







From movement to interaction and gesture: studies, techniques, tools and input devices

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"We are ocular centric, and displays are therefore much more mature. Input is still primitive, and wide open for improvement." **Bill Buxton, 2007**





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Kinect (Microsoft, 2010)



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Thomas Pietrzak Ludovic Potier Philip Quinn Nicolas Roussel Jean-Baptiste Sauvan Betty Semail Romuald Vanbelleghem Radu Vatavu Daniel Vogel Quan Xu



Indirect interaction, filtering and transfer functions



Touch and gesture based interaction













Indirect interaction, filtering and transfer functions

















Casiez, G., Vogel, D., Balakrishnan, R., & Cockburn, A. (2008). The Impact of Control-Display Gain on User Performance in Pointing Tasks. Human-Computer Interaction. Taylor and Francis, volume 23, issue 3, 215-250.





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http://libpointing.org











Géry Casiez and Nicolas Roussel. 2011. No more bricolage! Methods and tools to characterize, replicate and compare pointing transfer functions. In UIST '11, 603-614. ACM.





Elastic transfer functions



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Casiez, G., & Vogel, D. (2008). The Effect of Spring Stiffness and Control Gain with an Elastic Rate Control Pointing Device. In CHI'08, 1709-1718. ACM Press.

RubberEdge











Casiez, G., Vogel, D., Pan, Q., & Chaillou, C. (2007). RubberEdge: Reducing Clutching by Combining Position and Rate Control with Elastic Feedback. In UIST'07, 129-138. ACM Press.



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Scrolling transfer functions





Importance of transfer functions in interactive systems

Constant vs. dynamic functions

Hardware independent functions

Isotonic / elastic devices - hybrid devices

Pointing / manipulation / scrolling tasks

Recommendations, tools and libraries

Perspectives

"Transfer function law"

Domain of definition of Fitts' law $T = a + b \log_2 \left(\frac{D}{W} + 1\right)$

Better understand human motor capabilities

Hardware independent functions

Situated transfer functions

Consider other parameters

Touch and gesture based interaction





















Vogel, D., Cudmore, M., Casiez, G., Balakrishnan, R. & Keliher, L. (2009). Hand Occlusion with Tablet-sized Direct Pen Input. In CHI'09, 557-566. ACM Press.









Amberg, M., Giraud, F., Semail, B., Olivo, P., Casiez, G. & Roussel, N. (2011). STIMTAC, a tactile input device with programmable friction. In UIST'11 EA, 7-8. ACM Press.

Giraud, F., Amberg, M., Lemaire-Semail, B. & Casiez, G. (2012). Design of a Transparent Tactile Stimulator. In proceedings of Haptics Symposium 2012. 485-489. IEEE Computer Society.



Surfpad



Targets separated by 100 mm

12 participants

x 3 Techniques (Control, Semantic Pointing Ω & Surfpad II)

x 4 Blocks

- x 2 Widths (16 et 4 pixels)
- x 6 Density (0, 1, 2, 4, 8 & 12 distractors)
- x 3 = 5,184 trials

Main results

- Surfpad continues to improve movement time by 9,5% compared to Control, whatever the number of distractors
- Semantic Pointing degrades performance up to 100%, due to clutching





Géry Casiez, Nicolas Roussel, Romuald Vanbelleghem, and Frédéric Giraud. 2011. Surfpad: riding towards targets on a squeeze film effect. In CHI '11, 2491-2500.











3D Manipulation





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Martinet, A., Casiez, G. & Grisoni, L. (2012). Integrality and Separability of Multi-touch Interaction Techniques in 3D Manipulation Tasks. IEEE Transactions on Visualization and Computer Graphics. IEEE Computer Society, volume 18, issue 3, 369-380.



Vatavu, R.D., Vogel, D., Casiez, G. & Grisoni, L. (2011). Estimating the Perceived Difficulty of Pen Gestures. In INTERACT'11, 89-106. Springer.

Buttonless clicking

Time (ms)

60 (s/





Choumane, A., Casiez, G. & Grisoni, L. (2010). Buttonless Clicking: Intuitive Select and Pick-release Through Gesture Analysis. In IEEE VR, 67-70. IEEE Computer Society.

Mockup Builder

Figure 4: Calibrating 2D Touches: Kinect image camera with the four the user with the resulting screen plane on the right

5.2 Calibrating Gametrak Input Data

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ametrak input data is defined in a framework centered on the de vice base, requiring the computation of a transformation matrix into our primary coordinate system for each tracked finger. This is don using a set of one thousand matching 3D position pairs to comput the correspondence rigid transformation. The set is created by sam pling the multi-touch surface screen and gathering the touch post ions converted to our primary coordinate system using the matr defined on the previous section. The rigid ActiverSimutsern outed using a RANSAC algorithm [10], creating a matrix mapping Sametrak positions to our global coordinate system

Fusing Inputs into a Single User Model

Kinect belong to the same finger are fused ther as an ure. An input gesture might represent a stroke or gesture ove the surface. Data coming from the multi-touch surfac the Gametraks has a unique identifier defined by the input device fter the coordinates have been converted into the same coordinate e fusing consists in determining n the identifiers from JR Sterespond to the san It also consists in Emitteress nformation to each finger. A new input a finger touches the multi-touch surfa hch gesture, or when the finger performs nch and that finger was not touching the surface befor tures are deleted when fingers are lifted from the surface with binching or when the pinch button is released above rwise the input gesture is updated. Multi-touch and Gam of fused together based on close proximity multi-touch surface, we discard Game available as they were found to be Wultitesolen Table with 3D Projector

BIMANUAL INTERACTION ON THE SURFACE

The multi-touch surface is primarily used as a sketching canvas



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where the user interacts using fingers. As previously explained, we followed the Guiard bimanual asymmetric model allowing the A Jorge, J. A. (2012). Mockup Builder: Direct 3D Modeling On and Above the Surface in a Continuous Interaction Space. In GI'12, 173-180.



Summary

Occlusion

Rendering tactile feedback on touch interfaces

New input device to support multimodal input

Degrees of freedom integration and separation

Gesture interaction

Perspectives

Friction based interfaces: increased knowledge and new prototypes

Indirect interaction on touch interfaces

Additional degrees of freedom on touch interfaces

General perspectives



