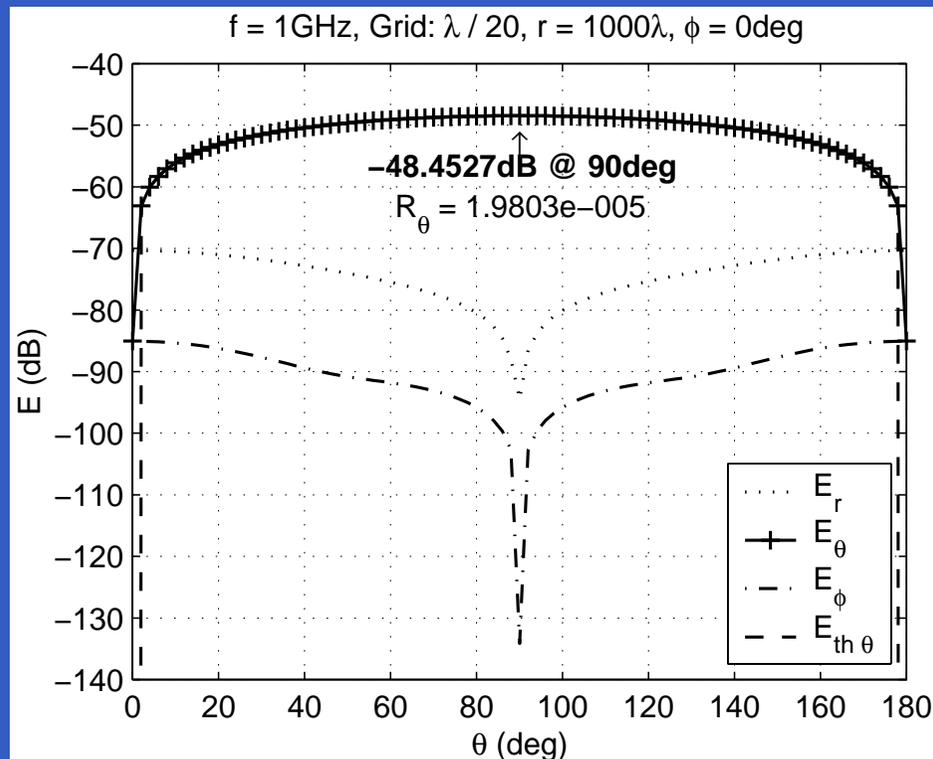
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✓ Fit theory to data  $\longrightarrow$  dipole length  $\lambda/44000$

# Conclusion and future work

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# Two-dimensional numerical modeling

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- ▼ Input information → optimum quantity:  
variety↑      redundancy↓

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# Study of the three-dimensional extension

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- ▼ FDFD GREC (General-purpose Rectangular-mesh Electromagnetic Code) 20k MATLAB lines

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# Perspectives

Future work

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# Perspectives

## ▼ Two-dimensional imaging

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  - ▶ Invert from real data (measurement  $\xrightarrow{?}$  field)

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  - ▶ Proceed to the inverse problem

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- ▼ Two-dimensional imaging
  - ▶ Invert from real data (measurement  $\xrightarrow{?}$  field)
  - ▶ Quantify the notion of information
- ▼ Three-dimensional imaging
  - ▶ Proceed to the inverse problem
  - Harder and easier to solve (a Zen statement)

# Perspectives

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  - ▶ Quantify the notion of information
- ▼ Three-dimensional imaging
  - ▶ Proceed to the inverse problem
  - Harder and easier to solve (a Zen statement)
  - ▶ Combine with different approaches

# Perspectives

- ▼ Two-dimensional imaging
  - ▶ Invert from real data (measurement  $\xrightarrow{?}$  field)
  - ▶ Quantify the notion of information
- ▼ Three-dimensional imaging
  - ▶ Proceed to the inverse problem
    - Harder and easier to solve (a Zen statement)
  - ▶ Combine with different approaches
- ▼ Use FDFD GREC independently



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- ▼ 1 in book
  - ▼ 7 in proceedings

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- ▼ 1 in book
  - ▼ 7 in proceedings
  - ▼ 2 citations in IEEE Transactions

