



Design of GaN-based microwave components and application to novel high power reconfigurable antennas

Abdelaziz Hamdoun

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components and application to
novel high power reconfigurable
antennas.**

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List of Acronyms

GaN	Gallium Nitride
AlGaN	aluminum gallium nitride
GaAs	Gallium Arsenide
SiC	silicon carbide
Si	silicon
InP	indium phosphide
SoP	System-on-Package
FET	Field-effect transistor
HEMT	High Electron Mobility Transistors
2DEG	two-dimensional electron gas
HBT	Heterojunction bipolar transistor
HEMT	High electron mobility transistor
HVPE	Hydride vapour phase epitaxy
LNA	Low-noise amplifier
PA	Power Amplifier
MBE	Molecular beam epitaxy
MEMS	Micro-electromechanical systems
MIM	Metal-insulator-metal
MMIC	Monolithic microwave integrated circuit
MOCVD	Metal-organic chemical vapour deposition
NRC	National Research Council Canada
PCB	Printed circuit board
RF	Radiofrequency
SPDT	Single-pole-double-throw
SPST	Single-pole-single-throw
AIA	Active Integrated Antennas

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O Allah, benefit me by that which You have taught me, and teach me that which will benefit me, and increase me in knowledge.

اللَّهُمَّ أَنْفَعْنِي بِمَا عَلَّمْتَنِي وَعَلِّمْنِي مَا
يَنْفَعُنِي وَزِدْنِي عِلْمًا

Abstract

This thesis demonstrates the feasibility of using gallium nitride (GaN) technology in reconfigurable RF systems. GaN-based varactor diodes and switch circuits are pursued as promising candidates for high-power/high-frequency applications. The first part is devoted to active GaN device development. Active components were realized using the Canadian National Research Council (NRC) GaN HEMTs process. Based on three process, such as, GaN150v0 (gate length of 0.15 μ m), GaN500v1 and GaN500v2 (both with gate length of 0.5 μ m), many varactor diodes with size different have been manufactured and characterized via DC and RF small-signal and large-signal measurements. Then, the varactor diodes were modeled by analytic equations containing empirical coefficients. These expressions have been introduced for the first time for the voltage dependency of equivalent capacitance (C_{Eq}) and series resistance (R_{Eq}) and can be used as a general model to represent the nonlinear behavior of GaN based varactors. For small-signal operation, all of the developed equations describing R_{Eq} and C_{Eq} are only bias voltage and device geometry dependent, while for large-signal operation, the influence of RF-power must be taken into account. In addition, different size single stand-alone switches were fabricated using GaN500v2. By analyzing the small-signal measurements, it was observed that the isolation is high at low frequencies but quickly drops with increasing frequency. Also, it was observed that the larger the device the lower the insertion loss and the poorer the isolation will be. Moreover, based on these small-signal measurements, a model was introduced.

The second part addresses the integration and design aspects of the reconfigurable proposed circuits, such as tunable phase shifter, reconfigurable 3-dB 90° hybrid coupler, tunable frequency oscillator, beam switching antenna array and matching reconfigurable patch antenna operating below 10 GHz. Here the developed GaN varactors and switches are used for achieving the tenability purpose.

Résumé en français

Cette thèse a pour objectif de démontrer la faisabilité de l'utilisation de la technologie Nitrure de Gallium (GaN) dans les systèmes RF / micro-ondes reconfigurables. La technologie GaN doit permettre de supporter des puissances élevées avec un rendement important. Le GaN qui présente une large bande interdite possède des propriétés physiques lui permettant d'être largement utilisé pour la conception de circuits actifs à forte puissance. En effet, ses qualités intrinsèques, champs de claquage élevé, forte conductivité thermique, forte densité d'électrons, et bonne vitesse de saturation, lui confèrent de très bonnes performances aux hautes fréquences que ce soit pour les applications de puissance ou faible bruit. La technologie GaN est donc un candidat très prometteur pour la réalisation de fonctions hyperfréquence haute puissance/haute fréquence, telles que les amplificateurs de puissance, les mélangeurs, les oscillateurs contrôlés en tension (VCO) ou encore les amplificateurs faible bruit (LNA).

Cependant, malgré les caractéristiques intéressantes des dispositifs GaN, il reste encore des défis de fabrication à relever avant que cette technologie ne soit largement adoptée à l'avenir. Ces défis sont liés à deux aspects, le premier technologique et le second commercial. Technologiquement, les dispositifs HEMTs basés sur le GaN sont affectés par deux phénomènes importants, à savoir l'effet de piégeage et l'effet thermique (ou auto-échauffement des dispositifs) qui peuvent directement causer la dispersion du courant. Commercialement, un inconvénient de la technologie GaN concerne le coût de fabrication des composants. La réduction du coût de production est un facteur important pour pouvoir largement commercialiser les dispositifs GaN. De plus, le peu de disponibilité de matière GaN conduit à épitaxier le GaN sur des substrats tels que Silicium (Si), Carbure de Silicium (SiC) et le Saphir, ce qui peut dégrader les caractéristiques des composants GaN. Ces aspects sont abordés dans le chapitre II de ce manuscrit.

Les travaux de thèse s'inscrivent dans une stratégie de développement des dispositifs GaN nécessaires à la conception de circuits RF reconfigurables. Les travaux sont divisés en deux parties principales. La première partie de ce travail de thèse est consacrée au développement et à la caractérisation des circuits actifs réalisés à base de la technologie GaN. Pour cela une investigation approfondie autour de diodes Varicap et de commutateurs a été menée et présentée. Les composants actifs ont été réalisés en utilisant le processus de fabrication GaN HEMTs offert par le Conseil National de Recherches du Canada (CNRC). Pour ce faire, trois processus GaN HEMT : le GaN150v0 avec une longueur de grille de 0,15 μm , le GaN500v1 avec longueur de grille de 0,5 μm et le GaN500v2, ont été investigués pour fabriquer des diodes varicap avec des tailles différentes. Ces diodes ont ensuite été caractérisées en DC, en petits et grands signaux RF jusqu'à 20 GHz. Ici, les diodes varicap sont réalisées simplement en reliant le drain à la source, conduisant à réaliser une jonction Schottky qui peut être considérée comme « Planar Schottky Varactor Diode (PSVD) ». La tension V_G de polarisation est alors appliquée entre le drain/source et la grille. En outre, ce type de diode ne nécessite aucun changement particulier des couches épitaxiales du procédé de fabrication HEMTs. Ensuite, les diodes varicap ont été modélisées en petit et grand signal par des équations analytiques. Ces expressions ont été introduites pour décrire la variation de la capacité équivalente (C_{Eq}) et la résistance série (R_{Eq}) en fonction la tension DC appliquée sur le composant. Ces équations peuvent être utilisées comme un modèle général pour représenter le comportement non-linéaire des diodes varicap basées sur la technologie GaN. Pour le modèle petit signal, les équations analytiques développées ne sont dépendantes que de la tension de polarisation appliquée sur le dispositif et de la géométrie de la diode, tandis que pour le modèle grand signal, l'influence de la puissance RF a aussi été prise en compte pour décrire le comportement de R_{Eq} et C_{Eq} . Pour étendre l'étude autour des composants GaN actifs utilisés dans les systèmes RF reconfigurables, plusieurs commutateurs avec différentes tailles configurés en grille commune ainsi que des structures de commutateurs tels que le SPST (Single Pole Single Throw) et

le SPDT (Single Pole Double Throw) ont été fabriqués, en utilisant le processus de fabrication GaN500v2. En analysant les mesures en petit signal des commutateurs simples, on a pu observer que l'isolement est bon aux basses fréquences, mais se dégrade rapidement avec l'augmentation de celle-ci. En outre, on a pu conclure que plus le dispositif est grand, plus les pertes d'insertion s'améliorent, alors que l'isolation se dégrade. Donc un compromis entre perte d'insertion et isolation a été fait pour choisir les transistors individuels qui ont par la suite été utilisés pour la conception des structures de commutateurs plus complexes (SPST et SPDT). De plus, en se basant sur ces mesures petit signal, un modèle circuit a été introduit.

La deuxième partie de ces recherches de thèse aborde les aspects de l'intégration de ces dispositifs actifs GaN (diodes varactor et commutateurs) et de la conception de circuits reconfigurables proposés, tels qu'un déphaseur reconfigurable, un coupleur (3dB, 90°) reconfigurable, un oscillateur accordable en fréquence, ainsi qu'un réseau d'antennes à commutation de faisceau et une antenne unitaire accordable en fréquence. Initialement, un nouveau RUN technologique devait nous permettre de concevoir de nouveaux designs complètement intégrés en technologie GaN notamment le déphaseur et le coupleur (3dB, 90°) reconfigurable en fréquence mais malheureusement ce RUN technologique n'ayant pas été assuré, il a donc été décidé d'utiliser les diodes varactors et les commutateurs préalablement fabriqués et testés sous pointe. Ceci a engendré des soucis puisque ces puces étaient de très petites dimensions et donc difficilement découpables puis intégrables dans les circuits imprimés tels que l'oscillateur ou les antennes. Toutefois, dans un souci de mener jusqu'au bout cette étude et de réaliser les circuits et antennes reconfigurables, de gros efforts ont été consentis afin de récupérer des diodes et commutateurs sur les wafers de base. Il a donc pu être possible de réaliser l'oscillateur et les deux types d'antennes reconfigurables. Si l'oscillateur contrôlé en tension et reconfigurable grâce à une diode Varicap préalablement fabriquée et caractérisée n'a pu aboutir à des résultats expérimentaux concluants, les prototypes d'antenne élémentaire reconfigurable en fréquence ou en diagramme à l'aide d'un réseau d'antennes

commutable ont permis de démontrer la faisabilité de tels concepts en utilisant des composants actifs en technologie GaN.

Chapter I

Introduction

I. Research Motivations

Nowadays, people are living in a society in which processing, flow and exchange of information are vital for their existence. Connectivity and mobility are two major issues in such society, which are related to the flow and exchange of information. On one hand, portable devices with internet provide connectivity which allows communication as well as access to information. On the other hand, wireless technologies bring mobility. People can move and still be able to communicate while having access to various kinds of information. This is the reason why radio frequency (RF)/microwave systems have evolved to integrated formats. This approach is called system-on-package (SoP), where many technologies are mixed in one package allowing increased simultaneous functionalities. Furthermore, the recent trend in RF/microwave technology is toward circuits that are highly miniaturized integrated

and reliable, with low power consumption, and reduced cost. Monolithic Microwave Integrated Circuits (MMICs), based on semiconductor technology, are one of the keys to meeting the requirements of this technology mixing. Additionally, most MMICs currently in production, such as gallium arsenide (GaAs), silicon carbide (SiC), silicon (Si), indium phosphide (InP), etc, operate in the microwave and millimeter-wave (mm-w) range with modest breakdown voltages and limited power handling capabilities. But there are increasing applications in the RF/microwave spectrum where higher power/frequency is required.

Over the past decade, several changes have drawn more attention to RF/microwaves power devices. Increasing demands of high power handling capabilities and worries about capabilities of functioning in harsh environments have created a need for alternatives to traditional semiconductors technology. Due to its high critical breakdown field associated with wide band gap energy as well as its high saturated electron velocity, gallium nitride (GaN) is a potential solution to satisfy these simultaneous requirements for RF, microwave and mm-w transmitters for communications and RADAR [1]. On one hand, GaN-based high electron mobility transistors (HEMTs) power devices are considered as an excellent candidate for future power devices due to its high breakdown voltage and high saturation drain current [1]. On the other hand, besides being used for high power purposes, GaN HFETs devices are also a strong candidate to be used in harsh environment receiver applications due to the robust nature and good low noise performance of these devices [2], where others semiconductors can suffer.

With the advent of this wide band gap material, enormous progress has been made until now especially in the development of GaN technology. Consequently, more and more industries and academic research labs in the field of semiconductors have introduced different GaN HEMTs processes (i.e United Monolithic Semiconductors (UMS), TriQuint, Cree, NRC (National Research Council Canada), etc). These devices are intended to fulfill the growing demands for high power at high

frequency electronic components as well as for high voltage power switches operating at higher frequencies. Furthermore, GaN HEMTs based MMIC technology is now challenging the other traditional semiconductor technologies such as GaAs mostly by offering the highest level of integration and the smallest form factor while keeping to operate with high voltage and to handle high power levels.

However, some challenges remain with GaN technology. The most serious problem is the cost of a GaN substrate in which the power devices are fabricated and the pace of maturation of their technological processes. Another issue is the lack of bulk GaN source material which leading to the need for GaN growth by using mismatched substrates such as Si, SiC and sapphire.

The recent trend in RF/microwaves technology is toward circuits that are highly reconfigurable compacted and reliable with more functionalities, with low power consumption, and reduced cost. In particular, the downsizing demands in RF/microwaves wireless communication systems are growing exponentially as the number of multi-band and multi-service systems has increased along with the need for high power handling capabilities at higher frequency. The tunable and reconfigurability aspect of modern RF/microwaves front-ends transceivers (Tx/Rx) is also an interesting subject concerning GaN HEMTs technology. Research into the usage of GaN based high power RF switches and varactors provide further opportunities for GaN to achieve these demands.

GaN technology is emerging as a major promising candidate for reconfigurable high power circuits for RF front-end Tx/Rx. Moreover, there is a wide consensus that the antenna system should be integrated in the same package with the front-end integrated circuit [3]. As an example, mobile communications (including SATCOM) imply that reconfigurable radiation pattern antennas are now of interest for such applications to steer the antenna beam. So antenna array system with a controlled gain and phase between single elements are often considered. In particular, for mobile applications, the antenna array must exhibit the capability to

align its beam in the direction of the strongest signal. Hence, an antenna array with beam-steering capability is imperative and could be integrated on the same package with its two crucial components, phase shifter and gain amplifier to produce the desired amplitude and phase.

Fulfilling the in-depth development of GaN HEMTs technology for tunable high power circuits, it has become the motivation of this research to investigate novel highly compact reconfigurable active microwave circuits operating up to X-band frequency by using developed GaN varactor and switch models.

The main aim of this thesis research is to investigate and characterize GaN-based varactor diodes and switches that will be integrated to realize reconfigurable RF/microwave circuits operating up to X-band frequency. This band of frequency from 8 GHz to 12 GHz is primarily used for military communications and Wideband Global SATCOM systems. It is mostly used in radar applications including continuous-wave, pulsed, single-polarization, dual-polarization, synthetic aperture radar and phased arrays. X-band radar frequency sub-bands are used in civil, military and government institutions for weather monitoring, air traffic control, maritime vessel traffic control, defense tracking and vehicle speed detection for law enforcement. This band is less susceptible to rain fade than the Ku Band due to the lower frequency range, resulting in a higher performance level under adverse weather conditions.

This thesis research has been conducted as a collaboration between University of Rennes 1 through “l’Institut d’Electronique et de Télécommunications de Rennes (IETR)”, and Carleton University through the “Department of Electronics (DOE)”. This collaboration is created from the PhD cotutelle (joint) program offered by both institutions. DOE has the expertise in CAD for electronic circuit design, RF and microwave circuits, photonics and integrated circuit using semiconductor technologies including GaN technology. A group of researchers from Carleton University is deeply involved in developing of circuits based on GaN technology.

These researchers have a good relationship with the National Research Council (NRC) which provides GaN HEMTs foundry facilities, via CMC, and are involved with NRC's GaN team to develop this novel semiconductor technology. As a result, students as well as researchers from Carleton University can get access to this foundry. On the other hand, IETR is one of the largest and most research intensive labs in the design and characterization of active antennas up to millimeter-wave bands. Moreover, IETR provides facilities allowing the design of antennas, such as, EM simulators (i.e. CST, HFSS, etc.), unique measurement facilities in France including network analyzers up to 110 GHz for S-parameter measurements, and an anechoic chamber working up to 110 GHz for measuring radiation patterns of antennas.

II. Objective of Research

The proposed overall objective of this research is to study reconfigurable integrated microwave circuits using developed GaN varactor and switch models for use, for example, in X-band systems. It is expected that this project will demonstrate a new concept of realizing reconfigurable large-signal microwave circuits based on GaN technology, which will be used for the first time as active varactors and switches co-integrated in low cost microstrip technology to achieve the tunability of circuits.

The proposed specific objectives are:

1. Explore possibilities of emerging GaN technology for integrated circuits that are miniaturized such as phase shifter and frequency reconfigurable hybrid couplers where the control functionality is achieved by using varactor diodes.
2. Investigate possibilities for RF reconfigurable circuits using active GaN components with a low-cost substrate. For this a reconfigurable oscillator, a beam switching antenna array and a matching reconfigurable patch antenna operating below 10 GHz were designed.

3. Demonstrate a working prototype that combines active GaN devices and passive components so as to experimentally validate the proposed concepts.

It will be shown that the developed GaN varactor and switch models can be used along with passive circuit designs in low cost microstrip technology so as to achieve, in the same circuit, reconfigurability and good RF performance. Additionally, this research project will demonstrate the great potential of GaN for use in other tunable microwave high power applications such as oscillators and reconfigurable antennas.

III. Thesis Organisation

The thesis begins with the chapter II dealing with a review of gallium nitride technology. Then, chapter III presents the characterization and modeling of gallium nitride varactor and switch devices manufactured with NRC process. The final chapter IV covers contributions and realized applications over this thesis research.

Chapter II

A Review of the Literature of Gallium Nitride Technology

I. Gallium Nitride Technology

1. Overview

Since gallium nitride (GaN) is used as a semiconductor technology to design the circuits for this thesis, it is necessary to review the characteristics of this technology and make a brief comparison with commonly used semiconductor technologies. GaN technology has been and still getting more and more attention for RF/microwave systems that require high power handling capabilities and low noise figure. This sets the field of GaN electronics in motion, and today the technology is improving the performance of several applications including, mobile communication,

wireless base stations, communication and military radar systems, where its focus is shifting to further advantages such as high efficiency as well as the reduction of worldwide energy consumption [4].

Historically, development of semiconductor technologies based on Monolithic Microwave Integrated Circuit (MMIC) has always advanced to more and more performance improvements in terms of more high power handling capabilities, more gain, high efficiency, high linearity, decreasing noise figure [2]-[5]. In the early 1990s, GaN was revealed as a potential solution to satisfy the simultaneous requirements of high frequency and power [1]. GaN material has the capability of satisfying system device requirements from low-frequencies [7]-[8] through millimeter-waves [9]-[10]-[11]-[12] and was deemed an excellent material for being useful in high power applications. Because of its special properties, GaN technology is truly recognized as a revolutionary wide band gap technology resulting in dramatic afforded power levels that exceed many times (> 5 times) those levels achieved with other traditional technologies such as, indium phosphide (InP), gallium arsenide (GaAs), and silicon (Si). As a result, current densities in excess of 2 A/mm have been reported [13]-[14]. High power densities of 40 W/mm have also been reported at 4 GHz with 1.2 A/mm by Cree using field-plated devices [15]. Watt-level output power has been demonstrated and reported at W-band in [9]-[10]-[11] by HRL, Raytheon and Fujitsu. In [12] Cree has demonstrated power density higher than 25 W/mm of gate periphery with unity current gain frequencies, f_t , greater than 40 GHz reported. As a brief comparison, Figure II.1 recapitulates the most used semiconductor technologies and their limits in terms of power handling capability and operating frequency.

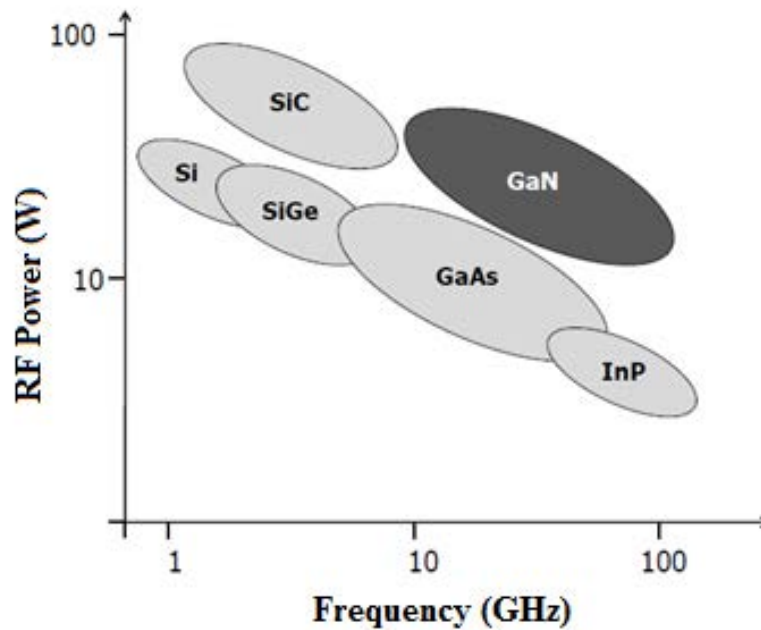


Figure II.1: Most used Semiconductor Technologies and their Frequency/Power limits [6]

GaN offers very high breakdown field, high electron mobility, and saturation velocity. It is also known that GaN has an excellent thermal conductivity and ability to operate at high temperatures which make it an ideal candidate for high-power and high-temperature microwave applications [1]. Moreover, GaN is a great candidate to enable the development of next generation of wireless and satellite communication systems that are needed to meet emerging demands for high data throughput, energy efficient wireless systems, reduced carbon footprints of wireless networks, high power electronic solutions for smart and efficient applications, and interoperability among diverse communication standards. Today, gallium nitride high electron mobility transistors (HEMTs) or heterojunction FETs (HFETs) are the most advanced electronic nitride devices. The hetero-structures offer many advantages such as high breakdown and transport properties of un-doped GaN.

As shown in Table II.1, a comparison between the electrical/physical properties of the commonly used semiconductor technologies is illustrated. GaN has high sheet carrier density and channel charge density, which produce high output power. Also it has high electron mobility, which is largely responsible for low on-resistance, and therefore, high power added efficiency could be achieved at higher frequencies. As a result, GaN HEMTs devices can achieve much higher breakdown voltage than the other technologies, very high current density, and sustain very high channel operation temperature. For comparison purposes, TriQuint's 0.25 μ m GaAs process has a typical breakdown voltage of 15V [16] while TriQuint's 0.25 μ m GaN process has a typical breakdown voltage of 100V [17]. Additionally, the combination of significant electron mobility and a good saturation velocity enable high speed operation of active devices. As a matter of fact, GaN circuits demonstrate their capabilities of operating adequately at high frequencies.

All of these presented factors indirectly improve the efficiency of GaN devices. Furthermore, possible epitaxial growth on SiC substrate, which has excellent thermal properties, makes this device optimal to operate at high power. Later in this chapter, the possibility of growing GaN over other substrates will be more detailed.

Table II.1: Comparison between properties of the most commonly used semiconductor technologies [1]

Semiconductor (Typical Materials)		Si	GaAs	InP	SiC	GaN
Characteristic	Unit					
Bandgap	eV	1.1	1.42	1.35	3.25	3.49
Electronic Mobility at 300 °K	cm ² /V.s	1500	8500	5400	700	1000-2000
Saturated Electronic Velocity	x10 ⁷ cm/s	1	1.3	1	2	2.5
Critical Breakdown Field	MV/cm	0.3	0.4	0.5	3	3.3
Thermal Conductivity	w/cm.k	1.5	0.5	0.7	4.5	>1.5
Charge channel Density	x10 ¹³ /cm ²	0.3	0.2			1
Resistivity	Ω .cm	1.5	1x10⁷		1x10⁵	
Relative Dielectric Constant	ϵ_r	11.5	12.8	12.5	10	9
Loss tangent (at 10 GHz)	Tg	0.015	0.0004		0.003	

However, despite the superior characteristics of GaN device, there still remain some issues at multiple levels with respect to fabrication (process, device, circuit and system) that must be overcome before being widely adopted in future. These challenges that are impacting the development of GaN technology can be summarized in two main challenges such as technological (device processing) and commercial tasks.

The first technological (device processing) challenge is that the GaN HEMTs are affected by two important phenomena, namely the trapping effect and thermal effect (or self-heating), which can directly cause current dispersion such as collapse and rolling off as shown in Figure II.2. This existence, of dispersion effects observed in GaN devices, acts to restrict the drain current and voltage excursions, thereby limiting the initial expectations of device's performances in term of high power and high frequency.

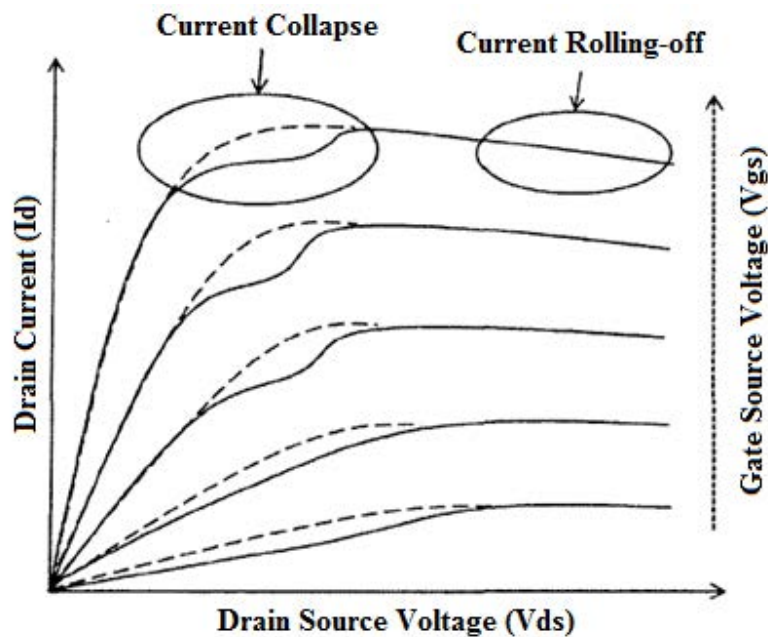


Figure II.2: Current due to trapping effect and thermal effect [18]

Current collapse is explained as a transient and recoverable reduction in drain current response caused by trapping effects. In general, this phenomena means that some electrons are captured by traps somewhere in AlGa_N/Ga_N HEMTs hetero-structures [18] as shown in Figure II.3. These captured electrons reduce the sheet electron density in the channel, leading to increase dynamic R_{on} leading to drain current dispersion [19]. In principle, electron trapping can occur at different locations such as metal/AlGa_N interface, the un-gated AlGa_N surface near the gate edge, AlGa_N/Ga_N interface, and the buffer Ga_N layer during HEMT operation.

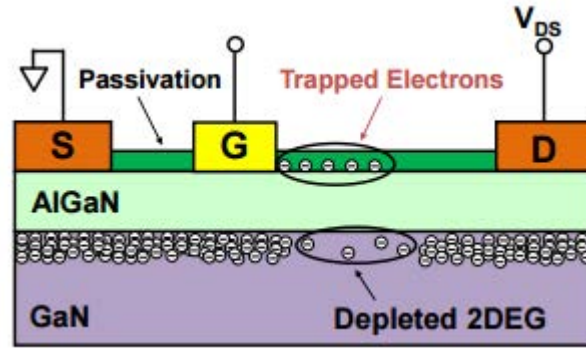


Figure II.3: A sketch of an AlGa_N/ Ga_N HEMT structure with trapped electrons [19]

Most reported works, explaining this effect, conclude that trapping effect can mainly reside at the surface [20]-[21], in the AlGa_N barrier layer, at the two-dimensional electron gas (2DEG) interface, and in the Ga_N buffer layer [22]-[23]. This effect is produced when a large bias voltage is applied between the source and drain, which induces a quick acceleration of the electrons in the conducting channel. These fast random moving electrons can be injected into an adjacent region of the device structure and became trapped if this region contains a significant concentration of traps which is the case for the Ga_N buffer layer.

On the other hand, thermal and self-heating effects exist in every power semiconductor device. Especially when the device is working in the high voltage and high power region, the self-heating causes electron carriers to accelerate in random directions instead of following the drain to source channel. Some of the electrons eject

themselves out of the channel, causing significant roll off in the high voltage and high current region, which is observed in DC current variations, as shown in Figure II.2.

The simplified vertical semiconductor structure of a GaN/AlGaN HEMTs is illustrated Figure II.4.

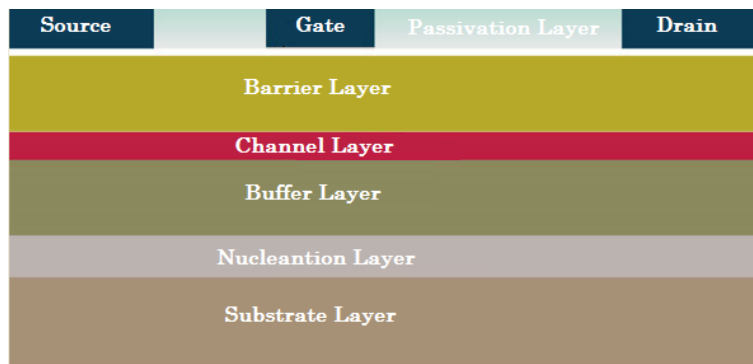


Figure II.4: Cross-Section of HEMTs (Not Drawn to Scale)

- **Barrier:** This semiconductor layer isolates the gate and the channel so that very low current flows between the channel and the gate. In GaN FETs, the barrier is typically made of aluminum gallium nitride (AlGaN).
- **Channel:** The channel or 2-DEG is the region where electrons flow from the source to the drain. The channel is typically made of high-quality GaN.
- **Buffer:** The role of the buffer is to restrict the movement of the electrons within the channel. In other words, the buffer acts as a barrier that prevents the electrons from wandering into the substrate. In a GaN FET, the buffer is typically made of GaN doped with carbon (C) or iron (Fe).
- **Nucleation:** The growth of GaN structures on a foreign substrate requires the careful matching of the GaN lattice to this substrate, involving the engineering of suitable nucleation layers between the substrate and the buffer layer.
- **Substrate:** The substrate provides mechanical support, heat spreading, and electromagnetic confinement. GaN FETs use a foreign substrate (that is, Sapphire, Si or (SiC), but not GaN). Because the substrate is not GaN, it has a different crystal lattice than the buffer. This creates dislocations in the

material and ultimately reduces the electrical isolation between gate and channel.

Even though there have been remarkable improvements in growth and device fabrication using GaN material, trapping effects is still a challenge and cannot be eliminated perfectly, which still an active key research topic in AlGaIn/GaN HEMT applications. Additionally, an accurate HEMT model including trapping effects is still needed for development of implementation of AlGaIn/GaN HEMT-based circuits.

The second aspect of GaN HEMTs that is a significant disadvantage is the cost of fabrication. Reducing the production cost is an important factor for power GaN HEMTs commercialization. This big commercial challenge is due to a general lack of availability. There are more and more companies over the world develop GaN devices, so it is possible to buy some GaN HEMTs from distributors today, but the selection is limited and still expensive compared to others technologies. Additionally, the lack of device standardization between these distributors means that there are no real second sources for any of the devices on the market today. No major manufacturer is going to use a GaN transistor in a high-volume application until interchangeable devices are available from multiple manufacturers. Furthermore, the unavailability of bulk GaN source material led to the need for GaN growth on mismatched substrates such as Si, SiC and sapphire, this also poses an issue which leads to poor quality epitaxial films with dislocation densities.

2. Choice of the Substrate

Choosing an appropriate substrate to grow GaN material is still an issue for developing GaN circuits. Beside Si or GaAs circuits for example, a Si or GaAs substrate is normally used; while GaN circuits have to be grown over another substrate because it is difficult to manufacture a GaN substrate due to the lack of the material. Since GaN is not easy found in nature, it must be grown on another

substrate, typically Si, SiC or Sapphire. There are three techniques to grow GaN over a mismatched substrate. These techniques have been employed widely in the past to reduce the high dislocation density and for the realization of GaN substrate with large size and high quality. One of the common methods is done by using metal organic chemical vapour deposition (MOCVD), after which the substrate is removed [24]. The success of this technique is resided in reducing dislocation density [24]; however it leads to selective area epitaxy due in large part to mechanical stresses and mechanical deformations, thus resulting on a limitation of GaN wafer. Typically GaN wafer are limited to two or three inches in diameter and thicknesses of about 100 μm . A second way to grow GaN, which is currently the most commonly used technique, is by hydrid vapour phase epitaxy (HVPE) [25] which is initially used in the growth of GaAs and InP. This is faster and has lower defect density than MOCVD ($5 \times 10^4/\text{cm}^2$ for HVPE, compared to $8 \times 10^7/\text{cm}^2$ for MOCVD). Additionally, it has been demonstrated that larger wafer sizes can be realized [26]. A third method for growing GaN is by ammonothermal growth [27]. This technique offers even better defect densities ($1 \times 10^3/\text{cm}^2$). However, growth of the crystal is much slower: 0.4–16 $\mu\text{m}/\text{h}$ [28], compared to 100–500 $\mu\text{m}/\text{h}$ for HVPE [29].

While GaN substrate is still unused, the decision of choosing a foreign substrate is crucial and based on several factors such as lattice constant, thermal conductivity, thermal expansion coefficient, wafer size and, of course, cost. The lattice parameter and the coefficient of thermal conductivity are the two crucial important properties that should closely be matched between the GaN and the mismatched substrate. Any mismatch between these two properties can result in defects in the film such as misfit and threading dislocations due to lattice mismatch and cracking or bowing due to the thermal mismatch. Table II.2 summarizes these parameters that are used when a substrate is selected.

Table II.2: Parameters used in the selection of a substrate for GaN devices: lattice constant (α), thermal conductivity at 300K (K_{300}), thermal expansion coefficient (αL), wafer diameter and approximate cost [30]

Material	α ($^{\circ}$ A)	k_{300} (W/K.m)	αL 5.59(ppm/K)	Diameter (inches)	Cost
GaN	3.189	130	5.59	≤ 4	High
SiC	3.08	490	4.2	≤ 4	Medium
Sapphire	2.747	41	7.5	≤ 6	Low
Si	5.4301	148	3.59	≤ 12	Low
AlN	3.112	285	4.2	≤ 2	High
Diamond	3.75	2000	1.18	≤ 4	High

In the process used for designing the circuits for this thesis, a SiC substrate is used. SiC substrate provides a good compromise between cost, excellent thermal properties which makes this device optimal to operate at high power.

II. NRC GaN500 MMIC HEMT Process Features and Limitations

The great interest raised by AlGaIn/GaN HEMT devices in the international semiconductor scientific community in general, for high power/frequency applications, has resulted in that an important number of industries and academics labs research (i.e United Monolithic Semiconductors (UMS), Fraunhofer IAF, Ferdinand Braun Institute (FBH), TriQuint, CREE, National Research Council Canada (NRC), etc) in the world are nowadays fully involved to demonstrate new microwave HEMTs devices in this new GaN technology. The presented varactor and switch circuits in this thesis were manufactured by the Canadian Photonics Fabrication Center (CPFC) at the National Research Council Canada (NRC).

NRC offers a foundry services for AlGaIn/GaN HEMT-based MMIC process for both university and industry customers. At the time of this thesis research, the technology features include a metal gate of 0.5 μm in the GaN500 process which was commercialized. Also, a metal gate of 0.15 μm in the GaN150 process was still under

development and months later its release was announced. Recently, the GaN500 process has been stopped to be commercialized in meanwhile the GaN150 process has just been released. Some varactors have been fabricated using the initial version (non-commercial) of this process when it was still under development. The access availability to the NRC GaN process is possible only through a company called CMC Microsystems which is an intermediate between NRC and costumers.

The proposed foundry [31], combines high power density, excellent thermal conductivity, and high gain performance. The HEMT devices are fabricated on an aluminum gallium nitride/gallium nitride (AlGa_N/Ga_N) hetero-structure grown on semi-insulating 4H-SiC substrates. Semi-insulating SiC is one of the most attractive substrate materials for electronic applications, because of the favorable combination of lattice mismatch, isolation, and thermal conductivity [[18]. In addition, AlGa_N/Ga_N HEMT structures are formed by using ammonia molecular beam epitaxy (MBE) in a SVTA nitride MBE system and are consisted of a 3 nm thick aluminum nitride (AlN) nucleation layer, a 1.1 μm thick carbon-doped Ga_N insulating buffer, followed by a 0.2 μm thick undoped Ga_N layer, and then 1.5 nm AlN spacer plus 20 nm AlGa_N barrier [32]. Currently both standard processes, GaN500 and GaN150, use 3-inch diameter SiC wafers of 75 μm thickness. More details about the wafer growth can be found in [32]-[33].

As shown in Figure II.5, where the complete process sequence is given, the first step in the GaN500 process fabrication as well as in GaN150 process is to deposit the Ohmic contact using the Ohmic mask (OHMIC Layer). The contacts are then annealed at a high temperature to ensure that a low-resistance contact is made to the two-dimensional electron gas (2DEG), where the carriers are located. The next step is to define the active area of the devices using the mesa mask (MESA Layer), and then it is isolated by etching it down to the buffer layer.

Gate metals are then formed by depositing a passivation dielectric layer in the channel area and etching a slot for the gate contact. The gate contact metal

(GATEMETAL layer) is deposited and a second dielectric encapsulation is applied. Openings are etched into the dielectric (VIA1 layer), where required, to allow connection to the ohmic and gate contacts.

Then, a thin layer of nichrome (NICHROME Layer) is deposited where resistors are required. The first level of interconnect metal (1 μm of gold) is next deposited using the 1ME mask (1ME Layer). The 1ME provides contacts to the ohmic metal and gate pads, as well as the nichrome layer. This layer is also used to form a field plate, which is connected to the source and overlaps the gate.

Next, the 1ME layer is isolated with a dielectric deposition and via openings are defined (VIA2 Layer) where required to define the vias. This layer of dielectric is used as the insulator in the MIM capacitors.

Finally, the areas where a second level of interconnect is defined (2ME Layer) to bridge over other layers is defined with a temporary layer of a special resist using the bridge mask (BRIDGE Layer). The 2ME layer is usually 1 μm of gold and is used to make the top layer of the MIM capacitors.

These process steps and Figure II.5 are reproduced with permission of the NRC.

Deposit and anneal
OHMIC contacts,
etch MESA,
deposit passivation



Etch gate slot,
Deposit gate



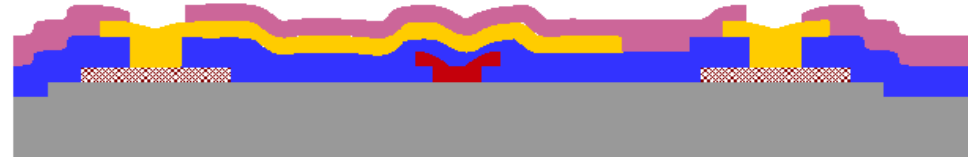
Deposit isolation
dielectric, etch VIA1



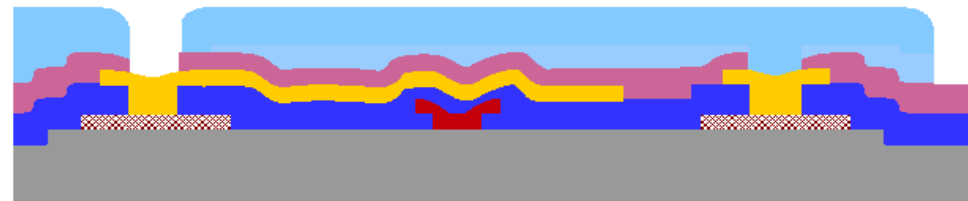
Deposit NICHROME
(not shown), deposit
1ME



Deposit second
dielectric, etch VIA2



Pattern wit sacrificial
BRIDGE resist



Deposit 2ME,
Remove sacrificial
resist

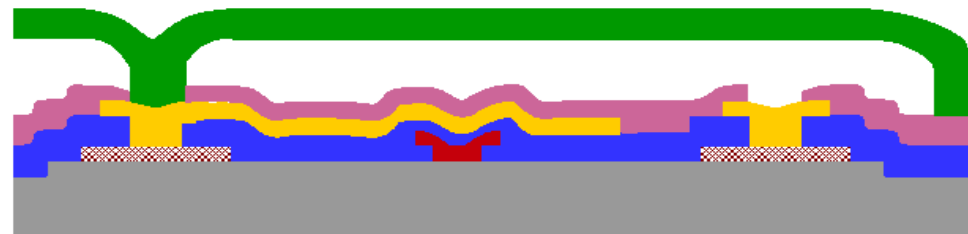


Figure II.5: Cross-sectional view of HFET, showing process sequence (not to scale)

[31]

Moreover the two processes involve two layers of $1\mu\text{m}$ and $3\mu\text{m}$ gold, respectively, 1ME and 2ME for interconnect, and the second layer may be used to form either 100nm metal-insulator-metal (MIM) capacitors of $0.19\text{ fF}/\mu\text{m}^2$ or $1\mu\text{m}$ air-bridges. Thin-film nichrome resistors with sheet resistance of $50\ \Omega/\text{sq}$ are also available. Spiral inductors in this process typically have a measured quality factor of about 12 to 18 and are wound a central empty area, with a recommended minimum size of $50 \times 50\mu\text{m}$. While capacitors with measured quality factors of at least 50 at X-band are attainable.

GaN500v2 offers transistors with a unity current gain frequency, F_t , of 13 GHz and a maximum oscillation frequency, F_{max} , of 60 GHz, and it is suitable for 30V maximum drain voltage bias, and yields power levels of $\sim 7\text{ W/mm}$ (measured at 8 GHz). While GaN150v1 offers transistors with F_t of 35 GHz and a F_{max} of 75 GHz. Furthermore, GaN500v2 HFETs devices exhibit breakdown voltages (measured with channel pinched-off) generally greater than 200V, however a maximum drain voltage of 40V is currently recommended. While a breakdown voltage $V_{\text{DS_BD}}$ (V_{DS} measured at channel pinched-off) greater than 100V and a maximum drain bias voltage of 30V is currently recommended for GaN150v1 devices. Finally, the gate source voltage can operate from -8V to 2V, with at least a threshold voltage of -4.6V needed to turn these devices ON [31]. Additional details about the technology are provided in NRC's GaN design manual process [31].

As is traditionally known, as a part of any technology fabrication process, proper and accurate models are usually set and provided in the process design kit (PDK) to achieve any circuit's functionality. In the used GaN fabrication process, there is still work to be done as it lacks essential components desired for reconfigurable applications, such as the lack of varactor models, and also the lack of common gate (CG) configured switch models, which are vital for revealing switch operation capabilities of these FETs. Moreover, the current version of the PDK only supports a limited number of active device sizes. This thesis will concentrate on

proposing equivalent circuit models, firstly, for varactor diodes and then for switch in common gate configuration. Equivalent circuit models analysis for varactor diodes will be conducted in small signal and large signal while only small signal analysis will be conducted for switch devices. These developed models will be used in RF designs to verify them and validate their abilities of use in some RF applications.

III. Use of GaN in Reconfigurable RF/Microwave Systems

Monolithic RF/microwaves integrated active reconfigurable systems are necessary for applications which require lightweight, low cost, high reliability, ease of integration, and high volume. The recent development of high electron mobility transistor (HEMT) makes it possible to realize a high level reconfigurable RF/microwaves design, such as power amplifiers, phase shifters, low noise oscillators, and reconfigurable antenna array designs. The high efficiency power amplifier and the phase shifting constitute the important parts of a RF/microwaves transmitter block.

Due to the mature development of GaAs technology, beam-former circuitry could be integrated into the same package as the antenna array system [34]. There have been intensive developments of these listed components, which have relied on high performance semiconductor technologies especially GaAs HEMT technology. In order to achieve higher RF output power with higher efficiency, GaN technology is a very promising candidate for realizing designs, such as high efficiency tunable circuits, highly reconfigurable low noise power oscillators and integrated active beam forming transmit antenna arrays [35]. The current studies of this technology reveal that GaN has the potential to be the technology of choice for the next generation of transmitter/receiver (Tx/Rx) modules where high power/frequency applications [36]-[37] and several functionalities on the same chip [38] are required.

Active reconfigurable circuitry for transmitting and/or receiving (Tx/Rx) modes has been widely used for many applications, such as space and defense. In addition, high efficiency compact Tx/Rx modules are increasingly needed in RF/microwaves applications. Their development is driving the enhancement of HEMT MMIC technology, now extending to the promising GaN technology. Indeed, the trend in the last generation of Tx/Rx module systems is to reduce the number of MMICs in the module by increasing their power handling capabilities and efficiencies using GaN [39]-[40]. The current state of art shows that GaAs technology has been intensively used for these systems at many frequency bands [41]-[42]. Meanwhile for GaN technology, many reconfigurable power amplifiers for Tx/Rx modules have been reported in the last ten years. There has been some work on Tx/Rx module using GaN for X-band [43], where three types of amplifiers (DA, HPA and LNA) were integrated on multi-layer low temperature co-fired ceramic (LTCC) substrates. In Figure II.6 the completely assembled front-end is shown. Output power levels of 6.8W (38 dBm) for the driver amplifier (DA) and 20W (43 dBm) for the high power amplifier (HPA). Measured results are depicted in Figure II.7 and Figure II.8. The measured noise figure of the low noise amplifier (LNA) is in the range of 1.5 dB as shown in Figure II.9.

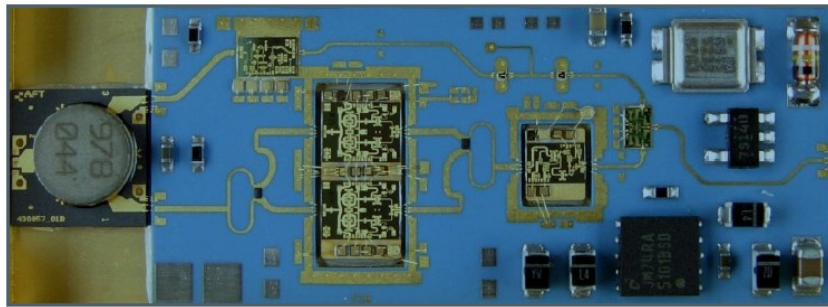


Figure II.6: Photo of a T/R-Module front-end with GaN MMIC chips [43]

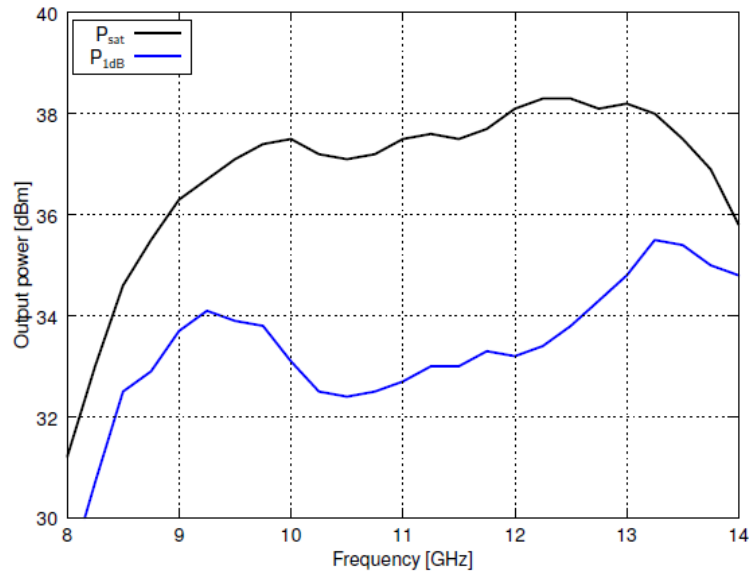


Figure II.7: Measured output power versus frequency of the GaN MMIC DA at 1 dB gain compression and at saturation with $V_{ds} = 30V$ and $V_{gs} = -4.9V$ [43]

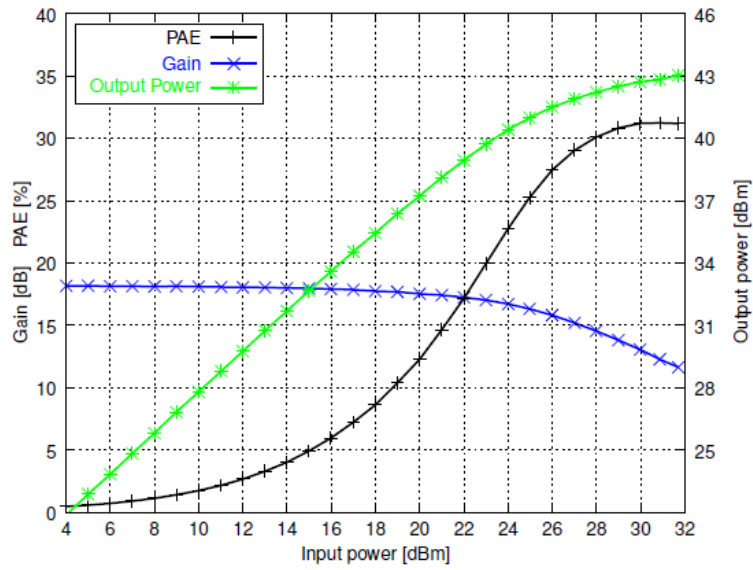


Figure II.8: Measured power performance of the GaN MMIC HPA at 11 GHz with $V_{ds} = 30V$ and $V_{gs} = -5V$. $P_{max} = 43dBm$ $PAE_{max} = 31\%$ [43]

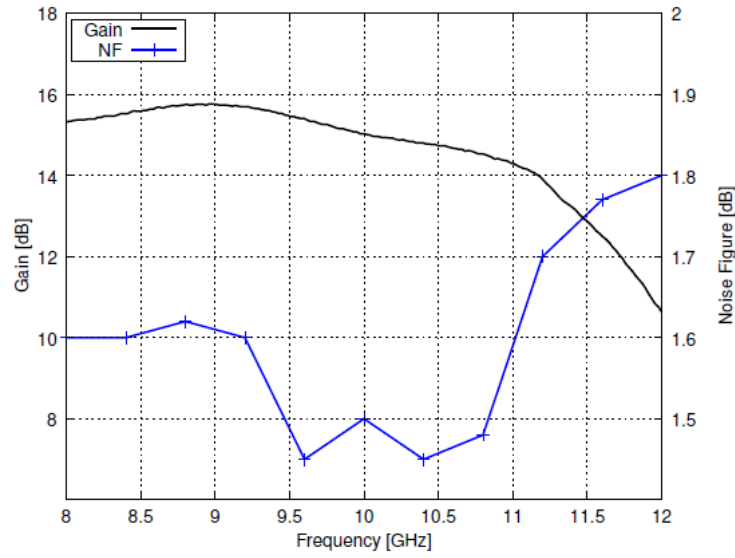


Figure II.9: Measured gain and noise figure versus frequency of the GaN MMIC

LNA with $V_{ds} = 15V$ and $V_{gs} = -3.5V$. $NF_{min} = 1.45dBm$ [43]

Another Tx/Rx module using GaN was reported [44], which contains a GaN power amplifier (PA) with output power higher than 10 W over 6-18 GHz and a GaN low-noise amplifier (LNA) with a gain of 15.9 dB over 3.2-20.4 GHz. Figure II.10 shows the fabricated T/R module, while the Figure II.11 and Figure II.12 illustrate, respectively, the measured P_{out} of fabricated T/R a function of frequency and the measured S-parameters of GaN LNA MMIC.

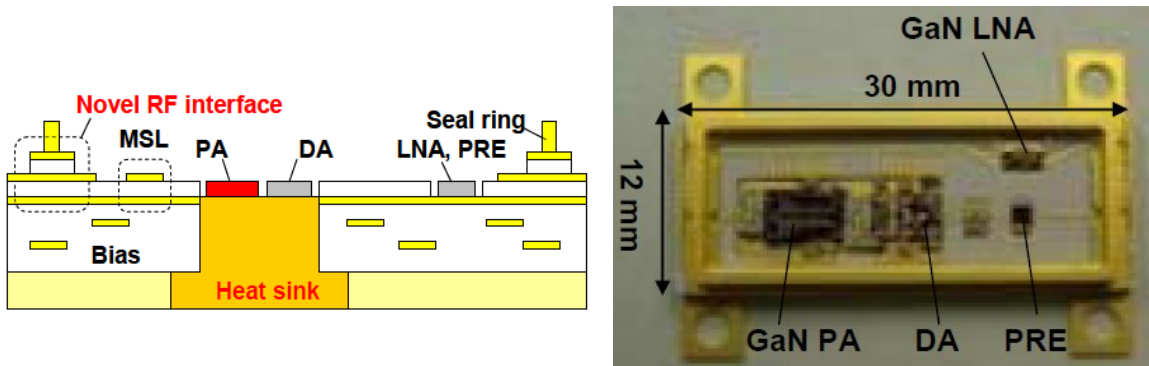


Figure II.10: (Left) A schematic view and (Right) a photograph of the Fabricated T/R module using HTCC technology [44]

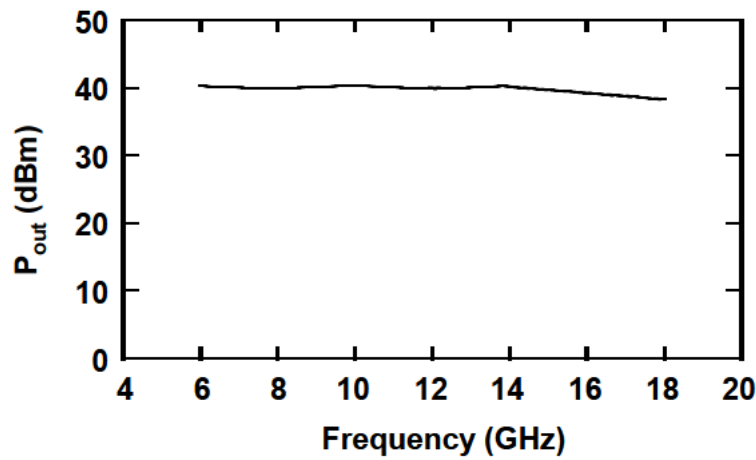


Figure II.11: Measured P_{out} of fabricated T/R module as a function of frequency, biased at 30 V [44]

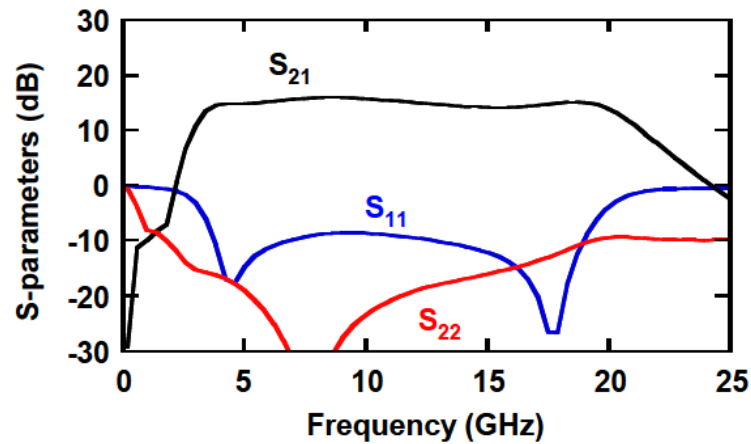


Figure II.12: Measured S -parameters of GaN LNA MMIC ($V_{ds} = 15$ V) [44]

Using GaN technology, some implemented reconfigurable PAs have been reported. A reconfigurable Doherty PA has been presented in [45] based on a GaN MMIC modified Doherty PA with large bandwidth and reconfigurable efficiency. Photograph of the fabricated amplifier is illustrated in Figure II.13. The total size measures 2.9×2.9 mm². This design presents a new theory that makes it possible to analyze how the performance of the amplifier depends on the input network properties and the choice of gate bias voltage. The design achieved a power added efficiency (PAE) more than 31% at 9dB output power back-off over a band from 5.8

GHz to 8.8 GHz. The measured PAE is plotted versus output power in Figure II.14. The measured gain is plotted versus output power in Figure II.15. As shown, a small-signal gain ($P_{out} = 18$ dBm) is larger than 7.4 dB up to 8.8 GHz is achieved, whereas the gain at high output power (≈ 33 dBm) stays within 8.5–9.0 dB for all frequencies.

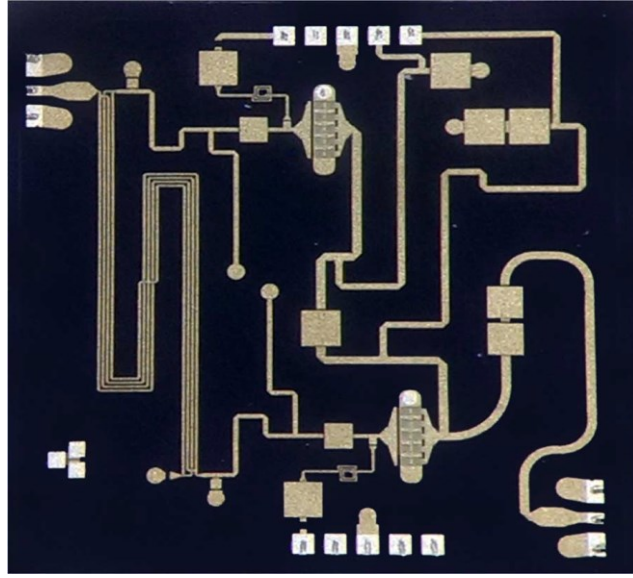


Figure II.13: Photograph of the fabricated amplifier [45]

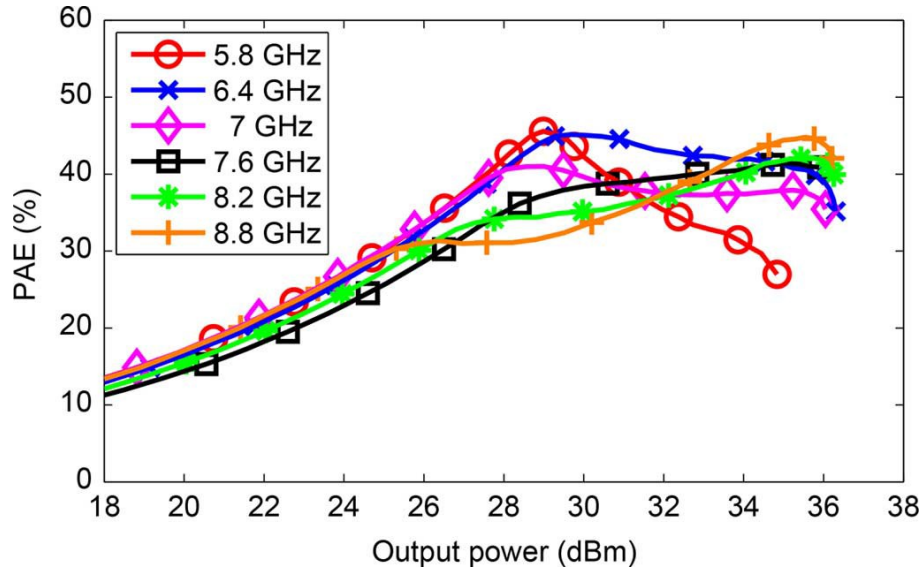


Figure II.14: Measured PAE versus output power [45]

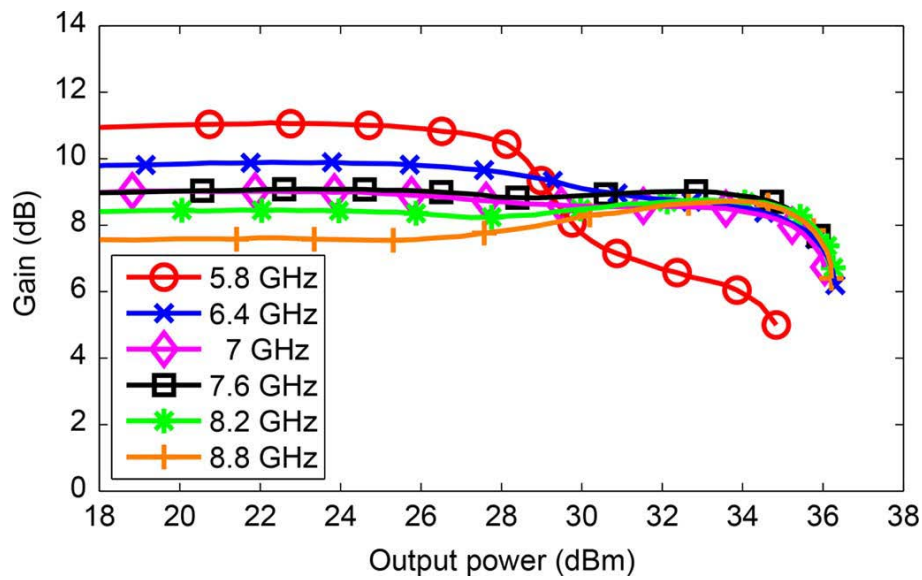


Figure II.15: Measured gain versus output power [45]

In [46] using tunable capacitors in the input and output matching networks, a 2.45 GHz GaN HEMT operating class and frequency reconfigurable power amplifier is reported. Figure II.16 and Figure II.17 show, respectively, the concept of impedance matching conditions and a topology of the photograph of the proposed reconfigurable PA. The proposed PA can be reconfigured to operate in class A or class B to achieve, respectively, an extreme high linearity and high efficiency where high linearity is not strictly required. As a result, the proposed reconfigurable PA design can be reconfigured for multiple bands and for switching between operating classes. This reconfigurability is clearly seen in Figure II.18, Figure II.19 and Figure II.20 where gain, output power and PAE versus the swept input power, respectively, are plotted.

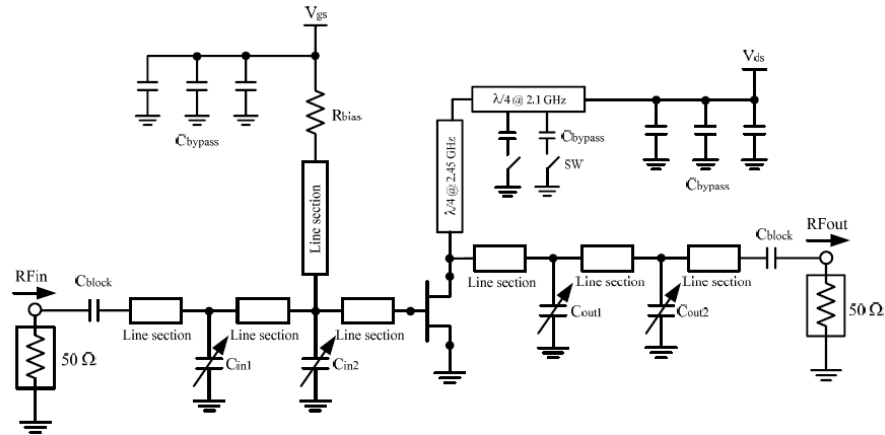


Figure II.16: The concept of impedance matching conditions of the band and class reconfigurable power amplifier [46]

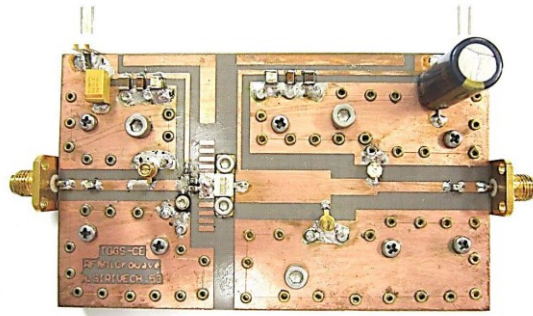


Figure II.17: Photograph of the fabricated class-reconfigurable power amplifier [46]

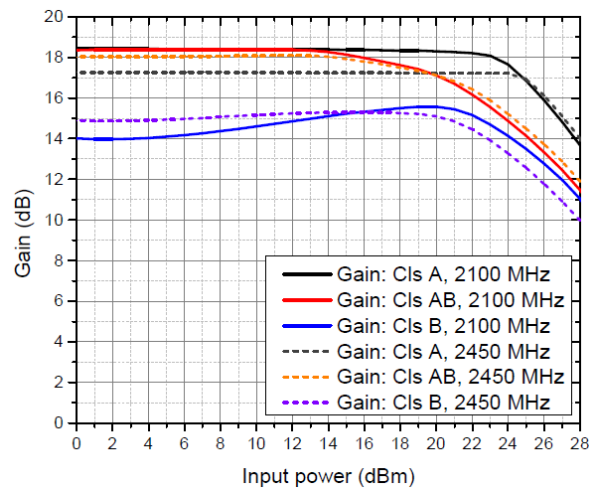


Figure II.18: Simulated gain verses input power at different matching states [46]

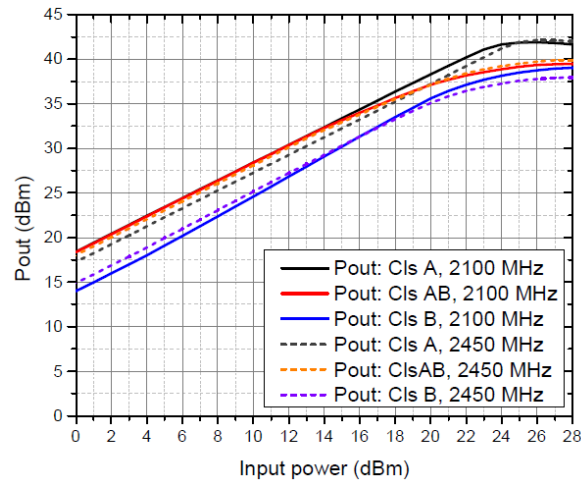


Figure II.19: Simulated output power verses input power at different matching states [46]

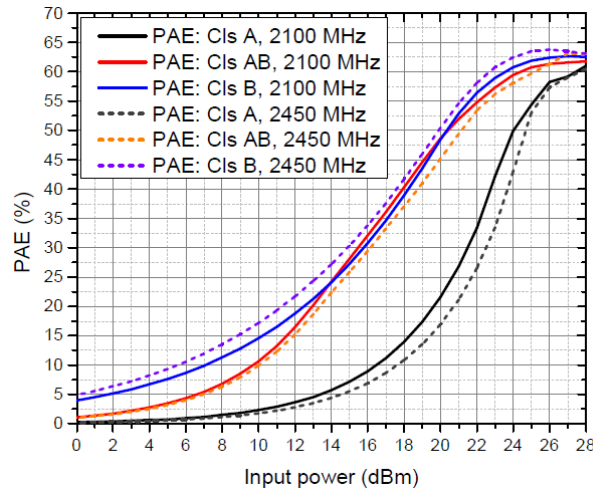


Figure II.20: Simulated power added efficiency verses input power at different matching states [46]

In [47], for the first time a novel technique on how to combine the advantages of the high power handling capabilities of GaN devices and microfluidic channels integrated in a multilayer organic substrate by designing a reconfigurable GaN-based PA at 2.4 GHz and 5.8 GHz is designed. An illustration of the packaged PA is shown in Figure II.21. The new technique regarding the design of tunable source and load matching networks frequency response is based on using different

fluids (acetone for 2.4 GHz and air for 5.8 GHz) injected inside their respective micromachined channels. As reported, the fabricated PA provides an output power of 35 dBm with a PAE of 36.41% at 2.3 GHz for an input power of 21 dBm, while at 5.7 GHz an output power of 36.88 dBm is achieved with a PAE of 44.03% for an input power of 25 dBm. These measured results are plotted in Figure II.22 and Figure II.23 for, respectively, acetone and air configuration.

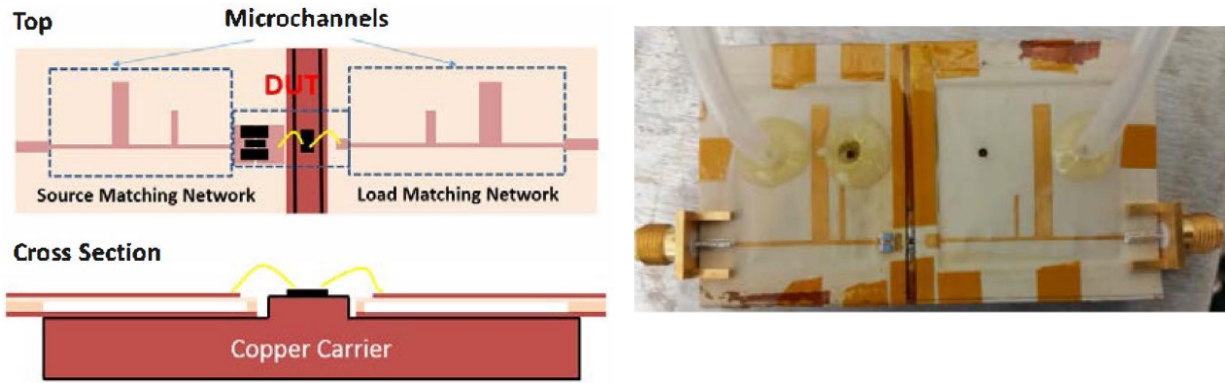


Figure II.21: (Left) Top and cross sectional view and (Right) Picture of the packaged PA [47]

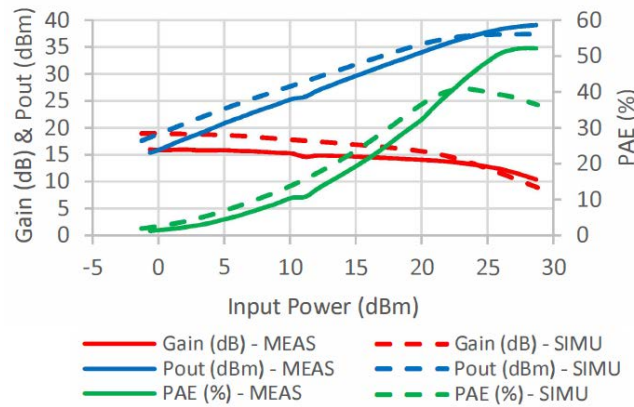


Figure II.22: Acetone configuration: measurements at 2.3 GHz, simulations at 2.4 GHz [47]

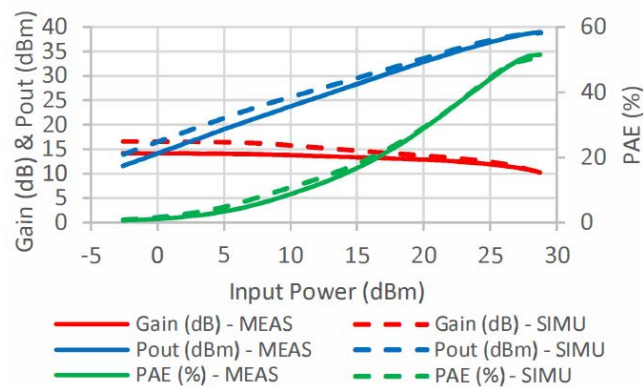


Figure II.23: Air configuration: measurements at 5.7 GHz, simulations at 5.8 GHz [47]

More studies revealed that due to the drawbacks of GaAs MMIC HPA as low efficiency and limited output power level have made it not to be a competent candidate of power chips against the high efficiency of GaN MMICs technology [39]. In this same reference, a GaN-based high power amplifier with output power of 85 W and operating at S-band is reported. In 2014, an investigation [38] revealed that the next generation of GaN MMICs will cover more functionalities on the same chip. Multifunctional MMICs will allow very compact Tx/Rx module designs, and will reduce the number of active devices [38].

In this context, this thesis research is focused to demonstrate the use of GaN on highly efficient reconfigurable designs for broadband RF/microwave applications operating below 10 GHz. GaN components such as varactors and switches used for tunable purpose are firstly fabricated, characterized and then modeled. The proposed models are used to achieve the reconfigurability of RF/microwave circuits. Tunable phase shifter, reconfigurable 3-dB 90° hybrid coupler, tunable frequency oscillator, beam switching antenna array and matching reconfigurable patch antenna are developed along with the development of GaN modeling varactors and switches, and are presented as applications results of this thesis research. A current literature review of these reconfigurable cited circuits will be presented along with the realization of these designs later in chapter IV.

IV. Summary

In this chapter the properties of GaN technology have been reviewed, discussed and compared with the commonly used semiconductor technologies. It has been clearly shown that GaN technology is a great promising semiconductor candidate for applications that high power and high frequency are required as well as high temperature. Its disadvantages and difficulties are also studied presented and discussed. Additionally the features and limitations of the used AlGaIn/GaN process throughout this thesis provided by NRC were summarized and presented. Furthermore, an overview of the ability to use GaN technology for tunable purposes such as power amplifier discussed. We also reviewed some previous work done on the development of reconfigurable power amplifier circuits using GaN technology that are used in Tx/Rx modules.

Chapter III

GaN Varactor and Switch Devices Modeling

I. Introduction

A general purpose reconfigurable integrated RF/microwave circuit could be realized using a promising semiconductor technology for the active device, and an interconnection technique such as wire-bonding technique to compact all the circuits. Recent technology trends favor greater integration of electronic devices and radiating elements, greater functionality and reconfigurability (on a single chip or via multi-chips), as well as high operating frequency/power with excellent efficiency and linearity. Such are the needs for next generation of Tx/Rx modules.

For the proposed thesis research, GaN-based varactor and switch components will be pursued; the main features of this type of semiconductor technology being its high power with high efficiency. Compact reconfigurable circuits, such as tunable phase shifter, reconfigurable 3-dB 90° hybrid coupler, tunable frequency oscillator, beam switching antenna array and matching reconfigurable patch antenna based on these developed varactors and switches will be studied. The first part of the work is devoted to active GaN device development and characterization. The second part addresses the integration and design aspects of the reconfigurable proposed circuits.

GaN technology to date has seen very little application to signal control devices such as varactors and switches. These two elements are key points to realize phase shifters (both continuous and discrete state), frequency reconfigurable circuits, and signal path selection circuits for beam switching or Tx/Rx selection.

Our investigation considers modeling in small- and large-signal of both GaN varactor devices and GaN switch devices, as outlined in the “Work Plan” chart below (see Figure III.1). The design of these GaN components was realized using the Canadian National Research Council (NRC) GaN HEMTs monolithic microwave integrated circuit (MMIC) processes. Three NRC GaN HEMTs processes, such as, GaN150v0 with a gate length of 0.15 μm , GaN500v1 with gate length of 0.5 μm and GaN500v2 which is the developed version of GaN500v1, have been used to manufacture the varactor and the switch devices.

An accurate large signal model requires extensive laboratory equipment to extract all the effects related to high power GaN devices, such as thermal and trapping effects typically present in GaN devices. Carleton University is not as well equipped with these laboratory facilities as are the NRC or IETR. Due to our incapability to have large signal measurement facilities, only small signal measurement will be presented and discussed. However, for varactors fabricated

using GaN500v2, we finally succeed to do large signal measurements. These measurements have been done at XLIM at University of Limoges, France.

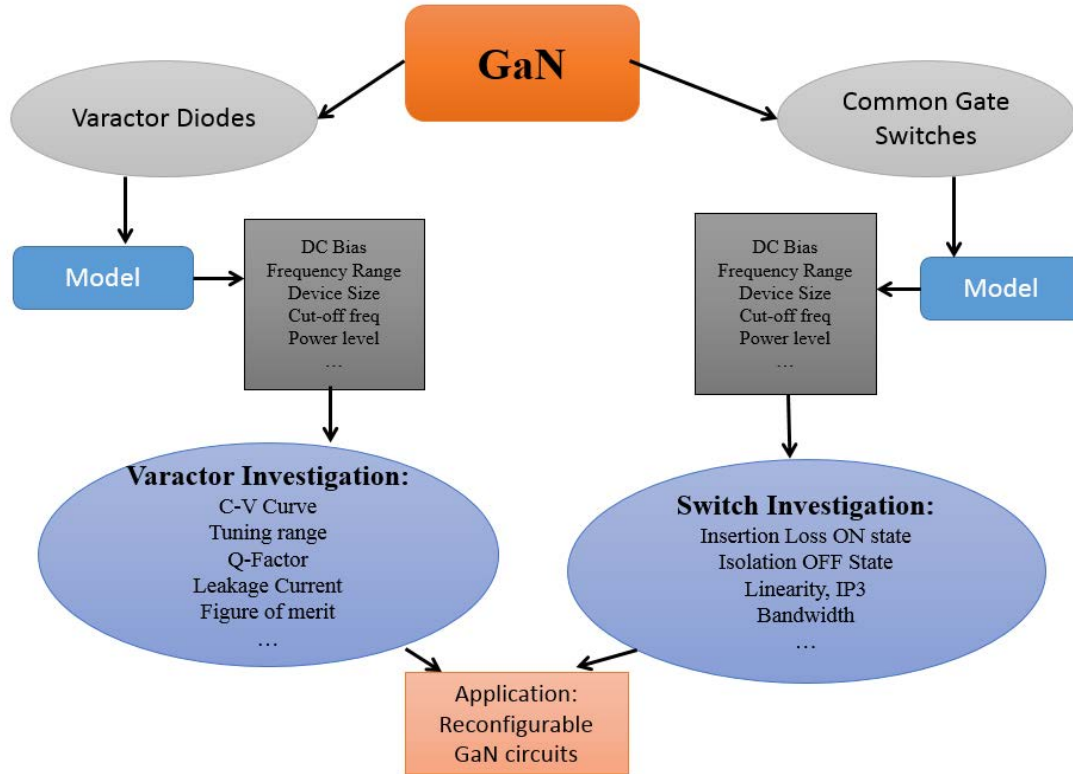


Figure III.1: Work Plan

First step, we start investigating varactor devices. For this, two NRC GaN HEMTs processes, GaN500 and GaN150, have been used to manufacture the devices. At this time the current version (v1) of GaN500 process was used; while for GaN150, the process was still under-development and its initial version (v0) was used which was non-commercialized one. Many size different devices have been manufactured and characterized in only small signal measurements, and then a small signal model has been implemented. This model describes clearly the behavior of GaN based varactor. Following the development of NRC GaN HEMTs process, another fabrication run has been launched to manufacture other varactor devices with different sizes and by using, in this time, only the newly developed version of GaN500 process, version 2. This time, small signal as well as large signal measurements have

been done on these novel realized varactors, respectively, to validate the proposed small signal model developed from GaN500v1 process' devices and to verify their capabilities in terms of different power levels. Secondly, single GaN switches with different sizes have been fabricated and measured in only small signal. A model is presented and discussed. These varactor and switch models will be used to simulate and design reconfigurable RF/microwaves designs shown in the chapter IV.

II. GaN-based Varactors Diodes Modeling

1. Review of GaN HEMT for Power Varactors Diodes Applications

GaN HEMTs semiconductor devices are no longer limited to RF power amplifier applications, but having been extended to other applications such as LNAs [48], VCOs [49], mixers [51], and phase shifters [50]-[52]. Furthermore, reconfigurable RF circuits, with high power/frequency, and excellent linearity, are in great demand. Varactors are key components in the design of these reconfigurable circuits [53] for microwave and millimeter wave applications. The varactor diodes can be fabricated from either p-n or Schottky junctions and both cases are under research today.

The superior characteristics (i.e high-temperature operation due to large energy band gaps, high breakdown field, high saturation velocities of electrons, etc) make GaN heterostructures promising candidates for realizing high power/tuning voltage varactors diodes. Up to now, the progress on developing GaN varactors have been limited and only a few works have been already reported. Based on GaN HEMT technology, some varactors have previously been reported, mostly employing a Metal-Semiconductor-Metal (MSM) junction [53]-[54]-[55]-[56] or Schottky barrier contact [57]-[58]-[59].

Later 2002, one of the first investigated GaN varactor work was reported in [53]. This work investigates the properties of MSM diodes that are based on an

AlGaIn/GaN HEMT layer structure (MSM-2DEG), which shown that devices made in this material system are realizable with tuning capacitance range. As can be seen from Figure III.2, the capacitance is constant between 2.7 and -2.7V and within a very small voltage range of about 0.3 V the capacitance starts getting changed. The reported measured C_{MAX}/C_{MIN} ratios vary from 5 to 100 and were dependent on electrode geometry. This investigation shown clearly that these ratio values were exceeding those ratios for varactor diodes in GaAs. However, a high series resistance varies from 40 Ω to 70 Ω was extracted and these values were dependent on the electrode spacing from 0.5 μm to 2 μm . This high series resistance of the device, which was announced as a challenge for varactors diodes, can affect directly the figure of merit, quality factor (Q-factor), of the device. In addition, this high value of series resistors is due to the unavoidable ohmic contact resistance. Researchers have begun to investigate the possibilities in order to reduce this specific contact resistance.

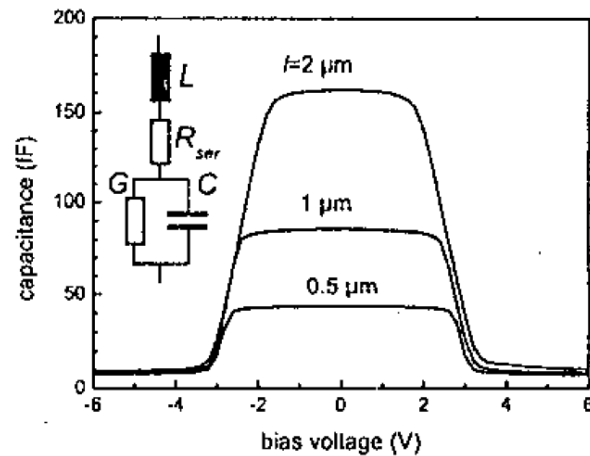


Figure III.2: C-V characteristics of devices with different electrode length (spacing = 1 μm , width = 50 μm) [53]

In [54], a work focused on characterizing the Q-factor of MSM AlGaIn/GaN varactors that operate in RF range was reported. The ohmic contact is eliminated and replaced by a Schottky contact, resulting in reduced overall series resistance and higher peak Q-factor. A standard AlGaIn/GaN HEMT process was fully compatible for manufacturing this MSM varactors. The C-V measurements (see Figure III.3)

revealed that the device was capable to valid the rapid change on capacitances values over a small range of bias voltage. At 1.1 GHz, the capacitance tuning range was varying from 1.62 to 0.12 pF corresponding to a $C_{\text{MAX}}/C_{\text{MIN}}$ ratio of 13.5. Moreover, a high series resistors values were still achieved. The dependence of the Q-factors on the bias voltage at 1.1 GHz is illustrated in Figure III.4. From both Figure III.3 and Figure III.4, it can be seen that the value of Q-factor decreased as well as the series resistor value increases. A physical equivalent circuit model was reported to explain the behavior of the voltage controlled capacitance and the corresponding Q-factor. It was revealed that the fundamental limit on the Q-factor in the intermediate capacitance range is the rapidly increasing channel resistance when the channel is depleted. Although, it was reported that further improvement of the Q-factor has to come from modification of the conventional single-channel HEMT using double- or multiple-channel structure in which additional low impedance current paths are available.

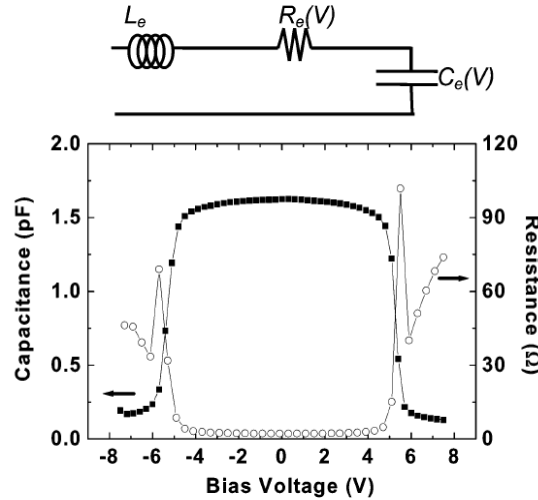


Figure III.3: Extracted capacitance (black line) and resistance (white line) of the MSM varactor over the entire bias range at 1.1 GHz. The inserted schematic shows the first-order equivalent circuit of the MSM varactor [54]

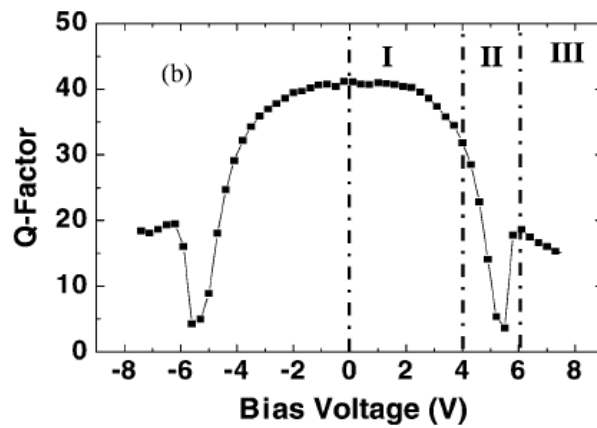


Figure III.4: Q -factor versus tuning bias at 1.1 GHz [54]

Another investigation MSM GaN varactor was reported in 2012 in [55]. In this work, a MSM varactor diodes on top of an AlGaIn/GaN-based epitaxial structure is proposed to the fast surge protection application. This works was focused on developing a surge to protect electronic devices against the natural or manmade surge threats, including lightning, electromagnetic pulse (EMP), electrostatic discharge (ESD) etc. Figure III.5 shows the schematic diagram of an AlGaIn/GaN-based varactor used in this study while the C-V curves of the surface untreated and the sulfur-treated AlGaIn/GaN-based MSM-2DEG varactors used in this study are presented in Figure III.6. This investigation showed that the varactor exhibits great potential to improve the surge protection for GaN-based HEMTs. Therefore, the fabricated process significantly affects the capacitance swing of MSM-2DEG varactors. Due to the variable impedance characteristics of the varactor, it is either within the high impedance region for blocking the surge energy or within the low impedance region for passing normally the signal.

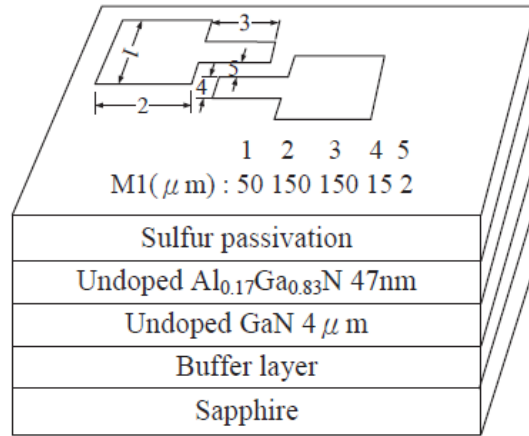


Figure III.5: A Schematic diagram of the AlGaIn/GaN-based varactor [55]

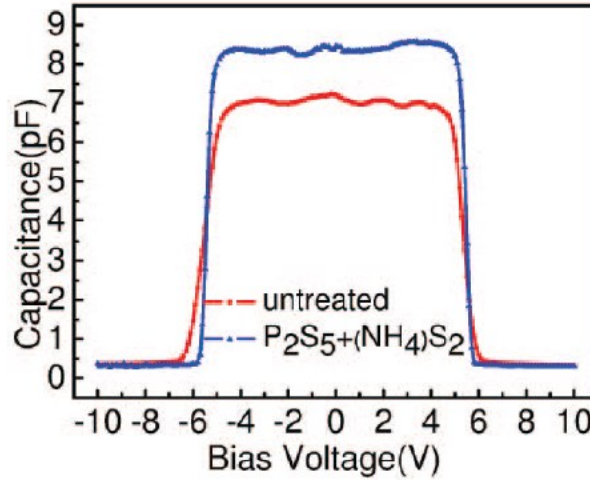


Figure III.6: Measured C-V curves of the untreated and sulfur-treated AlGaIn/GaN-based MSM-2DEG varactors [55]

In 2015, by the same group researchers of [55], a MSM varactor study has been reported in [56]. Here, the performance of the AlGaIn/GaN MSM-2DEG varactor with different dielectric films deposited by the E-beam deposition is investigated. In addition, different dielectric films are studied to verify the effect of the dielectric material on the capacitance ratio and the bias voltage of varactors. For this, three dielectric films have been used, such as, SiO₂, Gd₂O₃, and Si₃N₄ to conduct this study. Figure III.7 illustrates the schematic diagram of the AlGaIn/GaN MSM-2DEG varactor used for this study. From Figure III.8, it was observed that the capacitance

tuning ranges are almost identical irrespective of whether with dielectric film or not. However, the capacitance ratio (C_{MAX}/C_{MIN}) for each varactor is affected by the type of the dielectric film used. It was proved that the varactors with the SiO₂ and Gd₂O₃ dielectric films offer the benefit of a lower leakage current. It was also observed that the C_{MAX} , the C_{MIN} and the capacitance ratios show the same tendency of decreasing for varactors with dielectric films and are proportional to the increasing of the electrode areas.

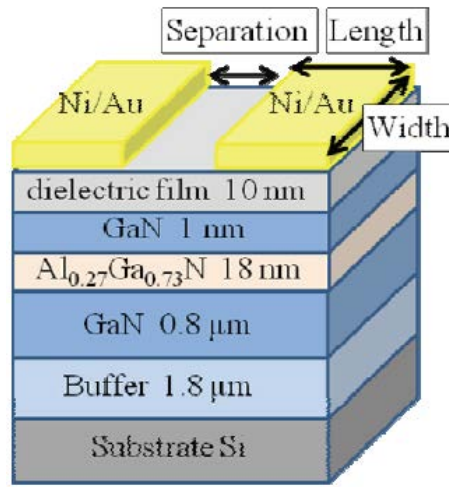


Figure III. 7: Schematic diagram of the AlGaIn/GaN MSM-2DEG varactor of the samples prepared in this study [56]

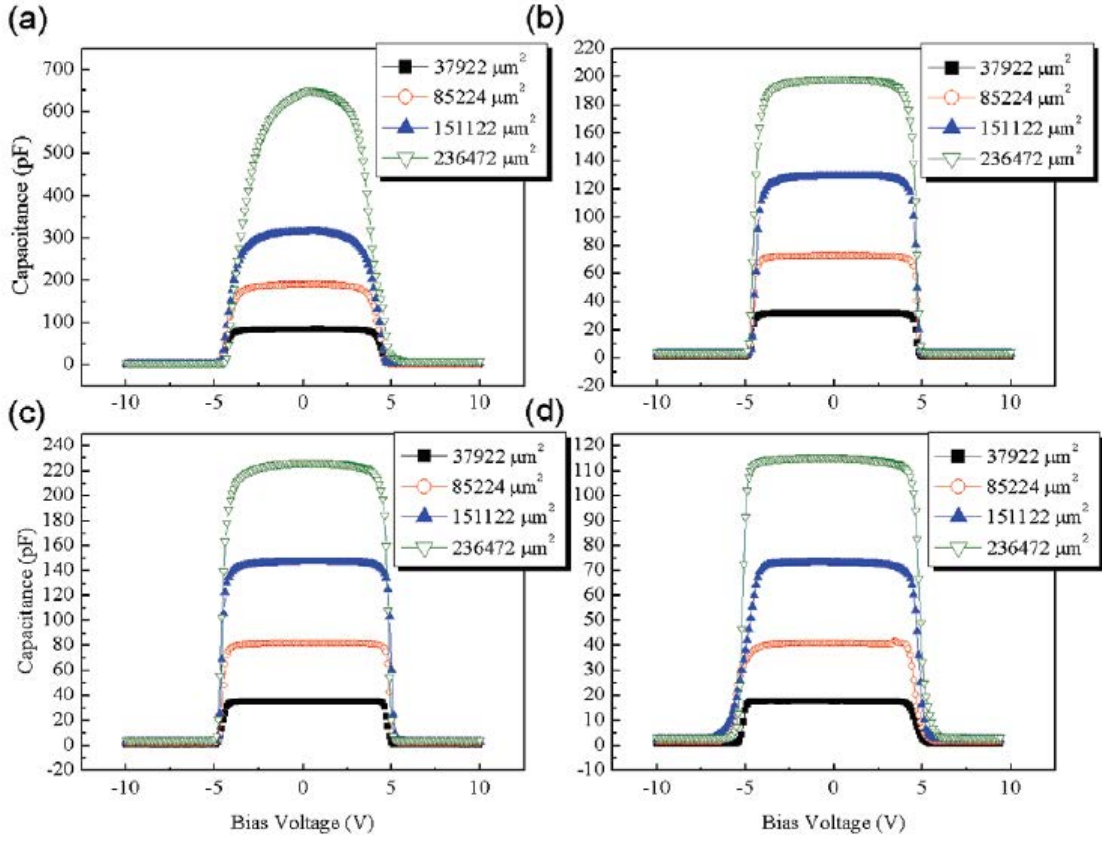


Figure III.8: Capacitance-Voltage (C - V) characteristics of varactors with different electrode areas (a) without any dielectric film, (b) with SiO_2 film, (c) with Gd_2O_3 film, and (d) with Si_3N_4 film. Measurement frequency = 1MHz, electrode area = 37922, 85224, 151122, and 236472 μm^2 , respectively [56]

In [57], a novel GaN-based high frequency varactor diode was reported. This main goal of this work is to investigate the high frequency performances expected from such GaN-based Schottky barrier varactor diode. The structure used in this work consists of a 2 μm bottom ohmic (n^+) contact layer and a 300 nm lightly doped (n^-) GaN layer which is grown on top of the ohmic layer. The ohmic contacts (Ti/Al/Ti/Au) were deposited once the mesa mask was isolated by Ar etching and then Pt was deposited which forms the Schottky contact metal. The schematic of the GaN Schottky varactor structure is shown in Figure III.9. It was shown that epilayer designs can help in controlling such characteristics. As shown in Figure III.10, the

maximum capacitance at 0 V bias is 40.476 fF and the minimum capacitance is about 26.4fF when a bias of less than -7 V is applied. This reported varactor had a breakdown voltage of 20 V and a cut-off frequency of 360 GHz.

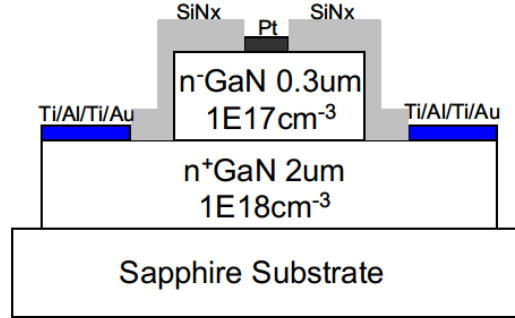


Figure III.9: Schematic Cross-sectional view of the GaN Schottky Varactor [57]

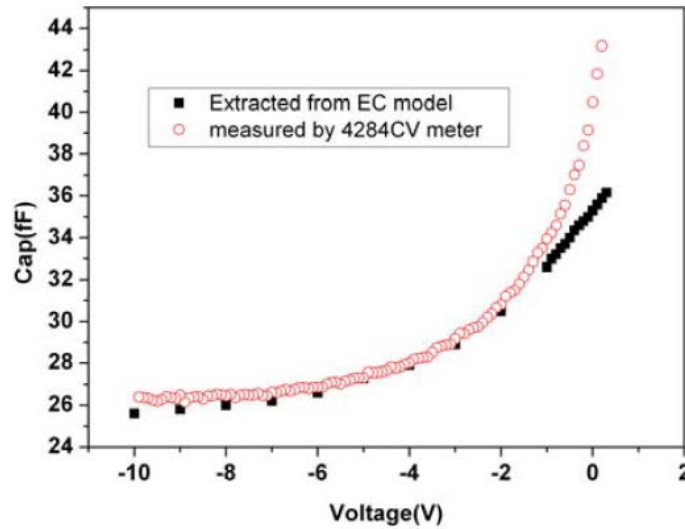


Figure III.10: C-V characteristics of the GaN Schottky Varactor [57]

Based on Schottky barrier, another work was reported in [58]. In this work, a design of InGaN/GaN schottky diodes with enhanced voltage handling capability with vertical geometry was discussed. It is, therefore, illustrated that a higher voltage handling capability may be obtained with a suitable InGaN surface layer design. Figure III.11 schematically shows the structure of a GaN varactor. Furthermore, the depletion width W varies in the n^- region under several external bias voltage, this resulting to a change in equivalent C as well as in its associated series resistors R .

The reported work shows that varactor diode made in GaN material are capable of bias voltages over 120V at a doping level of $1 \times 10^{17} \text{ cm}^{-3}$ over a 1- μm -thick depletion region. Furthermore, at 1 GHz, a significantly high Q value superior of 35 was reported which corresponds to series resistance of this device ($\sim 8 \Omega$) which was primarily from the underlying n^+ GaN and contact resistance. Figure III.12 shows the C–V curves over the range of 0–100 V for the InGaN-containing samples and for a control sample.

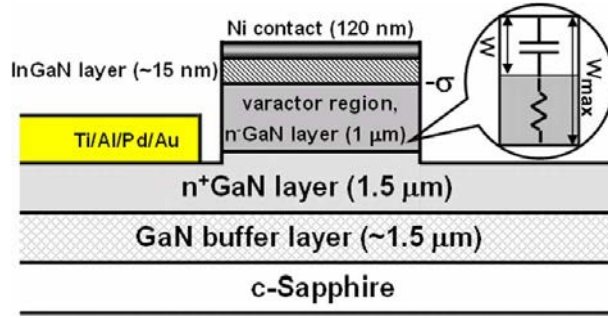


Figure III.11: Schematic diagram of a GaN-based varactor and its layer structure [58]

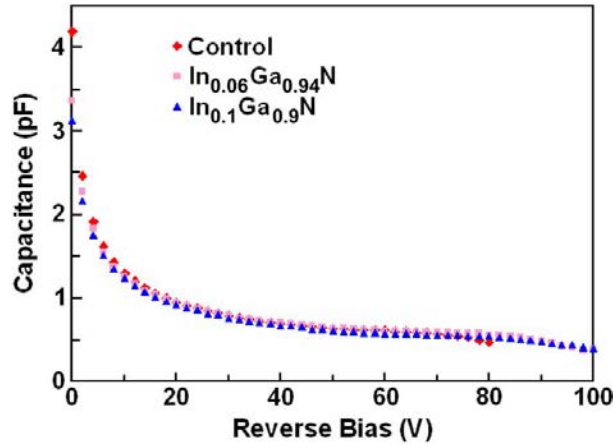


Figure III.12: C–V curves measured for the samples with area of $5 \times 10^{-5} \text{ cm}^2$ at $f = 1 \text{ MHz}$ [58]

Two years later, on 2012, the same group researchers of [58] reports a new work [59] where the critical design considerations for achieving GaN-based high voltage, high Q factor and high linearity microwave varactors were summarized and were discussed. In addition, detailed performances for a real fabricated GaN-based anti-parallel varactor diode structure that simultaneously achieving high Q, high-breakdown voltage and high linearity were presented. This investigation was based on using the same GaN structure presented in Figure III.11. It was highlighted that heavily doped semiconductor material is required to minimize the series resistor and achieve a high Q-factor. However, in order to achieve high breakdown voltage, the semiconductor needs to be lightly doped to keep the electric field in the semiconductor below its critical electric field. Furthermore, the two anti-parallel diodes structure was used to investigate the varactor linearity. It was reported that by using this structure, the RF signal induced capacitance variation is minimized. The linearity of the varactor diode is thus significantly improved. Figure III.13 shows the simulated C-V curves for single and two anti-parallel structures, while in Figure III.14, Q-factor versus the reverse external bias is depicted.

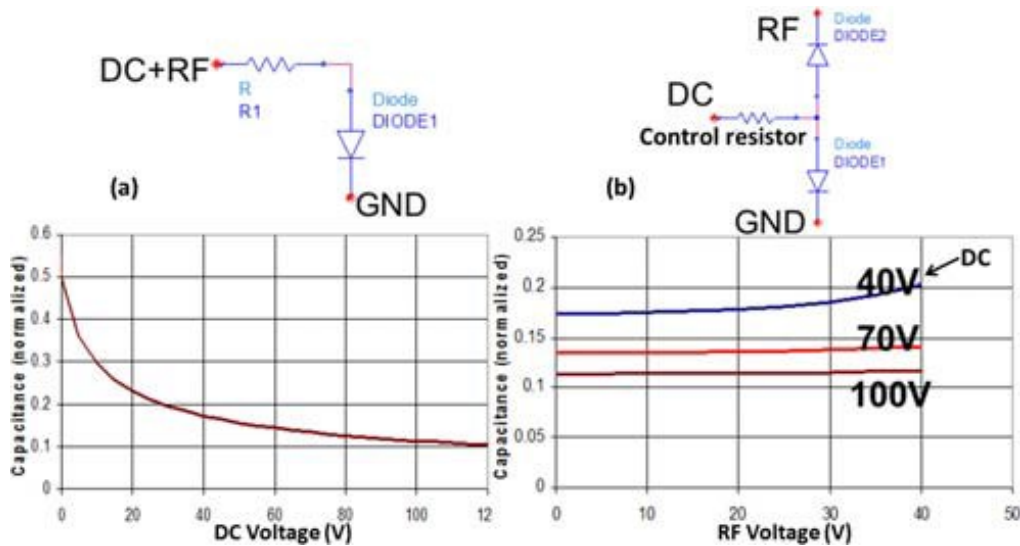


Figure III.13: Capacitance-voltage curves for (a) single diode structure and (b) two anti-parallel diode structure [59]

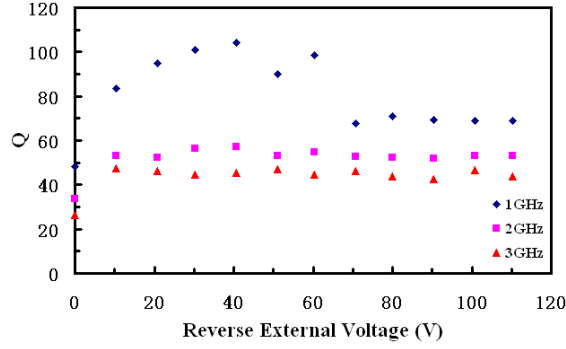


Figure III.14: Q factor versus reverse external bias for an anti-parallel varactor at $f = 1$ GHz, 2 GHz and 3 GHz. Each diode has an area of $3.8 \times 10^{-5} \text{ cm}^2$ [59]

2. Realized GaN HEMT-based Varactor Diodes

These previous reported works present good performance in term of high breakdown voltage, high Q -factor, and high linearity; however, the limited capacitance tuning range is still a challenge. Furthermore, to achieve good performance, most of these reported works require some changes in epitaxial and mask layer of the GaN HEMT process which results in a complexity of fabrication and cost increasing. These challenges have limited the progress of developing varactor diodes. In order to overcome the two above-mentioned drawbacks, here, for this thesis work, the varactor diode is realized by connecting together the drain and source terminations thus resulting in a single Schottky junction which can be considered as planar schottky varactor diode (PSVD) [68].

The bias potential V_G is then applied across the drain/source and gate terminations. This kind of varactor diodes do not require any additional selective changing in the epitaxial layers of the HEMT process. As a result, a standard GaN HEMT process can be used which minimize their cost production compared to the other reported type of varactor diodes. However, GaN-based PSVDs have not been widely used because of the unavailability of accurate large and small signal models which become our motivations to develop them. We investigate the equivalent

capacitance C_{Eq} and the equivalent series resistance R_{Eq} of the varactor, when the overall impedance is considered as a simple series RC circuit.

3. GaN500v1 and GaN150v0 Varactor Devices

Figure III.15 illustrates the layout design for one varactor device. To compare between the two processes (GaN500v1 and GaN150v0), two samples of each process with different fingers width are studied as detailed in Table III.1:

Table III.1: Presented GaN500v1 and GaN150v0 Devices Information

Device Terminology	Number of Fingers	Fingers Width	Fingers Length	Process Terminology
W40L0.5	2	40 μm	0.50 μm	GaN500v1
W100L0.5	2	100 μm	0.50 μm	GaN500v1
W50L0.15	2	50 μm	0.15 μm	GaN150
W100L0.15	2	100 μm	0.15 μm	GaN150

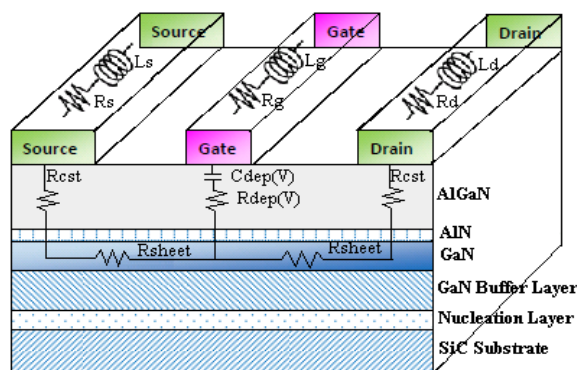


Figure III.15: Schematic cross-section of HEMT, showing contacts and epitaxial structures, and physical equivalent circuit origin at pinch-off ($V_G = -3.5$ V)

The W40L500v1 device is shown in Figure III.16 when it is positioned in Microwave probe test.

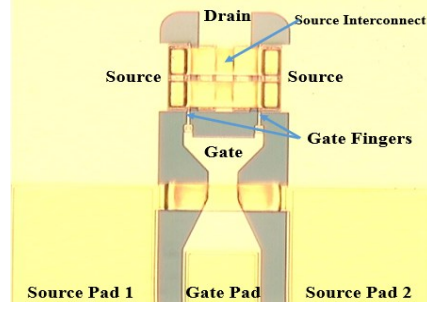


Figure III.16: W40L500v1 Device in Microwave Probe Test

3.1 Small Signal Modeling

The physical origins of the varactor device's equivalent model of both NRC GaN process are shown in the cross-sectional view in Figure III.15. R_g , L_g , R_d , L_d , R_s and L_s are, respectively, the metal resistance and the parasitic inductance of the gate, of the drain and of the source. R_{cst} is the constant resistor and is determined by the AlGaIn layer thickness. For GaN500v1 process, the thickness is about 20nm and R_{cst} is $1\Omega\cdot\text{mm}$. R_{sheet} refers to the channel resistance which is also constant and is determined by the two dimensional electron gas (2DEG), it is $300\Omega/\square$, while R_{dep} represents the resistance under the depletion region which is affected by the bias voltage, V_G , and changes slightly when the channel starts to deplete, this leads to a change in the series resistor of the equivalent circuit. C_{dep} represents the depletion capacitance; it changes significantly with V_G . The physical equivalent circuit shown in Figure III.15 could be transformed to a simple equivalent RC circuit model as shown in Figure III.17.

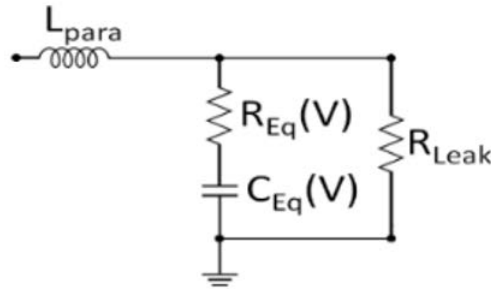


Figure III.17: Varactor equivalent circuit model

L_{para} , R_{Eq} , C_{Eq} and R_{Leak} , respectively, are the parasitic inductor, the equivalent series resistor, the equivalent series capacitance and the leakage resistor when the diode presents forward conduction current flow. The effect of L_{para} is negligible at low frequencies while the value of R_{Leak} is very high (about $8 \text{ G}\Omega$). The on-wafer RF measurements were performed with an Agilent VNA Network Analyzer over a frequency range of 0.1-20 GHz with a RF power of -15 dBm. As can be seen in Figure III.18, Figure III.19, Figure III.20 and Figure III.21, a good match between the experimental results and the simulation model results is generally achieved. For GaN150v0, agreement is nearly perfect, while for GaN500v1 there are some issues with the larger device at high frequencies for -6 V bias. Here the channel is fully depleted and some parasitic inductances are not captured in the equivalent model. For V_G of -3 V, -4 V and -6 V, the parameter values of the equivalent model are presented in Table III.2.

Table III.2: Parameters values of the equivalent circuit

Device	V_G (V)	L_{para} (pH)	R_{Eq} (Ω)	C_{Eq} (fF)
W40L0.5	-3	25	17	205
	-4	25	50	190.7
	-6	25	15.5	82.7
W100L0.5	-3	30	6.9	533
	-4	30	13.3	439
	-6	30	6.16	220
W50L0.15	-3	10	5	148
	-4	10	9.7	98
	-6	10	4.77	40
W100L0.15	-3	20	4.9	286
	-4	20	8.3	189
	-6	20	5	81

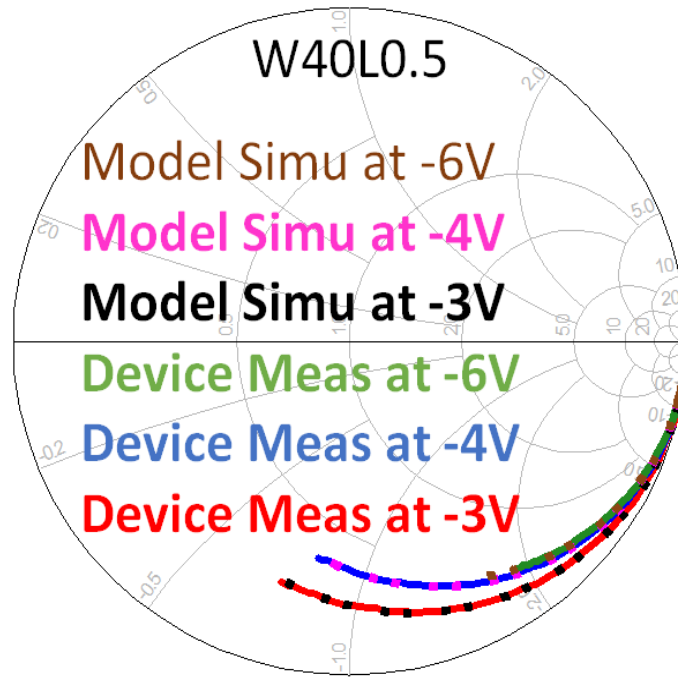


Figure III.18: Measured (lines) and Simulated (Dot) S_{11} -parameter for G W40L0.5

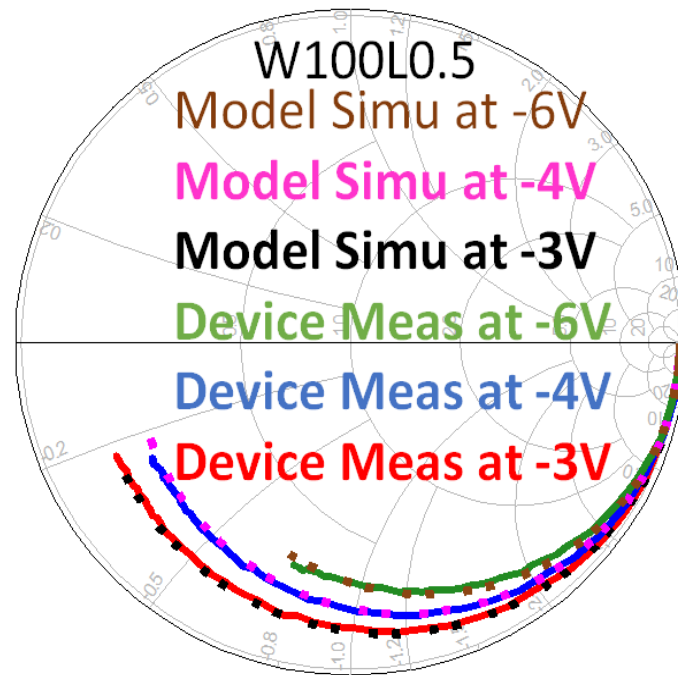


Figure III.19: Measured (lines) and Simulated (Dot) S_{11} -parameter for W100L0.5

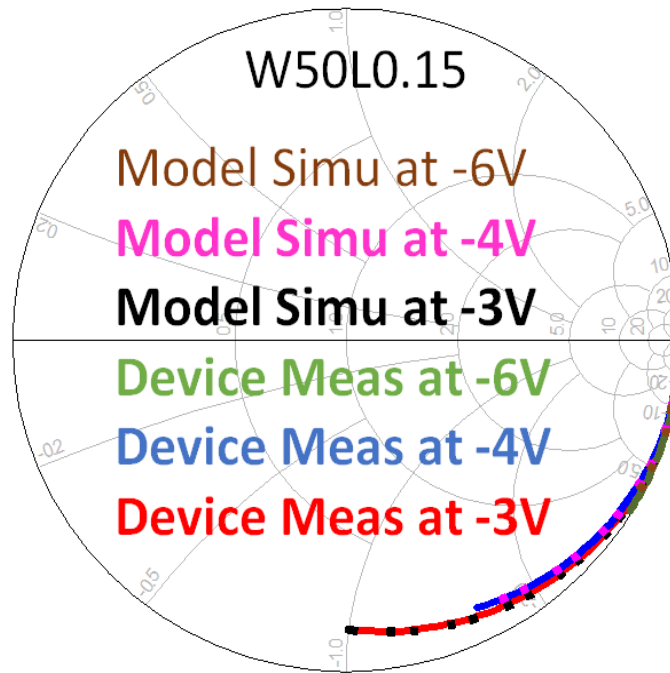


Figure III.20: Measured (lines) and Simulated (Dot) S11-parameter for W50L0.15

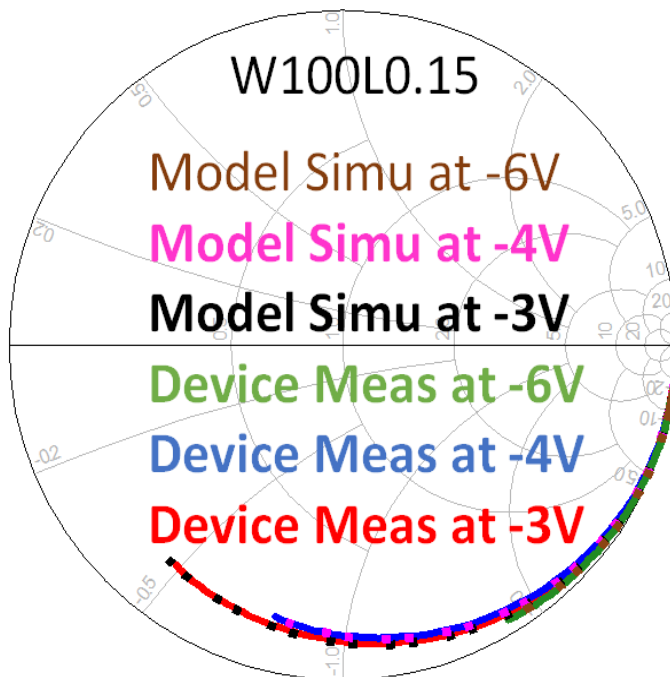


Figure III.21: Measured (lines) and Simulated (Dot) S11-parameter for W100L0.15

3.1.1 Analysis of Equivalent Capacitance

At an operating frequency f , the capacitance values were extracted from the Y-parameters using the Equation (1). The obtained capacitance values versus frequency for one device, are shown in Figure III.22. At $V_G = -3V$, it is seen that the capacitance values remain almost constant over a range of frequency up to 20 GHz, and then the capacitance behavior starts to become erratic due to high frequency parasitic element. This means that at very high frequency, the parasitic gate inductance, L_g , and other effects become self-resonant.

Equation (1)

$$C_{eq} = \frac{\text{img}(Y(1,1))}{2 \cdot \pi \cdot f}$$

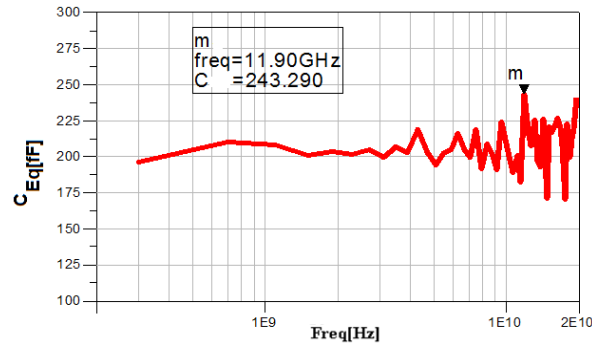


Figure III.22: C_{Eq} versus frequency for the W40L0.5 device at $V_G = -3V$

For both GaN500v1 and GaN150v0, the extracted capacitance values at frequency range up to 10 GHz versus V_G are shown in Figure III.23 and Figure III.24 (red curves). All C_{Eq} versus V_G curves exhibit the same general behavior, which can be separated into three regions: range (1) for V_G above $-3.5 V$, range (2) for $-4.5 V \leq V_G \leq -3.5 V$ and range (3) for $V_G < -4.5 V$.

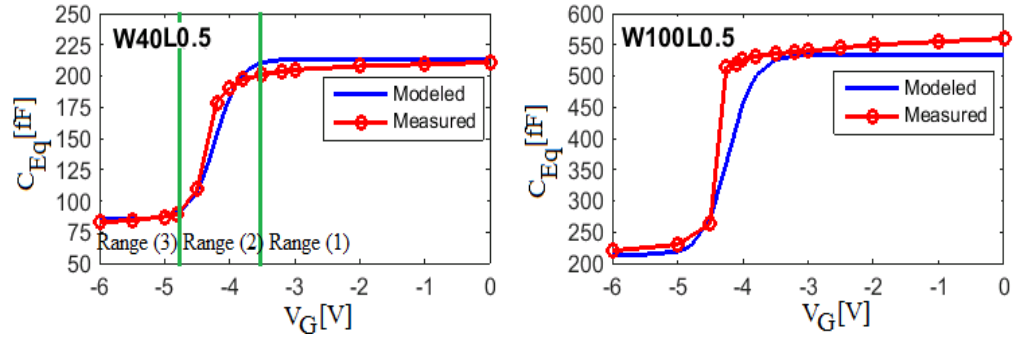


Figure III.23: Extracted and Simulated C_{Eq} versus V_G for GaN500v1 Devices

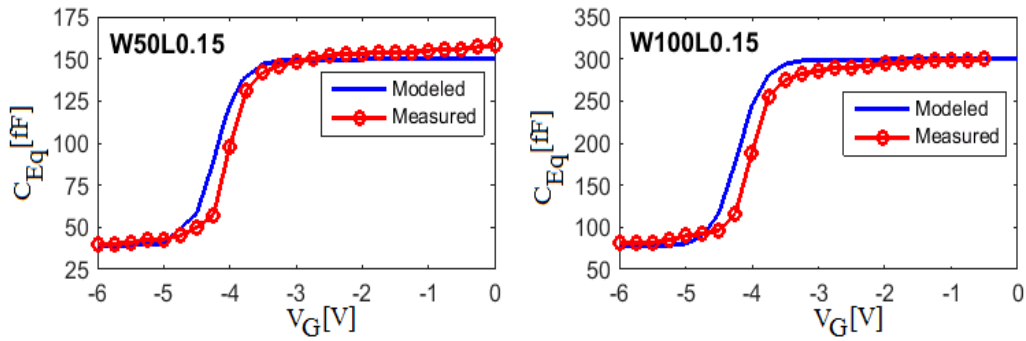


Figure III.24: Extracted and Simulated C_{Eq} versus V_G for GaN150 Devices

For range (1) and range (3) corresponding to the device's C_{MAX} and C_{MIN} , respectively, the capacitance values do not change. However, in range (2), the capacitance values change significantly, and rapidly over a small DC bias range from -4.5 V to -3.5 V. Based on these observations, we conclude that the capacitance tuning range is limited, and the region of variable capacitance exists only over a small reverse voltage of 1V. The capacitance C_{Eq} is given by the following equation:

Equation (2)

$$C_{eq} = \frac{\epsilon r \cdot A}{d} \quad \text{with } A = N \cdot W \cdot L$$

Where, ϵr is the permittivity of the material, A is the finger area, d is the distance between surface and 2DEG channel (or the depth of the depletion region), N is the number of fingers, W and L are the width and the length of finger. From Equation (2), the capacitance value depends on d . In other words, when d varies, this

leads to a change in the capacitance value. The maximum and the minimum C_{Eq} are obtained when the d reaches its minimum (d_{min}) and maximum (d_{max}), respectively. Furthermore, the capacitance value depends on the finger area. The variation in d is controlled by V_G and leading to the change in C_{Eq} which could be summarized as follow:

- Range (1): Before the channel starts depleting; C_{Eq} is at its maximum value where the depletion region is at d_{min} .
- Range (2): The channel starts depleting until it is completely depleted. The depleted region in the channel shrinks quickly, resulting in a rapid increase of C_{Eq} .
- Range (3): The channel is completely depleted; C_{Eq} is at its minimum values where the depletion region is at d_{max} .

In order to describe the nonlinear behavior of C_{Eq} for both GaN500v1 and GaN150v0, analytical equations based on empirical coefficients are derived from the measurements. The exponential of tangent hyperbolic function yields an approximate analytical expression for C_{Eq} versus V_G . It is seen that Equation (3) accurately describes the dependency of junction capacitance upon applied reverse bias, V_G , for all characterized devices.

Equation (3)

$$C_{eq} = 60 \frac{A}{M} \left(1 + \frac{1}{M}\right) (e^{\tanh[2.5V_G + 11]} + k)$$

The parameters M and K can be adjusted to properly fit the C_{Eq} equation to the measured characteristics of an arbitrary varactor size. According to Matlab simulations, the values of M and K can be fixed, respectively, as 40 and 1.2 for GaN500v1 devices and as 20 and 0.45 for GaN150 devices. The modeled curves are plotted in Figure III.23 and Figure III.24 (blue lines). All of these equations are dependent only on finger geometry (number, width and length of fingers) and on V_G . Equation (3) illustrates the behavior of C_{Eq} for GaN500v1 and GaN150v0 devices.

This equation describes the experimental results adequately under small signal excitation.

3.1.2 Analysis of Equivalent Series resistance

The equivalent series resistor contains all the resistors (R_{cst} , R_{sheet} , R_{dep} , R_g , R_s and R_d) presented in Figure III.15. In range (1), before the channel starts being depleted, there is no depletion resistor ($R_{dep} = 0$), leading to have a constant equivalent series resistor. In range (2) when the channel starts depleting, the R_{dep} becomes important and increases until the channel is close to be fully depleted resulting on R_{Eq} values. Over range (3), when the channel is fully depleted, R_{dep} goes to 0 resulting in a constant equivalent series resistor R_{Eq} . In Figure III.25 and Figure III.26, R_{Eq} versus V_G is plotted. R_{Eq} (red curves) is determined by extracting the real part of Z in the equivalent circuit model.

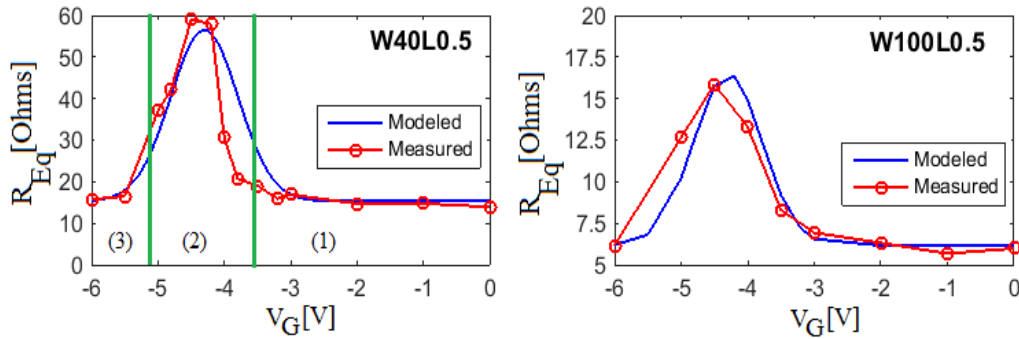


Figure III.25: Extacted and Simulated R_{Eq} versus V_G at 2.5 GHz for GaN500v1

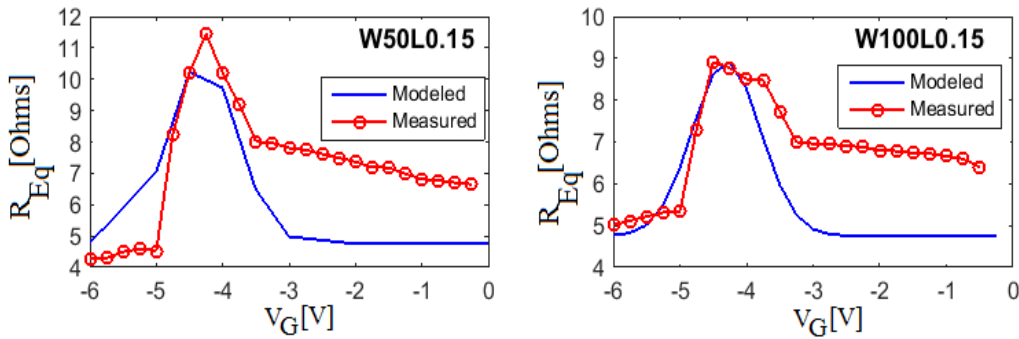


Figure III.26: Extracted and Simulated R_{Eq} versus V_G at 2.5 GHz for GaN150v0

The nonlinear behavior of R_{Eq} for both GaN500v1 and GaN150v0 can be described by analytical equations based on empirical. The R_{Eq} - V_G characteristics is a Gaussian form, as deduced from Figure III.25 and Figure III.26 (red dotted lines). Thus the R_{Eq} - V_G characteristics are taken to be:

Equation (4)

$$Req_{GaN500} = \frac{44}{A} \left[\left(\frac{1}{\sqrt{\frac{W\pi}{Y} 8.10^{-5}}} \right) (e^{-2(Vg+4.35)^2}) + Y \right]$$

Equation (5)

$$Req_{GaN150} = \left[\left(\frac{1}{6\sqrt{\frac{A\pi}{Y} 8.10^{-5}}} \right) (e^{-2(Vg+4.35)^2}) + Y \right]$$

Where A is the finger area. The parameter Y can be adjusted to properly fit the R_{Eq} equation to the measured characteristics of an arbitrary varactor size. According to Matlab simulations, the value Y can be fixed to 14 for GaN500v1 devices and as 4.75 for GaN150 devices. All of these equations are dependent only on finger geometry (number, width and length of fingers) and on V_G . Equation (4) describes R_{Eq} for GaN500v1 devices, while Equation (5) describes R_{Eq} for GaN150v0 devices. These equations describe the experimental results adequately under small signal excitation. Due to these resistance values, a part of the RF available power is consumed by the devices and losses will occur in the RF signal. More R_{Eq} is high more losses are high. A good agreement is obtained, except for R_{Eq} in range (1) of the GaN150v0 devices. A slightly more complicated model would be required here to capture the higher measured R_{Eq} .

3.1.3 Analysis of Q-Factor

In Figure III.27 and Figure III.28, the Q factor is plotted versus frequency. Referring to the equivalent model presented in Figure III.17, the Q factor can be evaluated by the following equation.

Equation (6)

$$Q = \frac{\text{img}(Z(1,1))}{\text{real}(Z(1,1))} = \frac{1}{(2.\pi.f.Ceq.Req)}$$

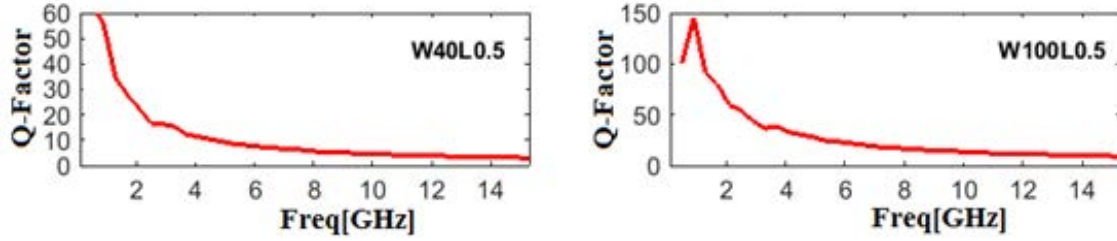


Figure III.27: Extracted Q factor versus Frequency at $V_G = -3.5$ V for GaN500v1

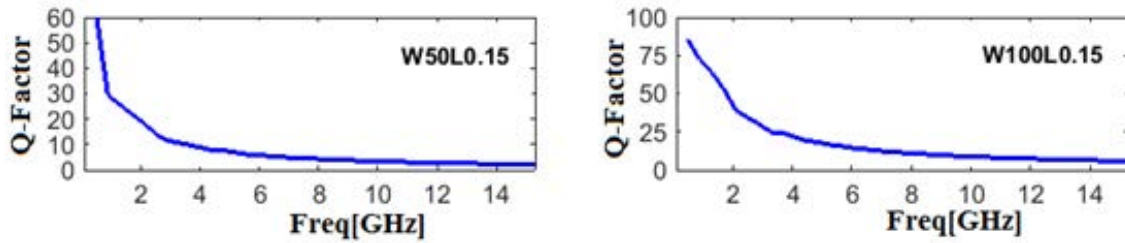


Figure III.28: Extracted Q factor versus Frequency at $V_G = -3.5$ V for GaN150v0

The Q factor decreases with frequency. It is notable that a minimum Q of ~ 25 and ~ 50 was achieved over a range of frequency below 2 GHz, respectively, for GaN500v1 and GaN150v0. Another most common used figure of merit for varactor is the cut-off frequency. The cut-off frequency is defined as the frequency at which the capacitive reactance is equal to the series resistance. Note that the cut-off frequency is also a function of voltage and that it achieves its maximum value at V_B . This FOM indicates that the maximum operating frequency of the circuit is dependent on the series resistance and the equivalent capacitance. FOM should be as high as possible, which can be mathematically given as:

Equation (7)

$$F_{\text{cut_off}} = \frac{1}{(2.\pi.Ceq.Req)}$$

At $f = 2.5$ GHz, maximum values of 164.9 GHz and of 419.2 GHz were achieved, respectively, for W40L0.5 and W100L0.5 at $V_G = -5$ V. While for W50L0.15 and W100L0.15, the maximum obtained values are 770.6 GHz and 335.9 GHz, respectively. These obtained values serve as figure of merit to compare with other varactor diode in terms of frequency operation capability. A comparison between the two GaN processes in terms of capacitor C_{Eq} is presented in Table III.3.

Table III.3: Comparison of capacitance performances between GaN500 and GaN150

	GaN500v1	GaN150v0
Capacitance	2.7fF/um	1.5fF/um
C_{MAX}/C_{MIN}	2.4	3.7
Tuning Voltage	-4.5 V to -3.5 V	-4.5 V to -3.5 V

4. GaN500v2 Varactor Devices

To conduct this second varactors modeling study, many samples with different sizes have been fabricated with the GaN500v2 process but only three of them are presented here (see Table III.4). The presented devices are W50L0.5, W100L0.5 and W200L0.5 (different fingers width).

Table III.4 : Presented GaN500v2 Devices Information

Device Terminology	Number of Fingers	Fingers Width	Fingers Length	Process Terminology
W50L0.5	2	50 μm	0.50 μm	GaN500v2
W100L0.5	2	100 μm	0.50 μm	GaN500v2
W200L0.5	2	200 μm	0.50 μm	GaN500v2

4.1 Small Signal Measurement

The on-wafer RF measurements were performed with an Agilent VNA Network Analyzer over a frequency range of 0.1-20 GHz with a fixed RF power of -15dBm, while the control voltage at the gate of varactors, V_G , was swept from 0 V to -10 V with a step of -0.1 V. Because it was observed that from 0 V to -3 V, the measured results are similar and also from -5 V to -10 V measured results are similar. So only measurements from -2 V to -6 V will be treated and analysed here. As can be

seen in Figure III.29, Figure III.30 and Figure III.31, a good match between the experimental results and the simulation model results is generally achieved. For W100L0.5 and W200L0.5, agreement is nearly perfect, while for W50L0.5 there are some issues with this device at high frequencies. Here some parasitic inductances are not captured in the simple proposed equivalent model. As detailed previously, there are three main ranges that describe the change in the parameters of the varactor model. Range (1) and range (3) corresponding to the device's C_{MAX} and C_{MIN} , respectively, while, range (2) corresponding to the tuning capacitance range. Table III.5 summarizes the parameter values of the equivalent model at three bias voltage, such as, V_G of -3 V (in range 1), -4 V (in range 2) and -6 V (in range 3).

Table III.5: Parameters values of the equivalent circuit

Device	V_G (V)	L_{para} (pH)	R_{Eq} (Ω)	C_{Eq} (fF)
W50L0.5	-3	5	7.9	466
	-4	5	11	375
	-6	5	9.5	279
W100L0.5	-3	16	5.3	870
	-4	16	7.35	637
	-6	16	6.5	501
W200L0.5	-3	100	4.7	1810
	-4	100	5.85	1403
	-6	100	5.2	1016

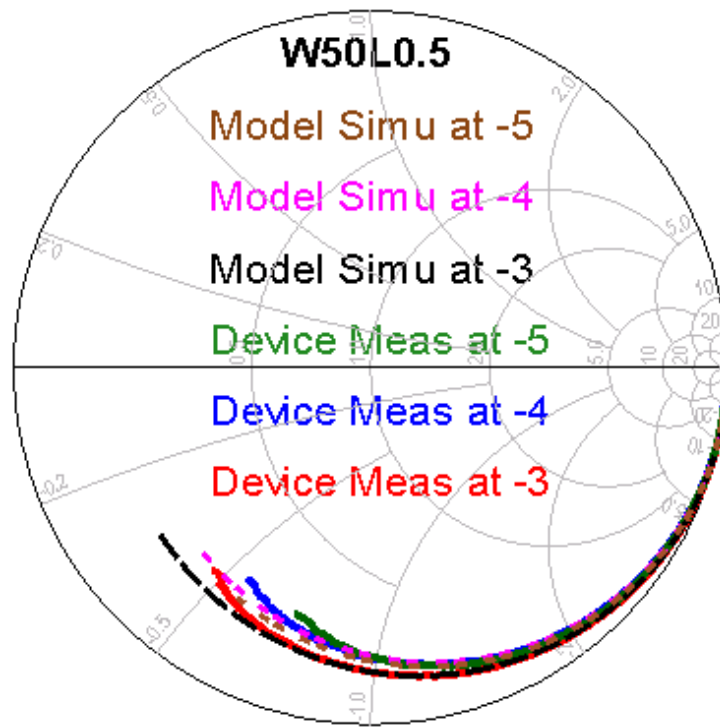


Figure III.29: Measured (lines) and Simulated (Dot) S11-parameter for W50L0.5

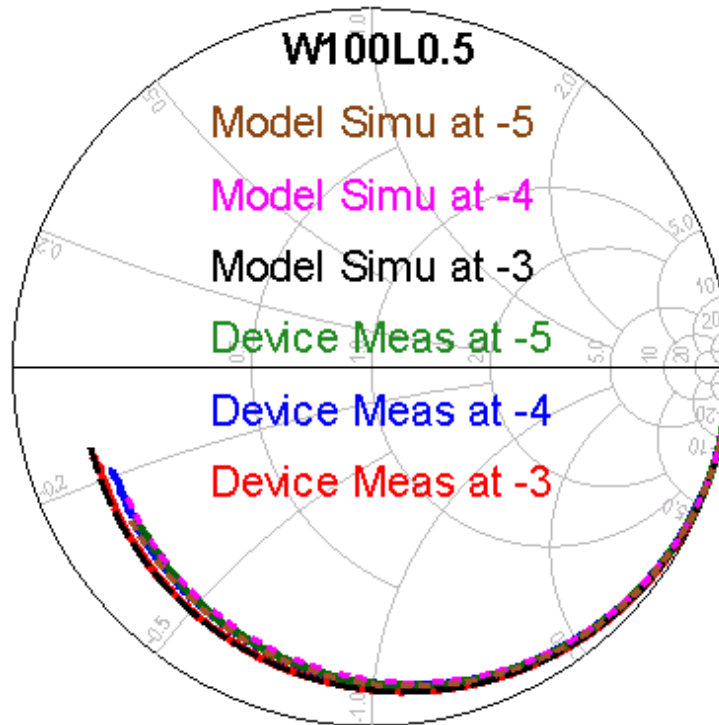


Figure III.30: Measured (lines) and Simulated (Dot) S11-parameter for G W100L0.5

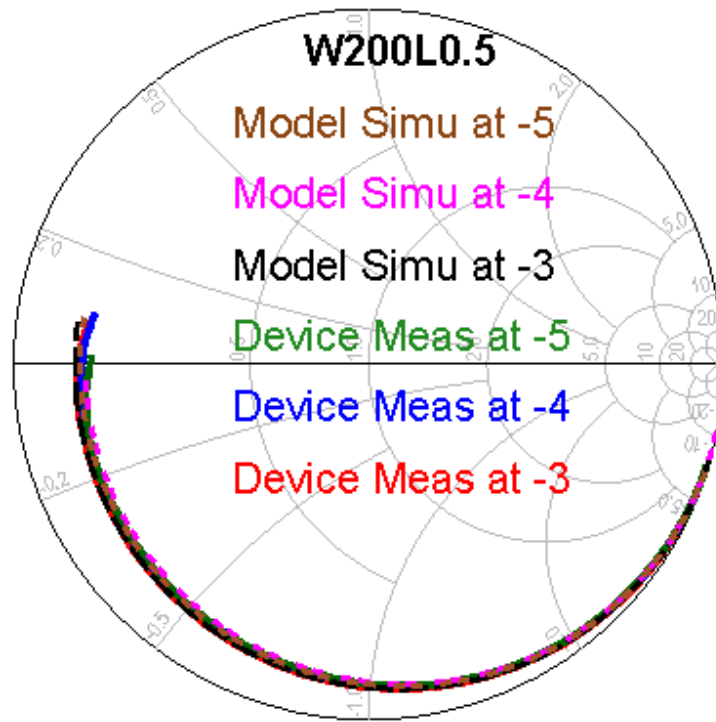


Figure III.31: Measured (lines) and Simulated (Dot) S_{11} -parameter for G W200L0.5

4.1.1 Analysis of Equivalent Capacitance

The same analysis drawn before for GaN500v1 devices will be also used here to discuss and develop the extracted equivalent capacitance values for GaN500v2 devices.

As previously mentioned, the capacitance values were extracted from the Y-parameters using Equation (1). The obtained capacitance values versus frequency for one device (W50L0.5), are shown in Figure III.32. At $V_G = -3$ V, it is seen that the capacitance values remain almost constant over a range of frequency up to 8 GHz, and then the capacitance starts to decrease due to high frequency parasitic elements. This means that at very high frequency, the parasitic gate inductance, L_g , and other effects become self-resonant.

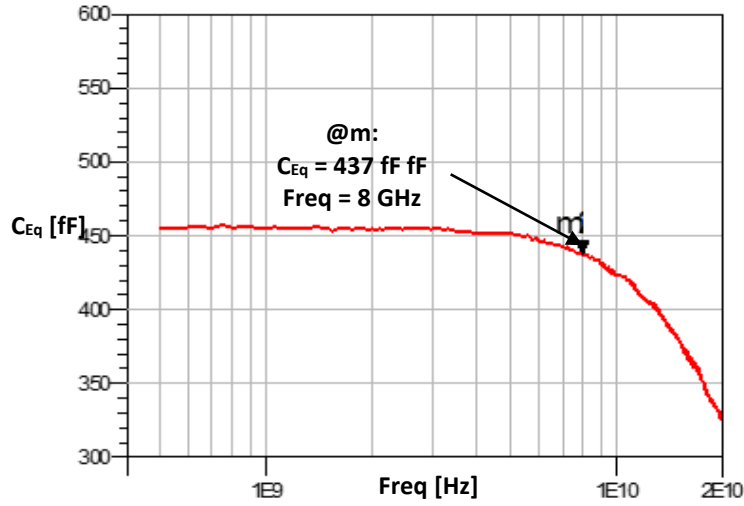


Figure III.32: C_{Eq} versus frequency for the W50L0.5 device at $V_G = -3V$

For all devices W50L0.5, W100L0.5 and W200L0.5, the extracted and the modeled capacitance values versus V_G are, respectively, shown in Figure III.33, Figure III.34, and Figure III.35. These extracted values are valid over a frequency range frequency up to 8 GHz where C_{Eq} starts drops versus frequency (see Figure III.32). As can be seen from these three figures, it should be mentioned that poorer agreement for large W (larger device) is a model optimization issue. This means that a slightly more complicated model would be required here to capture the all the parasitic elements for larger devices.

It is noted that the Equation (3) presented before for GaN500v1 devices is used here to describe the behavior of C_{Eq} versus V_G . It validates the general use of this proposed equation for GaN-based varactor devices. Only the parameters M and K were adjusted to properly fit the C_{Eq} equation to the measured characteristics of an arbitrary varactor size. For GaN500v2, the values of M and K were re-optimized to fit the model with the measurements, respectively, are 66 and 2.4. As mentioned before, for GaN500v1 devices, this equation is dependent only on sample size (number, width and length of fingers) and on V_G . As can be seen, C_{Eq} versus V_G characteristics exhibit the same general behavior observed for GaN500v1 devices, which is separated into three regions as discussed before.

The maximum value of capacitance (before the channel starts depleting) is observed for $-3.4 \text{ V} \leq V_G \leq 0 \text{ V}$ (range 1) and values of 466 fF, 870 fF and 1810 fF were extracted, respectively, for W50L0.5, W100L0.5 and W200L0.5 designs. While the minimum value (the channel is completely depleted) is observed for $-10 \text{ V} \leq V_G \leq -4.5 \text{ V}$ (range 3) and values of 278 fF, 501 fF and 1016 fF were extracted for, respectively, W50L0.5, W100L0.5 and W200L0.5 designs. As a result, $C_{\text{MAX}}/C_{\text{MIN}}$ ratio about 1.7 is achieved for all devices. In addition, it was observed that C_{MAX} and C_{MIN} values remain almost constant over a range of frequency up to almost 8 GHz and then starts to drop significantly due to high frequency parasitics. The -3.4 V represents the pinched of voltage of this device where the channel starts depleting. As highlighted before for GaN500v1 devices, in range (2), the capacitance values change significantly and rapidly over a small DC bias range of 1 V. This behavior is also observed for the devices using the GaN500v2.

Because we are essentially focused on the range (2) where capacitance values change significantly, the x-axis of all C-V plots is delimited from -2 V to -6 V . Values from 0 V to -2 corresponding to C_{MAX} are stable as well as ones from -6 V to -10 V corresponding to C_{MIN} .

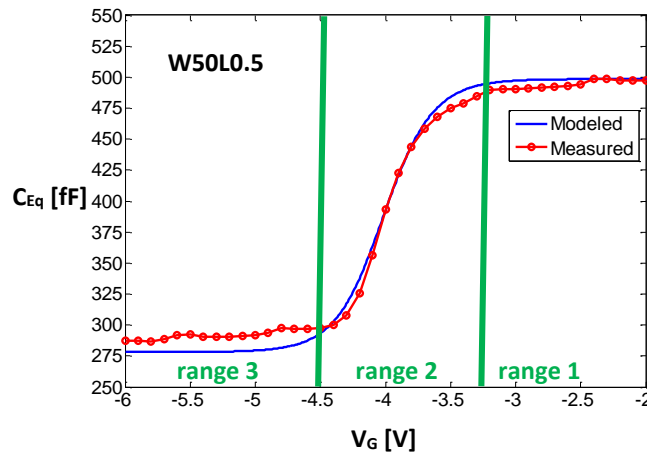


Figure III.33: Extracted and Simulated C_{Eq} versus V_G for W50L0.5

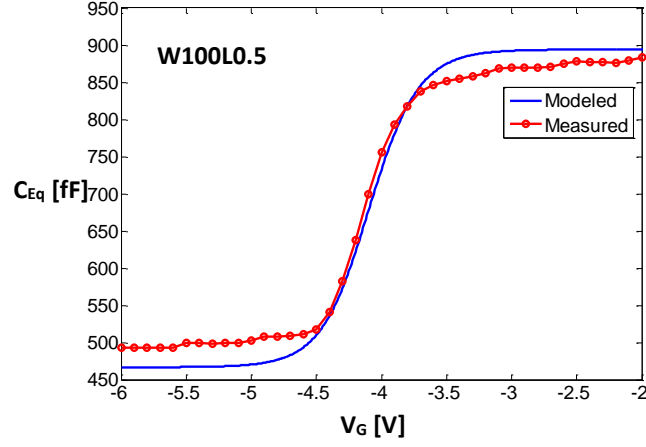


Figure III.34: Extracted and Simulated C_{Eq} versus V_G for W100L0.5

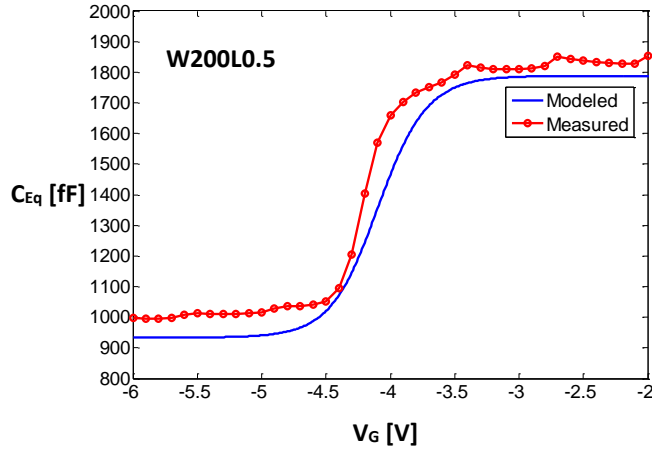


Figure III.35: Extracted and Simulated C_{Eq} versus V_G for W200L0.5

By comparing equivalent capacitance values extracted from GaN500v1 samples and from GaN500v2 samples, it was revealed that the achieved capacitance values from a device size manufactured with GaN500v2 are at least twice larger than those achieved with the same device size fabricated with GaN500v1 process. However, the overall calculated C_{MAX}/C_{MIN} ratios for GaN500v2 devices are smaller (~ 1.7) than ones calculated from GaN500V1 devices (~ 2.4). This significant change in equivalent capacitance values is essentially due to the additional field plate layer added in GaN500v2. As discussed in the GaN500 design manual provided by NRC, it should be pointed out that all devices included in GaN500v1, do not employ field plate

designs. However, the shape of the gates, using GaN500v1, results in better frequency performance, but slightly lower breakdown voltage compared to GaN500v2. For GaN500v1, values of 27 GHz and 75 GHz were reported by NRC, respectively, for f_T and for f_{max} . The process is suitable for 20V maximum drain voltage bias. While for GaN500v2 process, a field plated design is included in this version, and devices exhibit much lower gate leakage than in GaN500v1. However, RF performance frequency decreased; a f_T of 12 GHz and f_{max} of 24 values were measured and reported for this version. The process version is suitable for 40V maximum drain voltage, and yields power levels of ~ 5 W/mm. We assume that this additional field plate layer is the main parameter behind the significant increase in the equivalent capacitance values.

4.1.2 Analysis of Equivalent Series Resistance

The equivalent series resistor extracted from measurement versus bias voltage is depicted in Figure III.36 for all studied devices. This series resistor is not impacted by the frequency, so these extracted values are valid at all frequencies. Here the same general behaviour observed before for GaN500v1 is also noticed for the devices fabricated with GaN500v2, expect that the values of the series resistor are significantly different from a process version to another one.

Unlike the GaN500v1 devices where an analytic expression was introduced to describe the behavior of R_{Eq} versus V_G , here for GaN500v2 devices, as can be clearly seen the equivalent series resistor values do not change significantly and this is observed for all devices, so a mean value can be adopted as a fixed value to describe the R_{Eq} for a specific device size. In addition, it was observed that more the device size increases more the R_{Eq} decreases. The maximum peak value of R_{Eq} is observed on range (2) when the channel starts depleting because the depletion resistor (R_{dep}) becomes slightly important and increases until the channel is close to be fully depleted. This behavior has been also observed for GaN500v1 process' devices. It should be pointed out the overall series resistor values extracted from GaN500v2

devices are smaller than ones found with the previous process version (GaN500v1). In our point of view, this significant drop in series resistor can be due to the development occurred out on the stack of epitaxial layers and masks of the process to reduce the dynamic on-resistance and the Ohmic contact resistance that are constituting the series equivalent resistor (R_{Eq}).

As mentioned in chapter II, the trapping electrons phenomena in AlGaN/GaN HEMTs structure is directly reducing the sheet electron density in the channel, leading to increase dynamic R_{on} and provoking drain current dispersion. Moreover, many efforts for high performance AlGaN/GaN HEMTs have been made to suppress this current dispersion issue and increased R_{on} , which are directly related to modification of surface/interface states in AlGaN/GaN heterostructures. These modifications are surface passivation [60], a thin AlN barrier layer in AlGaN/GaN interface [61], application of a field plate [62], surface treatments with chemicals or plasma [63], and postgate-annealing [64]. On the other hand, in spite of the rapid development and the studies of GaN-based HFETs, achieving a low Ohmic contact resistance value still one important issue concerning these devices [65]-[66] and has a great effect on the output signal during device operation. Low Ohmic contact resistance is crucial to realization of good RF and power performances of AlGaN/GaN HEMTs heterojunction devices. As a matter of fact, in terms of power consumption, high Ohmic contact resistance values cause high electrical power losses and increase self-heating problem. For example, if the contact resistor is decreased from 10^{-5} to $10^{-6} \Omega\text{cm}^2$, a reduction of 60% of the power consumption could be achieved for devices with breakdown voltage of 600 V [67].

Due to the restricted information, we could not have information on how NRC group researchers have improved GaN500v2 process to reduce the Ohmic contact resistance or/and R_{on} . However, it is reported, by NRC in design manual of GaN500v2 [31], that a field plate is applied to all devices fabricated with GaN500v2.

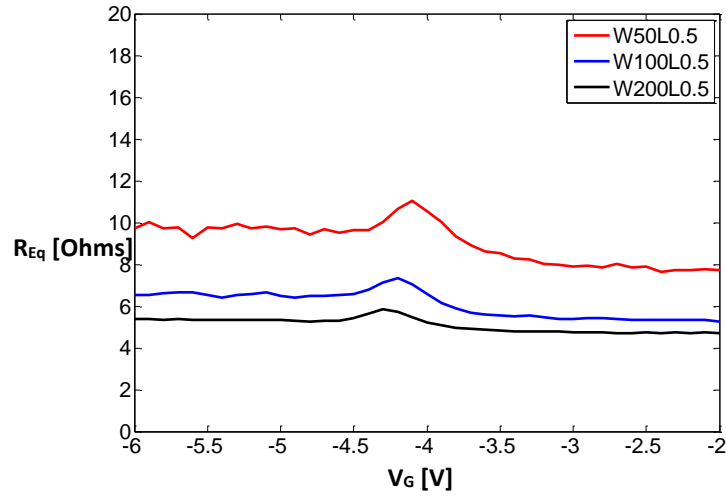


Figure III.36: Extracted R_{Eq} versus V_G for GaN500v2 Devices

A comparison between the two GaN500 processes, in terms of model circuit parameters (C_{Eq} , R_{Eq} and L_{para}) is presented in Table III.6.

Table III.6: Model Circuit Parameters Values

Device	V_G (V)	GaN500v1 Process			GaN500v2 Process		
		L_{para} (pH)	R_{Eq} (Ω)	C_{Eq} (fF)	L_{para} (pH)	R_{Eq} (Ω)	C_{Eq} (fF)
W50L0.5	-3	25	17	205	5	7.7	466
	-4	25	50	190.7	5	9.95	375
	-6	25	15.5	82.7	5	9.2	279
W40L0.5	-3	30	6.9	533	16	5.2	870
	-4	30	13.3	439	16	6.9	637
	-6	30	6.16	220	16	6.2	501
W200L0.5	-3				100	4.7	1810
	-4				100	5.6	1403
	-6				100	5.2	1016

4.2 Large Signal Measurements

As we have just presented, the small signal analysis leading to propose a circuit model has been discussed. In addition, analytical expressions describing the general behavior of C_{EQ} and R_{EQ} for several DC bias were introduced. Following our original modeling and analysis of GaN-based varactor diodes, by using only a standard GaN HEMTs process; here, the effect of larger power signal is studied and presented to complete the analysis of GaN varactor small and large signal modeling. Unlike to GaN500v1 devices, the newly developed version of GaN500v2 is used for manufacturing the samples which have been measured in large signal measurements.

Here the measurement calibration has been done at a fundamental frequency of 5 GHz. The measurement method consists in performing periodic CW time-domain large-signal load-pull RF measurements using Large-Signal Network Analyzer (LSNA). The LSNA can measure the harmonics of the high voltages and high currents at the DUT planes from 1GHz up to 18 GHz with a dedicated test bench. Thanks to on-wafer absolute and relative calibrations with absolute phase reference of LSNA, the time-domain RF voltages and currents (at fundamental and harmonic frequency [f0, 2f0 and 3f0]) and periodic CW power performance are obtained at the DUT planes. The choice of this frequency of 5 GHz was made for the reason that the equivalent capacitance versus frequency (as shown in Figure III.32) do not change up to around 8 GHz, and because one of these studied varactor will be used for frequency reconfigurable antenna around 7 GHz. For this, large signal analysis will be conducted around 5 GHz and we assume that this analysis is valid for all frequencies below 8 GHz. In addition, the RF power was swept from -15 dBm to 18 dBm (maximum output power from the source) while the V_G was also swept from -3 V to -6 with a step of -0.2 V.

The aim of this section is to propose an accurate analytical large signal model for GaN varactor diodes that could be used as general model, which offers the

ability to describe the behavior of the device at high power levels and for various bias points. The large signal analysis of the devices, which includes the impact of RF power on the C_{EQ} and R_{EQ} values is established and explained. In addition, the nonlinear model behavior of C_{EQ} - V_G characteristics is described by a simple analytical expression based on empirical coefficients which are derived from the large signal measurements. This developed analytical equation is valid for a linear size-scaling and is introduced for the voltage and RF power dependency of C_{EQ} .

4.2.1 Analysis of Equivalent Capacitance

In order to describe the nonlinear behavior of C_{Eq} impacted by the injected RF power, an analytical equation based on empirical coefficients is derived from the measurements. This developed equation (see Equation (8)) is based on the one (Equation (3)) proposed before to describe C_{EQ} - V_G curve for small signal which was only V_G dependency. However, the influence of RF power has been taken into account in Equation (8) to approximately describe C_{Eq} versus V_G for various power levels. It is seen that Equation (8) accurately describes the dependency of junction capacitance upon applied reverse bias as well as upon RF power for all characterized devices. The C_{Eq} - V_G curve can be expressed by the following analytic equation:

Equation (8)

$$C_{eq} = \left(\frac{B}{C}A\right)\left[\left(1 + \frac{1}{C}\right)\left(e^{\tanh[(Vg+F)(G-HPin)+I]}\right) + k\right]$$

Where A is the finger area. The parameters B, C, F, G, H, I and K were adjusted to properly fit the C_{Eq} equation to the measured characteristics of an arbitrary varactor size. According to Matlab simulations, the values of these empirical coefficients can be fixed for all devices, respectively, to 67, 44.4, 4.1, 1.5, 0.0565, 0.4 and 2.8. Equation (8) is dependent only on three main parameters, which are: finger geometry (number, width and length of fingers), bias voltage (V_G) and RF power (P_{in}). Due to their small size and to avoid breaking down the devices, we did

not use any driver power amplifier to apply larger RF signals. It was noticed that above 5 dBm, the value of C_{Eq} starts being affected by the power level.

Figure III.37, Figure III.38 and Figure III.39 show the measured and the modeled equivalent capacitance values versus V_G for various RF power levels (P_{in}), respectively, for W50L0.5, W100L0.5 and W200L0.5. It can be seen that all C_{Eq} - V_G curves exhibit the same general behavior. Under small power levels up to 5 dBm, this behavior can be separated into three regions which are range (1) for V_G above -3.4V, range (2) for $-4.5V \leq V_G \leq -3.4V$ and range (3) for $V_G < -4.5V$. However, more the power level increases more range (2) is extended. For range (1) and range (3) corresponding to the device's maximum (C_{MAX}) and minimum (C_{MIN}) values, the capacitance values do not change significantly versus V_G . In range (2), the capacitance values change appreciably and rapidly over a small DC bias range from -4.5 V to -3.4 V. This bias range extends as well as the power is increased. However, the C_{MAX} and the C_{MIN} values, respectively, decrease and increase as well while the input power increases. This means that the C_{MAX}/C_{MIN} ratio drops significantly, resulting in device saturation and non-linearity at high power levels.

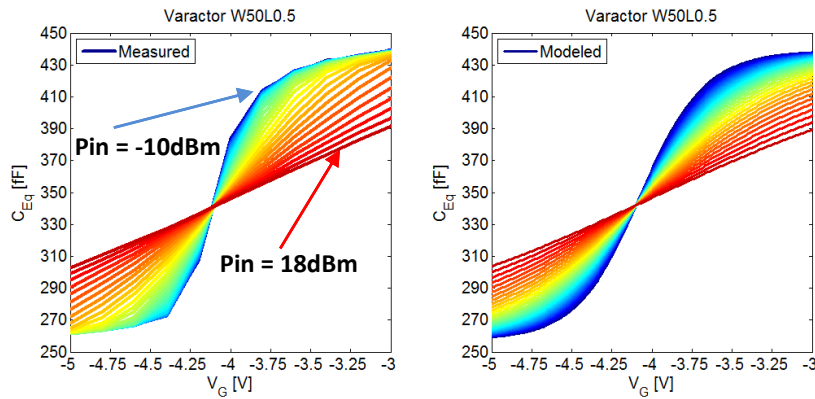


Figure III.37: Extracted (left) and Simulated (right) C_{Eq} versus V_G for various power levels [-10, 18] dBm for device W50L0.5

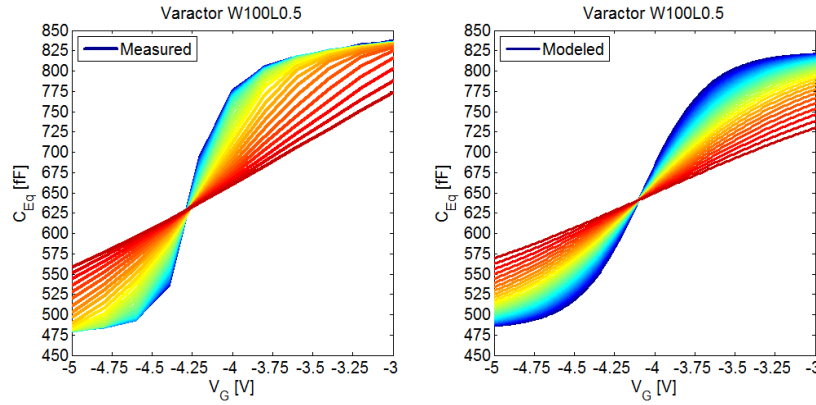


Figure III.38: Extracted (left) and Simulated (right) C_{Eq} versus V_G for various power levels $[-10, 18]$ dBm for device W100L0.5

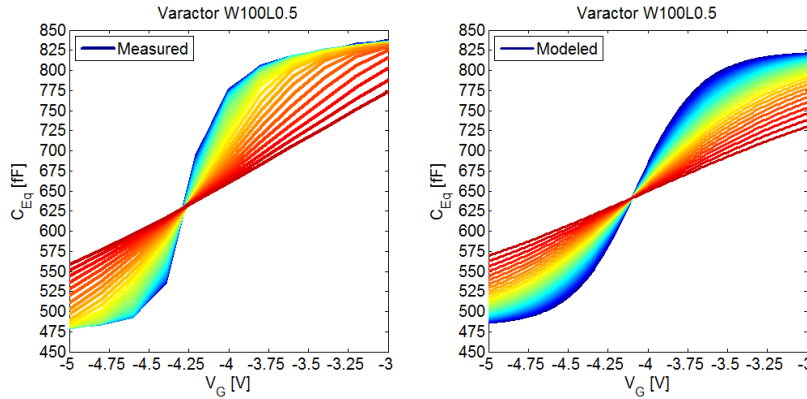


Figure III.39: Extracted (left) and Simulated (right) C_{Eq} versus V_G for various power levels $[-10, 18]$ dBm for device W200L0.5

4.2.2 Analysis of Equivalent Series Resistance

R_{Eq} versus V_G for various power levels are extracted and are depicted in Figure III.40. As can be seen from the R_{Eq} - V_G characteristics, the extracted value of R_{Eq} varies from 3 Ω to 6 Ω for W50L0.5, from 2.7 Ω to 4.4 Ω for W100L0.5 and from 3.4 Ω to 4.4 Ω for W200L0.5. So a mean value can be fixed to describe the behavior of the series resistor at any RF power level from -10 dBm to 18 dBm, as well as at any bias voltage V_G . These values of R_{Eq} are significantly smaller than those reported before for the GaN500 v1 devices. Due to these series resistor, a part of the RF available power (P_{av}) is consumed by the devices. For example, for the W50L0.5

varactor (the one has highest R_{Eq}), Figure III.42 clearly illustrates this power consumption (P_{con}) which follows the variation of the R_{Eq} and which slightly impacted by voltage V_G and the RF power. Figure III.41 (left) meanwhile depicts the power at the input of the device (P_{av}) after removing losses through the RF cable (between source and device under test) and Figure III.41 (right) illustrates the reflected power (P_{ref}) by the varactor. P_{src} represents the power delivered by the source.

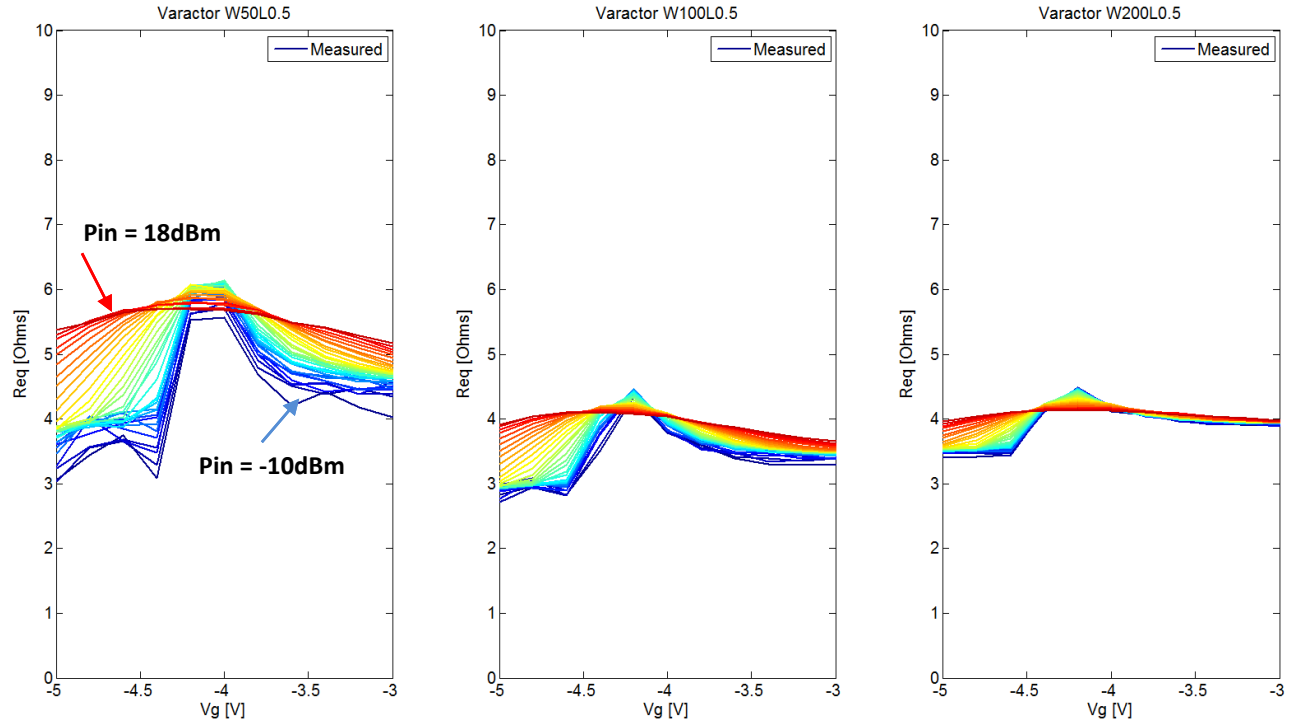


Figure III.40: Extracted R_{Eq} versus V_G for various power levels $[-10, 18]$ dBm for device W50L0.5 (left), for W100L0.5 (middle) and for W200L0.5 (right)

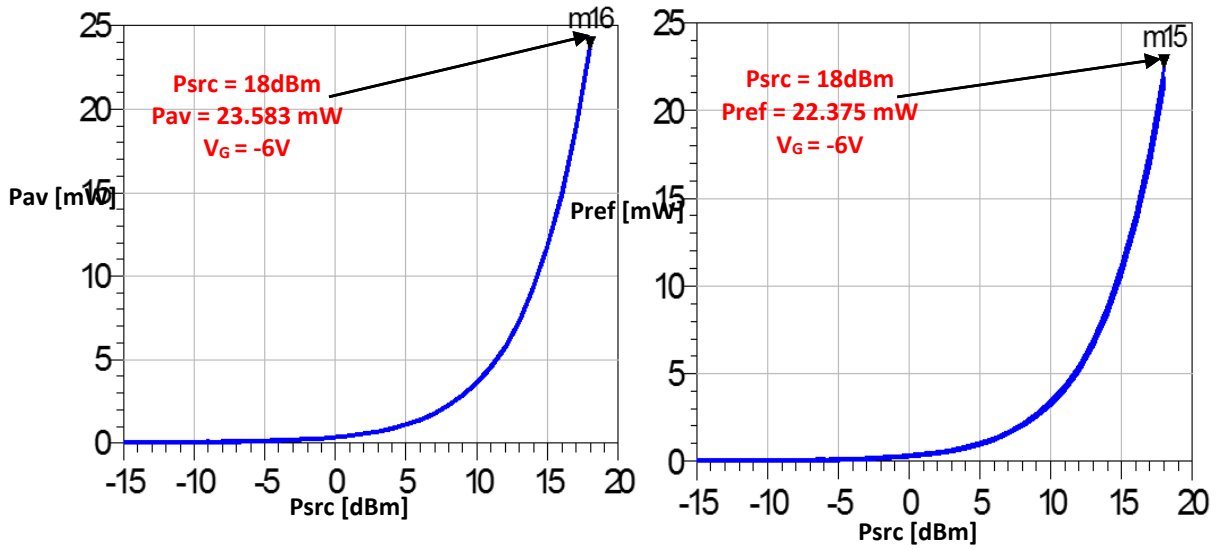


Figure III.41: Extracted Available (left) and reflected (right) RF Power versus Power from Source for various DC Points for W50L0.5

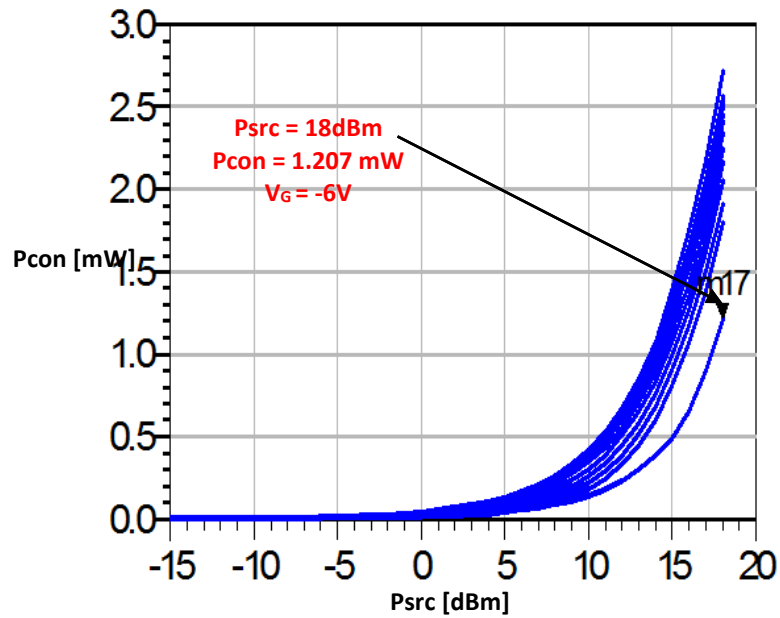


Figure III.42: Extracted Delivered RF Power versus Power from Source for various DC Points for W50L0.5

5. Summary

The varactor devices structure studied here is based on NRC GaN processes. Three GaN HEMTs process, such as, GaN150v0 with a gate length of 0.15 μm , GaN500v1 with gate length of 0.5 μm and GaN500v2 which is the developed version of GaN500v1, have been used for manufacturing the varactors diodes.

Small signal analysis has been done for all fabricated devices. Equivalent capacitance and series resistor behaviors have been detailed, and it was revealed that all C_{Eq} versus V_{G} exhibit the same general behavior for all devices. In addition, the capacitance tuning range is limited, and the region of variable capacitance exists only over a small reverse voltage of 1V. Furthermore, the capacitance value depends on the finger area. This means that larger is the device, higher are the capacitance values. Moreover, it was observed that the extracted capacitance values from varactors with GaN500v2 are at least twice larger than those extracted with the same device size fabricated with GaN500v1 process. This is due to the additional field plate layer in GaN500v2 process. It was, also, observed that the devices manufactured with GaN500v2 and GaN150v0 have lower series resistor value than those value reported with GaN500v1 devices. Two analytic equations describing the behavior of equivalent capacitance and series resistor versus bias voltage were proposed. These equations are only bias voltage and device geometry dependency.

Large signal analyses have been done only for devices manufactured with GaN500v2 process. The influence of RF power has been taken into account and an analytic expression was proposed to approximately describe equivalent capacitance versus bias voltage for various power levels. This equation accurately describes the dependency of junction capacitance upon applied reverse bias as well as upon RF power for all characterized devices.

This modeling work has led to one published journal paper [149] and one other submitted to IEEE Transactions on Device and Materials Reliability in August

2016 [151]. A conference paper has been also presented in European Microwave Conferences in Paris in 2015 [150].

III. GaN-based Switch Devices Modeling

1. Review of GaN HEMT for Power Switching Devices Applications

As previously mentioned in the introduction section, GaN-based switch components is a part of the proposed thesis research. The main aim of this part is to conduct a complete modeling GaN-based switch study using a GaN HEMT process from NRC. Our investigation was planned to consider both small and large signal analysis. Here in this section, different sizes single standalone switches and switch structures such as single pole single throw (SPST) and single pole double throw (SPDT) were fabricated using NRC GaN500v2 and will be presented. Due to our incapability to have large signal measurement facilities, only small signal measurement will be presented and discussed. An accurate large signal model requires extensive laboratory equipment to extract all the effects related to high power GaN devices, such as thermal and trapping effects typically present in GaN devices. Carleton University is not as well equipped with these laboratory facilities as are the NRC or IETR.

The fabricated switch circuits will be integrated with antenna system to realize and to demonstrate the ability of using GaN devices for a steering beam antenna array that will be presented later in chapter IV.

As a promising high power handling alternative, GaN technology is expected to be a good candidate for the realization of high power HEMT-based switches [69]-[70]. The HEMTs suitability for switch usage stems from the fact that the RF path between source and drain is considered as a voltage-controlled resistor [71]. The DC bias applied to the gate controls the two states of switching “ON and

OFF states”, with no DC bias applied to source or drain. In addition to this controlled-resistance there is also a capacitance associated with the HEMT structure. In other words, the equivalent circuit of a HEMT-based switch could be a simple variable resistor and capacitor in the path of the RF signal, as shown in Figure III.43. However, in practice a more complex model is used to model the GaN HEMTs-based switch. Subsection d explains in detail the modeling of the GaN switch.

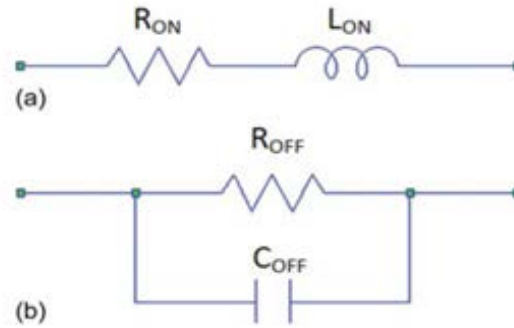


Figure III.43: Simple Model for a HEMT in the switch configuration (a) ON-state and (b) OFF-state mode

Over the last fifteen years, GaN HEMT-based switch circuits started appearing among the other semiconductor technologies, due to their improved material quality which gives GaN power switching devices an advantage for high power/frequency applications. The first preliminary investigation for RF switching devices using GaN has been suggested in 2001 [72]. Several reported works are based on simple standalone transistor or single pole double throw (SPDT) switch structures. They demonstrated an extremely linear power handling of 43 W (10 times higher than that of typical GaAs-based switch ICs) at 1 GHz with excellent performance in terms of insertion loss (-0.26 dB) and isolation (-27 dB) [73]-[74]. Another AlGaIn/GaN HEMT SPDT switch [75] has been realized and the measurements showed values of -0.87, -0.96, -1 dB insertion loss and -46, -42 and -41 dB isolation at 0.9, 1.8 and 2.1 GHz respectively. The switch also shows linear performance for power levels up to 1 Watt in the insertion mode and more than 2 Watts in the isolation mode. Due to its good characteristics, GaN technology could be extended to high frequency switch

applications without the need for purely resonant operation. This leads to some advantages such as switch size and ease of design [76]. As a result, many SPDT switches have already been successfully demonstrated around X-band, Ku-band or higher frequency. One of these works is [77] where an AlGaIn/GaN HEMT Ku-band SPDT switch has been reported with an insertion loss of -1.4 dB, isolation of -35 dB, and 36 dBm output power at 18 GHz. Clearly, this work demonstrates the high power capabilities of GaN technology at high frequency for switch device.

Improving the isolation of GaN switch circuits over large frequency bands was a reason leading to the use of resonance inductors in parallel with the HEMTs. Based on this technique, [78] presents an X-Band GaN SPDT MMIC switch with over 25 Watt linear power handling. The achieved isolation, for this work, is around -35 dB in X-band, while the insertion loss was high and was about -3.5 dB. This insertion loss is high due to the on-resistor value of the device. Continuing with the same concept, a PhD student, Tyler Neil Ross, from the Department of Electronics (DOE) at Carleton University, developed high-power broadband GaN HEMT SPST/SPDT switches based on resonance inductors and shunt-stacked transistors [79]. For the SPST an insertion loss less than -3 dB and isolation better than -13 dB from DC to 20 GHz were achieved, while for SPDT an insertion loss better than -2 dB, an isolation higher than -20 dB and a power handling at 1 dB compression (P1dB) greater than 10 W were reported. Going higher in frequency, in [80] a Ka-Band high power GaN SPDT switch MMIC was demonstrated with unprecedented 49 dBm at P1dB. Measured insertion loss is better than -1.3 dB over 27-31 GHz, and the minimum insertion loss of -0.8 dB has been achieved at higher frequencies. Measured isolation is greater than -25 dB over 27-31 GHz, with the highest isolation of -30 dB at higher frequencies.

Clearly, this literature review shows that GaN-based switches can achieve impressive high power handling capability beyond that of other wide band

semiconductor technologies. In addition, excellent performances in terms of isolation and insertion loss can be achieved.

2. NRC GaN Switch Modeling

The AlGaN/GaN HEMTs switches investigated in this thesis work were fabricated by the National Research Council of Canada (NRC). In this process, there is considerable doubt that the provided models are accurate for switching applications because only transistors in common source configuration for power amplifier purposes are provided. In this section, a brief review of GaN modeling will be discussed. Then, a small-signal transistor model useful for analyzing and designing GaN switching circuits using this foundry will be presented.

2.1 Proposed GaN Single Switch Model

The modeling part is crucial in HEMT circuit designs. A good model certainly relies on a circuit simulation tool that provides the capability to determine circuit performance with high accuracy against prototype measurements. Also, it allows to carry out a good verification of all the different test structures, leading to prediction of the transistor's overall physical phenomena. However, to cover all the major effects influencing directly the HEMT's characteristics and performance, it is necessary to present a good model that is as general as possible.

For GaN HEMT technology, there has been interest in modeling transistors as basic building blocks. Actually, most of these efforts have focused on empirical [81]-[82] and semi-physical formulations. GaAs and GaN technology are commonly referred to as wide bandgap compound semiconductors, which lead to the fact that the extraction of GaN HEMT parameters mostly follows the same procedures as those for GaAs HEMTs, with a few exceptions. GaN HEMTs have much higher conduction bands than the corresponding GaAs HEMTs. As a result, GaN

models are based on GaAs models, and are then extended or modified to better fit into the form of GaN device's properties.

Various types of models have been employed for HEMTs, most of them are semi-empirical. Therefore, models are today based only on formulas which, also, seem to work for HEMT devices. For example, the hyperbolic tangent function is employed to approximate drain current. For GaN HEMTs, the most important effects which should be considered in a nonlinear modeling are:

- Self-heating: Transistor's ability to predict the dynamic changes of its temperature during operation due to power dissipation [83].
- Nonlinear charge modeling, Q_{gs} , Q_{ds} and Q_{gd} , has been shown to be critical to accurately simulating bias dependence on all three terminal voltages (Gate, Drain and Source) [83].
- Surface traps effects where gate-lag effects and drain-lag effects are included [84]-[85].

An accurate model is imperatively related to the measure of all reported effects. A mismeasurement or a lack of one affects the results by improperly extracting the device's parameters [86]-[87]. An overly simple model can have significant effect at high power, leading to fail the device's performance. They are three main types of GaN HEMTs device's equivalent models, which are Chalmers model [81]-[88], EEHMEMT model from Agilent and Curtice model [83]-[89]. Chalmers model is mostly used where many properties of transistor are included [84].

As mentioned, the devices presented in this study were manufactured by NRC in Ottawa. To accurately capture the performances of switch circuits, a complex model is needed to properly model the GaN HEMT-based switch. NRC's GaN500 process foundry does not provide a transistor model suitable for switch designs. As a matter of fact, a challenging task resided in developing an accurate GaN HEMT model for NRC's GaN500v2 process as a switch that it will be used for our purpose simulations.

A linear model, as shown in Figure III.45, has already been presented by Tyler Ross in [[90]] using NRC's GaN500v1 process. This model is inspired from [91] where a linear model for GaAs HEMT is reported (see Figure III.44). Based on this available model several SPST and SPDT switch structures and standalone transistors (common gate) with different sizes were submitted to NRC for fabrication in GaN500v2. The idea, for this thesis GaN switches section, was to redo the small signal modeling by using GaN500v2 process and then for the first time the large signal modeling using this foundry. Unfortunately, as already mentioned, due to our incapability to have large signal measurement facilities, we are not able to provide measured results or complete the characterization for large signal study as was planned.

Using GaN500v1, some performances advantages have been achieved in terms of high breakdown voltage, low on-resistor and low leakage current at the gate [[30]]. This leads us to assume that the switch designs using GaN500v2 could have better performances compared to the ones fabricated using GaN500v1.

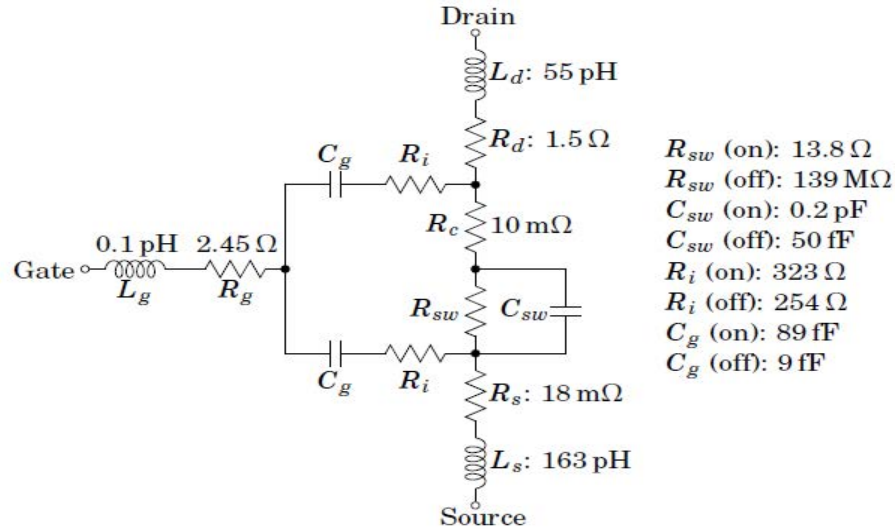


Figure III.44: Linear model used to model the switching GaN HEMT transistors
(4x40) [[90]]

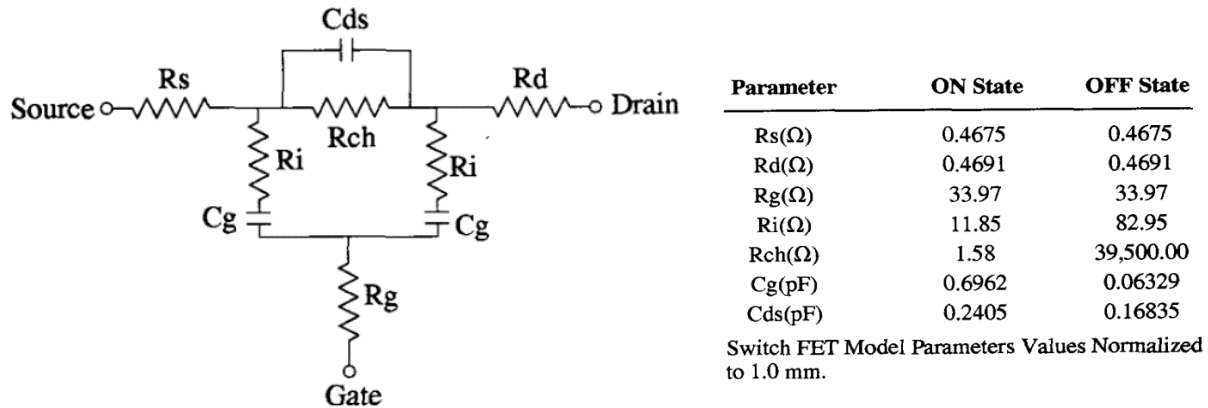


Figure III.45: Equivalent Linear Circuit Model of GaAs FET Switch [91]

The reported currently available simple linear model can be useful to estimate the power-handling capability of a switch circuit. The model presented can be easily integrated into the full circuit simulation, and the voltages across the transistor's terminals and the current through the device can be determined using a linear ac analysis available in virtually all simulators. As long as the input RF power does not induce a voltage swing across transistor's terminals that reaches the transistor's pinch-off voltage or breakdown voltage, the switch-based circuit should function largely as predicted from a linear S-parameter analysis. This simulation does not lend itself well to a quantitative prediction of the 1 dB compression point or input-referred third-order intercept point (IIP3). However, it does provide a designer with some useful information on the power-handling capability of the circuit, which can be refined once a large-signal model can be extracted, or when measurements are performed.

3. GaN500v2 Small Signal Switches Measurements

3.1 Different Sizes Standalone Signal Switch Devices

Here the conventional measurements setup of a transistor in common gate configuration is described. The simplified schematic presented in Figure III.46 (left) is used as a test bench to characterize the standalone switches while the Figure III.46 (right) illustrates the manufactured design for one switch device. As the ability to control the current through the switch should be independent of the current flowing, then it is recommended to put a strong gate resistance, R_{bias} , for isolation between the control and RF signals. The value of this resistor was chose to be 10 K Ω . The on-wafer RF measurements were performed with an Agilent VNA Network Analyzer over a frequency range of 0.1-10 GHz. The control voltage at the gate, V_G , was switched between 0 V and -5 V to control the switch, respectively, for ON and OFF states.

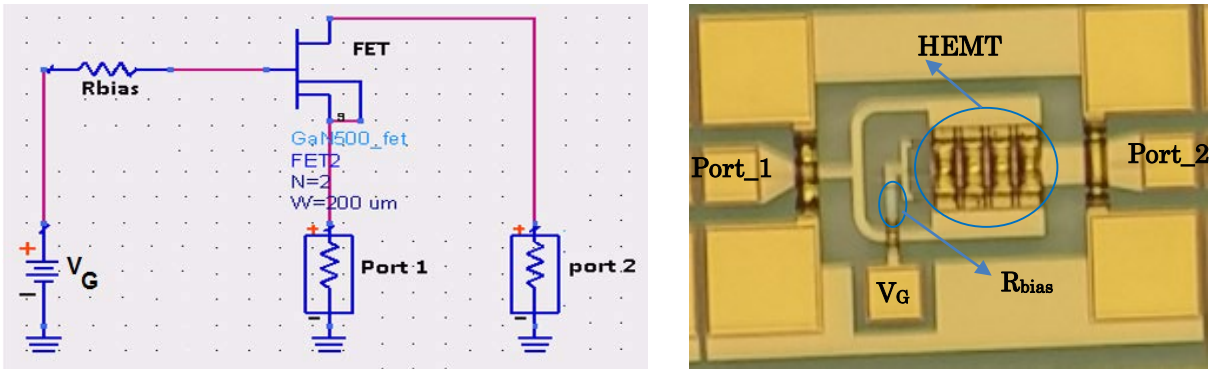


Figure III.46: Schematic (left) of Common Gate Configuration standalone switch 2x200_GaN500v2 and Device in Microwave probes measurement setup (right) to Evaluate RF behavior

Figure III.47, Figure III.48, Figure III.49 and Figure III.50 show, respectively, the insertion loss (ON state), the isolation (OFF state), and the return loss at ON state and at OFF state for the different sizes realized standalone single

switches. The measurements were limited at 10 GHz for two reasons. First, it was observed that the performances of the measured devices decrease at high frequency in terms of insertion loss and isolation. Second, the realized final structure is planning to be used for beam switching antenna at 2.45 GHz.

As can be seen, the isolation is good at low frequencies but quickly drops with increasing frequency. So, it can be said that the larger the device used, the lower the insertion loss is achieved but the poorer the isolation. These obtained results are in good agreement with the reported small signal analysis in [[90] using GaN500v1 from NRC.

A trade-off between insertion loss and isolation should be made to choose the single transistors that will be used for designing switch structure such as SPST and SPDT. Switch structures such as SPST and SPDT are very popular in semiconductor switches applications, they are used for improving the performances (insertion loss and isolation) over large frequency bands. Based on the investigated standalone switches, SPST and SPDT structures will be designed and measured result will be presented and discussed.

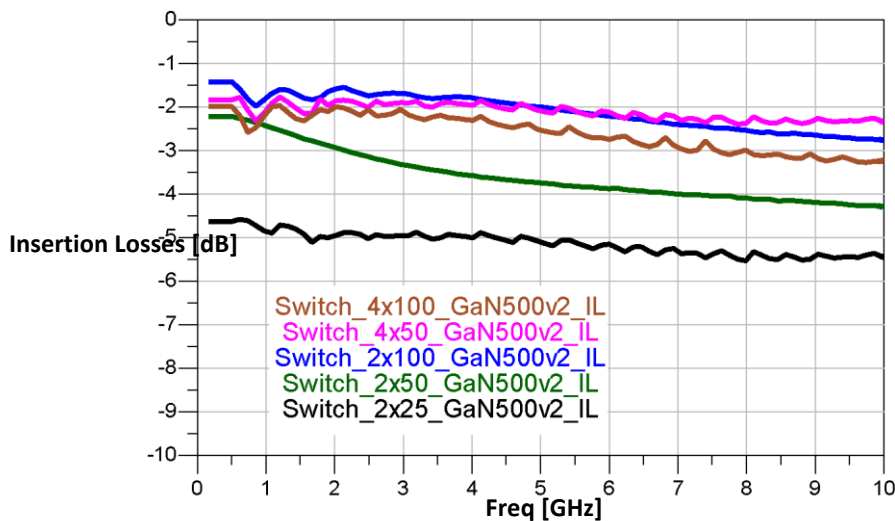


Figure III.47: Measured insertion loss of different transistor size in common gate, biased with $V_G=0V$ (ON state)

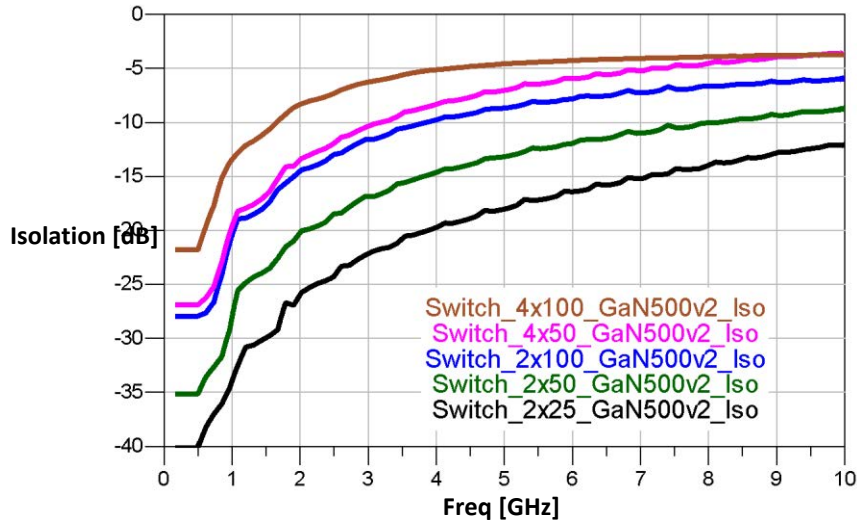


Figure III.48: Measured Isolation of different transistor size in common gate, biased with $V_G = -5V$ (OFF state)

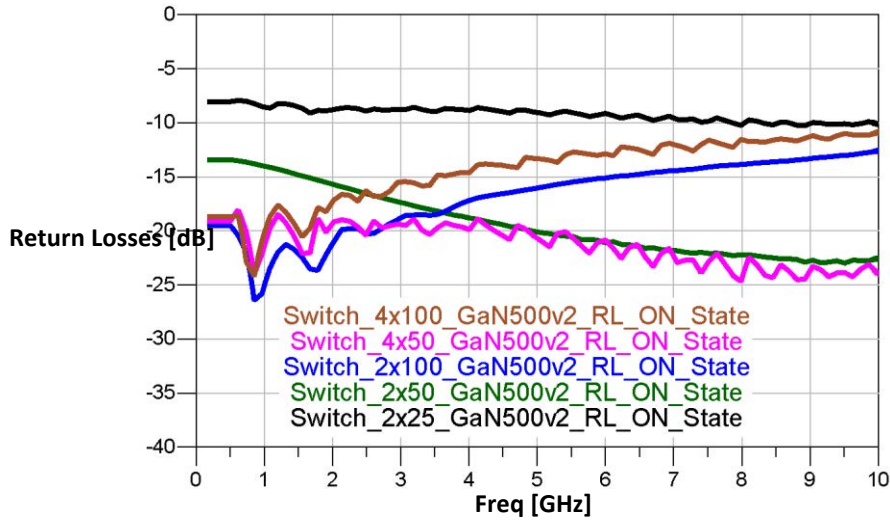


Figure III.49: Measured Return Loss (S_{11}) of different transistor size in common gate, biased with $V_G = 0V$ (ON state)

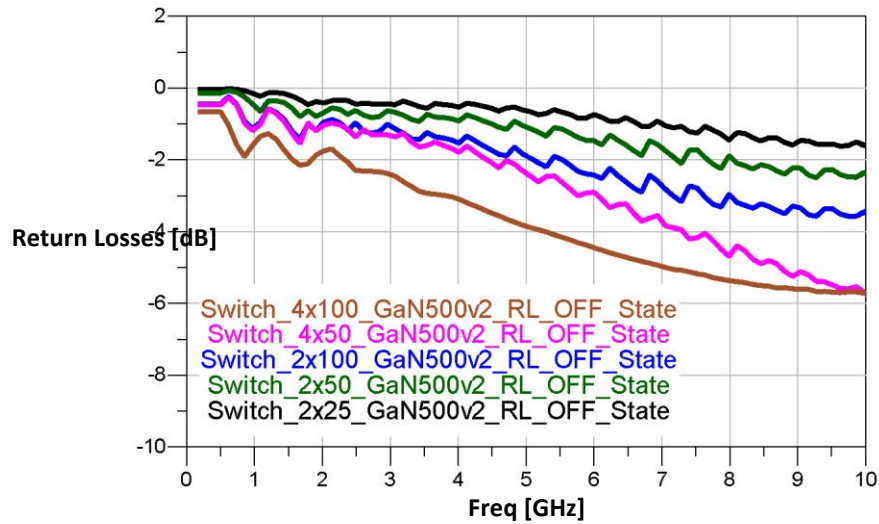


Figure III.50: Measured Return Loss (S_{11}) of different transistor size in common gate, biased with $V_G = -5V$ (OFF state)

Based on these small signal measurements, a model is introduced and detailed in Table III.7 and Figure III.51. It was observed that this linear model is the same to the one proposed in [90] by Tyler Ross using GaN500v1 from NRC foundry. A comparison of the S-parameters of both the ON and OFF states is shown in Figure III.52 and Figure III.53, respectively. As shown, the fit between model and measurements is very good. In Table III.7, parameters corresponding to a single switch (2x25) with total gate width of 50 μm and linearly scaleable with gate width are summarized. C_g , R_i , R_{sw} and C_{sw} vary with gate bias as indicated.

Table III.7: Model Circuit Parameters Values

	ON State (0V)	OFF State (-5V)
Gate Inductor (L_g)	0.14 pH	0.14 pH
Gate resistor (R_g)	3.92 Ω	3.92 Ω
Drain Inductor (L_d)	65 pH	65 pH
Drain Resistor (R_d)	7.74 Ω	7.74 Ω
Source Inductor (L_s)	112 pH	112 pH
Source Resistor (R_s)	26 Ω	26 Ω
R_c	16.6 mΩ	15.6 mΩ
C_g	49.25 fF	36 fF
R_i	178.8 Ω	396 Ω
Switch Resistor (R_{sw})	26.48 Ω	277.4 MΩ
Switch Capacitor (C_{sw})	0.39 pF	74.25 fF

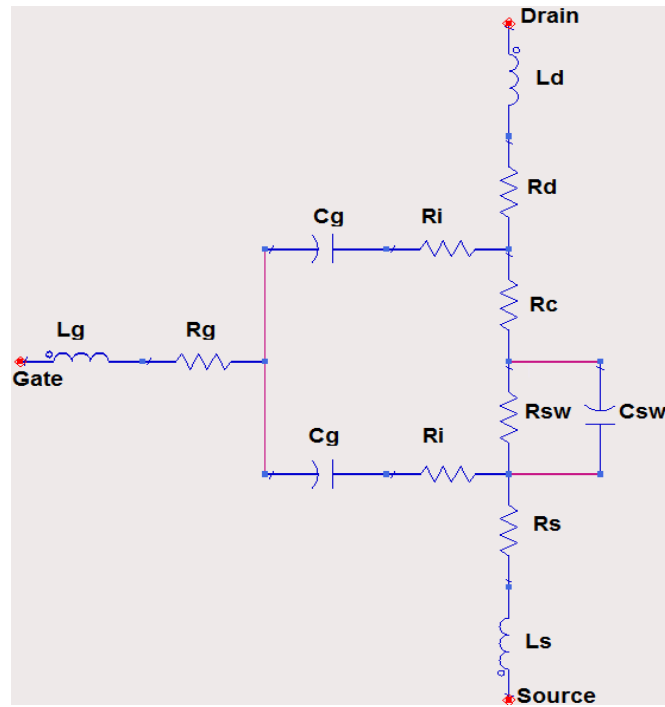


Figure III.51: Linear model used to model the switching GaN HEMT transistors.

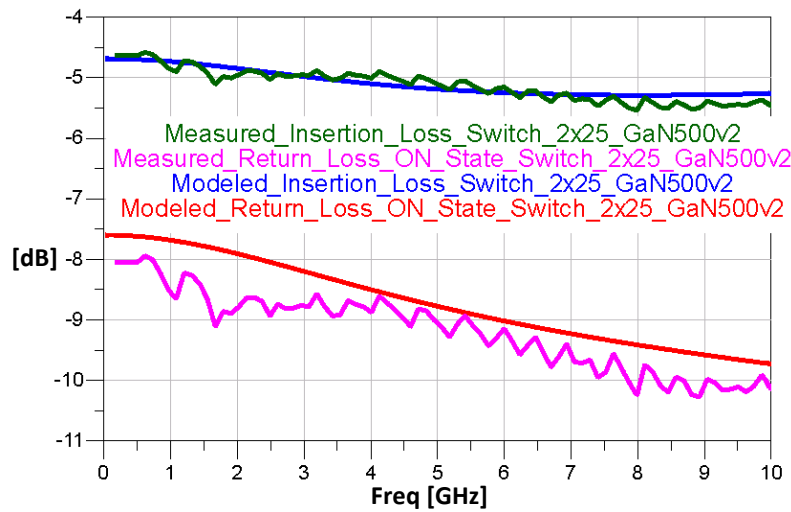


Figure III.52: Measured and Modeled Insertion Loss and Return Loss (S_{11}) of switch 2x25 biased with $V_G=0V$ (ON state)

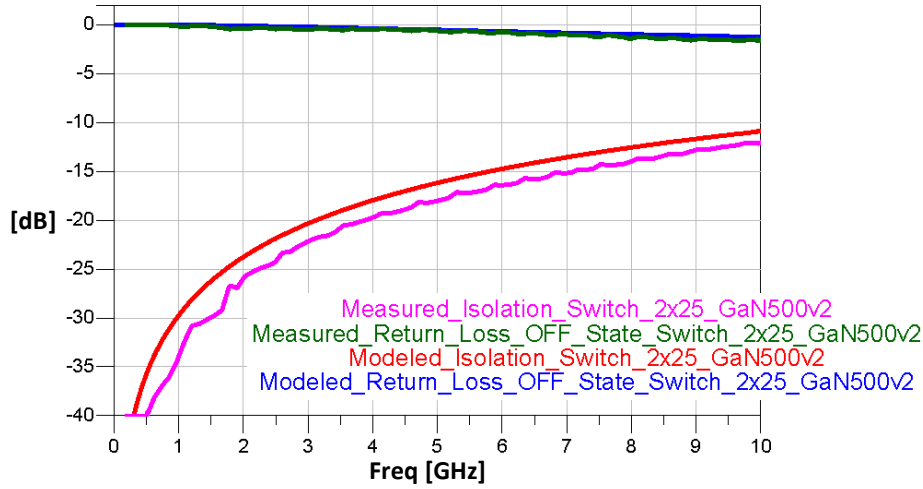


Figure III.53: Measured and Modeled Isolation and Return Loss (S_{11}) of switch 2x25 biased with $V_G = -5V$ (OFF state)

3.2 SPST Switch Structure

To improve the isolation and keep the insertion loss at its minimum, a SPST switch structure is proposed as in Figure III.54. A transistor with two fingers and a gate width of $100\ \mu\text{m}$ as used for the transmitted path to improve the insertion loss, while two transistors with 4 fingers and $50\ \mu\text{m}$ of gate width were used for the coupled path to improve the isolation. When the SPST switch operated in the ON state corresponding to $V_{G1} = 0\ \text{V}$ and $V_{G2} = -5\ \text{V}$, FET1 is in the linear region as represented by a small on-resistor, and FET2 is in the pinch-off region, which can be presented as a small capacitor. Then the RF signal goes from the input port to the output port through the FET1 because input impedance is near $50\ \Omega$. In the other hand, when the SPST switch is in the off-state, FET1 behaves as a small capacitor instead when a control voltage at $-5\ \text{V}$ is applied for V_{G1} , and FET2 can be treated as a small resistor by applying $0\ \text{V}$ for V_{G2} . Therefore, the input impedance is very high, and the input RF signals are completely reflected back to the input terminal.

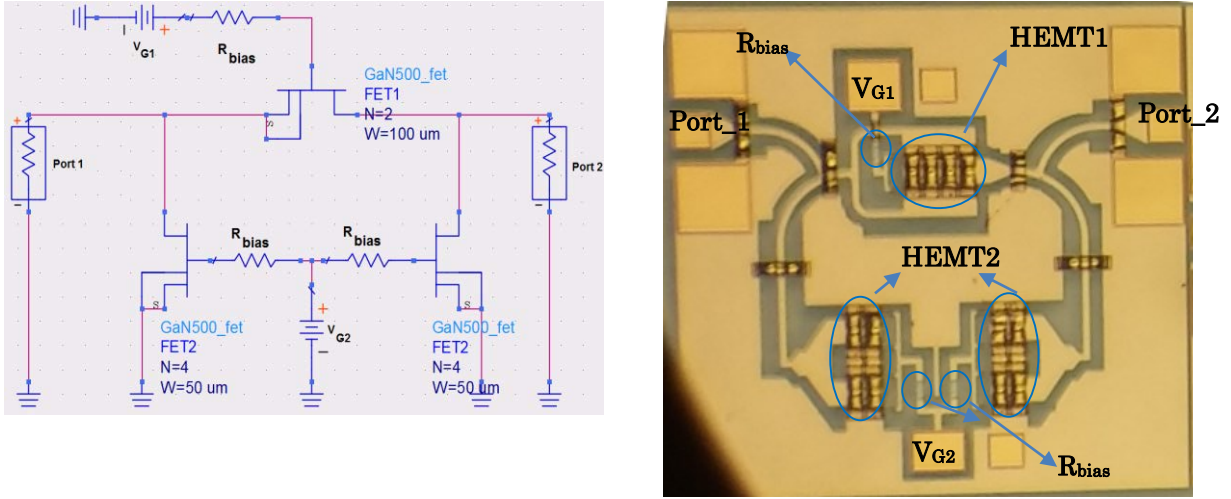


Figure III.54: Schematic (left) and Layout (right) of the Proposed SPST Switch Structure

As can be seen from Figure III.55, the isolation has been improved compared to the isolation of a 4x50 standalone switch (see Figure III.48). Up to 10 GHz, an isolation of -20 dB is still achievable while with 4x50 single switch an isolation of -10 dB was achieved at 3 GHz. In addition, the insertion loss value achieved by this structure is better than -3.5 dB up to 3 GHz and then starts degrading. However, the insertion loss of 2x100 single switch was better than -2 dB up to 5 GHz (Figure III.47).

Comparing to the 2x100 standalone device, the isolation is improved while the insertion loss slightly dropped by -1 dB. With this proposed topology, it is still a challenge to meet good performances at higher frequency. Another topology based on SPDT is proposed to improve again the switch performances.

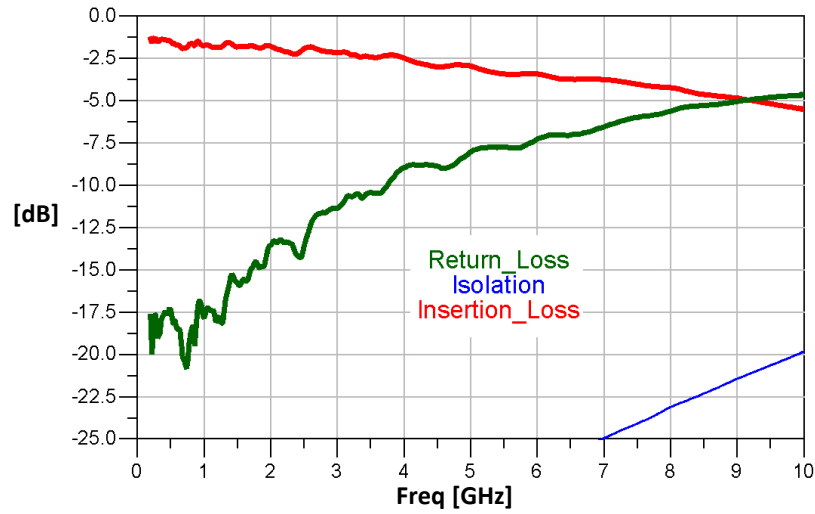


Figure III.55: Measured SPST performances

3.3 SPDT Switch Structure

A SPDT switch topology is proposed in order to improve the isolation at high frequencies. FETs are arranged in both series and shunt configurations. The series FETs provide a through-path for the ON-state, while the shunt FETs provide isolation for the OFF-state. The operation of the switch requires that series FETs and shunt FETs associated with each switch state have opposite (or complementary) conduction states and therefore opposite (or complementary) gate biases. Figure III.56 illustrates the SPDT topology. If the Port₁ to Port₂ path is ON and the Port₁ to Port₃ path is OFF, then FET1 and FET4 are biased ON, while FET2 and FET3 are biased OFF.

When the transistor FET1 as well as the FET4 are in the ON state corresponding to $V_{G1} = 0$ V and $V_{G2} = -5$ V, FET1 behave as a small resistor which allowing to the RF signal to go from port₁ to port₂. Verse-versa for the second state when the signal is from port₁ to port₂

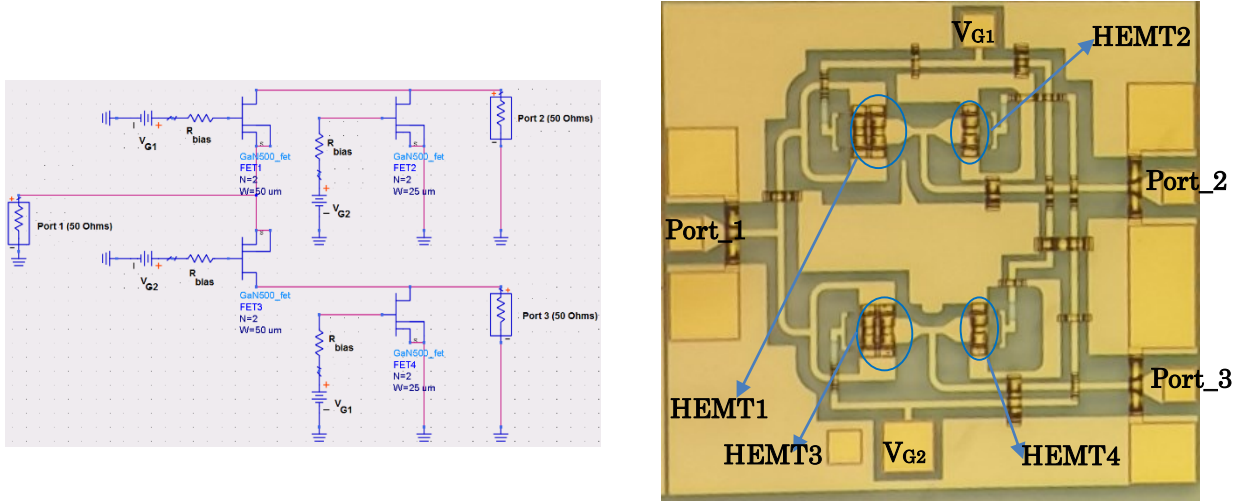


Figure III.56: Schematic (left) and Photograph (right) of the Proposed SPDT Switch Structure

As was expected with this topology, some improvement in isolation is achieved compared to SPST, while the insertion loss is increased by almost 1 dB. For example, at 3 GHz an isolation of -25 dB and an insertion loss of -3 dB were achieved. Unfortunately, the SPDT structure performances degrade with frequency. As we hope to go higher in frequency, around 10 GHz, with these realized switch topologies it will be impossible to achieve good performance. So, the SPDT structure which presents good overall performances compared to SPST will be used in a beam switched antenna system at 2.45GHz. At this frequency, an isolation better than -25 dB and an insertion loss of -3 dB are possible.

Due to the unavailability of having large signal equipment and also a RF probe of type GSGSG to measure the outputs of the SPDT either at IETR (University of Rennes 1) or DOE (Carleton University), we could not do the large signal measurement of this structure. However, as will be presented in Chapter IV (Section V), once this SPDT structure was mounted over a PCB by using wire-bonding technique, the large signal measurement have been conducted and results are presented and discussed in Chapter IV. In addition, by using ADS the SPDT small

signal model can be built based on the small signal model of a single standalone switch. Here as shown in Figure III.57, only small signal measurements of this structure are reported.

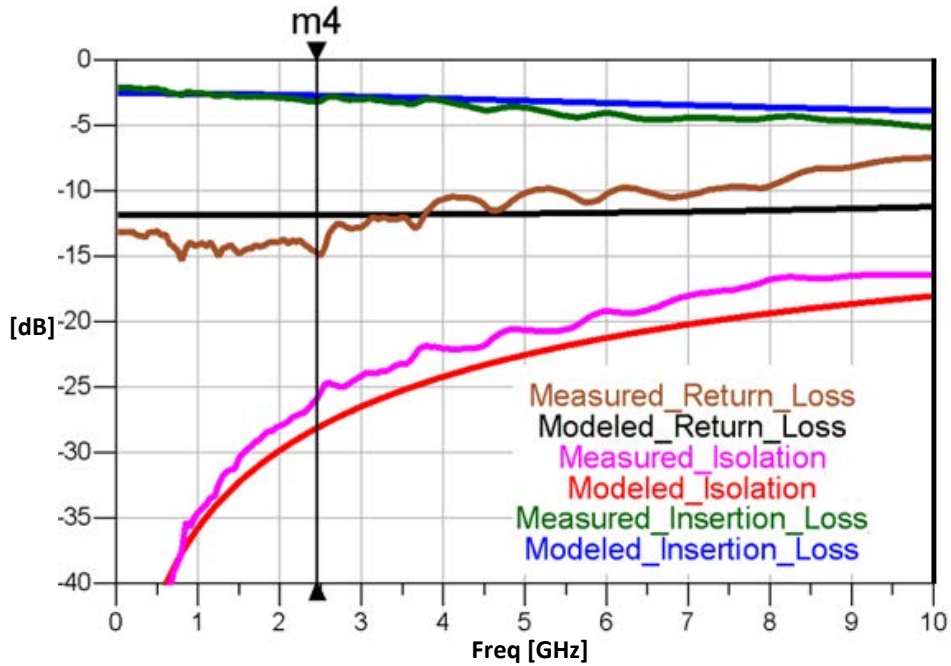


Figure III.57: Measured and Modeled Return Loss, Isolation, and Insertion Loss of SPDT Switch Structure

Table III.8: Performances of the SPDT at the Marker m4

Performances	Values
Modeled Insertion Loss	-2.723 dB
Measured Insertion Loss	-3.164 dB
Modeled Isolation	-28.158 dB
Measured Isolation	-25.937 dB
Modeled Return Loss	-11.847 dB
Measured Return Loss	-14.697 dB

IV. Summary

In this chapter, GaN HEMT-based varactor devices have been fully characterized and modeled for the first time, showing limited usefulness for high power applications due to their rapidly changing C-V characteristic. These GaN-based varactors were designed in a standard GaN HEMT process, and were fabricated with two different gate lengths, 0.5 μm (GaN500v1 and v2) and 0.15 μm (GaN150v0). The varactor diode is realized by connecting together the drain and source terminations thus resulting in a single Schottky junction which can be considered as Planar Schottky Varactor Diodes (PSVDs). First of all, a small signal analysis has been conducted and by analyzing the extracted $C_{\text{Eq}}\text{-}V_{\text{G}}$ curves, mathematical expressions have been proposed to capture the nonlinear behavior that can be used to represent a variety of different GaN based varactor sizes. These equations maintain the simplicity of equivalent circuit modeling while offering good agreement with measurements. In addition, an equivalent simple circuit model was proposed and simulated, yielding good agreement between the simulated and the measured results. The obtained $C_{\text{max}}/C_{\text{min}}$ ratios and figures of merit compare favorably with recently reported GaN varactors.

Secondly, a general large signal model for GaN varactor diodes manufactured with gate lengths of 0.5 μm (GaN500v2) has been presented. This model is based on an analytic expression which describes the $C_{\text{eq}}\text{-}V_{\text{G}}$ curve and has shown to maintain a high level of accuracy, well into the large power range up to 18 dBm. In addition, the proposed circuit model in small signal analysis is always valid for large signal by considering the new analytical equation of C_{Eq} versus the input power (P_{in}). With reverse bias and RF power level included in the model, the junction capacitance ratio ($C_{\text{MAX}}/C_{\text{MIN}}$) of the realized varactors was shown to be decreased from 1.73 to 1.25. This ratio can be much further decreased, if the RF power level is increased further. From the presented results and given GaN's high breakdown voltage, these varactors would be very useful in various applications in receive mode,

where power limiters could be completely excluded as protection circuitry from jammer signals.

Finally, in this chapter, different sizes single standalone switches and switch structures such as SPST and SPDT were fabricated and presented. As mentioned, only small signal measurement were reported. It was observed that, with single transistor in common gate configuration, the isolation is good at low frequencies but quickly drops with increasing frequency. In addition, it was observed that more the device is large, lower the insertion loss is achieved but poorer the isolation will be. A trade-off between insertion loss and isolation has been made to choose the single transistors that will be used for designing switch structures such as SPST and SPDT which could improve the performances at high frequencies. Comparing to the standalone device, it was revealed that with SPST structure, the isolation is improved while the insertion loss slightly dropped by -1 dB. With this proposed topology, it is still a challenge to meet good performance at our higher frequency. Another topology based on SPDT was proposed to improve more the performances. As was expected with this topology, some improvement in isolation is achieved compared to SPST, while the insertion loss is increased by almost -1 dB. For example, at 2.45 GHz (frequency of interest) isolation better than -25 dB and an insertion loss of -3 dB were achieved. However, the SPDT structure performances degrade with frequency. Moreover, based on these small signal measurements, a model was introduced. It was observed that this linear model is the same to the one proposed in [[90]] by Tyler Ross using GaN500v1 from NRC foundry. In addition, the fabricated SPDT switch structure will be integrated with antenna system to realize and to demonstrate the ability of using GaN devices for a beam switching antenna array.

Chapter IV

Realized GaN-Based Reconfigurable Circuits

I. Introduction

As a result of the emerging need for multi-band and multi-services requirements within a single design structure, the electronically tunable or reconfigurable devices have experienced [92], over the last years, with a significant growth in radio frequency (RF)/Microwave wireless front-end applications such as antennas, power amplifier, phase-shifters, oscillators and filters. Moreover, this has been the modern trends in technological of the new compact-structured RF transceivers [93].

Also, the use of wireless devices has increased dramatically over the last years. This increased utilization has led to a need for more efficiency RF circuits with

more functionalities. Therefore, the continuing demands for highly portable, more reliable and more power efficient, low cost wireless systems require that future wireless devices must be compatible with different communication protocols and capable of operating over a wide frequency range. Furthermore, applications of such systems in personal and satellite communications impose the specifications for circuits miniaturized in size and weight. Thus, as wireless devices become more and more compact, the appeal of reconfigurable circuits is that they can decrease the number of components with identical specifications, decrease the number of input/output pins, reduce the size of the integrated circuit area, and reduce power consumption [94].

Tunable devices with a high performance are, also, more crucial for mobile devices and are for selective applications. Generally, an adaptive RF circuit must have the capabilities to handle different functionalities such as signal routing, impedance matching agility, adjustable gain amplification, tunable phase shifting [95], etc. In contrast, a tunable circuit with embedded tuning elements can carry out a switching function of several parallel circuits with a simple change to one of the elements. Figure III.1 illustrates this example for the case of duplexers in a tri-band system where a single tunable duplexer can replace three fixed duplexers [96].

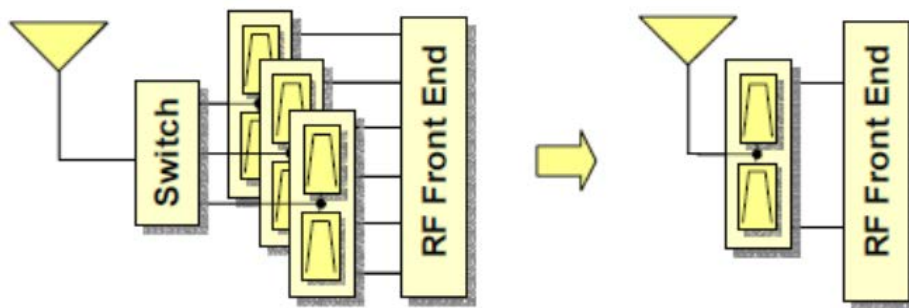


Figure IV.1: (left) Tri-band system with three fixed duplexers and (right) with a single tunable duplexer [96]

Comparing the above architectures, a single tunable duplexer offers higher flexibility, more functionalities, lighter weight and denser integration. In addition, such a circuit tuning allows an easier controlling of systems through baseband signal processing, which can add attractive features of smartness of combined multi-services. Therefore, it is obvious that due to the convergence towards the integration of multiple standards and services into a single circuit and maintaining their expected performances at various configuration parameters, wireless systems are becoming more complex and highly smart.

Depending on the specific RF design where reconfigurable components are suitable, the result may be a saving in cost, reduction in size, better performance, and/or increased functionality. In order to implement these electronically reconfigurable components, there are currently various main techniques [95] that could be listed as follow:

- Ferrite materials
- Ferroelectric technology
- Semiconductor varactor diodes or switches
- Micro-electromechanical systems MEMS

During the last years, Monolithic Microwave Integrated Circuits (MMICs) based on semiconductors technology have become more attractive for electronic reconfigurability due to their small size, easiness integrations, possibly to be mass-produced, etc. Most MMICs currently in production, such as GaAs, SiC, InP, etc, operate in the microwave and mm-w range with modest breakdown voltage and limited power handling capabilities. But there are increasing applications in the RF/microwave spectrum with higher power requirement.

As already presented in chapter II, GaN technology can be ideal for the design of high power devices for microwave and mm-w applications. In-depth research studies have been conducted to explore the performance of GaN technology, as well as reconfigurable RF/microwave circuits using GaN devices [97]. GaN HEMTs

semiconductor devices are no longer limited to RF power amplifier applications, having been emerged to other applications such as LNAs, VCOs, mixers, and phase shifters.

For the above mentioned strong points of reconfigurable components, GaN technology can be considered as a real promising candidate semiconductors technology, capable of significantly reducing the number of components with identical specifications, size and cost of devices utilized in transmitter and receiver chains of front-end modules used in RF/microwave systems.

II. Tunable Phase Shifters

1. Review

Phase shifters are important components that find their use in many RF/microwave systems. For example, they can be used in electronic beam-scanning phased arrays, microwave instrumentation and measurement systems, power divider, and as modulators [97] in communication sub-systems.

Phase shifters can be analog or digital. Analog phase shifters provide a continuously variable phase, which can be controlled by a voltage. Electronically controlled analog phase shifters can be realized with varactor diodes that change capacitance with voltage, or nonlinear dielectrics. In the other hand, digital phase shifters provide a discrete set of phase states that are controlled by two-state "phase bits". They are characterized by a certain number of bits. This number defines straightforwardly the achieved phase. More bits there are, smaller phase step will be. For example, a five bits phase shifter would have a $11.25^\circ (= \frac{360^\circ}{2^5 \text{ bits}})$ as a phase shift step. This means that each bit allows to get a phase shift successively over 11.25° , 22.5° , 45° , 90° and 180° .

There are various design parameters that should be considered such as frequency range, total phase variance ($\Delta\phi$), phase resolution, insertion loss, bandwidth, return loss, harmonics level, power handling and design area. This makes some challenges in the design and optimization of integrated phase shifters. In addition, there are five main phase shifter topologies and described as follow [98]:

- Switched line phase shifter
- Loaded line phase shifter
- Reflection type phase shifter
- All pass network phase shifter
- High Pass / Low Pass phase shifter

As highlighted in the PhD dissertation [[30] about GaN phase shifters, if phase shifters are implemented in a low power semiconductor technology, such as Si or GaAs, it may have to be placed in transmit and receive chains in RF front-end system, where it will not be damaged by large signals in any unexpected situation, thus resulting in relatively high cost and low integration density. Figure IV.2 shows a simplified RF front-end for a beamforming system. However, with recent developments in high power technology semiconductors such as GaN, it is possible to design phase shifters that can simplify the front-end system and make it more efficiently. An example of this is shown in Figure IV.3. Since the active devices in the phase shifter can handle both weak and strong signals, the circuit will operate properly and will not be damaged. As it is in the common path, only one phase shifter per antenna element is required as well, and the transceiver component count and cost can be drastically reduced. GaN-based Phase shifter with good high power handling and low loss hold the key to realize an affordable electronically steerable system, eliminating the need for active transceiver modules at every element.

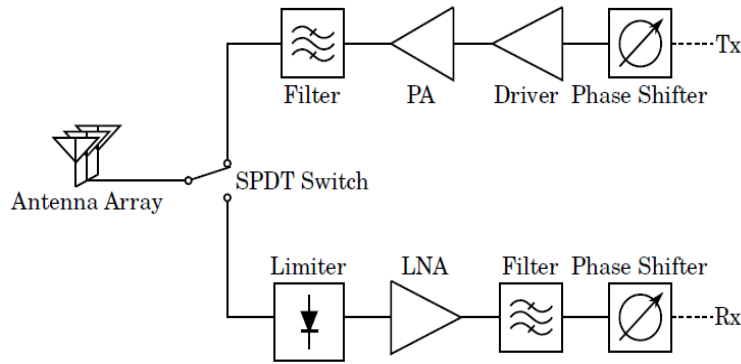


Figure IV.2: Simplified RF front-end for a typical beamforming system in a non-GaN technology [[30]]

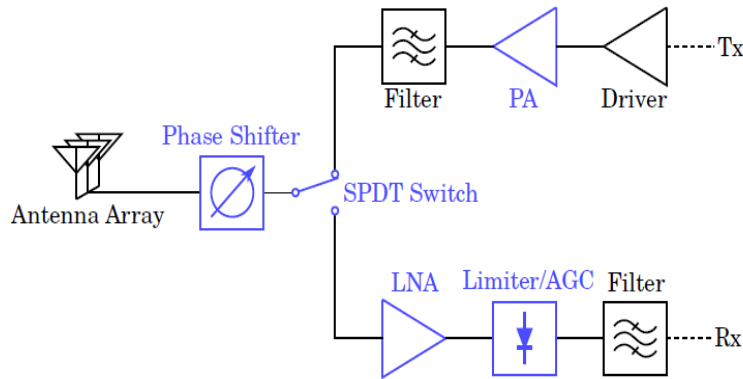


Figure IV.3: Example RF front-end possible with GaN with key components in blue [[30]]

While there has been significant progress made in developing GaN technology for high-power amplification applications as explained before in Chapter II, there have been few studies to date on the use of GaN HEMTs for high-power RF/microwave phase shifters applications. In future RF/microwave systems that are based on GaN device technology, the GaN control elements, such as phase shifters, will often be conjointly placed together with high-power GaN amplifiers, thereby requiring an in-depth look at these control devices in term of their parameters design presented previously.

Using GaN technology, a few phase shifters works have already been reported over the last few years. A new type of GaN HEMT based high power shifter at X-band permitting to switch between two states [99] was reported for the first time by a research group from Carleton University. As shown in Figure IV.4, this work is based on the high-pass/low-pass phase shifter or T-topology which has original advantage such as its superior power and phase-bandwidth capabilities compared with more conventional switched line, reflection, or loaded line phase shifters. As illustrated, the proposed phase shifter consists of two SPDT switches, a low pass network, and a high pass network. The $0^\circ/45^\circ$ signal shift is achieved by switching between two filters, low pass and high pass networks. As shown in Figure IV.5 and Figure IV.6, where measured results are depicted, the proposed $0^\circ/45^\circ$ high-pass/low-pass phase shifter exhibits low insertion loss (2.5 dB), good return loss, and amplitude variation lower than 0.5 dB for the two phase states over the entire operational bandwidth ranging from 6 to 13 GHz, while the measured phase difference between the two states varies from 45° to 55° over the design frequency range of 8–12 GHz (see Figure IV.7). This work has been demonstrated by using a $0.8\ \mu\text{m}$ gate GaN HEMT process from NRC foundry which is the first GaN HEMTs NRC developed process.

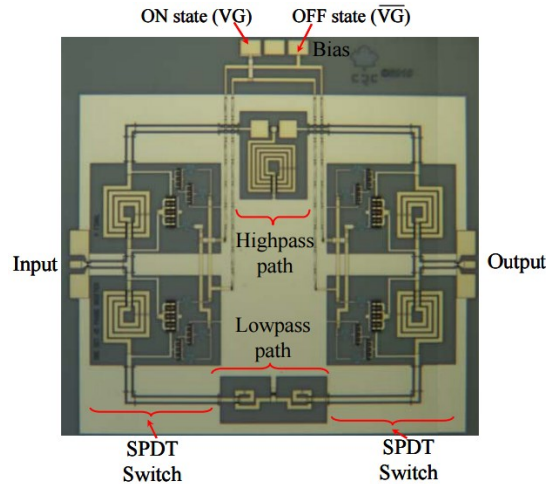


Figure IV.4: Photograph of a novel GaN HEMT based high power high-pass/low-pass phase shifter [99]

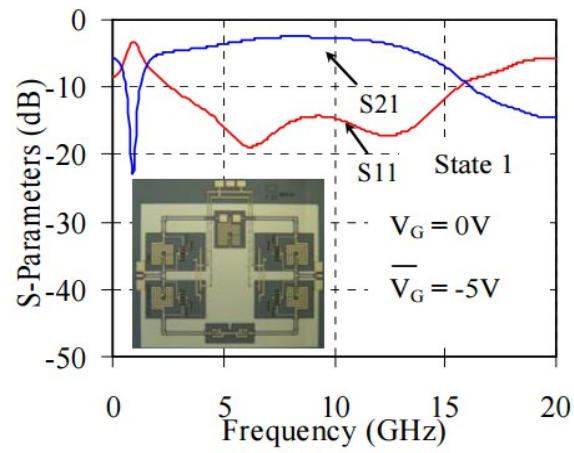


Figure IV.5: Measured insertion and return loss for high pass [99]

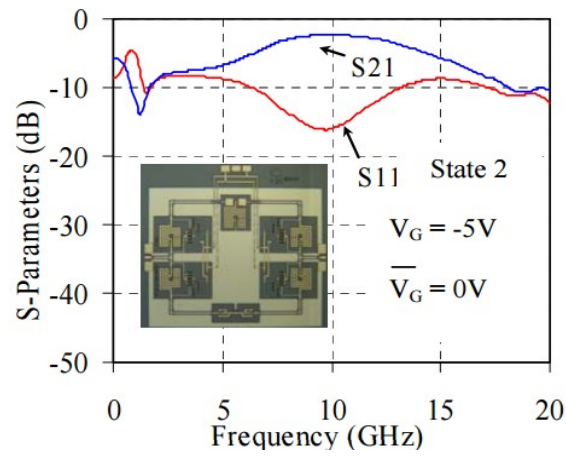


Figure IV.6: Measured insertion and return loss for low pass [99]

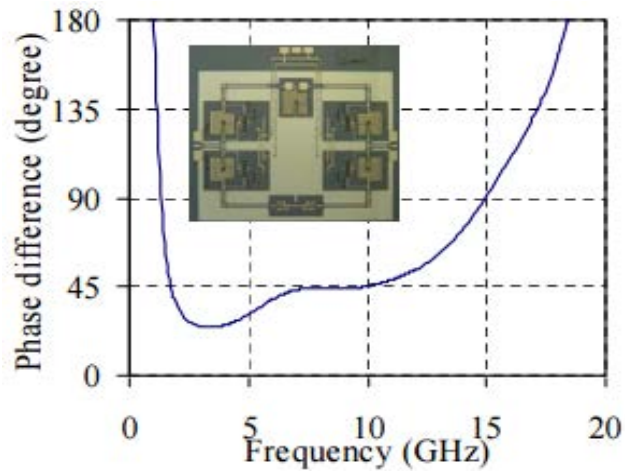


Figure IV.7: Measured phase difference between the two states [99]

Later on 2014, the same authors have reported a novel high power X-band GaN phase shifter [100] based on switched-filter configuration by using a novel developed NRC GaN fabrication process which is a $0.5\ \mu\text{m}$ gate width. The use of this topology is widely found useful when compact circuits are required because less chip area is required compared with other phase shifter topologies. Figure IV.8 shows a microphotograph of the designed phase shifter. The manufactured $0^\circ/22.5^\circ$ switched filter phase shifter has much wider bandwidth covering 8-16 GHz, while maintaining low insertion loss of 2 dB, good return loss $> 11.15\ \text{dB}$ and an amplitude imbalance of less than 1.03 dB across X-band. Figure IV.9 presents the obtained phase shift while the measurements of linearity and power handling capability of the circuit are depicted in Figure IV.10. With the 0° (bypass) state, the measured IIP3 was 46.2 dBm while for the 22.5° phase shift state had a higher IIP3 of 50.4 dBm. The obtained 1 dB compression point is well over 40 dBm.

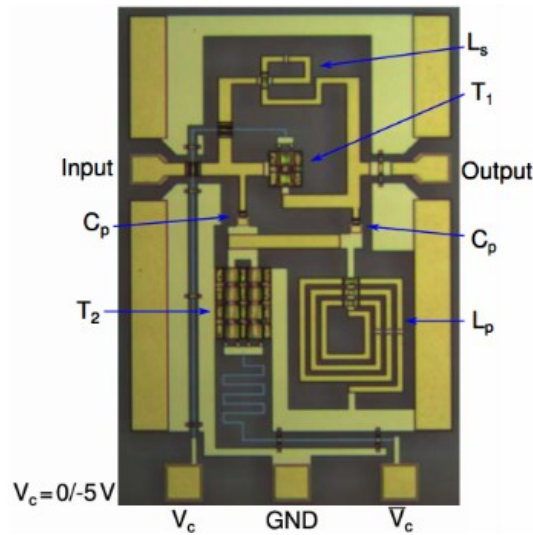


Figure IV.8: Microphotograph of the $0^\circ/22.5^\circ$ GaN switched-filter phase shifter [100]

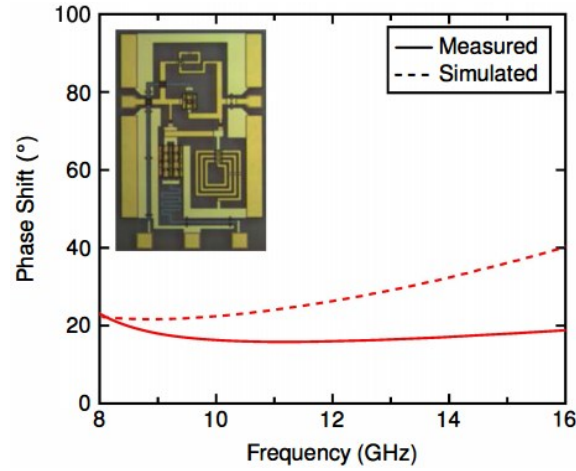


Figure IV.9: Measured and simulated phase shift [100]

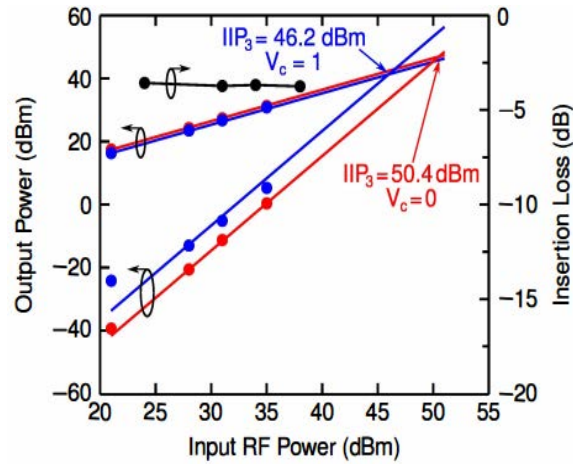


Figure IV.10: Linearity measurement [100]

Using the topology presented in [[30], an analog phase shifter using GaN Schottky diode is reported in [101] for 35 GHz operation. This design reports fabrication and experimental characteristics of a 35 GHz MMIC analog phase shifter using GaN Schottky diodes to enable continuous phase shifting. Figure IV.11 shows the schematic and photograph of the designed T-phase shifter. The reported design contains two series connected diodes and another diode in the shunt arm which is connected to a spiral inductor to achieve the optimum matching and phase shifting at 35 GHz. The phase shifter presents analog phase shifting capability up to 45° with ~ 7 dB insertion loss and a return loss of -10 dB in the 32 to 38 GHz range as

illustrated in Figure IV.12. Good power handling capability and robust performance is demonstrated through large signal analysis and experimental characterization as explained in this paper.

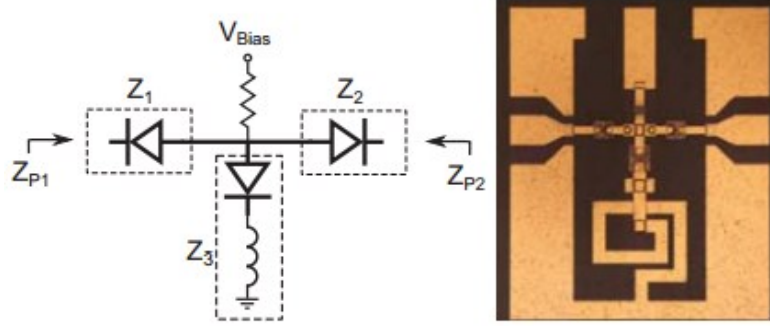


Figure IV.11: T-Phase shifter Circuit Configuration and microscope image [101]

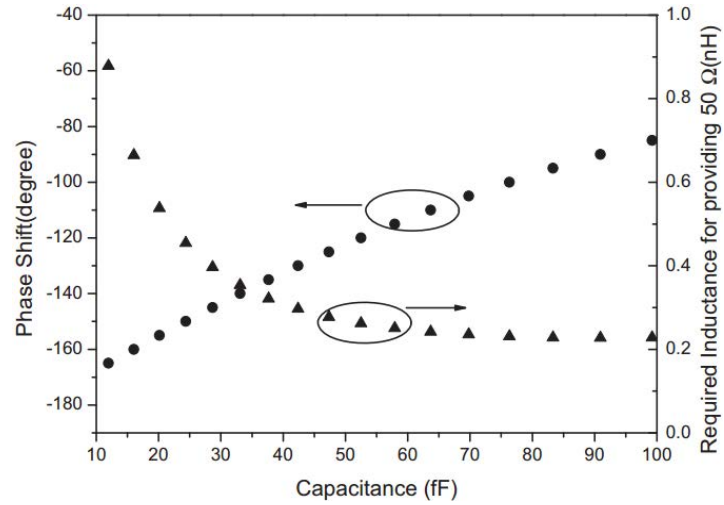


Figure IV.12: Phase shift of the high-pass T-network and the corresponding inductance for 50 Ω impedance matching [101]

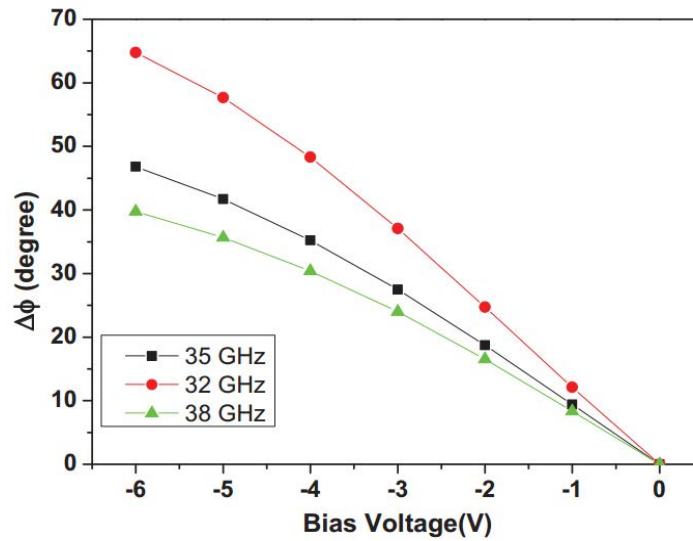


Figure IV.13: phase shift of the T-Phase shifter in the frequency range of 32 GHz to 38 GHz [101]

2. Design of Analog GaN-based Phase Shifter

Analog phase shifter based varactor diodes structure is, first of all, very simple to design. Secondly, compared to a digital MMIC phase shifter, the power consumption is low and only a single input control voltage is required. Additionally, a continuous phase shift is easily achievable, thus allowing to provide any desired phase shift. Among the more useful topologies for analog phase shifters are the loaded line structure and the reflective structure employing quadrature 3-dB 90° hybrid coupler using either lumped or distributed elements with two reflective loads at terminations. One of the major drawbacks of reflection phase shifter structure is that the overall insertion loss of the circuit is usually high. These insertion losses are especially related to the equivalent series resistor presented by the used varactor and also the coupler's elements.

Using the first commercialized NRC GaN150v0 HEMTs process, a phase shifter based on quadrature reflection structure was designed and simulated using ADS Agilent simulator, along with the development of the reported small signal GaN

varactor diodes model. Here this developed GaN varactor diode, already presented in Chapter III, is used as tuning load purpose. Moreover, at least two varactor diodes are required to achieve a theoretical phase shift of 180° [102], making the device smaller and less expensive to fabricate compared to digital phase shifter; and the diodes are operated at reverse bias, having very fast response times and requiring voltage but no current consumption.

It is highly import to keep in mind that, to the author knowledge's, this the first developed GaN phase shifter based on quadrature reflection structure even if only simulation results will be presented.

Here, before presented the simulated results, a description of how this phase shifter structure works is giving. As shown in Figure IV.14 and Figure IV.15, basically, a phase shifter based reflection structure consists of a quadrature hybrid coupler that splits the incident signal into two separate signals of equal amplitude and 90° phase difference over the two opposite ports (2 and 3), while isolating the adjacent one (port 4). These two signals reflect from the two tunable loads, GaN varactors connected to the coupled and thru ports of the hybrid, and add up in phase at the hybrid's isolated port if both of the loads are identical, and will ideally be isolated from the phase shifter's input signal. This means that the voltage at the output port can be written as [103]:

Equation (9)

$$V_{out} = j \cdot \Gamma \cdot V_{in}$$

Equation (10)

$$\Gamma = |\Gamma| \cdot e^{-j\phi}$$

The phase angle, ϕ , of the reflection coefficient, Γ , can be varied by changing the capacitance of the loading varactor diodes which are controlled by DC voltage and, theoretically, have to present a pure imaginary impedance. While $|\Gamma|$

must be unchanged and equal to 1 in order to not introduce any additional loss into the phase shifter. Practically, it is impossible to achieve perfect reflection from a load which means that some power will be dissipated in the load and $|\Gamma|$ will be less than one. Therefore, some loss will always occur between the input and output signals. By inserting varactors in the terminations, a continuous control of the phase shift is achieved in this manner.

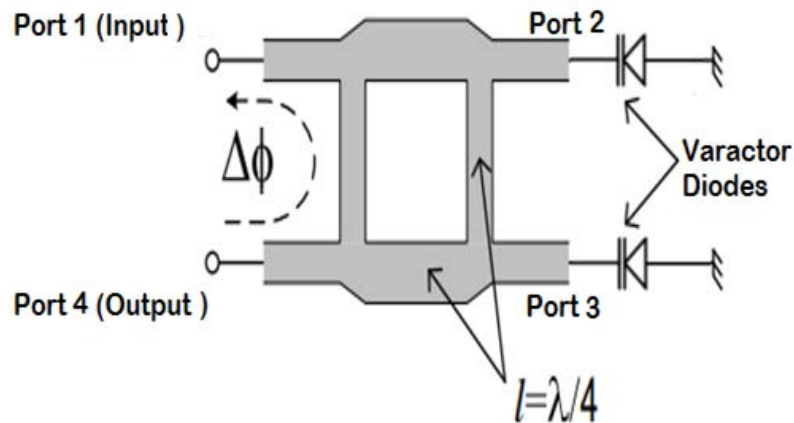


Figure IV.14: Phase shifter based on 3-dB/90° branch-line hybrid coupler using distributed elements

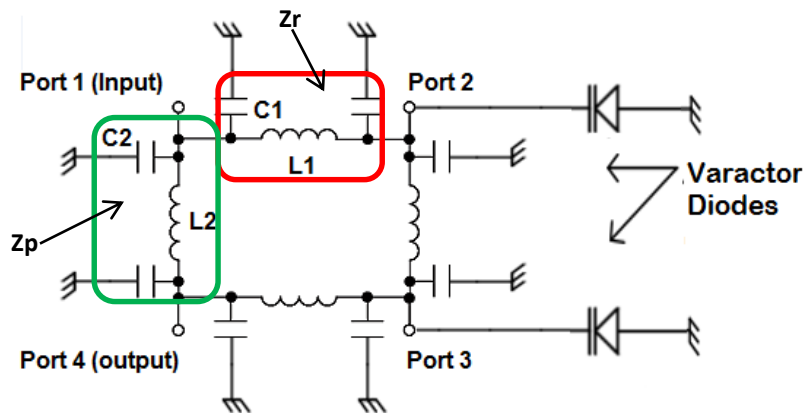


Figure IV.15: Phase shifter based on 3-dB/90° branch-line hybrid coupler using lumped elements

To design this phase shifter topology, firstly, a 3-dB 90° hybrid coupler has been designed and simulated. The simulated results will be discussed later in this section. Then, the two coupler's outputs ports have been loaded by GaN varactors.

The final phase shifter design presented in this section was designed and were planned to be manufactured by using GaN150v1 process. However, due to factors beyond our control, fabrication of this phase shifter at the CPFC-NRC could not proceed as planned. The design was planned to be submitted for fabrication on 7th September, 2015 and then four months later samples should be delivered. Since this design was the only application for 2x2mm² space in this run fabrication referenced as “1503GK” that cost \$70K/run and because it is outside of our funds to purchase the entire run. The number of participants is not enough so the run of manufacturing has been completely cancelled. Due to this unexpected fabrication issue, only simulation results and design steps will be reported here

2.1 Quadrature 3-dB 90° Hybrid Coupler

Quadrature 3-dB 90° hybrid couplers are usually realized in some type of microstrip or stripline technology using distributed quarter-wavelength ($\lambda/4$) transmission lines (see Figure IV.14). They have been extensively progressed because of their good bandwidth of operation and of its straightforward design and reliability. However, this design approach could require several mm² of area to be realized and renders their size relatively large even for mm-wave frequencies due to the length of $\lambda/4$ lines [104]. Thus it would consume considerable wafer space of the used semiconductor technology, and the design size gets much larger. Additionally, the most important issue of the distributed $\lambda/4$ hybrid coupler in MMIC applications is the chip area which is directly related to the chip cost. Also the most significant challenge when dealing with a priced semiconductor technology especially GaN HFET technology is the high expense costs for technology access. Hence, there have

been several attempts to reduce the size of coupled line coupler, the most important alternative solution is to use lumped elements instead of resonant $\lambda/4$ transmission lines [104]. However, the bandwidth of the structure hybrid coupler is usually narrower than that of the typical $\lambda/4$ structure. Another issue comes up is that this structure becomes inefficient at high frequency (i.e mm-w) because of the inductors become very lossy and also tend to resonate at frequencies very close to the operating frequencies.

In this approach, the quarter-wave lines are approximated at operating frequency with lumped elements as depicted in Figure IV.15. Theatrically, the ABCD matrix of a single segment representing a perfect transmission line characterized by a characteristic impedance of Z_r is written as follow:

Equation (11)

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{bmatrix} \cos \theta & jZ_r \sin \theta \\ j\frac{1}{Z_r} \sin \theta & \cos \theta \end{bmatrix}$$

The equivalent of this matrix by using lumped elements can be written as follow:

Equation (12)

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{bmatrix} 1 & 0 \\ j\omega C_1 & 1 \end{bmatrix} \begin{bmatrix} 1 & j\omega L_1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ j\omega C_1 & 1 \end{bmatrix} = \begin{bmatrix} 1 - \omega^2 L_1 C_1 & j\omega L_1 \\ j\omega C_1 (2 - \omega^2 L_1 C_1) & 1 - \omega^2 L_1 C_1 \end{bmatrix}$$

From Equation (11) and Equation (12), we can drive the following equations:

Equation (13)

$$\cos \theta = 1 - \omega^2 L_1 C_1$$

Equation (14)

$$Z_r \sin \theta = \omega L_1$$

Equation (15)

$$\frac{1}{Z_r} \sin \theta = \omega C_1 (2 - \omega^2 L_1 C_1)$$

The combining between Equation 14 and Equation 15 gives the following equation:

Equation (16)

$$\frac{1}{Z_r} = \sqrt{\frac{2C_1}{L_1} - (\omega C_1)^2}$$

So the passive elements, L_1 and C_1 , of the hybrid coupler can be calculated by the following driven equations:

Equation (17)

$$L_1 = \frac{Z_r \sin \theta}{\omega}$$

Equation (18)

$$C_1 = \frac{1}{\omega Z_r} \sqrt{\frac{1 - \cos \theta}{1 + \cos \theta}}$$

By using the same previous procedures, the other passives elements, L_2 and C_2 , can be, also, calculated as follow:

Equation (19)

$$L2 = \frac{Z_p \sin \theta}{\omega}$$

Equation (20)

$$C2 = \frac{1}{\omega Z_p} \sqrt{\frac{1 - \cos \theta}{1 + \cos \theta}}$$

So these previous equations give theoretically first guess values of the lumped elements of hybrid coupler.

Based on this topology, we report here a simulation analysis of a new fully embedded lumped element GaN MMIC 3-dB/90° hybrid coupler at X-band that it will be later used to conduct an analysis of a phase shifter design. A three-dimensional layout view of the coupler, showing embedded metal and vias layers, of the designed coupler is displayed in Figure IV.20.

The built block of the 3-dB/90° hybrid coupler using lumped spiral inductors and metal-insulator-metal (MIM) capacitors is very small in size (0.85x1mm²). It consists of lumped multi-turn spiral inductors and MIM capacitors from NRC GaN150 PDK components library [105]. The mutually coupled inductors turns are rectangular spiral inductor type and are implemented with reinforced between two metals, metal 2 (2ME) on metal 1 (1ME) by using via connection (VIA2), which results in an inductor having a higher Q-factor and size reducing. The current carrying capability of this inductor is limited by the width of the air-bridges. Higher currents can be sustained by increasing the width of the air-bridges, with a commensurate increase in the gap spacing between the inductor turns. A sample layout for a square inductor is shown in Figure IV.16, while in Figure IV.17 an inductor equivalent circuit is presented which is used to estimate the inductance (L_s), series resistance (R_s) and first resonance frequency F_{RES}.

The MIM capacitors are formed by 2ME on top of 1ME without a VIA2 connection. A layer of silicon nitride, also used to provide insulation, is used as the

dielectric layer. The dielectric constant of the silicon nitride is 6.5 and the thickness is 0.3 μm [105]. The capacitance density of the MIM structure is 0.19 fF/ μm^2 . Figure IV.19 illustrates the capacitor layout.

At 10 GHz, the optimized values of the four lumped elements, L1, L2, C1 and C2, constituting the hybrid coupler are, respectively, 6.7 nH, 8.45 nH, 369 fF and 136 fF. These values, firstly, have been determined by using the above equations (Equation (17), Equation (18), Equation (19) and Equation (20)) and then have been optimized in ADS to achieve good performances. So, these values are corresponding to parameters presented in Table IV.1 and Table IV.2.

Table IV.1: Optimized Values of Inductors L1 and L2

	Inductor L1	Inductor L2
Value (nH)	6.7	8.45
Ns (turns)	10	10
L1 (μm)	120	155
L2 (μm)	125	125
L3 (μm)	110	135
Ln (μm)	20	20
W (μm)	15	15
S (μm)	5	5
Wb (μm)	10	10
Ab	90	90
Be (μm)	30	30

Table IV.2: Optimized Values of Capacitors C1 and C2

	Capacitor C1	Capacitor C2
Value (fF)	369	136
W (μm)	43.86	26.63
L (μm)	43.86	26.63
Wc (μm)	15	10

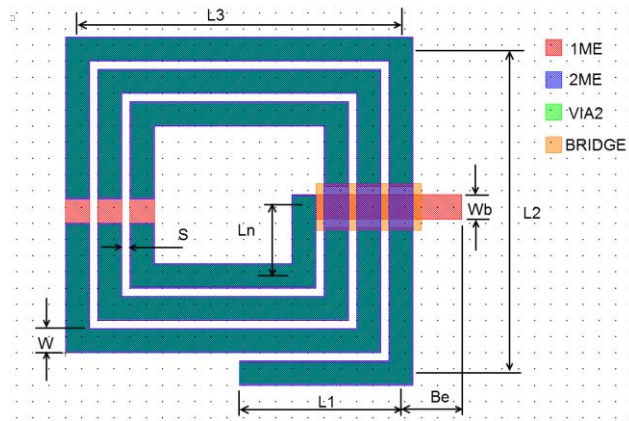


Figure IV.16: Layout of a Spiral Inductor Generated from NRC GaN150 PDK [105]

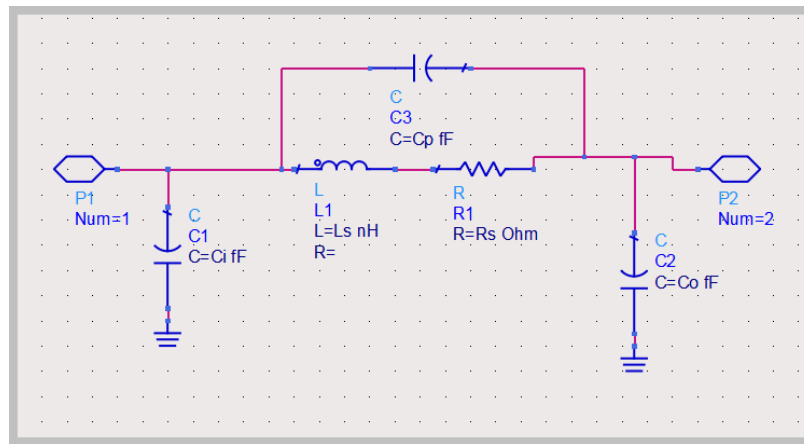


Figure IV.17: An Equivalent Circuit to Estimate L_S , R_S and F_{res} [105]

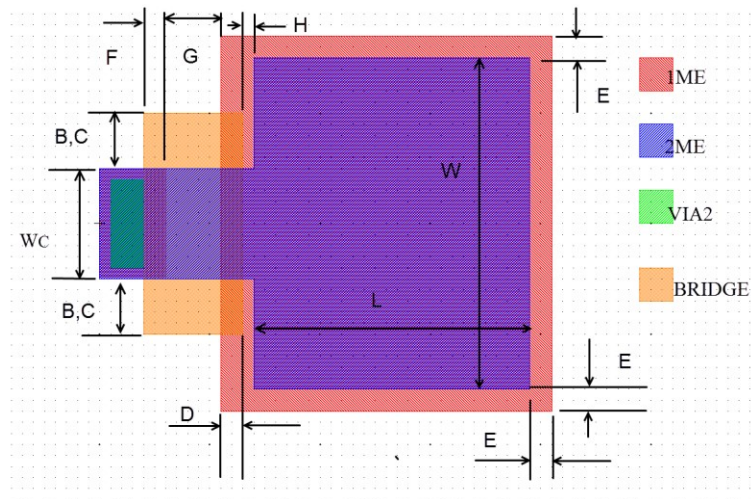


Figure IV.18: Layout of A MIM Capacitor [105]

For the presented hybrid coupler, as indicated in Figure IV.19, port 1 is designed as the input port, port 2 as the transmitted port, port 3 the coupled port and port 4 the isolated port. Since this is a symmetrical network, any port can be used as the input port and the function of the other ports appropriately defined. Through wafer vias (TWV) are used for connection to the backside ground wafer metal. The ports 1 and 4 consist of G-S-G pads that have a pitch of $150\text{ }\mu\text{m}$ to be compatible with RF probes of the same geometry.

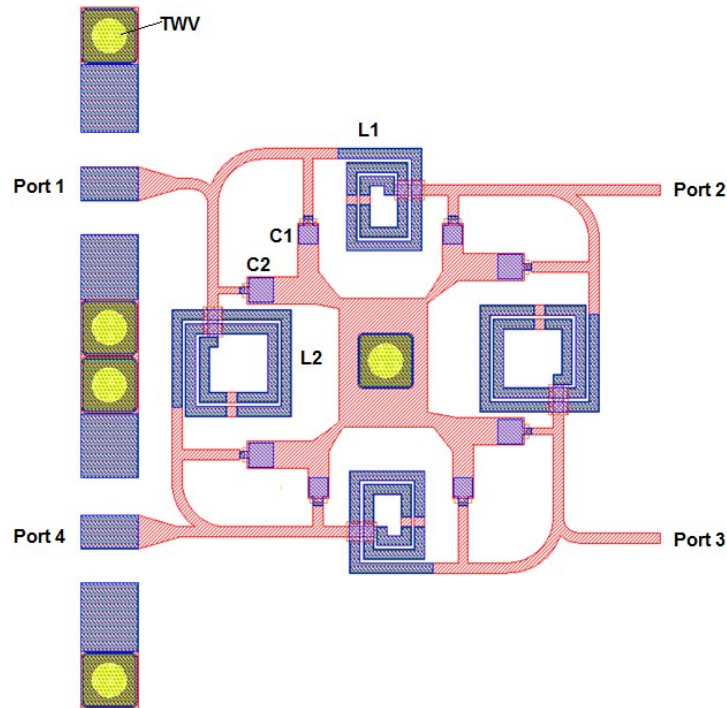


Figure IV.19: Layout of the designed hybrid coupler

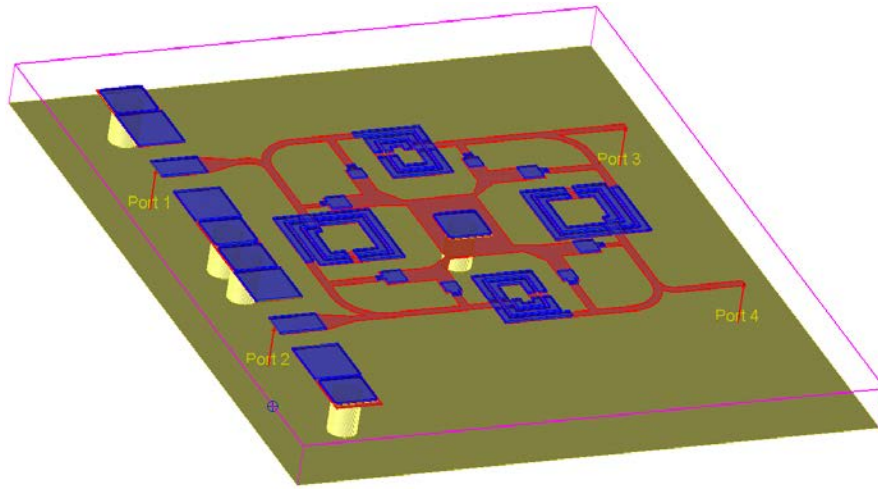


Figure IV.20: 3-D Layout view of the designed hybrid coupler

2.1.1. Simulated Results and Discussion

The ADS co-simulated layout results for the complete hybrid coupler are plotted in Figures from Figure IV.21 to Figure IV.24. The insertion loss at port 2 and port 3 are -0.7 dB at 10 GHz and has a maximum variation of -0.4 dB over a 1 GHz bandwidth (see Figure IV.21). The amplitude imbalance at the center frequency is almost 0 dB. The phase difference (see Figure IV.24) between the outputs of ports 2 and 3 is about 89.5° at 10 GHz and varies by only 0.5° over a 1 GHz bandwidth. The return loss is better than -20dB at 10GHz (see Figure IV.22) and the isolation between the ports is better than -35dB (see Figure IV.23).

This compact 3-dB 90° GaN MMIC hybrid coupler based on lumped elements has been successfully designed by using NRC GaN150v1 process. The advantages of size reduction and good performance of the proposed 3-dB 90° hybrid coupler at X-band have been confirmed through the simulated results. Comparing to a reported GaAs hybrid coupler using distributed elements [106] with a size of $3.1 \times 2.3 \text{ mm}^2$, this design (size of $0.85 \times 1 \text{ mm}^2$) has shown a size reduction of 70 % in the circuit area at 10 GHz. These results indicate that the proposed hybrid coupler is very promising for high density and tunable MMIC applications. Moreover, the hybrid coupler is used for designing a highly miniaturized and tunable phase shifter.

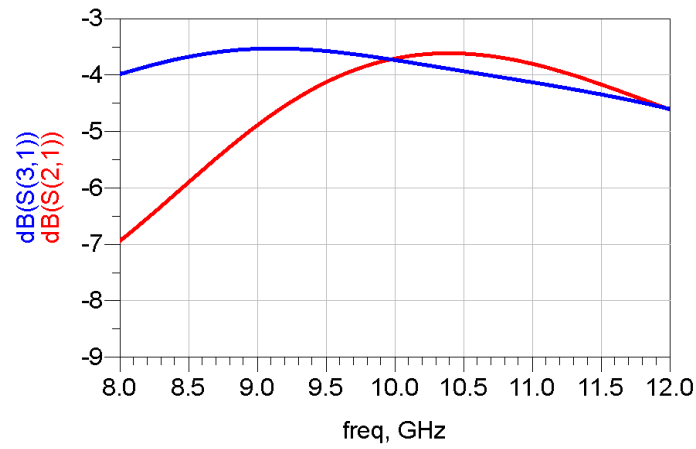


Figure IV.21: Insertion Loss versus frequency

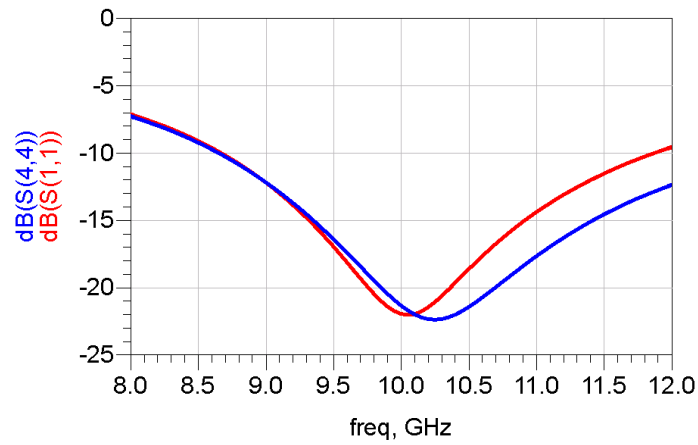


Figure IV.22: Return Loss versus frequency

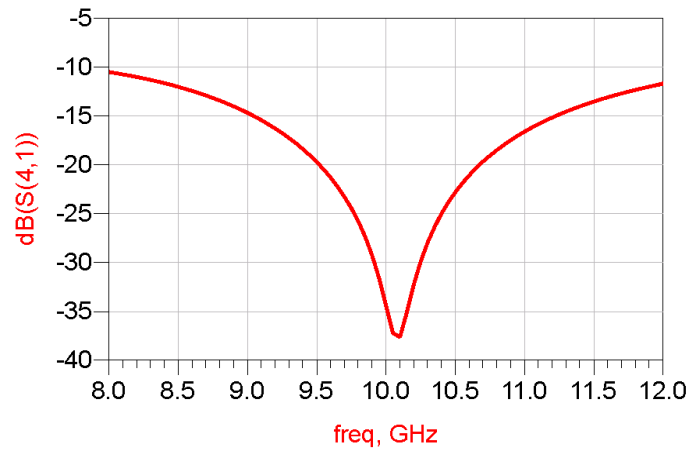


Figure IV.23: Isolation versus frequency

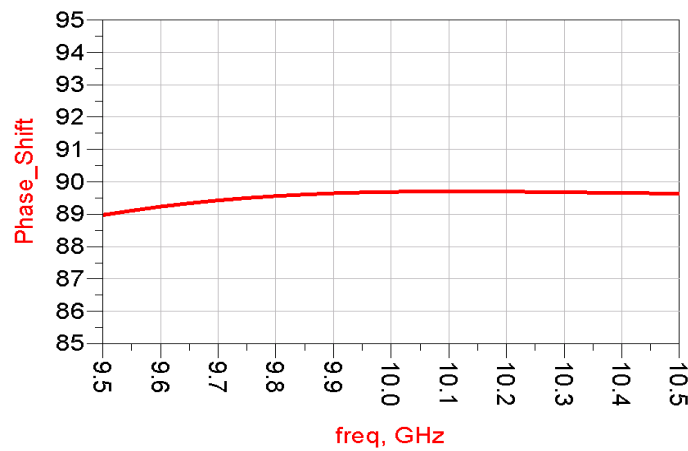


Figure IV.24: Phase Shift Difference versus frequency

2.2 Phase Shifter Design

As previously stated, the developed hybrid coupler will be used to design a phase shifter. This section discusses the design analysis of X-band GaN-based phase shifter. As depicted in Figure IV.25 and Figure IV.26, a layout photo as well as a 3-D view of the phase shifter are presented.

Here two identical GaN varactors were used as tuning loads purpose and placed at the transmitted and coupled ports of the hybrid coupler. These devices have a gate width of 200 μ m and two fingers for each. The actual used GaN device model is scaled from the two characterized original gate width GaN devices of 50 μ m and 100 μ m model described previously in Chapter III. DC biasing is provided to the GaN varactors via DC probes with external bias tees. The circuit was simulated in Agilent's Advanced Design System (ADS) and Momentum was used to model the passive circuitry. The circuit was optimized to provide a maximum continuous phase shift at 10 GHz.

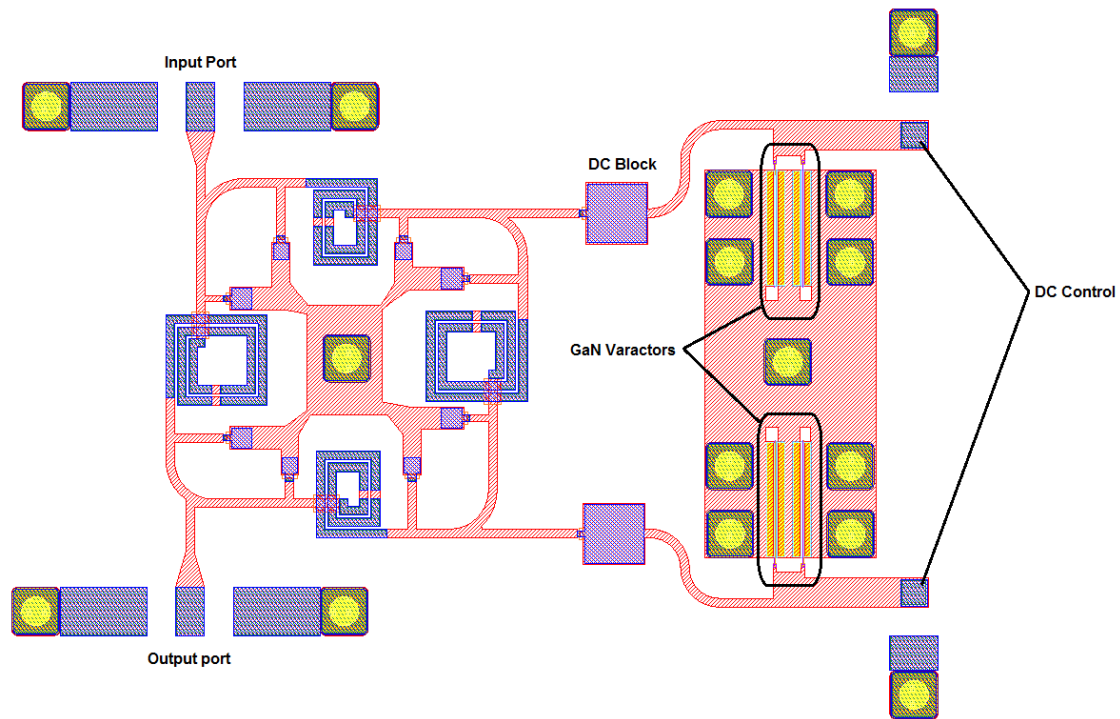


Figure IV.25: Layout of the designed Phase Shifter

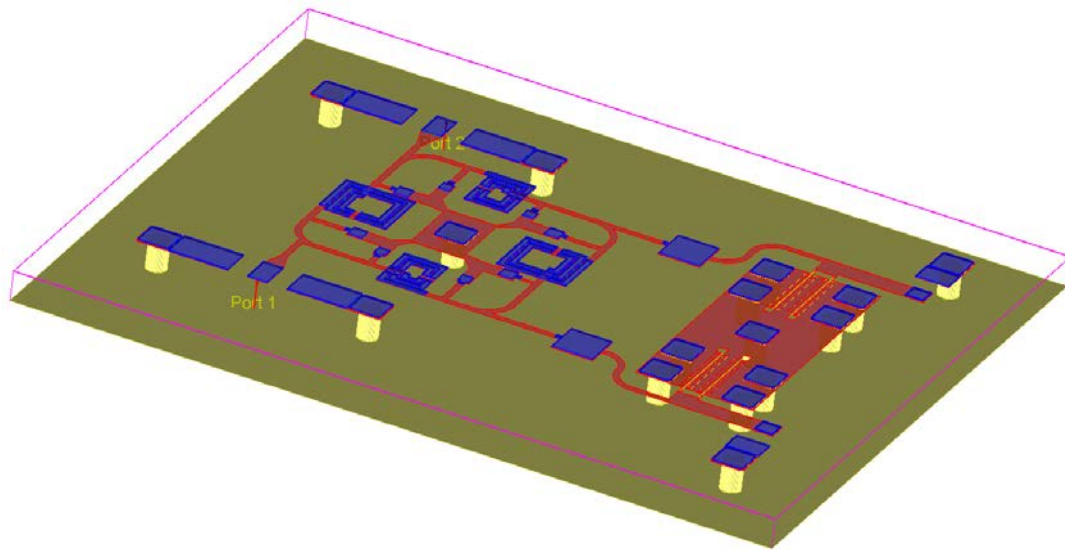


Figure IV.26: 3-D Layout view of the designed Phase Shifter

2.1.2. Simulated Results and Discussion

In Figure IV.27, the return loss of the phase shifter under different bias conditions is presented and is better than 20 dB across a 1 GHz bandwidth centered at 10 GHz. As clearly can be seen, a good match is achievable over this range of 9.5–10.5 GHz for all bias point varying from -3.5 V to -5.5 V which corresponding to the tuning range of the developed GaN varactor as stated previously in Chapter III.

Figure IV.28 shows the insertion loss of the phase shifter in different bias level from -3.5 V to -5.5 V. At 10 GHz worst case of the insertion loss is about -3 dB and occurs at a bias point of -4.3 V. This value could be due to the higher series resistor value, 9 Ω , of the used varactor (i.e W100L0.15) at this bias voltage as reported in Chapter III (see Figure III.26). The amplitude imbalance between the two extreme DC bias states (i.e -3.5 V and -5.5 V) is about 1.07 dB at 10 GHz, and is therefore better than 1.2 dB over the extended band from 9.5 to 10.5 GHz.

Figure IV.29 presents the phase shift obtained from the circuit versus DC bias at 10 GHz. Therefore, a continuously variable phase-shift range of 80° is achieved as shown. This phase shift range versus DC bias exhibits the same general behavior as for equivalent capacitor or varactor versus DC bias as discussed in Chapter III in Figure III.24, which can be separated into three regions: range (1) for V_G above -3.5 V corresponding to the minimum phase shift value (-80°), range (3) for $V_G < -5$ V corresponding to the maximum phase shift value (0°) and range (2) for $-5 \text{ V} \leq V_G \leq -3.5 \text{ V}$ where the phase shift values change significantly and rapidly.

Maximum loss figure-of-merit (FOM) of this phase shifter of 74.76°/dB at 10 GHz and 66.66°/dB in the range of 9.5 –10.5 GHz were achieved. The loss FOM can be expressed as:

Equation (21)

$$FOM = \frac{|\Delta\phi|^{(^\circ)}}{\alpha_{\max}^{(dB)}}$$

Where $\Delta\phi$ and α_{\max} are the differential phase shift and maximum insertion loss, respectively.

Based on this phase shifter structure, one varactor diode placed at the two coupler's output ports could enough to get a theoretical phase shift of 180° as explained in [102]-[107]. However, varactor diodes are not perfect. This mean that there are losses due to their equivalent series resistor also these diode have a limited tuning capacitance range, thus makes it hard to achieve a 180° complete phase shift.

The overall simulated performance and operating frequency range of this phase shifter are compared favorably with those of the reflection phase shifters using GaAs MMIC technology [108]-[109]-[110]. In [108] a phase shift of 109° with an insertion loss of 1.8 dB over 16-18 GHz was achieved by only placing one inductor and varactor at each coupler's output port. This inductance increases more the overall impedance (varactor and inductor) tuning range. It is possible to achieve a 360° phase shifter range with 4.2 dB insertion loss in the same frequency range by connecting three phase-shifter chips in series as reported in this same work [108]. Using GaAs MMIC technology, another work [109] was presented where a phase shift of 210° with a loss of 4.9 dB and a 1-dB input compression point of higher than 5 dBm was measured at 6.2 GHz. Based on the same structure, a miniaturized Ku-band GaAs MMIC phase shifter using two quarter-wave-length transmission lines was reported in [110]. A phase shift of more than 180° and an insertion loss of 3.6 dB are obtained at the frequency range from 12 to 14 GHz. The chip size of the experimental MMIC phase shifter is less than 3.0 mm^2 .

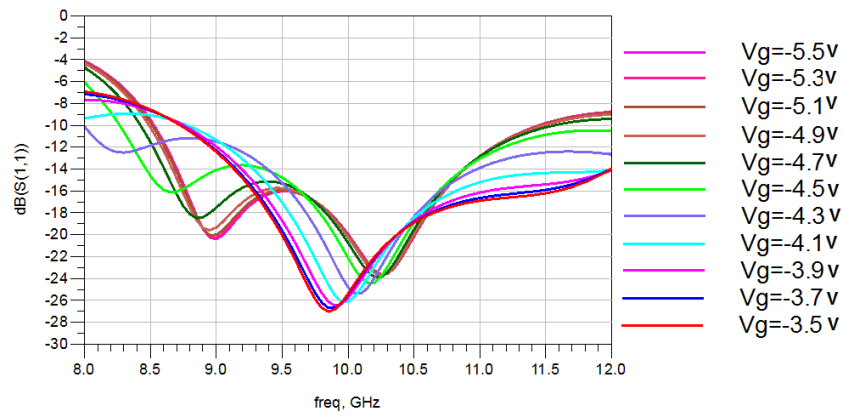


Figure IV.27: Return Loss at several DC Bias from -3.5 V to -5.5 V

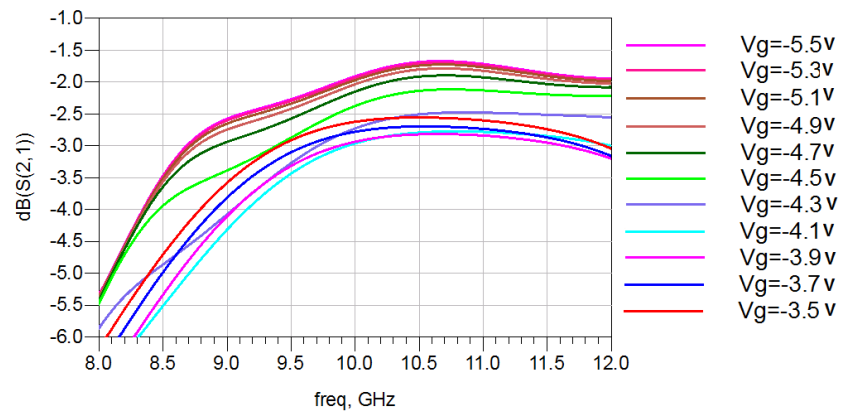


Figure IV.28: Insertion Loss of the Phase Shifter at several DC Bias from -3.5 V to -5.5 V



Figure IV.29: Phase Shift versus DC Bias at 10 GHz

In this section, a GaN phase shifter design based on reflective topology has been presented for high RF power source application. First, the 3-dB 90° hybrid coupler has been designed and simulated using NRC GaN150 PDK. Then two developed GaN varactors were paced on the two coupler's output ports as loads.

Under different bias conditions varying from -3.5 V to -5.5 V, the return loss of the phase shifter is better than 20 dB across a 1 GHz bandwidth centered at 10 GHz, while good match is achievable over this range of 9.5–10.5 GHz. Worst case of the insertion loss is about -3 dB at 10 GHz and occurs at a bias point of -4.3 V where the equivalent resistor of the used varactors is significantly high. Therefore, a continuously variable phase-shift range of 80° is achieved at 10 GHz. These achieved performances were compared favorably with other works that use GaAs technology.

III. GaN Reconfigurable 3-dB/90° Hybrid Coupler

1. Review

Based on the previous presented 10 GHz GaN hybrid coupler, a frequency reconfigurable 3-dB 90° hybrid coupler is designed. In order to achieve frequency reconfigurability, varactors diodes are used instead of the four fixed shunt lumped capacitors C_1 of the previous static frequency hybrid coupler (see Figure IV.19). In this configuration, an electronically frequency tuned is achieved by changing the bias voltage applied across the varactors. This means that changing the resonance frequency of branch-line (LC parallel resonator) hybrid of the coupler, we can provide the different operating frequency bands. Additionally, the tuned frequency of the coupler is defined as the frequency at which high isolation and low return loss are achieved, while realizing phase shift of 90° between the isolated and the coupled ports. The novel tunable GaN hybrid coupler employs the developed GaN varactors elements to provide the reconfigurability from 10 GHz to 16 GHz.

Recently, considerable work in tunable couplers consist of MMIC-based active couplers and varactor diode based passive couplers have been reported in the literature which most of them are operating below X-band frequency. However, most of these reported couplers exhibit, in general, a small frequency tuning range. It is still a challenging task to design tunable couplers with tuning ranges wide enough to cover desired frequency bands. For instance, in [111] a tunable hybrid coupler is reported using GaAs technology. This presented tunable GaAs MMIC directional coupler design uses tunable capacitances to achieve a tunable coupling coefficient ($|S_{31}|$) at 2 GHz. Over a bias range of 0 V to -1.5 V the measured S-parameters for the coupled port demonstrate a tuning range of -6.6 dB to -60 dB. The input return loss is better than -12 dB for all bias voltage levels with isolation better than -17 dB. This design is implemented in a 0.5 μm GaAs process with Schottky varactor diodes, and occupies an area of $2.2 \times 1.4 \text{ mm}^2$. In [112] a frequency tunable broadband MMIC active directional coupler is discussed. The coupler provides various coupling gains such as 3 dB, 0 dB, -3 dB, and -6 dB, also a tuned frequency from 5.5 GHz to 7.8 GHz was achieved by applying different bias voltages. Using varactors for tunability purpose, a novel compact dual-band reconfigurable power divider is presented in [113] for smart antenna applications. Measured results show that, by biasing one varactor and keeping the other one at 0V, good performance are achieved at the center frequency 2.45 GHz, while this frequency can be tuned to 5.25 GHz by only switching the bias state of varactors. Also, any value of power ratio can be selected from 1:0 to 0:1 for both the center frequencies 2.45 GHz and 5.25 GHz, maintaining an average insertion loss better than -1.5 dB and -3 dB in the 2.45 GHz and 5.25 GHz bands, respectively, along with a return loss better than -15 dB in both frequency ranges. Measured isolation at port 2 is always better than -20 dB in both frequencies.

2. Design of Reconfigurable 3-dB/90° Coupler

In this context, here we report a continuous broadband frequency tunable GaN hybrid coupler. The achieved tuning range is from 10 GHz to 16 GHz corresponding to a bandwidth of 46%. As far as the authors know, this proposed frequency reconfigurable hybrid coupler is the first reported work that uses GaN HEMTs technology. Figure IV.30 and Figure IV.31 show the tunable layout design version of the coupler, where the shunt MIM capacitors are replaced by the developed GaN varactors model. The varactors provide the function of frequency tunability by adjusting their voltage level. This varactor device, W200L0.15, is a two fingers and 200 μm gate length and is fabricated using GaN150 process.

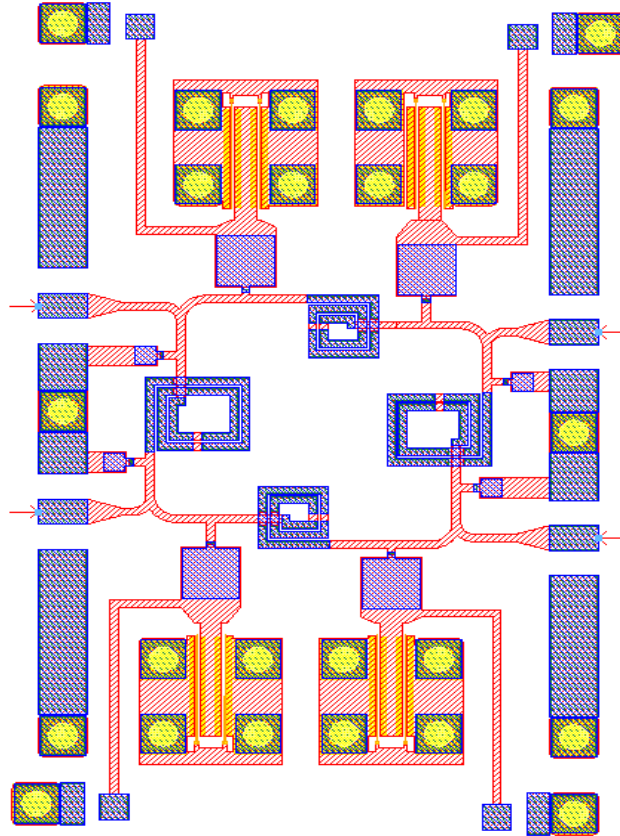


Figure IV.30: Layout of the designed hybrid coupler

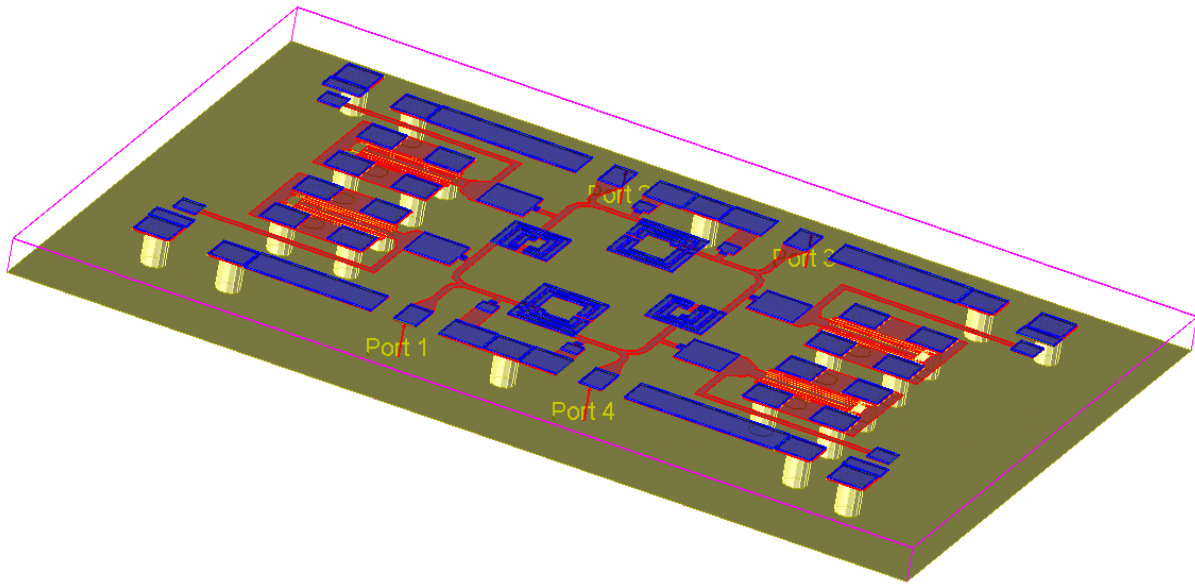


Figure IV.31: 3-D Layout view of the designed hybrid coupler

2.1 Simulated Results and Discussion

Simulation results, which are shown in Figure IV.32, Figure IV.33, Figure IV.34, Figure IV.35 and Figure IV.36, respectively, are illustrating, at several DC level voltage for return loss, isolation, power division at transmitted port and loss insertion at coupled port.

The overall return loss depicted in Figure IV.32 is better than -13.5 dB over all the tuning range from -3.7 V to -4.8 V. This worst case of -13.5 dB is achieved at a DC bias of -3.7 V corresponding to the maximum value of varactor capacitance. In Figure IV.33, the isolation is clearly below than -14 dB over the full tuning range.

The simulated magnitude of S21 parameter, as illustrated in Figure IV.34, is close to -3.5 dB and is getting poorer as varactor capacitance values decreases. A worst value of -5 dB is achieved at the minimum capacitance value. While at port 3, the S31 parameter (see Figure IV.35) behaves as S21 but in a reverse way. This means the worst case which is about -3.7 dB achieved when the varactor capacitance

is at its maximum. As a result, the amplitude imbalance is varying from -0.2 dB at 10 GHz and -2 dB at 16 GHz.

A minimum well-balanced quadrature phase of 86.5° is obtained between the coupled port 2 and the through port 3 as plotted in Figure IV.36. This phase is increasing and getting closer to 90° as varactor capacitor values are decreasing. The tunable quadrature coupler has 46% center-frequency tunable range from approximately 10 to 16 GHz.

There are four DC blocking capacitors on each port to block the DC bias from the output. This simplified bias network aids in reducing the overall size and complexity of the circuit.

Unfortunately, as for the phase shifter, this design has not been manufactured because the run of manufacturing on GaN150 process has not been done in time by NRC.

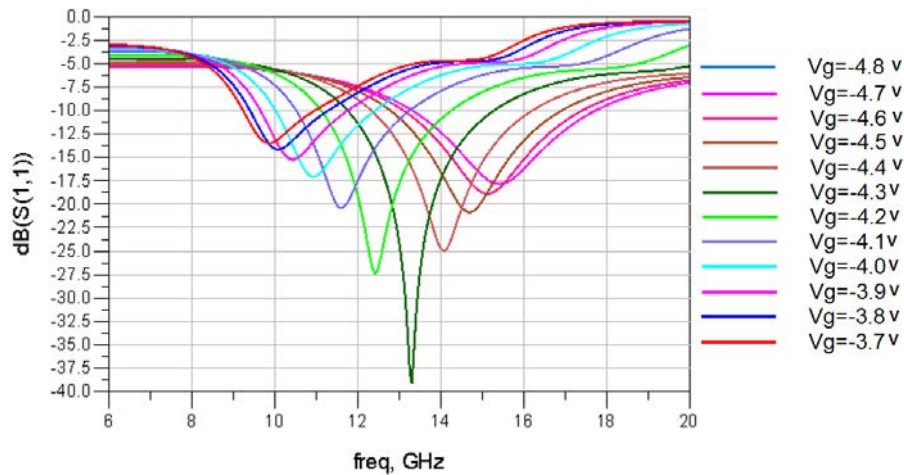


Figure IV.32: Return Loss at several DC Bias from -3.7 V to -4.8 V

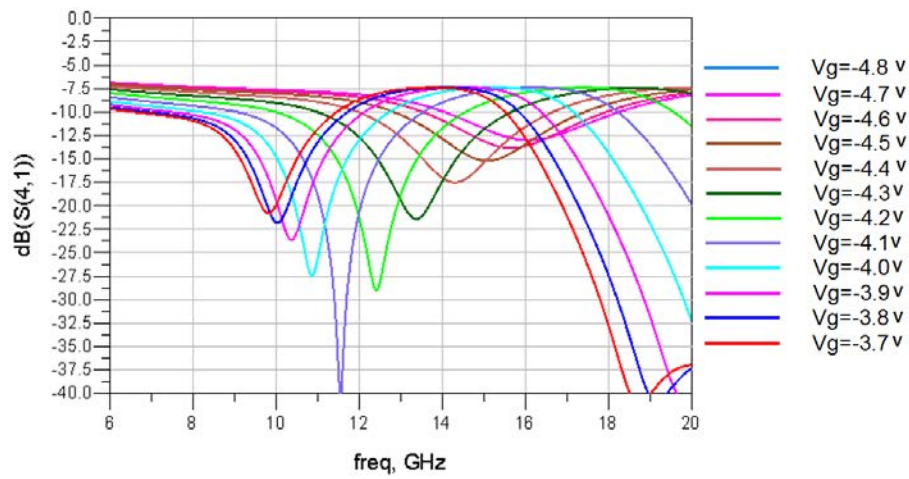


Figure IV.33: Isolation at several DC Bias from -3.7 V to -4.8 V

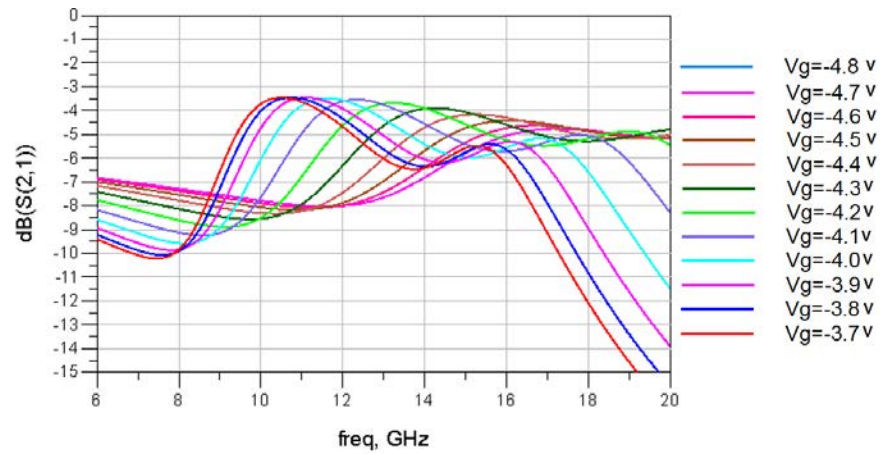


Figure IV.34: Level of S_{21} at several DC Bias from -3.7 V to -4.8 V

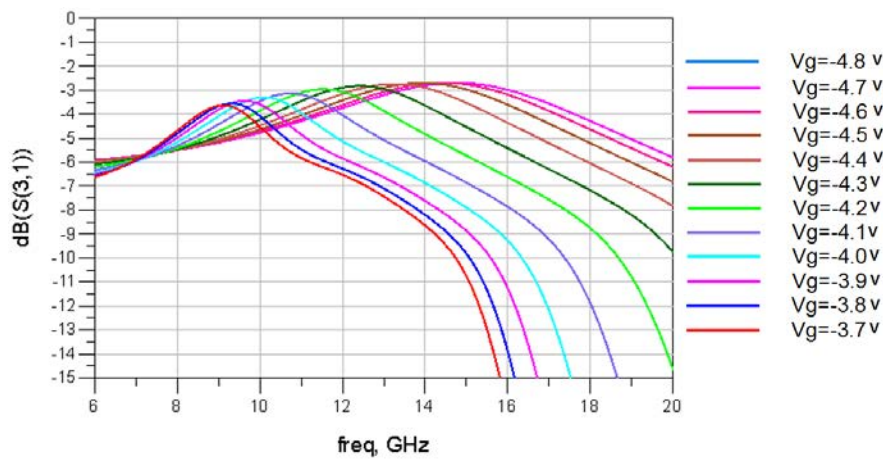


Figure IV.35: Level of S_{31} at several DC Bias from -3.7 V to -4.8 V

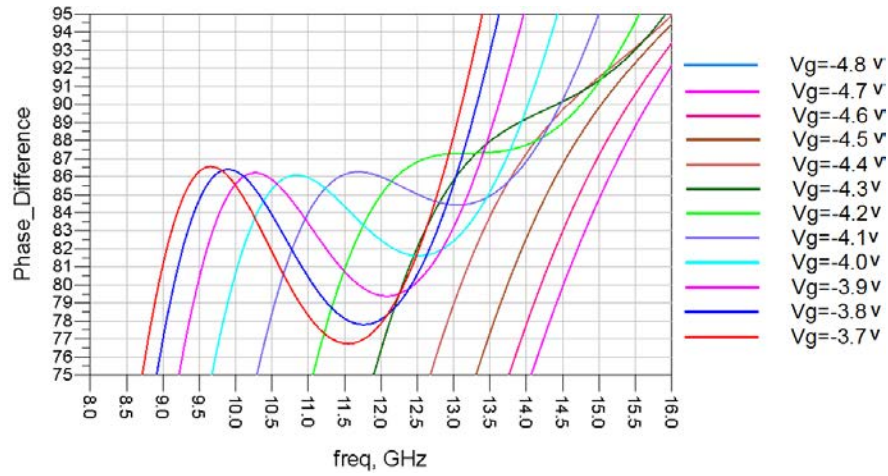


Figure IV.36: Phase Difference at several DC Bias from -3.7 V to -4.8 V

A varactor tunable broadband quadrature hybrid coupler has been investigated and simulated from X-band to Ku-band frequencies applications. First, a static coupler has been designed to meet the specifications of a typical quadrature hybrid coupler (3-dB insertion loss, good return and isolation loss, and 90° phase difference between coupled and through ports) at 10 GHz. Then, a tunable broadband coupler has been designed by inserting varactor diodes as shunt capacitance elements in order to control the operating frequency. This design is implemented in a 0.15 μm GaN process from NRC, and occupies an area of 1.35 \times 0.9 mm². Good simulation results have been demonstrated.

This novel varactor reconfigurable hybrid coupler is proposed to overcome the need of high power tunable RF/microwave circuits which are required for multi-standard and multiservice applications. By changing the bias voltage of the varactor to control the resonance condition of parallel LC resonator, this proposed hybrid coupler can provide the desired operating frequency from 10 GHz to 16 GHz.

IV. GaN-based Oscillator

1. Review

Microwave oscillators are widely used in wireless communication systems. An oscillator is an electronic circuit which can generate a periodic signal by converting DC power to RF power. Two approaches, such as feedback oscillator and negative resistance oscillator [114], are commonly used for the design of oscillators. In the feedback topology, the oscillator is constituted of an amplifier with a positive feedback network (see Figure IV.37) that are forming a loop. The condition for oscillation is that a part of output signal is combined in phase with the input signal and the amplitude of the loop gain is larger than unity. This topology is used to design two oscillators in this thesis.

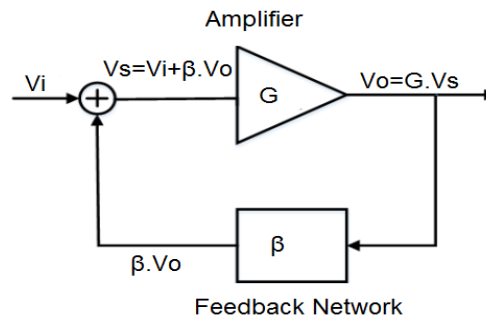


Figure IV.37: Block diagram of a feedback oscillator

In state-of-the art most of low-phase noise oscillators are designed in mature semiconductor technology such as GaAs, InP and SiGe, with key property for good low phase noise. However, one of the drawbacks of such oscillators is that the output power is limited by the relatively low breakdown voltage. In the other hand, GaN HEMTs technology with significantly higher breakdown voltage is become more and more used in oscillators that potentially reach relatively low phase noise [115], very high power handling capabilities and good linearity. GaN oscillators also have the advantage of not needing an additional output buffer amplifier stage between

them and a load, thus simplifying the circuit. As a result, a GaN-based system will be less complex, and thus smaller.

Currently, a number of published works have been devoted to improve the high power performances of oscillators by adopting GaN HEMTs technology with high power capabilities advantages. Most of these reported GaN-based oscillators are designed mainly for low frequency such L-band [116]-[117], S-band [118]-[119]- [120], C-band [121]-[122]-[123]-[124]-[125]-[126]-[127]-[128] and X-band [129]-[130]- [131]- [132]- [133]- [134], while there are a few reported works for millimeter-wave frequency such as Q-band [135] and V-band [136].

Earlier in 2001, the first report of AlGaIn/GaN HEMT-based VCOs operating at 6 GHz is presented in [121]. An output power of 27 dBm and phase noise level of -92 dBc/Hz at 100 KHz offset were achieved. This achieved phase noise value was favorably equivalent to the single-sideband noise of a GaAs FET-based oscillator [137]. It is also clearly shown in [121] that GaN oscillators with large tuning range can achieve a phase noise of -123 dBc/Hz at 1MHz, whereas those fixed frequency ones can achieve a phase noise as low as -135 dBc/Hz [125] at 1MHz. To the authors' knowledge of [125], this GaN-based oscillator achieves the lowest phase noise compared to other GaN HEMT based integrated oscillators. An output power of 21 dBm is achieved at 7.9 GHz when the device is biased at V_{gs} of -3V and V_{ds} of 28 V. Another design is presented in [122], which used an in-house GaN HEMT facility. The phase noise of the designed 5 GHz oscillator can be kept more or less as low, -105 dBc/Hz at 100 kHz, as the ones (-112 dBc/Hz at 100 kHz) designed in GaAs [138] while an output power of more than 20 dBm is achieved. Still over the C-band, differential GaN oscillators are reported in [123]. An output power level of 23dBm at 4.16GHz is reported, while phase noise is -86 dBc/Hz at offsets of 100 kHz and -115.7 dBc/Hz at offsets of 1 MHz. The second and third harmonic suppression are equal to -45dB and -70dB respectively. High power single-ended Colpitts-type GaN oscillators using field-plated HEMTs are described in [126]. Both output power and operation bias can

be significantly increased to 32.8 dBm and $V_{ds} = 40\text{V}$ with an output power density of 3.8W/mm at 5GHz. The DC-to-RF-conversion efficiency amounts to 21%, while the measured phase noise at 1MHz offset from the carrier amounts to -132 dBc/Hz. A recent C-band work is reported in [128] where a MMIC GaN HEMT VCO with high tuning linearity and low phase noise is presented. The designed VCO is based on a balanced Colpitts topology and is tunable between 6.45-7.55 GHz with good tuning linearity, constant output power of 2 dBm at a bias condition of $V_d = 6\text{ V}$ and an associated I_d of 33 mA, and a good phase noise with little variation over the tuning range. The measured phase noise is -98 dBc/Hz at 100 kHz and -132 dBc/Hz at 1 MHz offset frequency.

Over the X-band frequency, some GaN-based oscillators have been implemented. In [129] a VCO with an output power of 35 dBm between 8.5 and 9.5GHz is presented. Output power density of 2.1W/mm is reached at $V_{ds} = 30\text{V}$. The technology uses GaN HEMTs with a gate length of 0.15 μm . The phase noise is estimated to be -87 dBc/Hz at 100 kHz offset. Another interesting X-band GaN HEMTs-based oscillator is also designed in an in-house facility and is presented in [130]. The VCO exhibits a frequency tuning range from 9.11 to 9.55 GHz, an average output power of 3.3 dBm with phase noise of -82 dBc/Hz at 100 kHz offsets and -110 dBc/Hz at 1 MHz. These performances are investigated under a 5 V drain bias instead of utilizing large device with high drain bias to achieve the high output power. Although the phase noise of this oscillator still needs to be further improved, it opens up a new examination on the design of oscillators in GaN HEMT technology for low voltage, moderate output power as well as low phase noise. A design of an X-band GaN oscillator is discussed in [131]. At 9.9 GHz, an output power of 20 dBm is measured, with a phase noise level around -105 dBc/Hz at 100 kHz offset frequency, but with a poor 2nd harmonic found at -10 dBc, while the third harmonic is rejected more than -30 dBc from the carrier. An X-band oscillator is presented in [132] using common-gate balanced Colpitts oscillator topology. A commercial Triquint's 0.25 μm GaN MMIC HEMT process is used. Using the same commercial GaN HEMT process

as in [132], a recent X-band ultra-low phase-noise GaN HEMT oscillator is described in [134] by the same authors of [132]. The designed oscillator is based on a GaN HEMT MMIC reflection amplifier and a rectangular aluminum cavity. It oscillates at 9.9 GHz with an output power of 5 dBm and an excellent phase noise of -145 dBc/Hz at 100 kHz and -160 dBc/Hz at 400 kHz. These are the best reported phase noise values so far by using GaN HEMT devices. Going higher in frequency, a low phase noise power-efficient MMIC GaN-HEMT Oscillator at 15 GHz based on a Quasi-lumped on-chip resonator is reported in [133]. An excellent phase noise of -106 dBc/Hz and -133dBc/Hz, respectively, at 100 kHz and 1 MHz offsets and a low output power of -6 dBm are experimentally demonstrated.

A Q-band MMIC oscillator (39GHz) is presented in [133]. An output power of 25 dBm at $V_{ds} = 25V$ ($I_d = 156$ mA) is reported with a low-phase noise level of -120 dBc at 1MHz offset from the carrier. The DC- to RF-conversion efficiency is about 12%. Around 53 GHz, the same authors report a new V-band GaN MMIC VCO [136] realized on a gate length of 0.2 μ m AlGaIn/GaN HEMT process. The delivered output power is around 11 dBm at 53 GHz with an estimated phase noise of -97 dBc/Hz at 1 MHz offset with bias conditions of $V_d = 15$ V and $V_g = -3V$. These reported works [135]-[136] demonstrate the potential of using GaN technology for military and commercial applications that require high frequency, high power, and low phase noise frequency sources.

2. Design of GaN-based Oscillators

In this perspective, using GaN HEMT technology, two X-band oscillators are presented in this section: a fixed frequency oscillator (FFO) and a tunable frequency oscillator (TFO). The two oscillators are designed based on feedback oscillator topology and are fabricated. The GaN HEMT based FFO is designed to operate around 10 GHz while the GaN HEMT based TFO is tunable between 7.8-8.6 GHz, corresponding to a tuning range close to 10%. The frequency reconfigurability

of the designed TFO oscillator is based on the in-house developed GaN varactor detailed in chapter III.

2.1 Feedback Oscillator Topology

Oscillator based on feedback topology using amplifier approach is introduced in this section. The GaN PA design used here is presented in next section. A frequency-selective feedback network printed on Neltec NX9300 substrate is designed to return part of the output signal to the amplifier input. From Figure IV.37, it can quickly derive the expression of the transfer function of the feedback oscillator as:

Equation (22)

$$\frac{V_o}{V_i} = \frac{G}{1 - \beta.G}$$

This design topology offers some very attractive features, including a straightforward design, a relatively pure sine-wave output, and a very stable frequency.

2.2 Power Amplifier Design

As reviewed in Chapter II, many GaN-based PAs have been reported.. In this thesis, a single frequency power amplifier operating at X-band is designed and realized, using a GaN discrete bare die transistor from Cree. This PA will be used to conduct the complete analysis of the reconfigurable frequency oscillator using GaN HEMT technology at X-band.

2.2.1 PA Design Procedure

a) Cree's CGHV1J025D GaN Discrete Transistor Die

Cree's CGHV1J025D GaN discrete transistor die is chosen as the active device to design the PA as well as the fixed frequency and the tunable frequency oscillators. The manufacturer provides a nonlinear model for the device, so DC and small signal analysis can be easily done using one of commercially available electromagnetic simulation tool. Again for this design, ADS Agilent was used as EM and schematic simulator.

From the datasheet [139] provided by Cree, the total gate length of the CGHV1J025D is 5 μm and specified power density of the device is around 5 W/mm. Therefore, it can provide approximately 25 W output power with 10 dB power gain in 9-11 GHz frequency band. However, these values are measured using on-wafer measurements so they do not include any circuit loss. A photo of the transistor is shown in Figure IV.38.

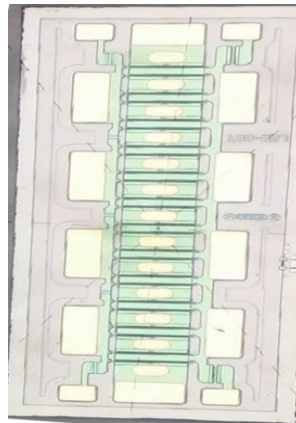


Figure IV.38: Photo of the CGHV1J025D GaN Transistor Die

Choosing this device has been made on some purposes which are summarized as follow:

- The maturity of using this device in previous GaN PA works
- Its performances around X-band appears very interesting
- The cost is relatively moderate (\$75 US/Unit)

The GaN PA is implemented with matching circuits on a Neltec NX9300 substrate which its proprieties are:

- Dielectric Constant of 3
- Thickness of 0.786 mm
- Loss Tangent of 0.0006 to 0.0011 @ 10GHz
- Thermal Conductivity of 0.381 Watts/m/K

By selecting a material with a ϵ_r of 3 allows to design a 50 Ohms TL of width of 2 mm at 10 GHz which falls in Cree's device's width, 1.9mm. Since wire-bond technique will be used between transistor die and matching network substrates to provide connection, a TL of width of 2 mm will be good to dispatch symmetrically the wires bond over the entire surface (see Figure IV.39).

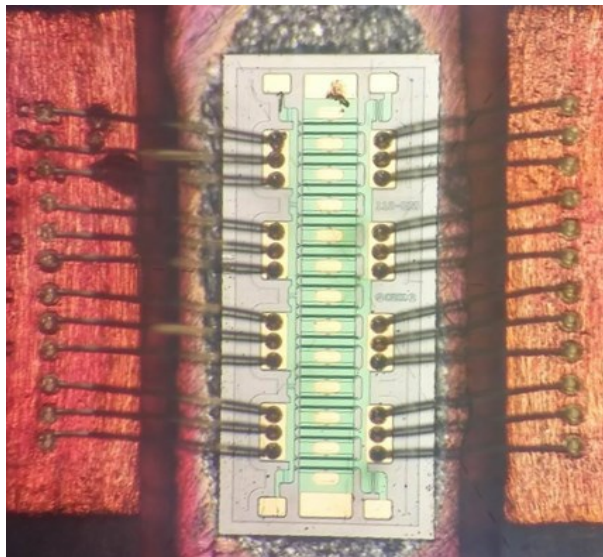


Figure IV.39: 3D Bond wire model.

b) PA Operating class, DC and Stability Analysis

Since a nonlinear model of the transistor is available, this simplifies the design procedures such as DC analysis, stability analysis and simulations. Based on the provided model, the PA is designed and biased in class AB for V_{ds} of 40 V and

V_{gs} of -2.5 V corresponding to a drain quiescent current I_{dq} of 240 mA. As already said, the designed PA will be used in a feedback frequency reconfigurable oscillator. This topology of oscillator is mainly based on a PA that may be biased in class A, B, C or AB since a gain more than 1 dB is reached, this allowing to satisfy the first oscillation condition. For this PA, the class AB operation was chosen.

Figure IV.40 shows the simulated I-V curve of the device. The FET transistor is biased at $V_{gs} = -2.5V$ for class AB operation with a bias current which is approximately 10.2 % of maximum I_{ds} . The high V_{ds} allowed by Cree is about 40V and the device's breakdown voltage is about 125 V. As reported in datasheet [139], the active device is unconditionally stable above 12 GHz and potentially unstable otherwise. Therefore, a series gate resistor of a small value around 0.175Ω is required by Cree to get device stable at 10 GHz. Since, S-parameter response of the device is function of the bias points, stability factors must be simulated at the operating bias conditions. This step in designing the PA is to determine with the small signal model whether the FET transistor is unconditionally stable or potentially unstable. This can be easily analyzed using the stability factor (K-factor) and stability measure delta (Δ). $\Delta > 0$ and $K > 1$ are necessary and sufficient conditions for stability. The equations for K-factor and Δ are defined as follow:

Equation (23)

$$K = \frac{1 + |\Delta|^2 - |S(11)|^2 - |S(22)|^2}{2|S(12)S(21)|}$$

Equation (24)

$$\Delta = S(11)S(22) - S(12)S(21)$$

However, there is an inverse proportionality between k-factor and maximum available gain (MAG) so that k-factor must be barely higher than 1 in the frequency band of interest but as large as possible out of band to have high gain and to prevent out of band oscillations. Stability analysis must be done from very low

frequencies to very high frequencies to observe potentially unstable regions. The simulated K-factor and Δ results are shown in Figure IV.41.

So a series resistor of 1.45Ω [139] was required for this design to get device stabilized. Therefore, this stability resistor is thought as a part of the input matching circuit.

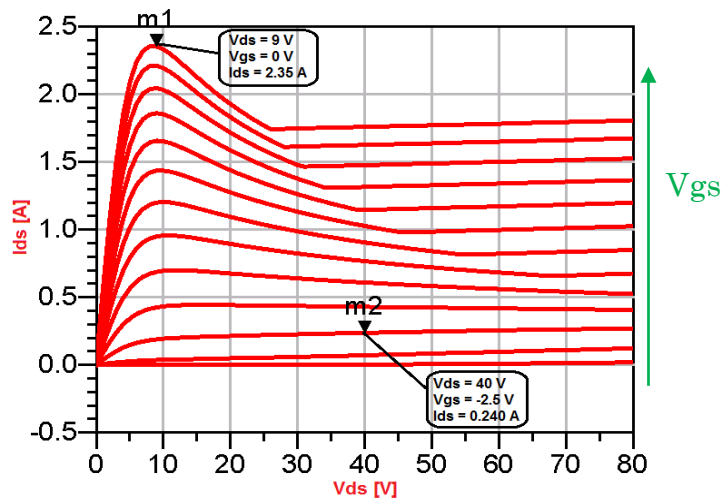


Figure IV.40: Simulated I-V Curves of the transistor

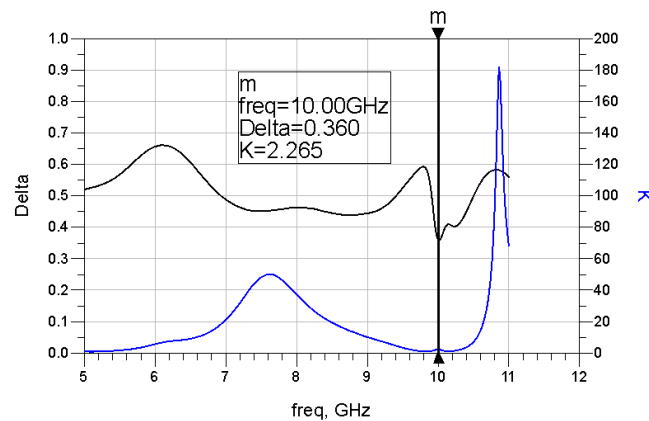


Figure IV.41: K-factor and Delta

c) Bias Network

The bias network is designed by using a quarter-wavelength ($\lambda/4$) associated with a radial stub instead of a decoupling capacitor to avoid more wires

bond. Radial stub should be properly designed at the operating frequency to provide a very low input impedance which is equivalent to RF short circuit, and then this short circuit will be transformed to RF open circuit by a properly designed $\lambda/4$ transmission line. This means the DC voltage can go through the $\lambda/4$ transmission line to bias the transistor, while RF signal at 10 GHz see an open circuit due to the $\lambda/4$ transmission line thus allowing decoupling the circuit from the DC supply (*Figure IV.43*). In this PA design, two bias networks can be cascaded in series to achieve more RF to DC decoupling (see *Figure IV.43*).

Some decoupling capacitors have to be placed to isolate both bias DC at drain and gate (V_{ds} and V_{gs}). For this, GX03 ultra broadband decoupling capacitors from the market were chosen. This capacitor has good performances in term of insertion loss and return loss over a broad band range from 16 KHz to 40 GHz. At 10 GHz this capacitor has an insertion loss of -0.1 dB and a return loss value better than -25 dB.

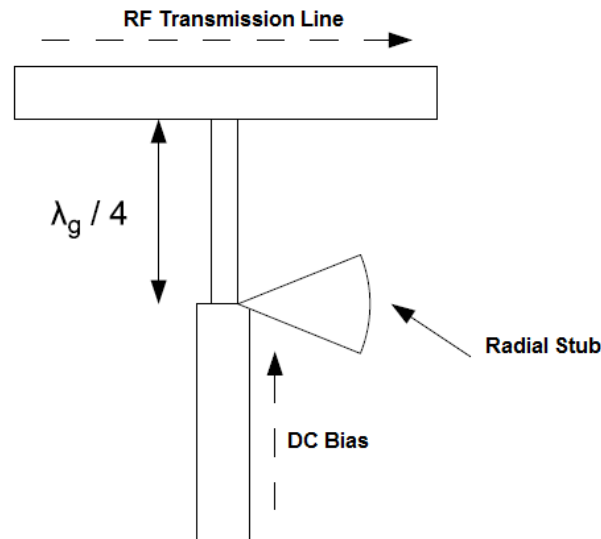


Figure IV.42: A typical distributed bias network with radial stub

d) Matching Network

As given in datasheet and verified with simulations, optimum load and source impedances of the Cree's active device at 10 GHz for V_{ds} of 40 V and I_{dq} of 240 mA are, respectively, $0.866-j0.461 \Omega$ and $3.08-j8.705 \Omega$. In addition, the matching networks were designed by adding parallel open stubs at the input and output of PA. These open stubs transform both optimum load and source impedances to provide maximum gain matching. Table IV.3 summarizes the dimensions of the used stubs. The fabricated PA prototype is shown in Figure IV.43. GaN power device are soldered on heat-sink plate with high thermal conductivities. It allows to transfer the heat generated by PA and provides an infrastructure to mount the PCB and the RF connectors. Copper was used for the reason that it has a higher thermal conductivity than other ordinary material such as aluminum, however copper makes the prototype more heavier. Also the transistor was mounted directly to the Cu plate using an epoxy glue.

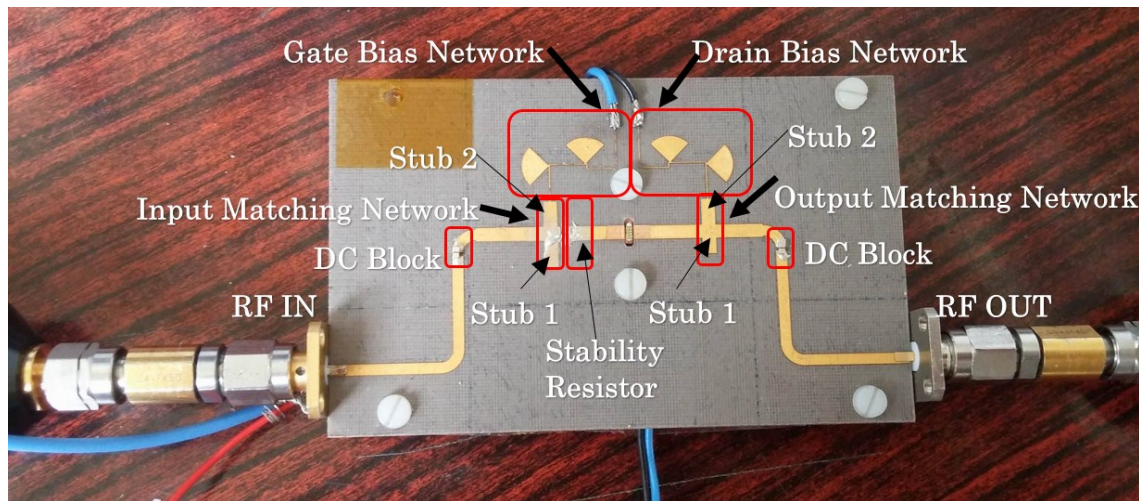


Figure IV.43: Fabricated PA under Test

Table IV.3: Dimensions of Stubs

		Input Matching Network	Output Matching Network
Stub 1	Length	3.8 mm	2.24 mm
	Width	2 mm	2 mm
Stub 2	Length	3.66 mm	3.75 mm
	Width	2 mm	2 mm

2.2.2 PA Simulated Results

Since this PA design will be used as a feed-back oscillator, large signal simulation will not be conducted. So Small signal simulation results of the PA are given in Figure IV.44. It is showing that gain of the amplifier is around 6 dB which satisfies the first oscillation condition (> 1 dB) at 10.1 GHz. Moreover, input and output return loss value of the PA is better than -12 dB, this clearly shows that a good matching is achieved. In addition, S_{12} is lower than -12 dB.

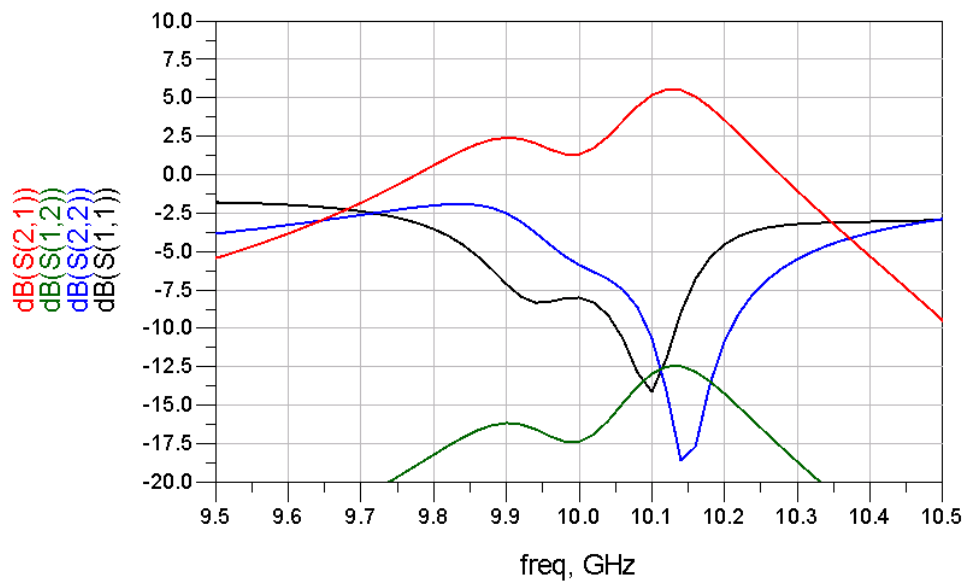


Figure IV.44: Simulated Small Signal S-Parameters

2.2.3 PA Measured Results

As a recall during the measurements, the PA is biased in Class AB mode whose quiescent drain current about 240 mA should be achieved for V_{gs} of -2.5 V and V_{ds} of 40 V.

Figure IV.45 represents the small signal measurement results of the fabricated PA. It is observed that the PA does not have any gain, a value of -5.3 dB was observed for S_{21} at 9.6 GHz, even good match is achieved at the input ($S_{11} = -16.4$ dB) as well as the output ($S_{22} = -11.6$ dB) as can be seen. It seems that this PA does not work

as expected. As shown in the picture illustrated in Figure IV.46, the desired quiescent drain current of 260 mA is achieved but at a lower V_{ds} of 18 V.

During the measurement, V_{gs} was fixed at -2.5V and then we start increasing slightly the V_{ds} to get the wanted I_{ds} current. Once the V_{ds} gets higher than 19 V, it was observed that the V_{gs} starts getting changed alone randomly. The V_{ds} starts to control the V_{gs} value and we lost completely the control over the V_{gs} . We could not very understand this weird behaviour. It is known that when there is a drop value in gain this means that the PA is not stable. Maybe a little bit more complicated stability circuits than a simple series resistor recommended by CREE is required to make sure that the device is stable.

The transistor model of the CGHV1J025D provided by CREE Inc. only has one input port and one output port, despite the fact that the transistor itself is constituted from twelve cascaded single transistors, so CGHV1J025D has twelve input ports and output ports. Unfortunately a distributed transistor model that can allow to check if all the single devices work well was not available, also it was impossible to check if the mounded device was damaged or not. Due to our limited funds, we could not offer another fabrication prototype. In addition, to redo another fabrication will be considered as very time consuming.

Since this PA is planned to be used as a feed-back power oscillator, it will be very difficult to achieve our objective and make the oscillator works well. Nevertheless, the study of the two oscillators has been done and presented in the following section.

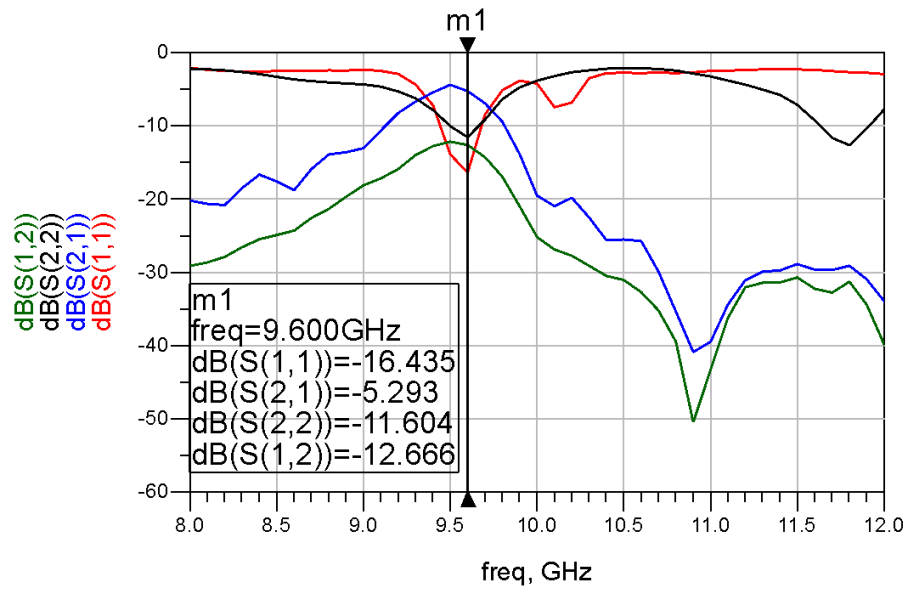


Figure IV.45: Measured Small Signal S -Parameters

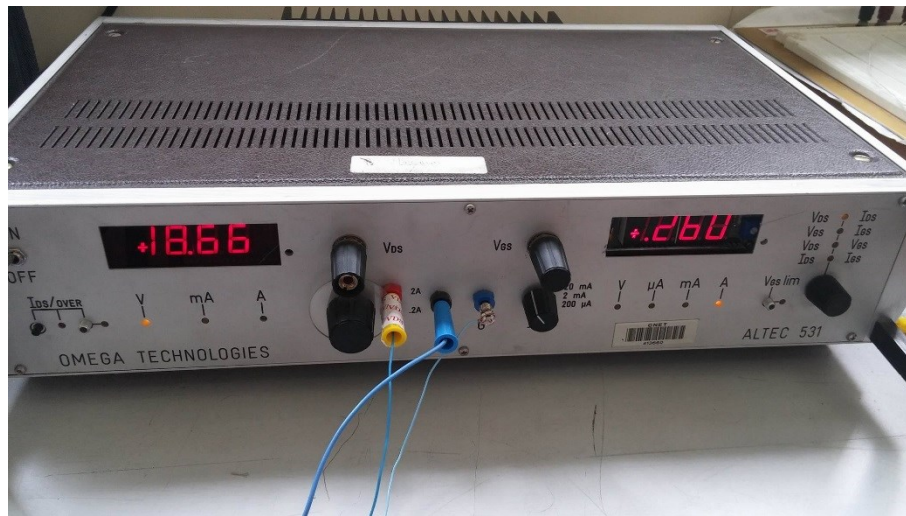


Figure IV.46: I_{ds} of 260 mA at V_{ds} of 18.6 V and V_{gs} of -2.5 V

3. Oscillator Design

3.1 Start-up Oscillation Condition

Under proper bias conditions, a feedback oscillator start to oscillate from the RF noise level without a real input RF signal. This noise presents at the input of

the oscillator or generated by the active and passive devices in the oscillator, is responsible for starting-up the oscillation regime. As the power supply is turned on, noises will be shown up and then oscillation will grow in amplitude. Although, this noise is characterized by a broadband spectrum but only noise at the oscillation frequency will be amplified. The gain of the amplifier and feedback loop must be equal or greater than one at the desired oscillation frequency, while the phase shift through the loop must be zero or some integer multiple of 2π . These are known as Barkhausen Criterion [140] of oscillations and are required to get the oscillating regime process ongoing.

Usually the designed loop gain magnitude is slightly larger than unity at the desired frequency of oscillation because if exact unity is designed, a slight reduction in gain would result in oscillations that decays to zero. So the oscillation conditions in open loop can be summarized as:

$$\begin{aligned} S_{21} &>> 1 \\ S_{11} &<< 1 \\ \text{Arg}(S_{21}) &= 0 \text{ _or_ } [n.2\pi] \end{aligned}$$

When designing this kind of oscillator topology, it is preferred to proceed firstly by get the matching done ($S_{11} << 1$), then secondly the gain and the phase can be optimized to satisfy the oscillation conditions.

To ensure that the design meets the necessary conditions for oscillation, a small signal gain analysis has to be done before connecting the feedback network to the amplifier's input. This analysis is mostly called open-loop analysis where gain and phase have to satisfy Barkhausen Criterion of oscillations. In addition, when dealing with oscillator designs, closed-loop analysis is also required to explore the oscillator's performances such as frequency and power of oscillation as well as phase noise. This analysis is conducted once the feedback loop is connected to the amplifier's input terminal. Oscillator's performances at both open-loop and closed-loop are discussed here for FFO as well as for TFO.

The goals of the two discussed oscillators designs is firstly to fulfill the in-depth progress of GaN oscillator design, and to achieve an high oscillator output power at 10 GHz with low phase noise. Also a frequency reconfigurability over X-band is another goal of this conducted study. The configuration of both the FFO and TFO designs is shown, respectively, in Figure IV.47 and Figure IV.54. The circuits was simulated using ADS. Small signal and harmonic simulations were performed.

3.2 Phase Noise in Oscillator

Phase noise is one of the most important figures of merit of a signal generating device and it is often the limiting performance metric. The basic concept of phase noise involves frequency stability, which is defined as the degree to which an oscillating source produces the same frequency throughout a specific period of time. Phase noise is generally specified in dBc/Hz at a given offset frequency for a particular carrier. Therefore, phase noise can be found by measuring the ratio of the power spectral density (1-Hz bandwidth) at a given offset frequency to the total power at the carrier frequency. In the literature, it is common practice to refer to the values of phase noise as “close-in” for the frequency offset range of 1 Hz to 100 Hz. That is, “close in phase noise” refers to the phase noise close to the carrier, less than 1 kHz away. Similarly, “far out” phase noise commonly refers to values 1 MHz or more from the carrier. That is, “far out phase noise” refers to the phase noise far from the carrier, more than 100 kHz away. The mid-range region, 1 kHz to 100 kHz offset, especially for signal generator phase noise, is sometimes referred to as the pedestal region.

It is well known that depending on the application, the offset frequency is selected. Here in this designed oscillator, phase noise is simulated at three offset frequencies, such as 10 KHz, 100 KHz and 1 MHz. As mentioned, the idea behind the design of this oscillation is to verify the performance of using the developed GaN

varactors, so these offset frequencies were selected only because most of the reported GaN oscillator designs found in the literature also use these three selected offset frequencies, and we assumed that for a good comparison, the noise phase should be simulated also at the same offset frequencies.

3.3 Fixed Frequency Oscillator (FFO)

3.3.1 Simulation Results

Figure IV.47 illustrates the final realized FFO prototype. As can be seen in Figure IV.48, the open-loop analysis has been done and simulated results are displayed. An open-loop gain around 6 dB with a good matching at the input is achieved at 10.12 GHz. While the signal phase is around 0° at this frequency. These values satisfy the required oscillation conditions.

Once the open-loop simulations are done, the feedback network has been connected to the input and a $50\ \Omega$ port was used as oscillator's output to conduct the second analysis, closed-loop simulation. Figure IV.49 shows the simulated spectrum for the FFO providing 34.7 dBm output power at 10.01 GHz oscillation frequency. The circuit is biased at V_{ds} of 40 V, I_{ds} of 240 mA, and V_{gs} of -2.5 V. The power levels of the second and third harmonics appear in same Figure IV.49. The second harmonic was typically better than 40 dBc while the third one was so small as 50 dBc. In Figure IV.50 and Figure IV.51 a pure sinusoid was generated at the output of the FFO. An output voltage of 17.3 V was achieved.

Figure IV.52 shows the results of phase noise at 10 KHz, 100 KHz and 1 MHz offset where values of -103 dBc/Hz, -110 dBc/Hz, and -143 dBc/Hz were simulated, respectively.

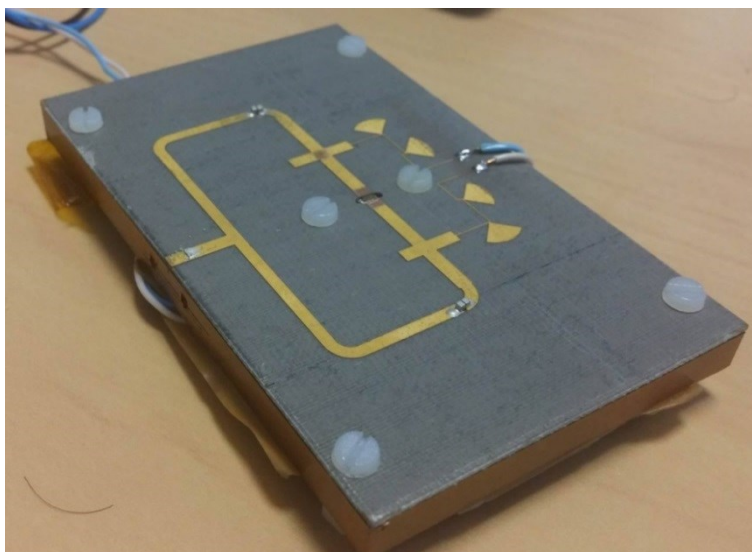


Figure IV.47: Fixed Frequency Oscillator Fabricated Prototype

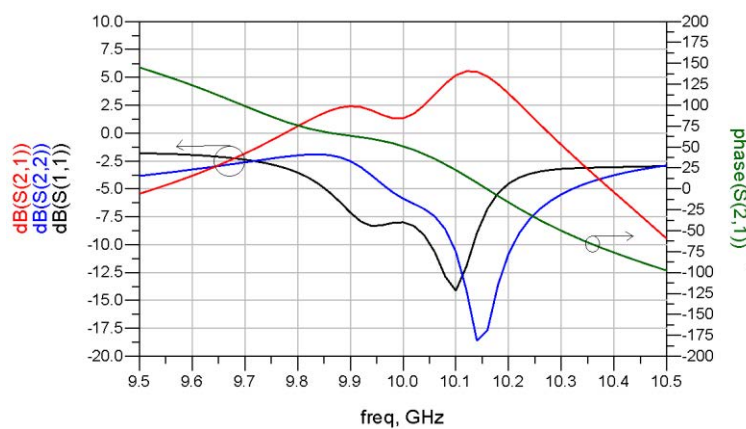


Figure IV.48: Small Signal Simulation Results (Open-Loop)

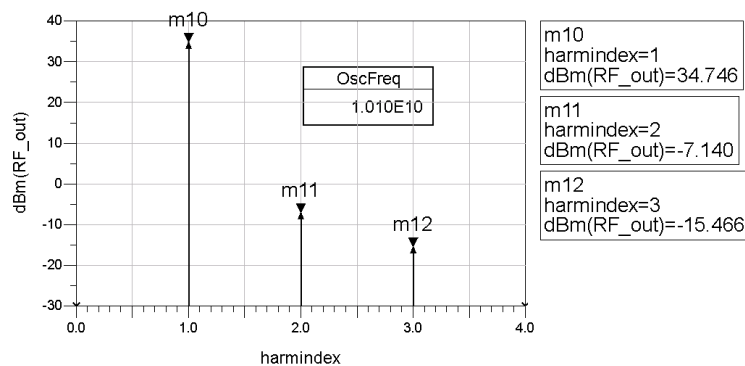


Figure IV.49: Harmonics Power Simulation of the FFO

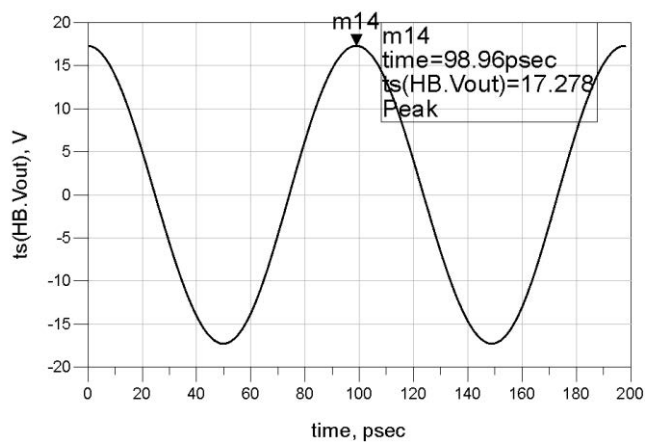


Figure IV.50: Pure Voltage Sinusoid at the Output of the FFO

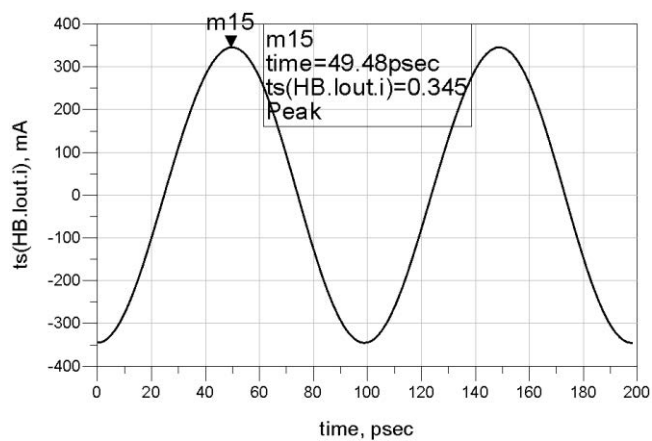


Figure IV.51: Pure Current Sinusoid at the Output of the FFO

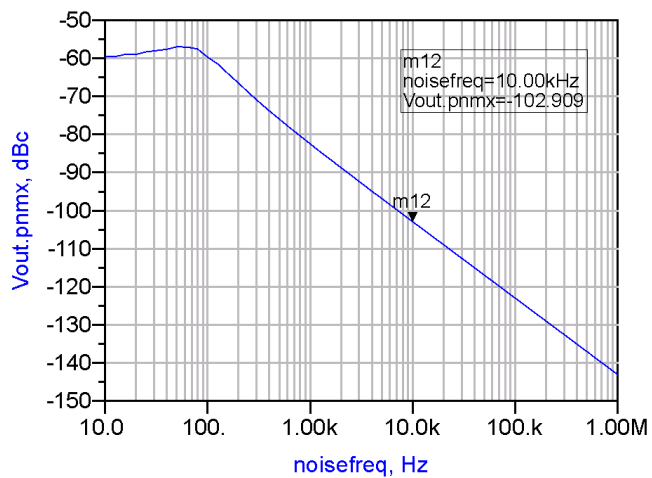


Figure IV.52: Simulated Phase Noise of the FFO

3.3.2 Measurements Results

First of all, to prevent damage on laboratory equipment a 20 dB attenuator was added at the input of the spectrum analyzer. With Matlab, this attenuated power was recovered and real measured oscillation power is depicted in Figure IV.53.

As can be seen there are a lot of oscillation frequencies below 10 GHz, this means that the feedback network do not filter these frequencies. As already reported, the PA that is used here for this oscillator did not work as intended from simulation, so it is obvious that the FFO does also not work as expected. At the operating frequency of 10 GHz, it is observed that a peak of a power of -10 dBm is measured while the highest power peak of 26 dBm was observed at very low frequency around 500 MHz as reported in Figure IV.49. These results are recorded at bias points of V_{gs} of 18 V and V_{gs} of -2.5 V where an I_{ds} current of 260 mA was achieved. The same problems observed for the PA with the biasing are also observed during the FFO measurements. It was noted that the V_{ds} starts controlling the V_{gs} .

Due to the fact that the design did not work as intended from simulations, measurements of the power levels of the second and third harmonics as well as of the phase noise are not reported.

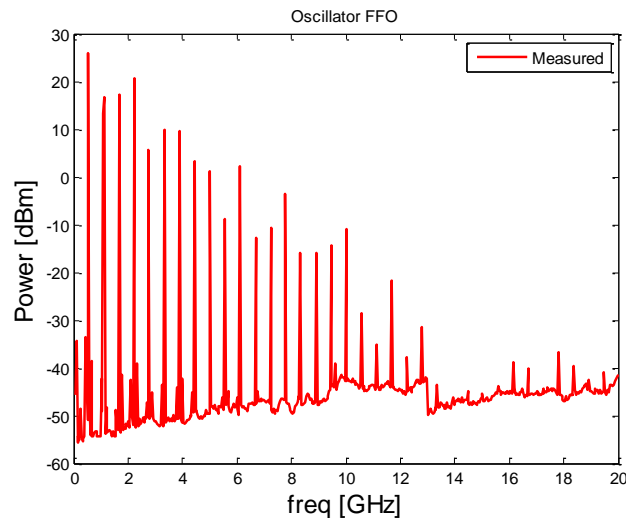


Figure IV.53: Harmonics Power Measurement of the FFO

3.4 Tunable Frequency Oscillator (TFO)

3.4.1 Simulation Results

In order to tune the oscillation frequency, the feedback loop of the previous FFO design was symmetrically loaded by two GaN varactor diodes to design a frequency reconfigurable GaN oscillator. A small signal model of these varactors has been developed and presented in Chapter III. Varactor diodes are commonly used in RF/microwave oscillators, enabling the tuning of the oscillation frequency which is controlled by the reverse applied voltage. The tuning voltage across the varactor is swept from -5 V to -3.7 V. In Figure IV.54 the fabricated TFO is shown.

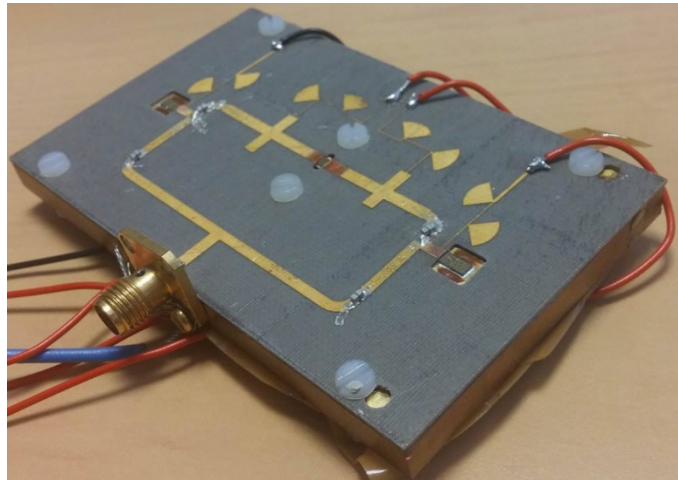


Figure IV.54: Tunable Frequency Oscillator fabricated Prototype

Figure IV.55 presents the oscillation frequency versus varactor bias voltage V_G of the TFO. In terms of variation, it is seen that the frequency oscillation versus bias voltage curve exhibits an inverse behavior of C_{EQ} versus V_G presented in chapter III. A minimum oscillation frequency of 7.8 GHz was achieved when C_{EQ} is at its maximum over range (1) for V_G above -3.5 V, and a maximum oscillation frequency of 8.6 GHz was simulated when C_{EQ} is at its minimum over range (3) for $V_G < -4.5$ V. While, in range (2) from -5 V to -3.7 V, the oscillation frequency values change significantly and a tuning bandwidth of 0.8 GHz is obtained, corresponding

to a tuning range about 10%. This rapid change corresponds to the variation of C_{EQ} over range (2).

In Figure IV.56 the output power versus bias voltage V_G of the TFO is illustrated. It can be seen that the power is about 20.5 dBm and almost stable over all bias levels with a slight variation over range (2) where V_G is between -5 V and -3.7 V. This drop in power variation can be due to the variation in equivalent series resistor of varactor as presented in previous Chapter III. Compared to the output power of the FFT which is about 34.7 dBm, the output power of TFO is decreased to 20.5. This can be due the RF losses of varactors used for tuning purpose.

Simulated phase noise versus bias voltage across varactors at three offset frequencies for the TFO is shown in Figure IV.57. For all bias points, phase noise values of -92 dBc/Hz, -112 dBc/Hz and -132 dBc/Hz are met at 10 KHz, 100 KHz and 1 MHz, respectively. Also, due to the variation of R_{EQ} , a slight variation of phase noise is noticed from -5 V to -3.7 V.

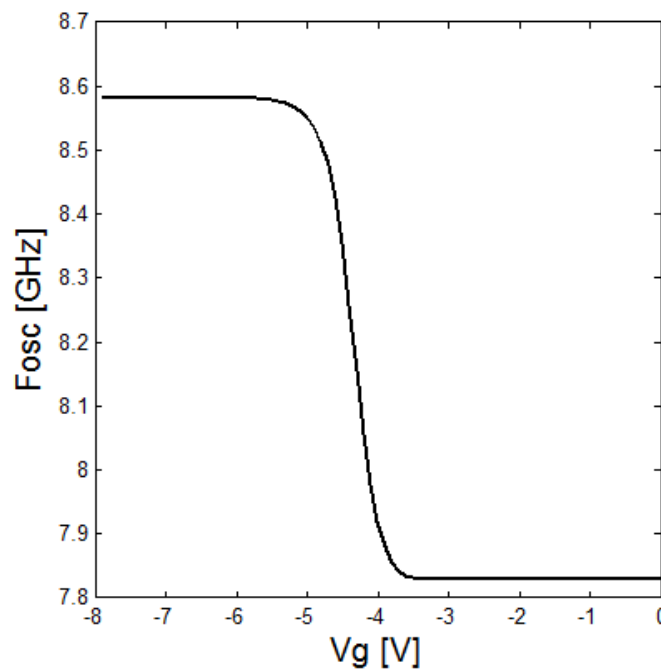


Figure IV.55: Oscillation frequency versus gate voltage

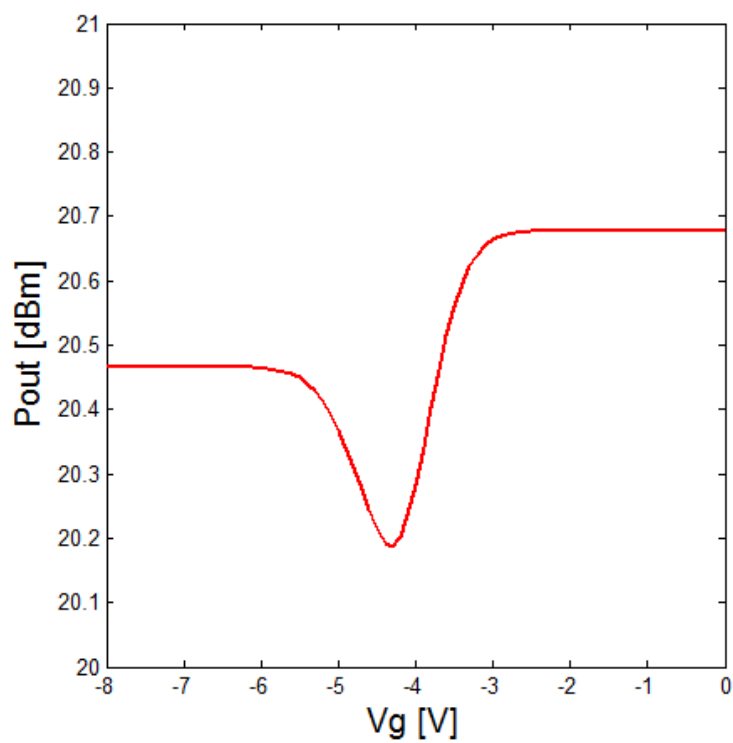


Figure IV.56: Output power versus gate voltage at fundamental frequency

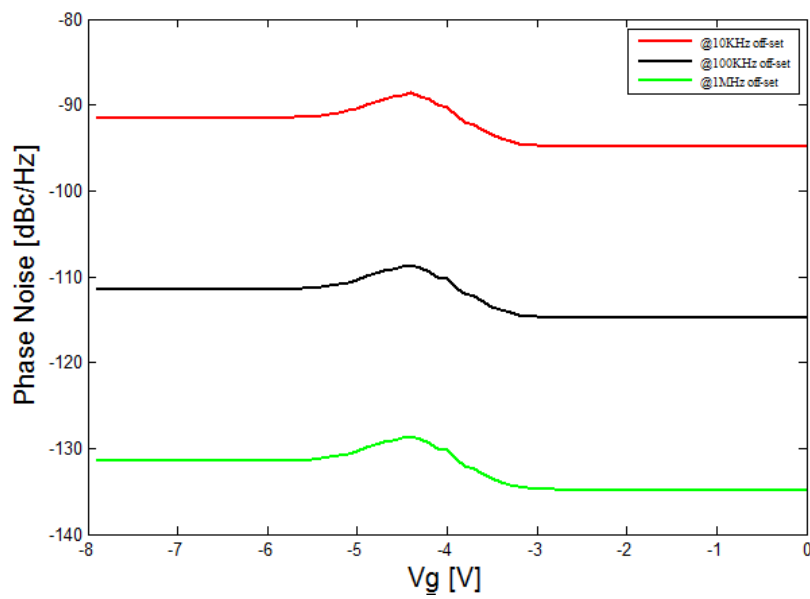


Figure IV.57: Phase Noise versus gate voltage at 10 KHz, 100 KHz, and 1 MHz

3.4.2 Measurement Results

For the measurements part, the same remarks as for the PA and the FFO have been observed for the TFO design.

In this section, two GaN oscillator designs based on feedback topology have been presented for high RF power source. First, the power amplifier and optimized feedback loop were designed and fabricated using a Cree's discrete active FET device and NELTIC9300 substrate for the PCB design. The amplifiers has an open-loop gain of 6 dB, good return loss at input and output better than -12.5 dB, and phase of 0° at 10.12 GHz.

Secondly, the feedback loop was closed to design the first oscillator (FFO). Phase noise about -110 dBc/Hz @ 100 kHz was simulated at the bias V_{ds} of 40 V and I_{ds} of 240 mA while the output power obtained for the FFO is 34.7 dBm at center frequency of 10.12 GHz. The second and third harmonics were very low and typically better than 40 dBc. These simulations results are favorably compared to the best reported performances of high power GaN oscillator [129]-[134]. In [129] Using a GaN HEMTs with a gate length of 0.15 μm process, an output power of 35 dBm between 8.5 and 9.5GHz was achieved at $V_{ds} = 30\text{V}$ while the phase noise was estimated to be -87 dBc/Hz at 100 kHz offset.

Finally, a tunable frequency GaN oscillator (TFO) is designed by loaded symmetrically the feedback loop. For tuning purpose, GaN varactor were used. The oscillation frequency values change significantly and a tuning bandwidth of 0.8 GHz, corresponding to a tuning range about 10% was achieved. The output power is about 20.5 dBm and almost stable over all bias levels with a slight variation over range (2) while a good phase noise value of -112 dBc/Hz is met at 100 KHz.. However, the output power was not impressive compared to FFO design, being only 20.4 dBm and 20.9 dBm at best. This drop of power can be explained as there is a RF power consumption of varactors due to the presented high equivalent series resistor.

These two reported oscillators prove clearly that GaN HEMT technology, with its high breakdown voltage, is a good promising choice for the high RF power sources. Unfortunately the measurements did not work as expected from simulation, this may be due to a difficulty to bias the active device and/or do not have the same ground at drain and gate.

V. Frequency Reconfigurable Active Antennas

1. Review

Active integrated antennas (AIAs) researches have shown unprecedented development along with growing interest for wireless systems applications [141]. The designs of AIAs are towards the designs that are more and more small, have the capability of operating at multi-frequencies [142] and of handling significant high power levels, which has been the greatest challenge. There are a plenty of techniques [141] in which antennas can be frequency tuned such as using switches, varying substrate properties [143] and using PIN diodes. Using varactors diodes [144] integrated with printed antennas can be another way to tune the antenna operating frequency. This technique based on varactors could be found in various types of reconfigurable active integrated antennas systems. However, active device such as varactor diodes presents some non-linear behaviors with high power RF signals that influence the performances of antenna.

As a result of advanced GaN based HEMT semiconductor devices such as good linearity, the designs of AIAs with high power handling capability and high frequency operation are now achievable. GaN-based HEMT semiconductor devices are no longer limited to radio frequency integrated circuit (RFIC) [145], having now been more attractive to AIAs systems [146].

Furthermore, reconfigurable AIAs, with high power/frequency, and excellent efficiency, are in great demand. In this chapter, firstly, a novel frequency

tunable annular slot antenna using GaN HEMT varactor is presented for the first time. However, using GaN varactor requires a high voltage DC biasing. In addition, GaN varactor presents a rather high insertion loss caused by its series equivalent resistance resulting on reducing the radiation efficiency of antenna. A second frequency tunable aperture coupled slot antenna is then investigated to improve the gain.

Thirdly, a radiation pattern reconfigurable antenna is studied using different oriented printed antenna arrays and integrated with GaN HEMT switches to choose the beam direction of the complete antenna system.

2. Reconfigurable Annular Slot Antenna using GaN Varactor

2.1 Antenna Design

The used planar antenna is a simple element annular slot coplanar antenna. The structure of the realized antenna is illustrated in Figure IV.58. This antenna was already presented in [147]. The whole size of antenna is about $50 \times 50 \times 0.7$ mm³ and is printed onto glass substrate with ϵ_r of 5.7 and $\tan\delta$ of 0.006 at 2 GHz. CST Studio simulator was used as an EM simulator to design and simulate the antenna. First, the antenna itself was simulated and results are presented and discussed. Then the developed GaN varactor model was added to load the antenna. This allows to electronically adjust the antenna frequency by varying the varactor bias voltage applied at the gate. As will be shown, measurement results of the frequency tuning range showed good agreement with the simulations.

The frequency tunability of this antenna has been investigated firstly by loading a GaAs varactor diode bought from the market [147], after that the developed GaN varactor diode (W200L0.5) using GaN500v2 process is used instead. Since, the used GaN varactor provides various capacitive load to the antenna, the resonant

frequency of the antenna can be tuned electrically by implementing the GaN varactor between radiation element and ground as it is shown in Figure IV.58. The varactor junction capacitance varies as a function of bias voltage as discussed in chapter III. These different capacitive loadings correspond to various electrical lengths of the antenna, and thus different resonant frequencies.

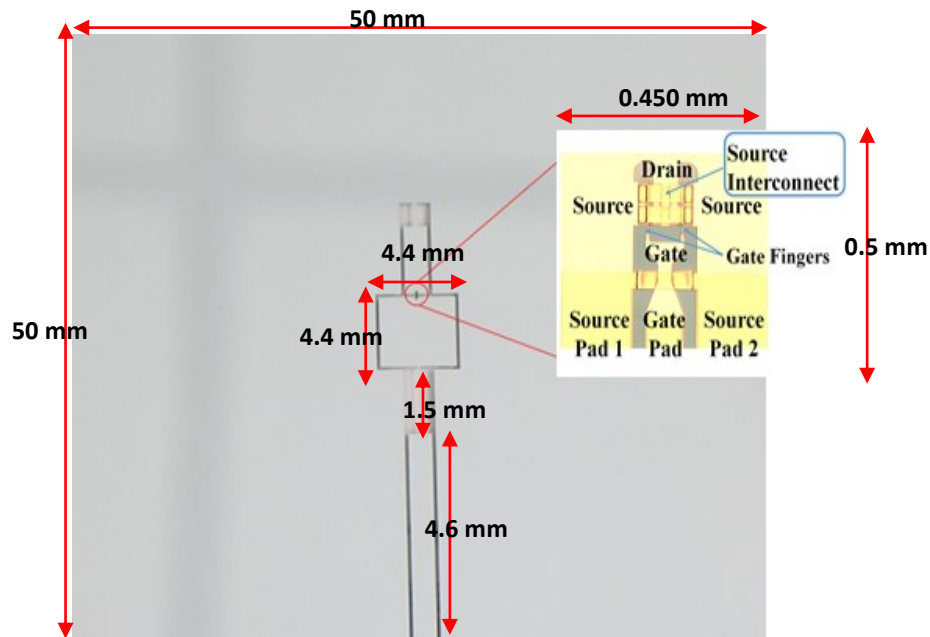


Figure IV.58: Printed antenna prototype with GaN varactor load.

2.2 Simulated Return Loss and Radiation Pattern

The antenna itself without the diode was firstly simulated and good matching was obtained at resonant frequency around 11 GHz as shown in Figure IV.59. At this frequency, the simulated gain was about 4.6 dB as displayed in Figure IV.60. The radiation pattern of the antenna is simulated in the E-plane and H-plane for co-polarization (copol) at 11 GHz and results are plotted in Figure IV.61. The E-plane and H-plane are normalized to the maximum gain of the antenna. Because the antenna structure is a coplanar simple element, it radiates in two opposite directions. In E-plane, the maximum beam direction occurs symmetrically around 30° and -30° where a max gain was observed, this can be due to the diffraction

of the limited size of the ground conductor and also some perturbation caused by the SMA connector used for the antenna excitation. The presented results of the antenna will be later experimentally verified and rediscussed.

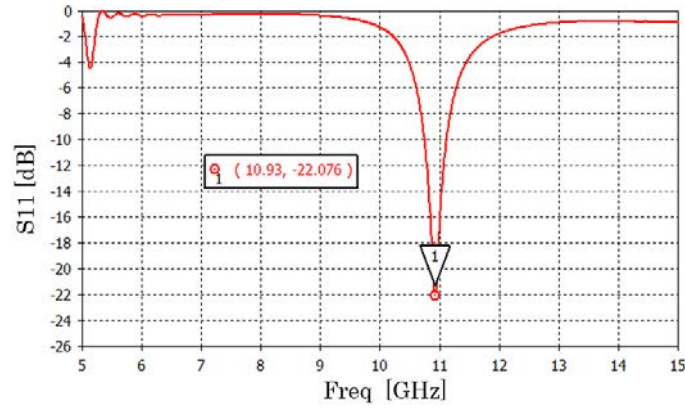


Figure IV.59: Simulated return loss of the antenna alone

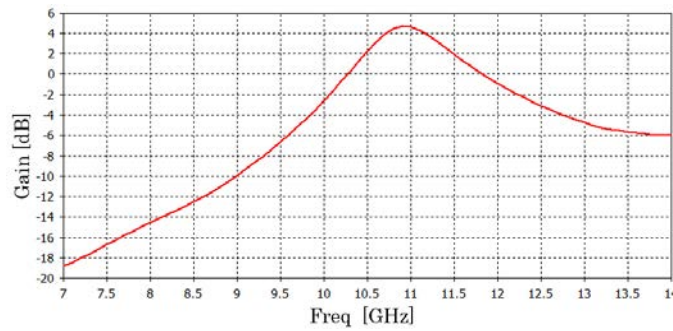


Figure IV.60 : Simulated antenna gain versus frequency

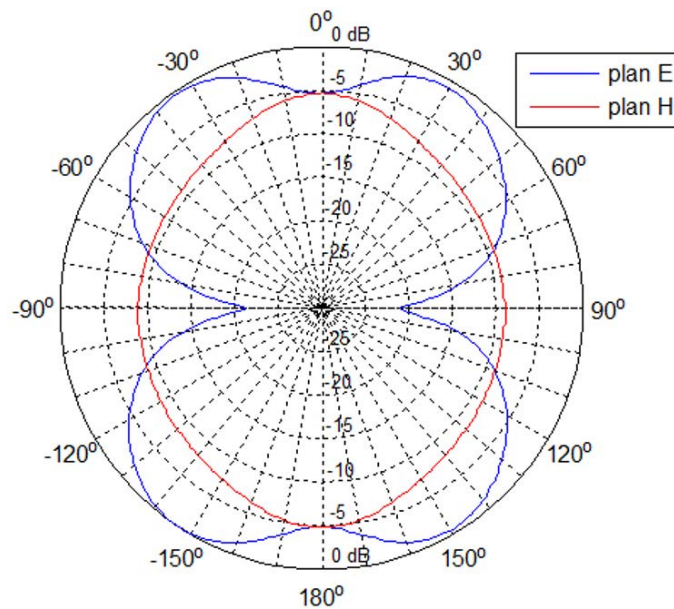


Figure IV.61 : Simulated normalized radiation pattern of the antenna at 11 GHz

Once the antenna alone was simulated and good performances were achieved, then the developed model of the W200L0.5 varactor device was integrated with the antenna to realize the matching reconfigurability operation. The simulated return loss of the AIA under various DC bias from -3.2 V to -5 V is presented in Figure IV.62. As can be seen, the minimum and the maximum values of the simulated return loss are, respectively, -10 dB and -6 dB over the bandwidth from 7.53GHz to 7.85GHz corresponding to a tunability up to 4% narrow bandwidth inside. It is clearly demonstrated that the S11 is not good as for the first simulation with only the antenna itself; here the overall impedance presented by the varactor is significantly impacting the matching of the antenna. As said before this antenna was designed and optimized to be integrated with a GaAs varactor diode. Because the antenna was already fabricated and prototypes were available in the laboratory (IETR), we kept the same design and only integrate the model of GaN varactor and the simulations were relunched. This is why we could not re-optimize the antenna design to achieve a good matching once the GaN varactor is integrated. However, the idea here was to validate the developed GaN varactor model and demonstrate the use of GaN varactor for reconfigurable AIA. This can be seen from the simulated S11 results where the

resonant frequency of the antenna is electronically controlled by the DC voltage applied over the varactor model.

The structure of this used antenna is discussed in [147] where the design procedures, fabrication steps and details are presented. Maximum return loss occurred when the GaN varactor presents a high R_{Eq} at some bias DC as plotted in chapter III.

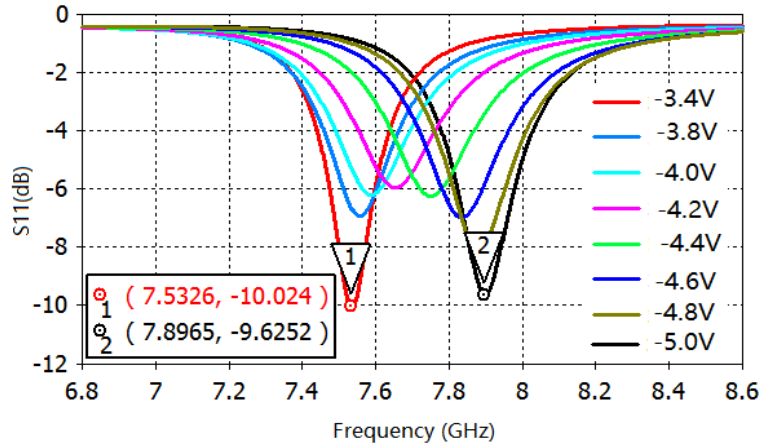


Figure IV.62: Simulated return loss of the loaded antenna for different reverse-bias voltages

2.3 Measured Return Loss and Radiation Pattern

In this section, we provide experimental results of the proposed active integrated antenna. In order to verify the tunability of the antenna experimentally, the GaN varactor was integrated with the antenna using the wire banding technique and then the whole design was measured.

Firstly, the measured return loss was measured and it can be seen from Figure IV.63, the S_{11} varies from -7.13 dB to -6.9 dB in the band from 7.53 GHz to 7.83 GHz which corresponds to the same simulated tunable bandwidth. Therefore, as can be seen from both Figure IV.62 and Figure IV.63, the simulation results match quite well with the actual prototype measurement even though the minimum return loss has been decreased slightly from the simulation results that can be probably

caused by the effects of wires-bonding that connecting the GaN varactor terminals to the antenna and some parasitic resistance and inductance that is not captured in the whole equivalent proposed model. Then, in an anechoic chamber, the gain and the normalized radiation pattern of the fabricated AIA were measured in the E-plane and H-plane for several DC bias and results are, respectively, depicted in Figure IV.65 and Figure IV.66. Both E-plane and H-plane are normalized to the maximum gain value obtained at bias point of -6 V. The maximum beam direction occurs around -6° for the H-plane as well as for E-plane. However no diffraction in E-plane is observed unlike to what it was observed in simulations. It can be seen that in both planes, the fabricated prototype antenna generates a low cross-polarization level in the main-lobe direction about -20 dB and -25 dB. The gain has been measured under various external applied DC bias voltages, and results are depicted in Figure IV.64. The antenna exhibits a very poor gain values from -6.5 dB to -4.7 dB at the frequency range from 7.55 GHz to 7.9 GHz. The gain value decreases as the antenna resonant frequency becomes lower, which is due to the electrically downsizing effects of the antenna [148]. In addition, the relative higher R_{Eq} values of the GaN varactor contributes to reduce the gain values. This R_{Eq} was discussed before in chapter III.

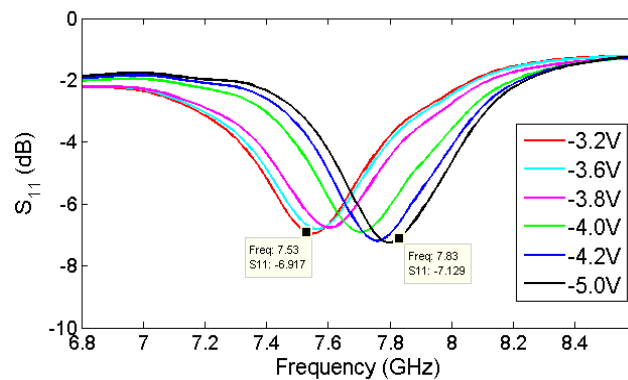


Figure IV.63: Measured return loss of the loaded antenna for different reverse-bias voltages

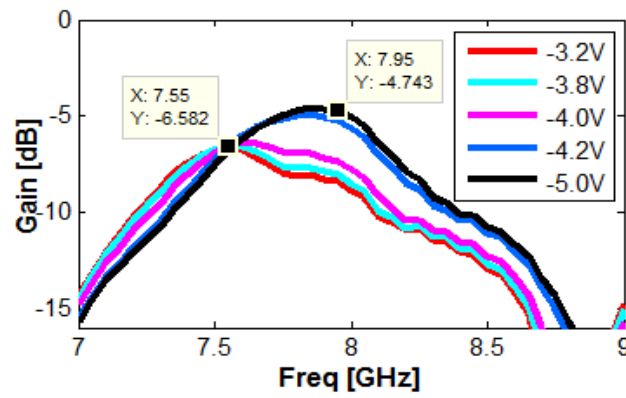


Figure IV.64 : Measured loaded antenna gain versus frequency for various DC bias

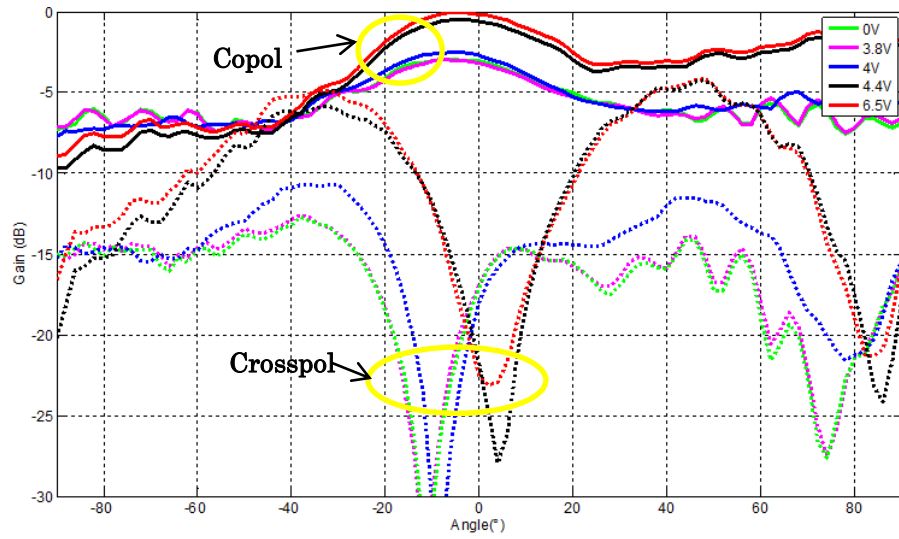


Figure IV.65 : Measured radiation pattern in H-plane of the loaded antenna under various DC bias

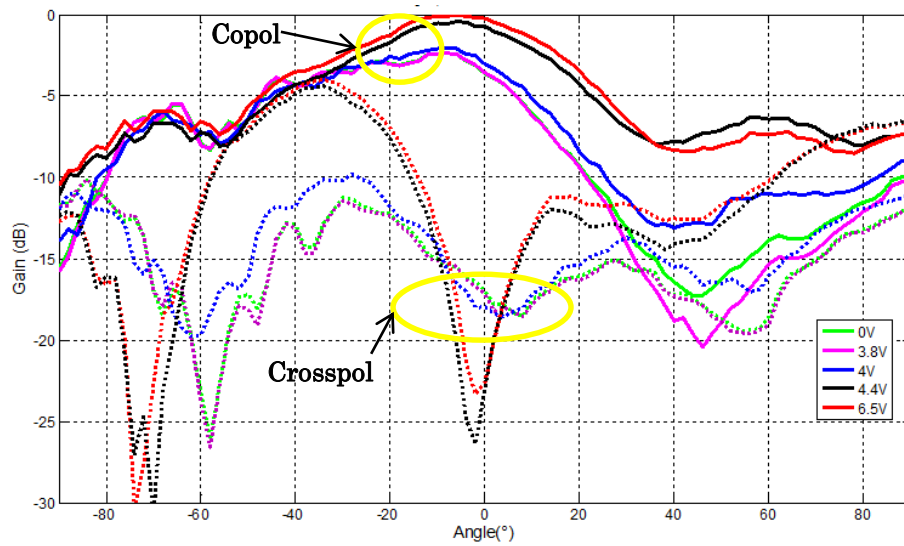


Figure IV.66 : Measured radiation pattern in E-plane of the loaded antenna under various DC bias

The performance of GaN varactor has limitations for the antenna radiation efficiency due to its high R_{Eq} values, which is quite difficult to avoid. In addition, bandwidth is the limiting factor in using GaN varactor because of its quick variation of C_{Eq} over a limited DC bias range as discussed in chapter III and shown in figures C_{Eq} versus DC. Also because, we could not re-optimize the antenna design to achieve good matching over the tuning range of the varactor and good antenna gain performances, another antenna structure will be proposed to improve the performances and demonstrate the use of GaN varactor in reconfigurable matching antenna. This structure of antenna will be presented and discussed in the next section.

3. Reconfigurable Aperture Coupled Slot Antenna using GaN Varactor

3.1 Antenna Design

In order to improve the previous proposed antenna gain and to validate the use of the developed GaN varactor diodes, another structure based on aperture coupled microstrip patch antenna feed technique is proposed. The structure of the aperture-coupled microstrip patch antenna is depicted in Figure IV.67. The antenna structure with overall dimensions L of 50 mm and W of 50 mm consists of two dielectric layers: a slot layer and a simple element patch layer and between them an air-gap layer of 1 mm. This air-gap is obtained by using a Rohacell foam with a thickness of 1 mm and a relative permittivity of 1. The square microstrip patch size is $13 \times 13 \text{ mm}^2$ is placed above the top surface of the coplanar waveguide (CPW) slot layer with relative permittivity ϵ_{r_p} of 2.2 and thickness T_{sub_p} of 0.8 mm. This means, the bottom surface of the slot layer is without metallization. The ground plane of the microstrip patch is created by the top metallization of the slot layer which is a CPW, thus resulting to improve the overall gain. The microstrip patch is fed by the slot fabricated on the bottom substrate with relative permittivity ϵ_{r_s} of 6.15 of and thickness T_{sub_s} of 0.64 mm. The slot width is 0.3 mm and the slot length is 10 mm. In order to simplify the understanding the geometry of the antenna, Figure IV.68 illustrates the stack up of the different layers. The patch is placed symmetrically to the center of the slot.

To achieve tunable frequency operation, the developed GaN-based varactor (W2000L0.5) is used and placed in the middle of the slot as zoomed and depicted in Figure IV.67. Here, the idea here is again to verify the developed GaN varactor by integrating them with a simple frequency antenna design and to design and predict the performance of reconfigurable antennas with the embedded GaN varactor.

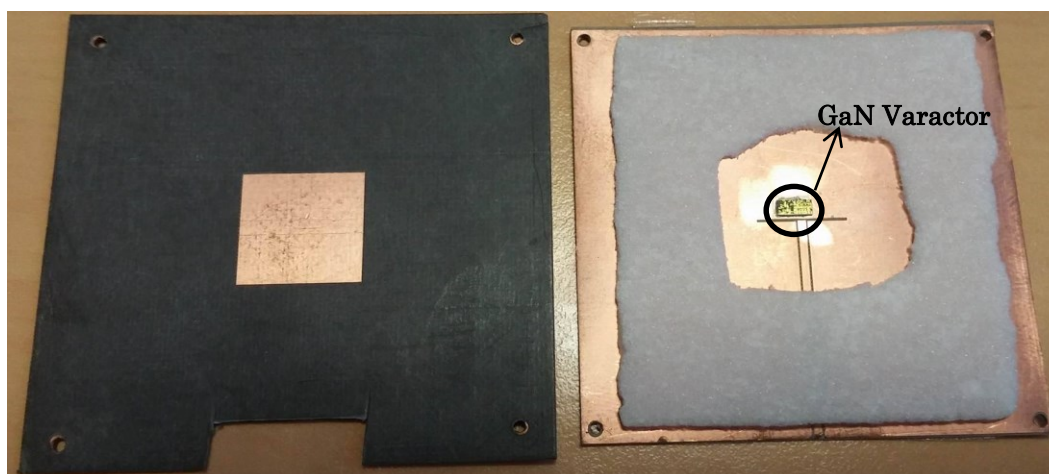


Figure IV.67 : (left) patch antenna (right) slot feeding loaded with GaN varactor

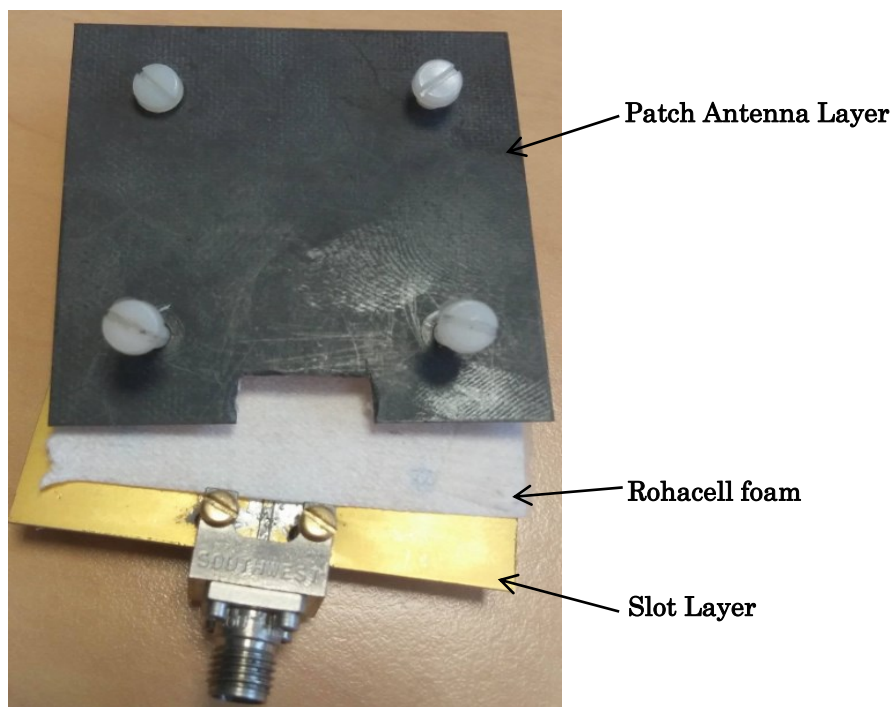


Figure IV.68 : Stuck-up whole antenna system structure

3.2 Simulated Return Loss and Radiation Pattern

The planar antenna is firstly simulated without integrating the developed varactor diode model. By this way, the simulated results related to the antenna itself are presented. As is shown in Figure IV.69, the simulated return loss of the antenna

is around -5.65 dB at 11.35 GHz. Once the varactor model will be added, the return loss of the antenna will be more improved and resulting to a good matching of the antenna. The maximum gain of the antenna is around 7.1 dB at the frequency of 11.35 GHz as seen in Figure IV.70. This is an ordinary gain value of a single patch antenna. In Figure IV.71, the normalized radiation pattern (co-polarization) of the patch antenna is simulated in H-plane and E-plane at 11.35 GHz and is presented; it corresponds to a classical radiation pattern of a microstrip patch antenna in air. A very low cross-polarization level in the main lobe direction is simulated which is about -30 dB in both the E-plane and in the H-plane while a back lobe level of -12 dB is achieved.

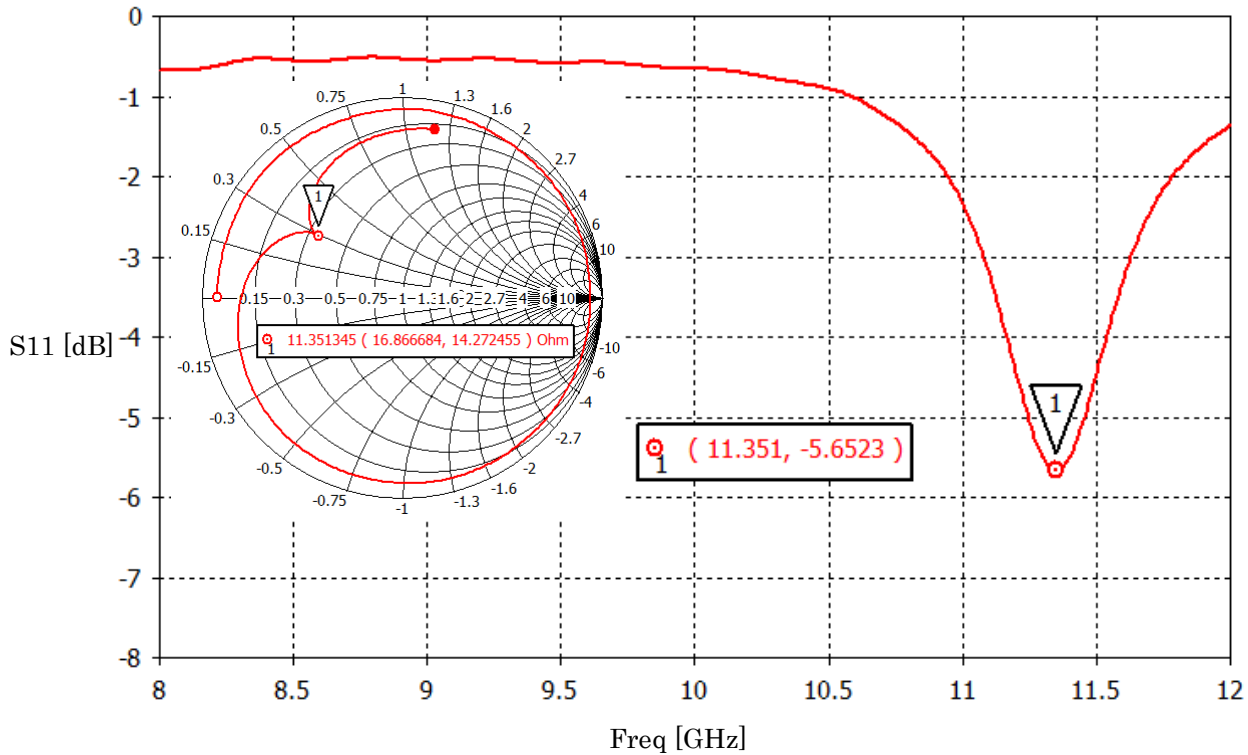


Figure IV.69 : Simulated return loss of the antenna alone

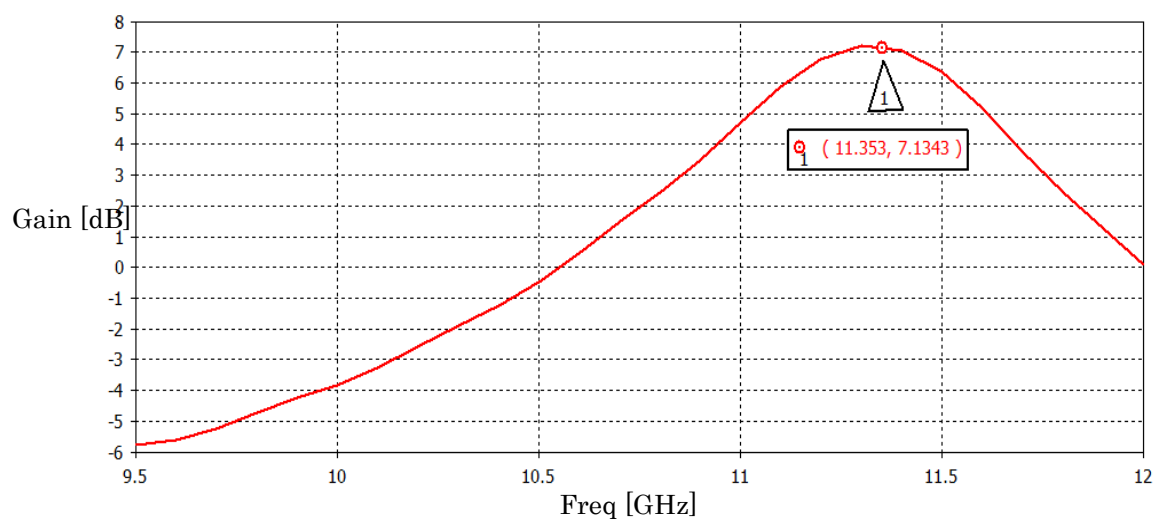


Figure IV.70 : Simulated antenna gain versus frequency

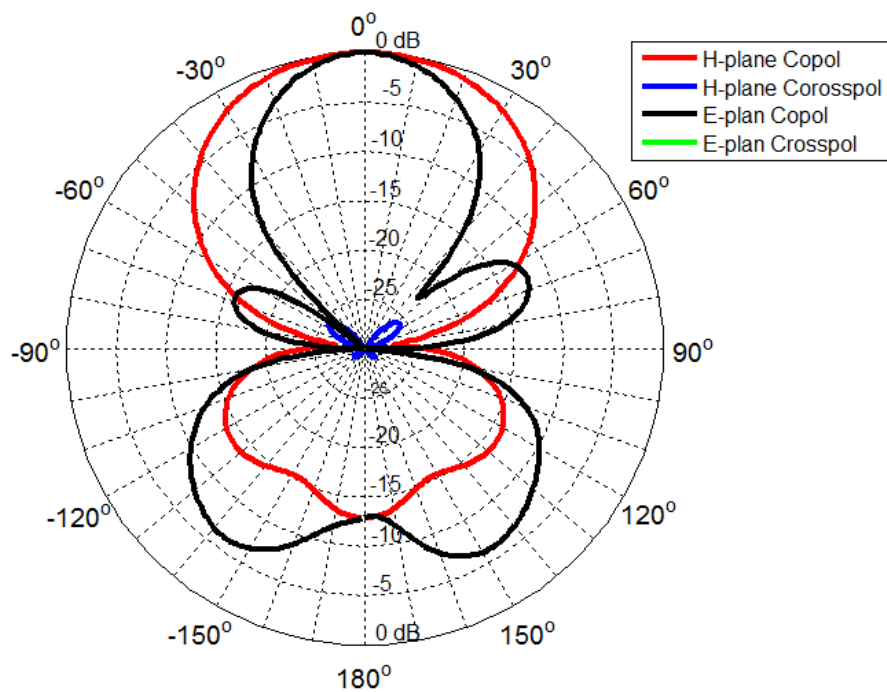


Figure IV.71 : Simulated normalized radiation pattern of the antenna at 11.35 GHz

The developed varactor diode was integrated with the antenna design, and the whole active antenna system was simulated. Figure IV.72 presents the variation of the return loss of the antenna versus frequency for different values of the varactor diode bias voltage. As can be seen, the minimum and the maximum values of the simulated input return loss are, respectively, -46 dB and -11.4 dB over a narrow bandwidth from 9.34GHz to 9.5GHz. Also it can be observed that, once the varactor model was added, the antenna achieves a good matching for all the DC bias voltage better than the simulated matching for the first proposed antenna (annular slot antenna). However, the tunability of the achieved bandwidth is two times narrower. It is about 1.7% of bandwidth from 9.34 GHz to 9.5 GHz.

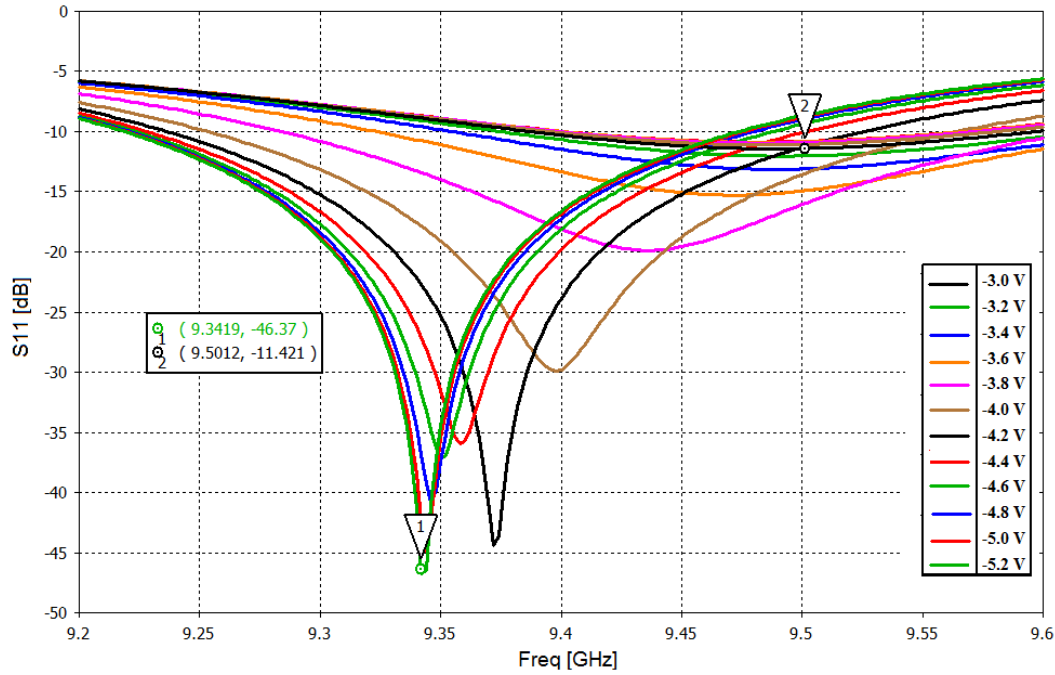


Figure IV.72: Simulated reflection coefficient (S_{11}) of the loaded antenna for different varactor reverse-bias voltages

3.3 Measured Return Loss and Radiation Pattern

To experimentally verify the simulated results of the antenna, the GaN varactor was wire-bonded over the slot layer as depicted in Figure IV.67. The first step is measure the return loss of the antenna at various DC bias value. Unfortunately, when varying the DC bias nothing change on the input reflection coefficient. We spent a lot of time to figure out where this problem comes, but we could not understand. This can be due to misconnect of the varactor with the antenna or/and the varactor device was broken during the wire-bonding steps. However, the reflection coefficient, gain and radiation pattern have been measured at 0 V. As is shown in Figure IV.73, the measured return loss of the antenna is around -7.3 dB at 10.6 GHz. Normally, at this bias point of 0 V, as was expected with simulation, the return loss should be -11.4 dB at 9.5 GHz. There a shift of almost 1 GHz, this can be due to the presence of the varactor even if it does not work as expected. The antenna gain versus frequency at this bias point is displayed in Figure IV.74. A gain value of 5.6 dB is achieved at 10.6 GHz, while the simulated gain value for the antenna alone at 11.35 GHz was around 7.1 dB. This gain difference can be due to the wires-bonding, the SMA connector used for exciting the antenna, slightly higher dielectric losses of the used substrates, and measurement uncertainty (e.g. a direction error) that were not included in the simulation. The normalized radiation pattern in the E-plane and H-plane at 10.6 GHz is depicted in Figure IV.75. In both planes, the antenna array generates a cross-polarization level about -15 dB in the main lobe direction which is two time larger to the simulated value. The simulated back side lobe in the main lobe direction is about -10 dB which is closely corresponding to the simulated value (-12 dB). With the measurement of the radiation pattern, no side lobes are observed unlike the simulation. This can be due to the presence in the E-plane of the connector that excites the antenna. The simulation has been done without this connector.

It was a depth disappointment that the varactor cannot work as expected to verify the simulation results. If so, this simple antenna structure would, no doubt,

have been a good application to validate our developed GaN varactor and also to demonstrate the use of GaN device in reconfigurable antenna systems.

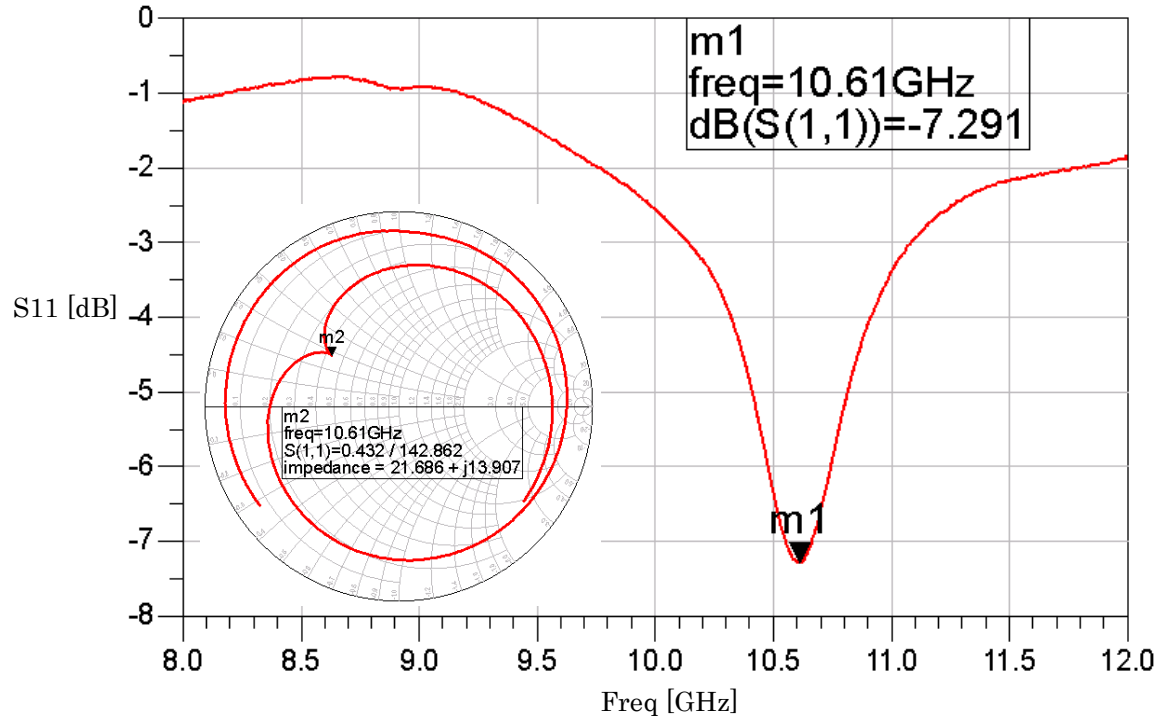


Figure IV.73: Measured return loss (S_{11}) of the loaded antenna at no DC bias applied

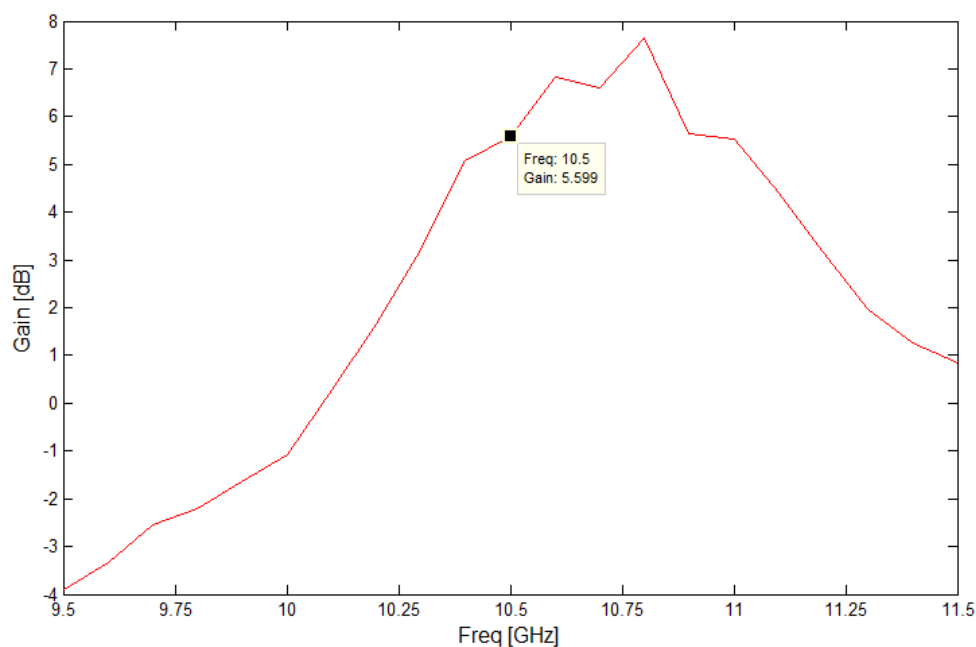


Figure IV.74 : Measured loaded antenna gain versus frequency at no bias DC applied

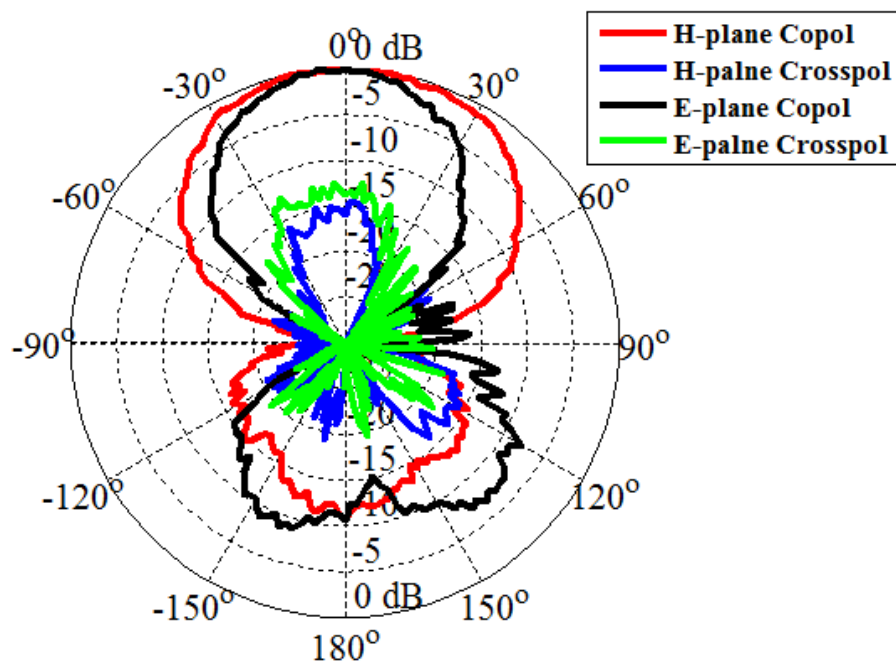


Figure IV.75 : Measured normalized radiation pattern of the loaded antenna at 10.6 GHZ with no bias DC applied

4. Beam Steering Patch Antenna Arrays using GaN SPDT Switch Structure

4.1 Antenna Design

In this section, an electronically beam steering antenna using the developed SPDT switch structure is proposed for applications that operate at 2.45 GHz frequency. Again, the idea here is to validate the developed GaN SPDT switch structure fabricated in NRC GaN500v2 process, for this a global system with four rectangular 4x1 patch array antenna is designed to achieve a beam steering over the H-plane for four Φ possibilities such as, 0° , 90° , 180° and 270° . With the use of this structure, the global array antenna can steer its beam in H-plane by a single control DC voltage (V_{c_1} , V_{c_2} , V_{c_3} and V_{c_4}) applied at the different single switches constituting the SPDT structure. In E-plane the beam is stable for all the SPDT switch structures possibilities. As discussed in the section about SPDT switch structure, the RF performances of this switch structure degrade versus frequency, so at this frequency of 2.45 GHz, an isolation better than -25 dB and an insertion loss around -3 dB have been predicted from the measurements of the single switches. In addition, the antenna system was designed on Neltec substrate 9300 having ϵ_r of 3.5 and a thickness t of 1.6 mm. Due to its high thickness, this substrate is very rigid and make the vertical system easier to be mounted. Therefore a cooling plate was cut from a piece of aluminium (Al), and is mounted on the backside (ground plane) of each 4x1 patch arrays antenna and of the feeding system design to transfers the heat generated by GaN switch structure and provides an infrastructure to mount the whole antenna system, the supply circuits and the RF connectors. The 3D model of the designed antenna system is illustrated in Figure IV.76. The whole concept size is $14 \times 14 \times 29 \text{ cm}^3$. As shown in Figure IV.76, the four sides rectangular 4x1 patch array antennas with series feed are placed perpendicular over the feeding system as illustrated in Figure IV.77. Here 4 elements are used and each elements has the same

dimensions with a length of 32 mm and a width of 38 mm in order to achieve higher gain that can be still higher to 0 once the RF signal goes through all the losses due to the SPDT (around -6 dB, wire-bonding and the substrate). In this design, the patch elements are connected using microstrip line with a length around half-wavelength ($\lambda_g/2$) in series feed and have been designed to operate around 2.45 GHz with input impedance of 50 Ω . The length and the width of the each connecting microstrip line are, respectively, 37.7 mm and 1 mm.

The SPDT switch structure are connected to the feeding system illustrated in Figure IV.78 by using wires-bonding technique as zoomed and depicted in Figure IV.79 while in Figure IV.80 a zoomed picture of the wires bonding is displayed to show the connected pads of the SPDT switch. Moreover, to facilitate the wire bonding connection between the feeding system design and the SPDT circuit, a gold layer over the copper metal was added as seen in Figure IV.78.

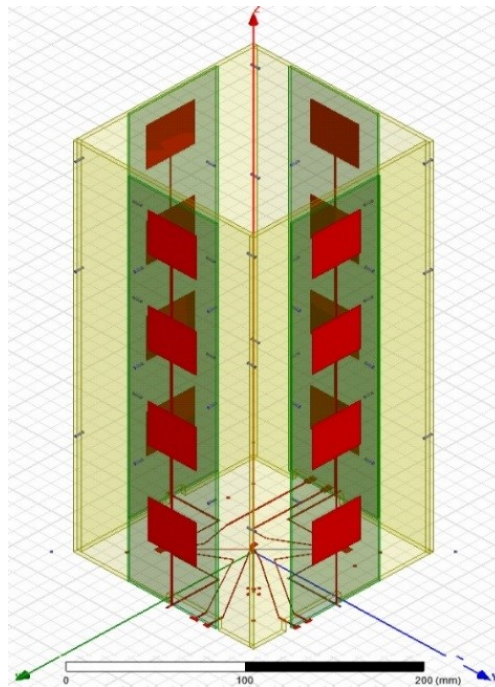


Figure IV.76: 3D model of designed antenna system.

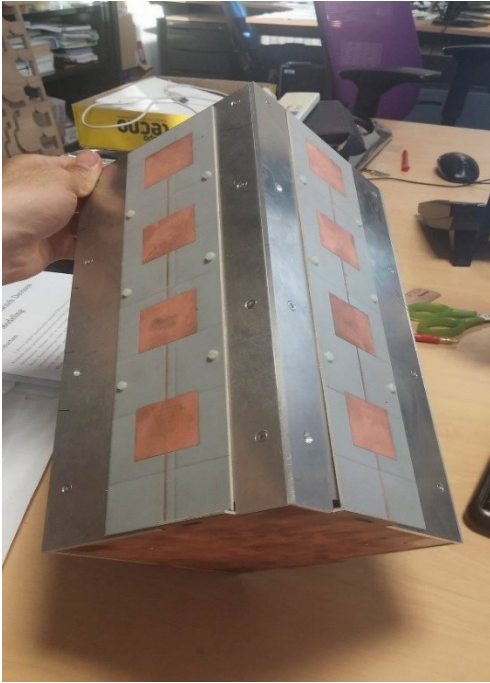


Figure IV.77: Fabricated prototype of the antenna

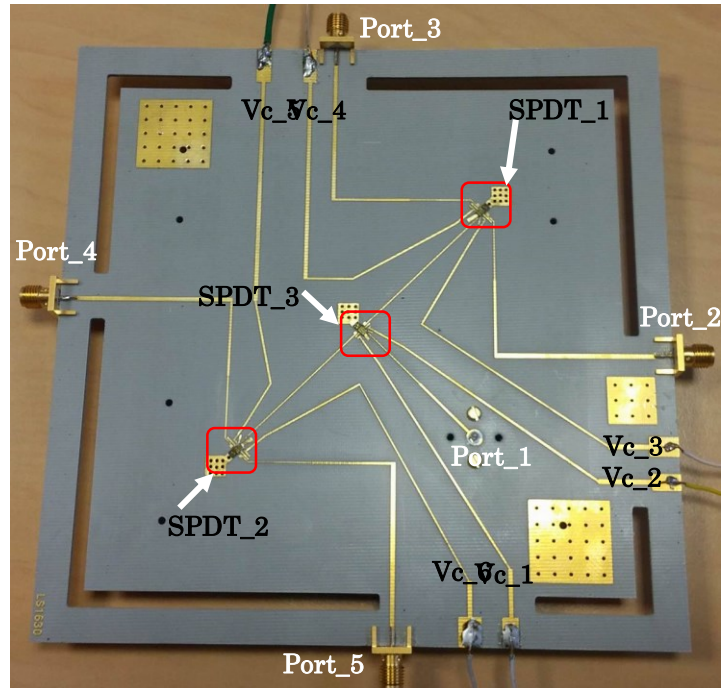


Figure IV.78: The feeding system including the three SPDT switch structures

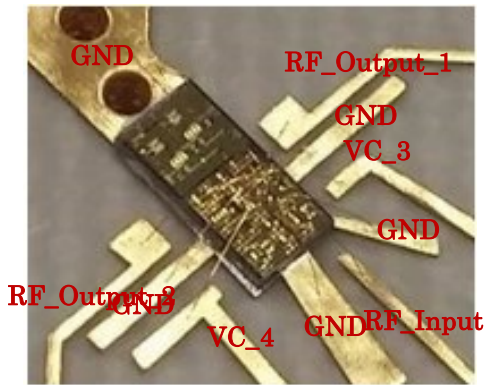


Figure IV.79: Zoom on SPDT_1 switch

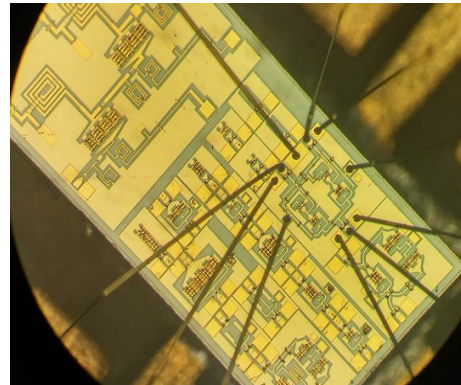


Figure IV.80: Zoom on the wires bonding connecting the SPDT_1 to The feeding system

For a better understanding of the antenna geometry, in Figure IV.77 the fabricated final prototype is shown. One of the four 4x1 patch array antenna is depicted in the Figure IV.81. The four 4x1 patch arrays antenna are fed by four separated horizontal strips that are placed over a separated design using same Neltec substrate (see Figure IV.78) along with the bias DC control network of the SPDT switch structure. This design is called the feeding system. The four excitation strips are joined together by matching circuit including the SPDT and the 4x1 patch antenna array to $50\ \Omega$. This matching circuit is based on quarter-wavelength ($\lambda/4$) matching technique. It depends of the switching states of the SPDT ports, the predicted impedances are summarized in Table IV.4. The coaxial probe is located at joint point of all the four excitation strips, which acts as antenna feed.

Table IV.4: Predicted different impedances of the SPDT ports.

	RF_Output_1 Port is ON and RF_Output_2 Port is OFF	RF_Output_1 Port is OFF and RF_Output_2 Port is ON
Impedance at RF_Input Port	$75-j*20.6\ (\Omega)$	$75-j*20.6\ (\Omega)$
Impedance at RF_Output_1 Port	$77.05-j*18.6\ (\Omega)$	$60.10-j*9.85\ (\Omega)$
Impedance at RF_Output_2 Port	$60.10-j*9.85\ (\Omega)$	$77.05-j*18.6\ (\Omega)$

As depicted in Figure IV.78, three SPDT switches were placed between the four patch antenna arrays and the matching circuit. The first one was placed to steer the beam for 0° and 90° , the second one to scan the beam for 180° and 270° , while the third one was placed between the main feeding transmission line (connected to the cable coaxial) and the two first SPDT to switch the RF signal to a one of them at once. Due to unavailability of a complete model of the SPDT switch structure, as mentioned in Chapter III in SPDT switch section, depending upon the state of the SPDT switch a short circuit or open circuit was used between the corresponding patch antenna array and the matching circuit when necessary to conduct the EM simulation.

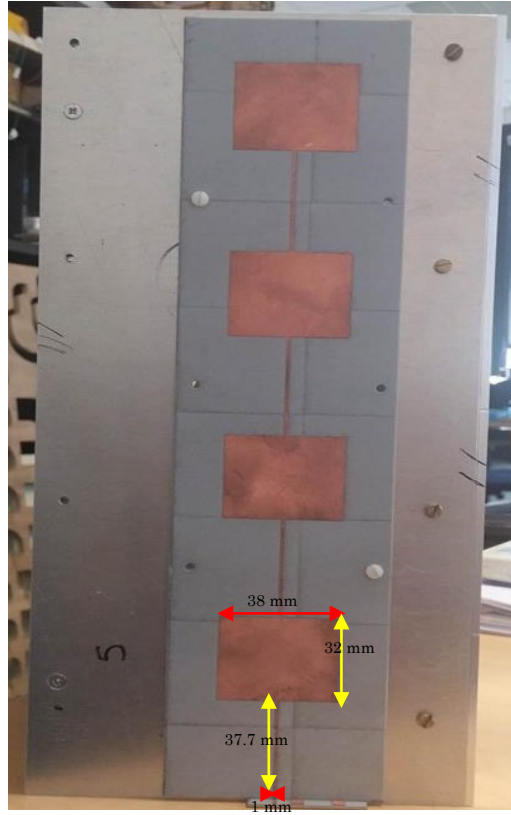


Figure IV.81: Front view of the fabricated antenna

4.2 Simulated Return Loss and Radiation Pattern

The EM simulations allowing to get the return loss and the radiation pattern were performed by using HFSS. Table IV.5 summarizes the four cases or the four beam steering possibilities corresponding to the three SPDT switches states.

Table IV.5: Switching configuration to achieve radiation pattern reconfigurability.

	SPDT_1		SPDT_2		SPDT_3		Φ (deg)
	RF_Output_1	RF_Output_2	RF_Output_1	RF_Output_2	RF_Output_1	RF_Output_2	
Case_1	ON	OFF	OFF	OFF	OFF	ON	0°
Case_2	OFF	ON	OFF	OFF	OFF	ON	90°
Case_3	OFF	OFF	ON	OFF	ON	OFF	180°
Case_4	OFF	OFF	OFF	ON	ON	OFF	270°

As highlighted in one 4x1 patch arrays antenna return loss which is shown in Figure IV.82, an impedance bandwidth of approximately 40 MHz (2.45 GHz to 2.41 GHz) is achieved, with a resonance frequency sensing at approximately 2.43 GHz. At this frequency, a return loss value better than -30 dB is obtained in simulation for one 4x1 patch arrays antenna. Because the return loss of the four 4x1 patch arrays antenna are similar, here we report only return loss for one which corresponding to one case.

The radiation pattern in H-plane corresponding to the four cases possibilities is shown in Figure IV.84. A shift of 90° between the four cases in the radiation pattern is clearly achieved. The 3-dB beam width where the four beam configuration cases intersect for each case is found to be approximately 85°.

For a better understanding of beam switching, the antenna radiation pattern is tilted towards the positive z-axis having maximum at $\Phi=90^\circ$, $\theta=0^\circ$, here switches are configured as mentioned in Table IV.5 for case 1, is tilted towards the positive x-axis when switches are configured as mentioned in case 2 having maximum at $\Phi=0^\circ$, $\theta=90^\circ$, is tilted towards the negative z-axis when switches are configured as mentioned in case 3 having maximum at $\Phi=90^\circ$, $\theta=-180^\circ$ and for the fourth case it is tilted towards the negative x-axis when switches are configured as mentioned in case 4 having maximum at $\Phi=-180^\circ$, $\theta=-90^\circ$.

The overall gain of one 4x1 patch arrays antenna is found to be above 10.9 dB at the operating frequency of 2.43 as depicted in Figure IV.83. It is important to keep in mind that in the EM simulation only short and open were used instead of the model of the SPDT, this means that almost -3dB of losses of one SPDT switch structure has to be considered. So this will results on the maximum antenna gain value that would decrease with almost -6 dB because the RF signal go through two SPDT switch structures as explained in Table IV.5 . Furthermore, there will be also other losses due to the substrate and the wires-bonding connecting the SPDT to the

transmission lines. The overall losses is measured for every case and will be presented later in this section.

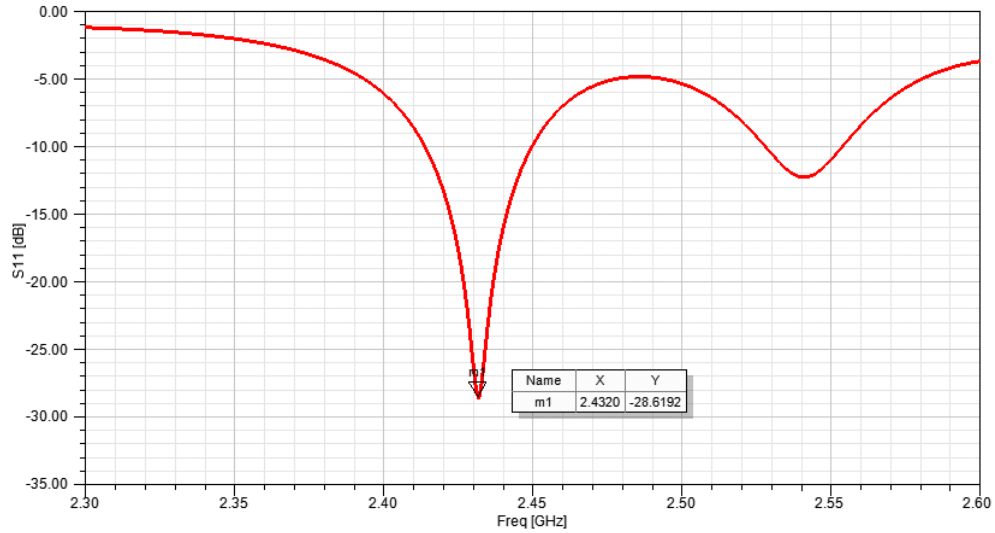


Figure IV.82: Simulated return loss of the antenna

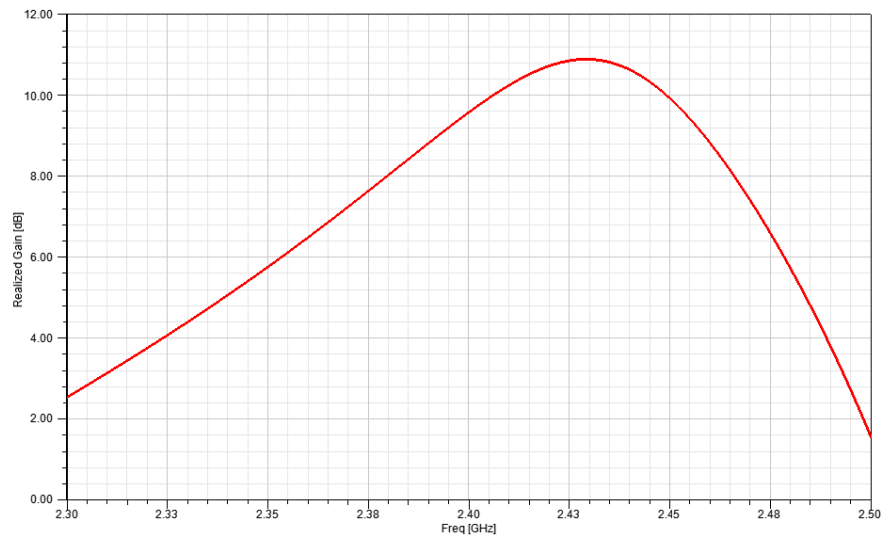


Figure IV.83: Simulated antenna gain versus frequency

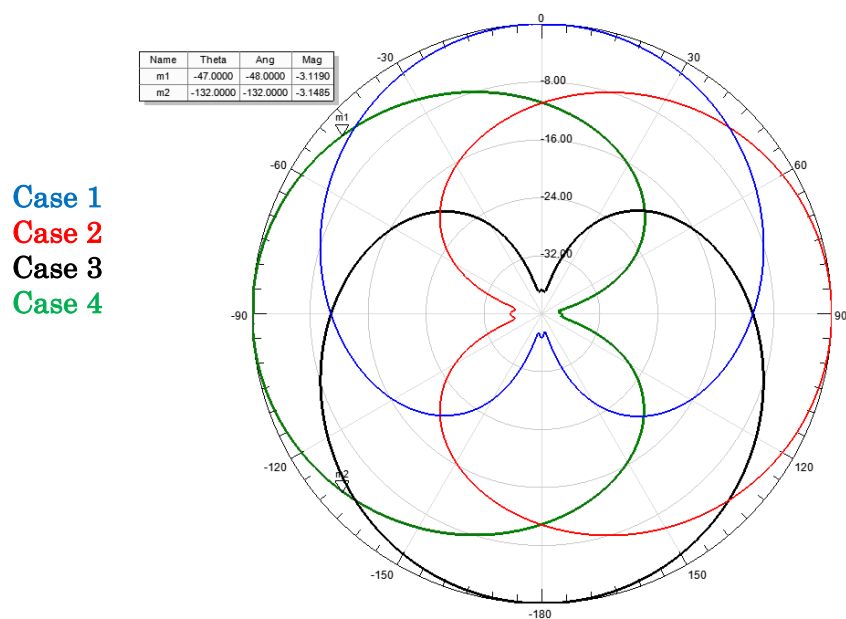


Figure IV.84: Simulated normalized *H*-plane at 2.43 GHz for four cases mentioned in Table IV.4

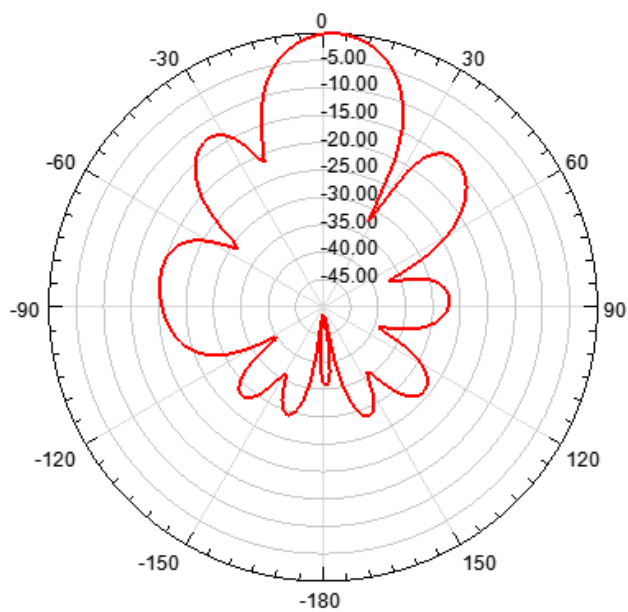


Figure IV.85: Simulated normalized *E*-plane at 2.43 GHz

4.3 Measured Return Loss and Radiation Pattern

Here, the experimentally measurements are presented and results are discussed. These measurements will verify the simulation results. Figure IV.86 shows the return loss of one fabricated 4x1 patch arrays antenna prototype. It indicates that the 4x1 patch arrays antenna presents a good match with $|S_{11}|$ of -25.5 dB at a resonant frequency of 2.43 GHz which is completely corresponding to what was achieved with simulation where a $|S_{11}|$ of -28.6 dB was obtained at 2.43 GHz. This value of the return loss was verified for all four fabricated 4x1 patch arrays antenna, and here we report only return loss for one which corresponding to one case. The antenna gain versus frequency is displayed in Figure IV.87. A gain value of 10.1 dB is achieved at 2.43 GHz, while the simulated gain value for the antenna alone at this frequency was around 10.9 dB. Conductor losses, slightly higher dielectric losses of the used substrate, also some set up errors during the measurement, can be the main reasons of the 0.8 dB gain difference. As was expected, this measured gain of 10.1 dB decreased by almost -7 dB once the measurement with the SPDT structure is conducted. -6 dB corresponding to the losses of the two SPDT structures as explained in Chapter III in Figure III.57 while the -1 dB is due to the substrate losses, the transmission lines and the wire banding.

The simulated radiation pattern of the patch array antenna in both H-plane and E-plane has been verified by measurement at 2.43 GHz. Satisfactory agreement with the simulation was achieved as shown in Figure IV.88 where the measured radiation pattern in the H-plane for four cases is illustrated while in Figure IV.89 depicts the measured radiation pattern in the E-plane. It is seen that the beam steering operation of the radiation pattern in H-plane is achieved over the expected four direction. The radiation pattern shows the cross-pol level in the broadside direction lower than -30 dB in the H-plane and -25 dB in the E-plane and a low side lobes of -15 dB in the E-plane.

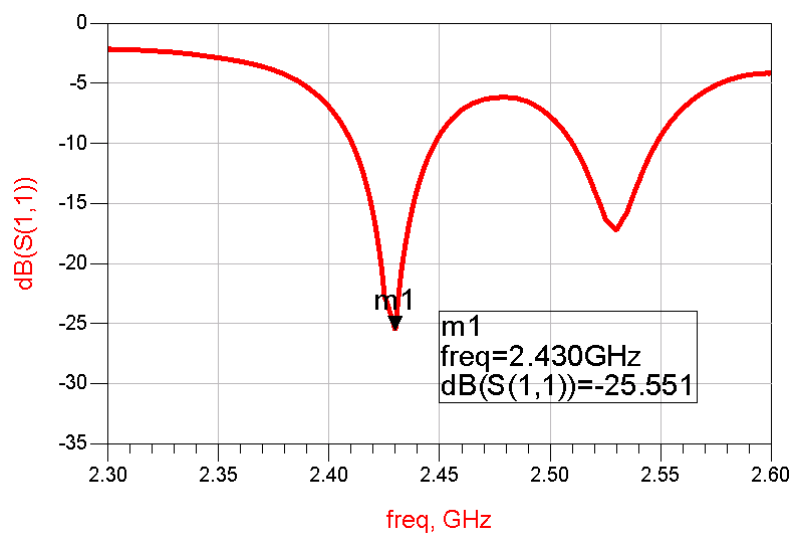


Figure IV.86: Measured return loss of the antenna

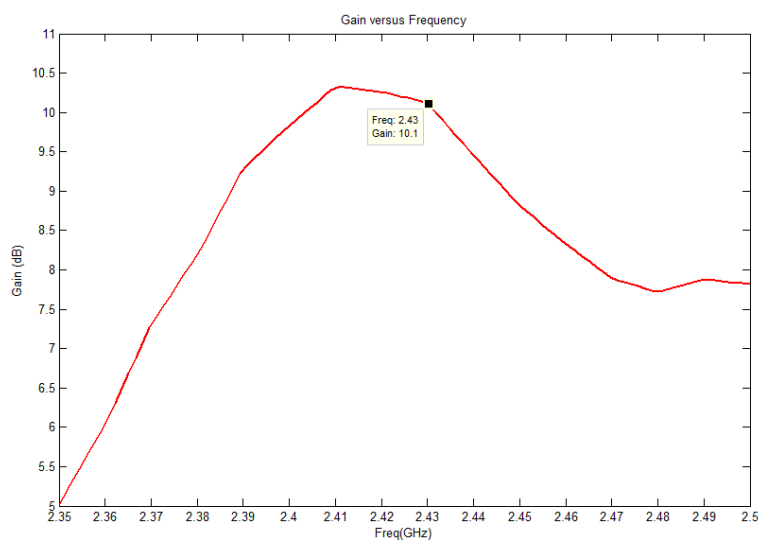


Figure IV.87: Measured antenna gain versus frequency

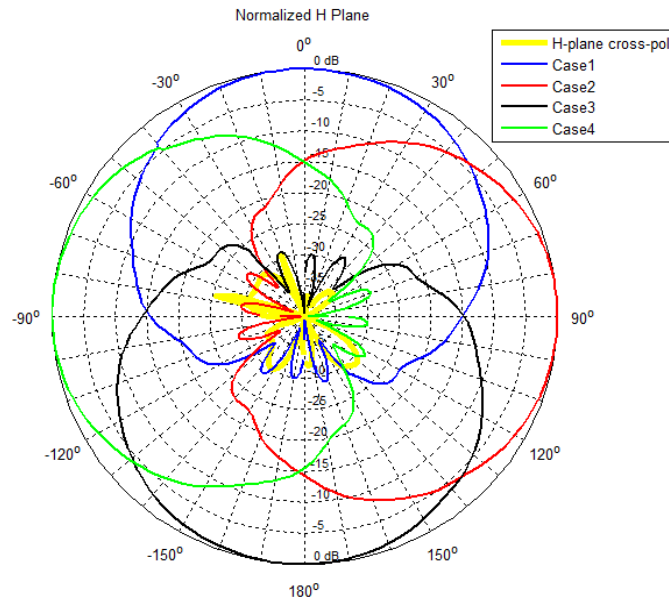


Figure IV.88: Measured normalized H plane at 2.43 GHz for four cases mentioned in Table IV.4

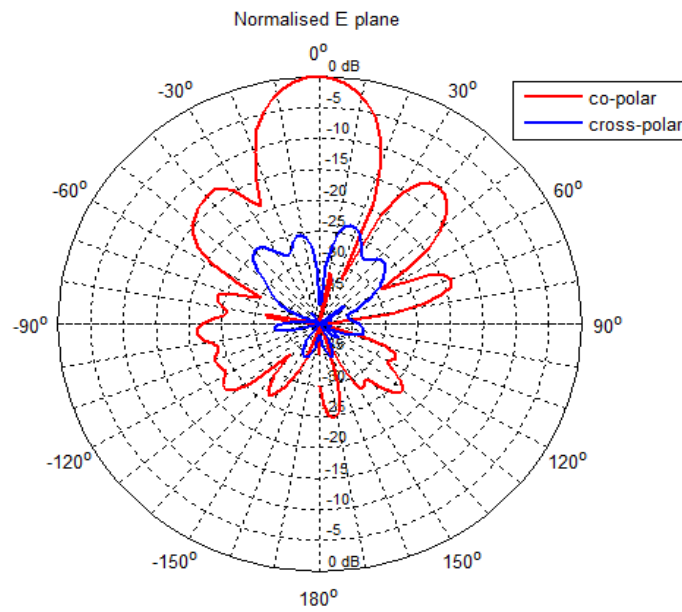


Figure IV.89: Measured normalized E plane at 2.43 GHz

4.4 Measured Insertion Loss and Isolation of the Feeding System

4.4.1 Small Signal Measurements

Depending on the two states of the three SPDT switch structures (as indicated in Table IV.5), the *s*-parameters at the different four ports, Port_1, Port_2, Port_3, Port_4 and Port_5, (see Figure IV.78) of the feeding system design have been measured. The *s*-parameters measurements are to be made between the common port, Port_1, and one of the others output ports, either Port_1, Port_2, Port_3 or Port_4.

When the SPDT is configured for case_1, the insertion loss is measured between the Port_1 and the Port_2 along with the isolation at the other ports. As illustrated in Figure IV.90, the insertion loss and the isolation are shown. It can be seen that the return loss at both ports (i.e Port_1 and Port_2) indicates low reflections around -6.8 dB at the frequency of interest 2.43 GHz since at this frequency the input port and the two output ports of the three SPDT have well matched to 50 Ω . Because the RF signal go from Port_1 to Port_2 through two SPDT switch, the measured -6.8 dB insertion loss value is due to the insertion loss of SPDT switches which was around -3 dB as would be expected for one SPDT and the losses of the used substrate, the metal and the wires bond which can be -0.8 dB. The measured isolation is higher than -25 dB at all ports and all configurations cases.

Similarly, the same considerations of measurement are applied if the measurements are between the Port_1 and the other output ports. In Figure IV.91, Figure IV.92 and Figure IV.93, the measured insertion loss and the isolation are displayed, respectively, for case_2, case_3 and case_4. It is clearly seen that, depending the case, measured the insertion loss is around -7.14 dB (i.e case_2) at the worst value and is around -6.62 dB (i.e case_4) at the good value. This difference of

0.5 dB can be due mainly to the misconnection (i.e weld the connector) of the SMA connector at the different ports.

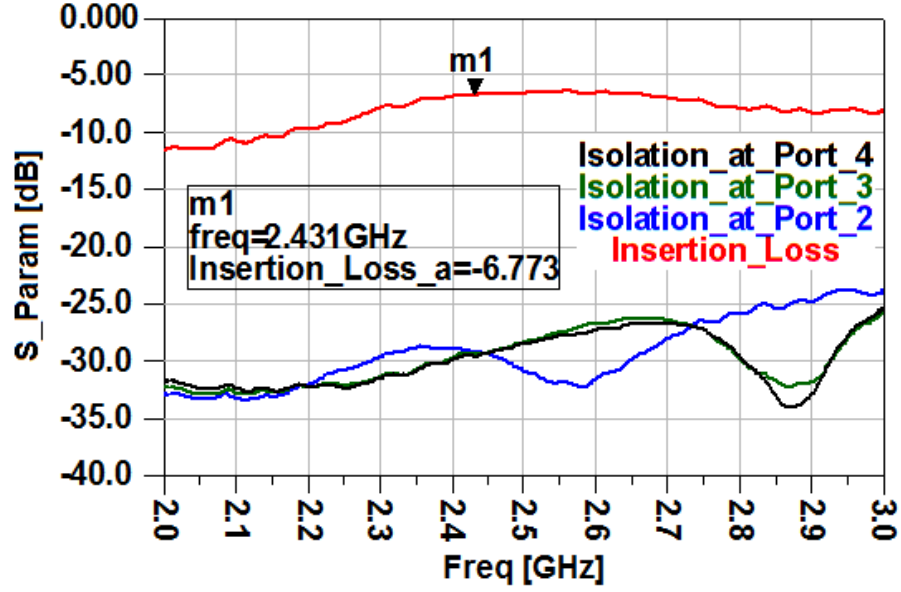


Figure IV.90: Measured S -parameters for case_1 at Pin of 0 dBm

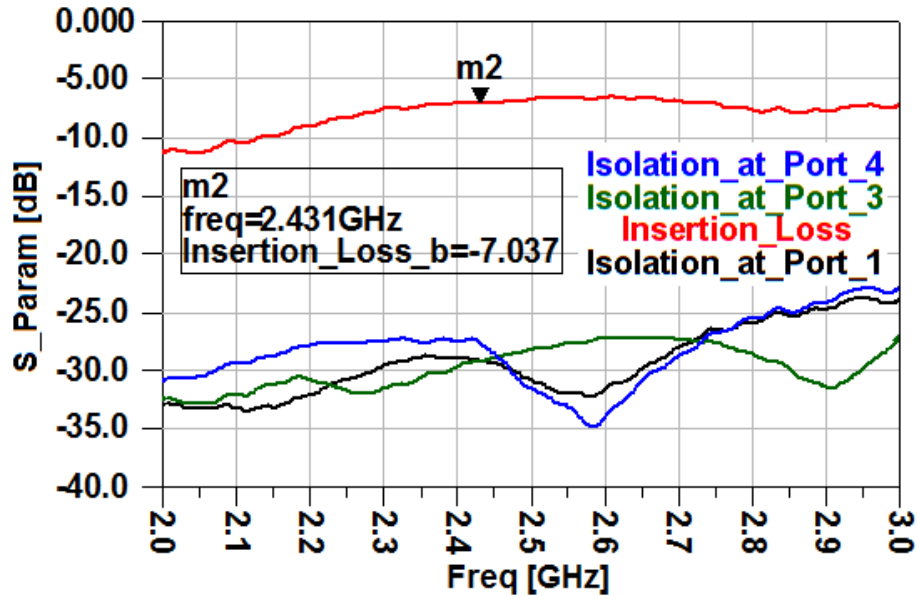


Figure IV.91: Measured S -parameters for case_2 at Pin of 0 dBm

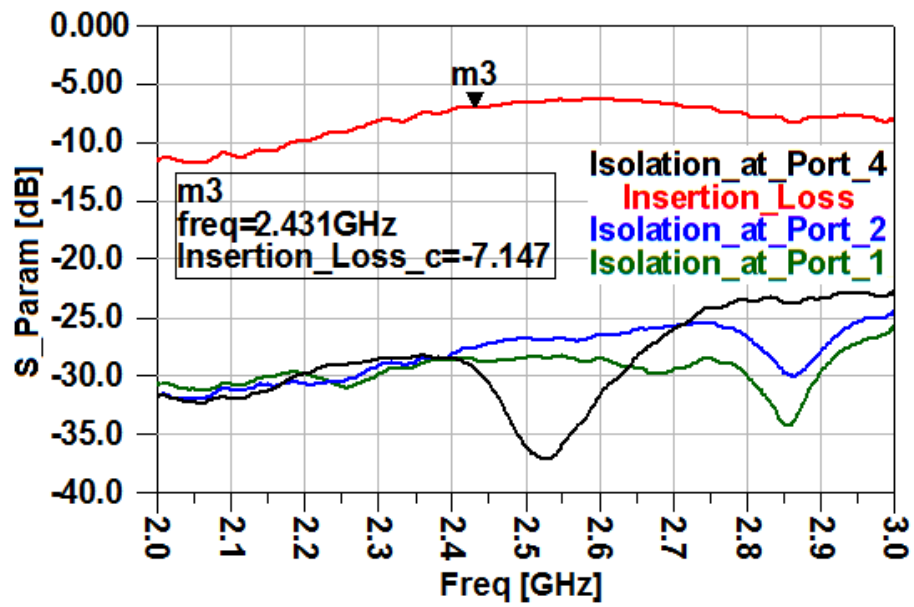


Figure IV.92: Measured S -parameters for case_3 at Pin of 0 dBm

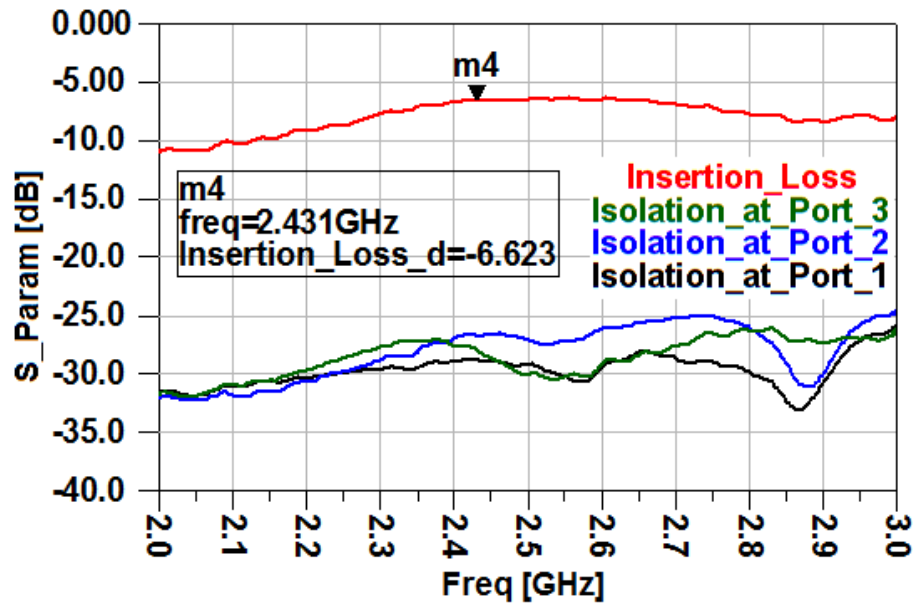


Figure IV.93: Measured S -parameters for case_4 at Pin of 0 dBm

4.4.2 Large Signal Measurements

The objective here is to demonstrate that GaN-based switch structure can simultaneously achieve reasonably high power handling capability without sacrificing insertion loss and isolation. To satisfy these requirements, a RF power sweep from 0 dBm to 30 dBm at the Port_1 has been done and the insertion losses were measured between Port_1 and Port_2 at these different level of power.

The measured power handling capability of the SPDT switch at 2.43 GHz is shown in Figure IV.94. The insertion loss for ON state was measured with the increasing of input power level at 2.43 GHz for case_1 configuration. As seen the insertion loss remains almost constant up to 16 dBm input power. The measured data shown in Figure IV.94 demonstrates less than 1 dB of compression for 20 dBm incident RF power at 2.43 GHz. The input power capability of 20 dBm handled by the used GaN transistor can be confirm the potential of using GaN technology for high power regarding the small size of these used devices (as mentioned in Switch modeling section, the devices used are $2 \times 25 \mu\text{m}$ and $2 \times 50 \mu\text{m}$ gate width).

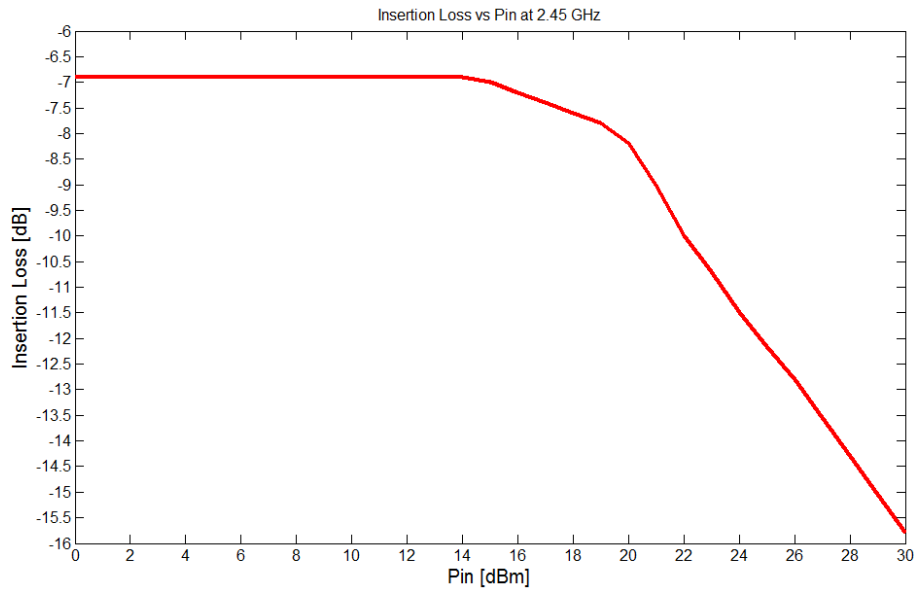


Figure IV.94: Measured insertion loss versus input RF power for case_1 at 2.43 GHz

VI. Summary

This preceding chapter deals with implementing reconfigurable designs to validate and verify the use of our developed GaN varactors and switches and demonstrate the feasibility of using GaN technology in tunable RF/microwaves systems. Reconfigurable designs such as phase shifter, 3-dB 90° hybrid coupler, oscillator and patch antenna arrays were designed and discussed. The reconfigurability operation is achieved by using the developed GaN HEMT-based varactor and switch devices as was expected. These GaN circuits were embedded with the listed design by using the wire bonding technique.

Chapter V

Conclusion and Future Work

This thesis is primarily focused on developing models of varactor diodes and switches fabricated using the newest semiconductor technology, gallium nitride (GaN). Varactor and switch devices play a crucial role in design, development and overall performance of wireless communication systems that require reconfigurability. The thesis can be divided into two major parts: modeling of GaN-based devices such as varactor diodes and switches, and reconfigurable designs where these developed GaN devices are integrated.

The active devices structure studied here are based on GaN HEMT processes offered by National Research Council. Three GaN processes, such as, GaN150v0 with a gate length of 0.15 μm , GaN500v1 with gate length of 0.5 μm and GaN500v2, have been used for manufacturing the varactor diodes and the switches. Based on these three GaN processes, many varactors have been fabricated and characterized. A general small signal and large signal model based on analytic

equations containing empirical coefficients have been introduced for the first time for the voltage dependency of equivalent capacitance (C_{Eq}) and series resistance (R_{Eq}). For small signal model, all of the developed analytic equations, which describe R_{Eq} and C_{Eq} versus the control DC voltage (V_G), are only bias voltage and device geometry dependent, while for large signal, the influence of RF power has been taken into account in the proposed analytic expressions describing the behaviour of R_{Eq} and C_{Eq} . These proposed analytical solutions agree remarkably well with the experimentally extracted C-V curves for several RF power and can be used as a general model to represent the nonlinear behavior of GaN based varactor devices. By analyzing the C-V curve, we conclude that the equivalent series capacitance is dependent on the geometry of fingers. This means that the larger is the device, the higher are the capacitance values. Moreover, it was observed that the extracted capacitance values from varactors with GaN500v2 are at least twice as large as those extracted with the same device size fabricated with GaN500v1 process. The tuning range of the varactor diode is limited, and it was found that over a range of 1 V, the C_{Eq} changes rapidly. In addition, an equivalent simple physical circuit model was proposed and simulated, yielding good agreement between the simulated and the measured results. The obtained C_{max}/C_{min} ratios and figures of merit compare favorably with recently reported GaN varactors.

On the other hand, different size single standalone switches and switch structures such as single pole single throw (SPST) and single pole double throw (SPDT) were fabricated using NRC GaN500v2 and were presented. Here only small signal measurement were presented and discussed. It was observed that, with a single transistor in common gate configuration, the isolation is good at low frequencies but quickly drops with increasing frequency. In addition, it was observed that the more the device is large, the lower the insertion loss achieved but the poorer the isolation will be. A trade-off between insertion loss and isolation has been made to choose the single transistors that will be used for designing switch structures such as SPST and SPDT which could improve the performances at high frequencies.

Comparing to the standalone device, it was revealed that with SPST structure, the isolation is improved while the insertion loss slightly dropped by -1 dB. With this proposed topology, it is still a challenge to meet good performance at our higher frequency. Another topology based on SPDT was proposed to improve more the performances. As was expected with this topology, some improvement in isolation is achieved compared to SPST, while the insertion loss is increased by almost -1 dB. For example, at 2.45 GHz (frequency of interest) isolation better than -25 dB and an insertion loss of -3 dB were achieved. However, the SPDT structure performances degrade with frequency. Moreover, based on these small signal measurements, a model was introduced. In addition, the fabricated SPDT switch structure will be integrated with antenna system to demonstrate the ability of using GaN devices for a beam switching antenna array.

Finally, in this thesis, the use of GaN on highly efficient reconfigurable designs for broadband RF/microwave applications operating below 10 GHz was demonstrated. The varactors and switches used for tunable purpose were firstly fabricated, characterized and then modeled. The proposed models were used to achieve the reconfigurability of RF/microwave circuits. Tunable phase shifter, reconfigurable 3-dB 90° hybrid coupler, tunable frequency oscillator, beam switching antenna array and matching reconfigurable patch antenna were developed along with the development of GaN modeling varactors and switches, and were presented as applications results of this thesis research.

Using GaN150v0 process, two reconfigurable RF designs have been designed and reported. Firstly, a GaN phase shifter design based on reflective topology has been described, and only simulation results were presented. First, the 3-dB 90° hybrid coupler has been designed and simulated using NRC GaN150 PDK. Then two developed GaN varactors were placed on the two coupler's output ports as loads. Under different bias conditions varying from -3.5 V to -5.5 V, the return loss of the phase shifter is better than 20 dB across a 1 GHz bandwidth centered at 10 GHz,

while good match is achievable over this range of 9.5–10.5 GHz. Worst case of the insertion loss is about -3 dB at 10 GHz and occurs at a bias point of -4.3 V where the equivalent resistor of the used varactors is significantly high. Therefore, a continuously variable phase-shift range of 80° is achieved at 10 GHz. Secondly, a varactor tunable broadband quadrature hybrid coupler has been investigated and simulated from X-band to Ku-band frequencies applications, and only simulated results were reported. First, a static coupler has been designed to meet the specifications of a typical quadrature hybrid coupler (3-dB insertion loss, good return and isolation loss, and 90° phase difference between coupled and through ports) at 10 GHz. Then, a tunable broadband coupler has been designed by inserting varactor diodes as shunt capacitance elements in order to control the operating frequency. This design occupies an area of 1.35×0.9 mm² and good simulation results have been demonstrated. This novel varactor reconfigurable hybrid coupler is proposed to overcome the need of high power tunable RF/microwave circuits which are required for multi-standard and multiservice applications. By changing the bias voltage of the varactor to control the resonance condition of parallel LC resonator, this proposed hybrid coupler can provide the desired operating frequency from 10 GHz to 16 GHz. Over this bandwidth, the overall return loss is better than -13.5 dB over a tuning range 1 V while the isolation is below than -14 dB. In addition, the simulated magnitude of S₂₁ parameter is close to -3.5 dB and is getting poorer as varactor capacitance values decreases. A worst value of -5 dB is achieved at the minimum capacitance value. While at port 3, the S₃₁ parameter behaves as S₂₁ but in a reverse way. As a result, the amplitude imbalance is varying from -0.2 dB at 10 GHz and -2 dB at 16 GHz. A minimum well-balanced quadrature phase of 86° is obtained between the coupled port 2 and the through port 3. This phase is increasing and getting closer to 92 ° as varactor capacitor values are decreasing.

Using GaN500v2 process, a tunable frequency GaN oscillator was designed by loading symmetrically the feedback loop, and was presented. For tuning purpose, the previous developed GaN varactors were used. The oscillation frequency values

change significantly and a minimum oscillation frequency of 7.8 GHz was achieved when C_{Eq} is at its maximum for V_G above -3.5 V, and a maximum oscillation frequency of 8.6 GHz was simulated when C_{Eq} is at its minimum for V_G below -4.5 V. While, when V_G varies from -5 V to -3.7 V, the oscillation frequency values change significantly and a tuning bandwidth of 0.8 GHz is obtained, corresponding to a tuning range about 10%. The output power is about 20.5 dBm and almost stable over all bias levels with a slight variation over range (2) when V_G varies while a good phase noise value of -112 dBc/Hz is met at 100 KHz. Also three reconfigurable antennas were designed and presented. The first design is a simple element square loop coplanar antenna printed onto glass substrate. The frequency tunability has been achieved by loading the previous developed GaN varactor diode. The antenna was electronically tuned by varying the varactor bias voltage applied at the gate, V_G . As reported, the minimum and the maximum values of the measured input return loss are, respectively, -6.9 dB and -7.1 dB over the bandwidth from 7.53GHz to 7.85GHz corresponding to a tunability up to 4% narrow bandwidth inside. This frequency tunability is achieved by using a developed GaN varactor. Another frequency reconfigurability antenna was described and presented. The used structure is based on aperture coupled microstrip patch antenna feed technique. The antenna structure with overall dimensions L of 50 mm and W of 50 mm consists of two dielectric layers: a slot layer and a simple element patch layer and between them an air-gap layer of 1mm. As presented, the minimum and the maximum values of the simulated input return loss are, respectively, -48 dB and -13 dB over a narrow bandwidth from 9.34GHz to 9.5GHz. This tunability is achieved by integrating a developed varactor with the antenna design. The last reported reconfigurable antenna design is an electronically beam steering antenna using the developed SPDT switch structure is proposed for applications that operate at 2.45 GHz frequency. The idea here is to verify the developed GaN SPDT switch structure fabricated in NRC GaN500v2 process, for this a global system with four patch arrays antenna with beam steering over the H plane for four Φ possibilities such as, 0° , 90° , 180° and 270° is designed.

With the use of this structure, the global array can steer its beam by a single control DC voltage applied at the different single switches constituting the SPDT structure.

Some contributions to the field of microwave integrated and reconfigurable circuit designs have been made from this thesis research. As mentioned in Chapter III, one journal paper [149] has been published and one other has been submitted [151]. A conference paper has also been presented at the European Microwave Conference in Paris in 2015 [150]. Furthermore, a part of the work of the beam steering patch antenna arrays using GaN SPDT switch that was presented in Chapter IV section 4 will be presented at the European Conference on Antennas and Propagation in Paris in 2017

[152] and also based on the antenna work one journal paper is expecting to be submitted for publication.

Despite all the obstacles that we faced during the manufacturing of the GaN design (such as, runs cancelled, chips dicing ...), we succeed to overcome some of them and develop GaN varactor and switch devices which were later integrated with PCB designs to achieve reconfigurability.

There are several areas related to this thesis which are ripe for study. First, if the required equipment became available, large-signal GaN device modeling, particularly for varactor switch devices is an area which should be developed. Improved performance in large signal operation and going higher in frequency of these devices can be expected when improved commercial NRC GaN150 become fully available.

Initially, a NRC GaN150 run was planned and highly miniaturized phase shifter and reconfigurable hybrid coupler designs were planned to be fabricated and tested. Unfortunately these designs have not been manufactured because the run has been cancelled by NRC. So future work could be include both phase shifter and reconfigurable hybrid coupler using the advanced developed version of NRC GaN150

process. Also it was expected to develop a frequency tunable antenna feeder such as annular slot antenna using varactor diode for reconfigurability. This feeder can be used to tune the frequency of an antenna that is fabricated by using a low cost substrate.

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